## **Exercise 1 -- Flash an LED**

#### **Host Computer Setup**

This exercise requires you to first install the Ada toolchain for your computer and check out some **git** source code repositories, per the instructions in:

http://git.munts.com/ada-remoteio-tutorial/Setup.pdf

After completing the standard setup procedure, the Ada compiler toolchain should be accessible at **C:\PROGRA~1\GNAT** for Windows or **/usr/local/gnat/** for Linux and MacOS X.

#### Last Minute Setup

If you have **not** already set up your computer per **Setup.pdf**, you can now perform a quick installation procedure, using an archive file provided on a USB memory stick that will be passed around at this time.

Just unpack the archive file on the USB memory stick appropriate for your computer (windows.zip, linux.tgz, macos.tgz) into your home directory.

Note: For Debian and Ubuntu Linux, you must also install these packages:

sudo apt install build-essential libhidapi-dev

Note: For MacOS, you must also build and install the HID API library:

cd \$HOME/hidapi ./bootstrap ./configure make sudo make install

After completing the last minute setup procedure, the Ada compiler toolchain should be accessible at **%HOMEDRIVE**%**\*MOMEPATH**%**\gnat** for Windows or **\$HOME/gnat** for Linux and MacOS X.

# **Hardware Setup**

Plug the development board assembly (Raspberry Pi Zero or BeagleBone Green) from the hardware kit into a USB port on your computer. Your computer should automatically configure a USB raw HID device, possibly requiring you to deal with one or more pop-ups.

#### **Exercise Instructions**

Following are instructions for Windows, and Linux/MacOS X for this exercise. For each operating system there are two sets of instructions: One using the command line and another using the **gps** IDE for GNAT. It is advisable to use **gps**, if possible, because it allows you to easily examine all of the component source files.

### **Microsoft Windows**

Note: The **set GNAT** commands below are unnecessary if the Ada toolchain **bin** directory is already in the program path.

#### **Using the DOS Command Line**

1. Open a DOS command window by running **cmd.exe** and run the following commands:

The LED on the LPC1114 I/O processor board should begin blinking.

2. When you are done observing the LED, stop the program with **CONTROL-C** and then run the following command to remove all of the working files and return **ada-remoteio-tutorial/** to the pristine state:

clean.cmd

### **Using the GPS IDE (Optional)**

1. Open a DOS command window by running **cmd.exe** and run the following commands:

```
set GNAT=C:\PROGRA~1\gnat or set GNAT=%HOMEDRIVE%%HOMEPATH%\gnat
cd ada-remoteio-tutorial
copydll.cmd
%GNAT%\bin\qps -P test led.qpr
```

- 2. Press F4 to build test led.
- 3. Press **SHIFT-F2** to run **test led**.

The LED on the LPC1114 I/O processor board should begin blinking.

## **Going Further**

Try temporarily replacing the Raspberry Pi or BeagleBone Green assembly with one of the other Remote I/O server devices that are being passed around. With the notable exception of the red **FEZ**, most of the other servers also have an LED on Remote I/O GPIO channel 0. You should be able to run **test\_led** unmodified with them.

If you want to try the same thing on the FEZ, you will need to change the value for the constant Channel\_LED to 20 or 21 and then rebuild test\_led. (The FEZ assigns Remote I/O GPIO channels 0 to 13 to the D0 to D13 signals of the Arduino expansion headers. See the package RemoteIO.FEZ for more information.)

## **Linux and MacOS X**

Note: The **export** commands below are unnecessary if the **bin** directory for the Ada toolchain you will be using is already in the program path (e.g. you are using the Debian native Ada toolchain).

#### **Using the Command Line Shell**

1. Open a terminal window to get a command shell and run the following commands:

```
export GNAT=/usr/local/gnat or export GNAT=$HOME/gnat
cd ada-remoteio-tutorial
make test_led
./test led
```

The LED on the LPC1114 I/O processor board should begin blinking.

2. When you are done observing the LED, stop the program with **CONTROL-C** and then run the following command to remove all of the working files and return **ada-remoteio-tutorial/** to the pristine state:

make clean

### **Using the GPS IDE (Optional)**

1. Open a terminal window to get a command shell and run the following commands:

```
export GNAT=/usr/local/gnat or export GNAT=$HOME/gnat
cd ada-remoteio-tutorial
$GNAT/bin/gps -P test_led.gpr
```

- 2. Press F4 to build test led.
- 3. Press **SHIFT-F2** to run **test led**.

The LED on the LPC1114 I/O processor board should begin blinking.

## **Going Further**

Try temporarily replacing the Raspberry Pi or BeagleBone Green assembly with one of the other Remote I/O server devices that are being passed around. With the notable exception of the red **FEZ**, most of the other servers also have an LED on Remote I/O GPIO channel 0. You should be able to run **test led** unmodified with them.

If you want to try the same thing on the **FEZ**, you will need to change the value for the constant **Channel\_LED** to **20** or **21** and then rebuild **test\_led**. (The **FEZ** assigns Remote I/O GPIO channels 0 to 13 to the **D0** to **D13** signals of the Arduino expansion headers. See the package **RemoteI0.FEZ** for more information.)