# **Remote I/O Package Specifications**

## **Introduction**

This document contains selected package specifications from **libsimpleio/ada/** that are pertinent to the Ada-Europe 2019 Remote I/O Tutorial.

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### **Messaging.Fixed**

This generic package defines an abstract interface for fixed length messaging services. It must be instantiated with a message size parameter. It defines an interface type **MessengerInterface** and a classwide access type **Messenger**. It also defines **Byte** and **Message** types.

#### **GENERIC**

```
MessageSize : Natural;

PACKAGE Messaging.Fixed IS

TYPE MessengerInterface IS INTERFACE;

TYPE Messenger IS ACCESS ALL MessengerInterface'Class;

TYPE Byte IS MOD 256;

TYPE Message IS ARRAY (Natural RANGE 0 .. MessageSize -1) OF Byte;

-- Send a message

PROCEDURE Send
(Self : MessengerInterface;
msg : IN Message) IS ABSTRACT;

-- Receive a message

PROCEDURE Receive
(Self : MessengerInterface;
msg : OUT Message) IS ABSTRACT;

-- Dump a message in hexadecimal format

PROCEDURE Dump(msg : Message);

END Messaging.Fixed;
```

### Message64

This package is an instantiation of **Messaging.Fixed** for 64-byte messages. It defines the 64-byte message API used by the Remote I/O Protocol. Packages such as **HID.hidapi** and **Message64.UDP** implement **Message64.MessengerInterface** to provide concrete messaging services.

```
WITH Messaging.Fixed;

PACKAGE Message64 IS NEW Messaging.Fixed(64);
```

### HID.hidapi

This package implements Message64. MessengerInterface as the type MessengerSubclass, using the *HIDAPI Library* (<a href="https://github.com/signal11/hidapi">https://github.com/signal11/hidapi</a>) for communicating with USB raw HID devices.

The **Create** function returns a messenger instance of type **Message64.Messenger**. Optional vendor ID, product ID, and serial number parameters to **Create** can select a specific USB raw HID device if more than one are attached to the host computer.

```
WITH HID. Munts;
WITH Message64;
PACKAGE HID. hidapi IS
  -- Type definitions
  TYPE MessengerSubclass IS NEW Message64.MessengerInterface WITH PRIVATE;
  Destroyed : CONSTANT MessengerSubclass;
  -- Constructor
  -- Allowed values for the timeout parameter:
  -- -1 => Receive operation blocks forever, until a report is received
  -- 0 => Receive operation never blocks at all
  -- >0 => Receive operation blocks for the indicated number of milliseconds
  FUNCTION Create
             : HID.Vendor := HID.Munts.VID;
   (vid
             : HID.Product := HID.Munts.PID;
    pid
    serial : String := "";
    timeoutms : Integer := 1000) RETURN Message64.Messenger;
  -- Send a message
  PROCEDURE Send
   (Self : MessengerSubclass;
   msg : Message64.Message);
  -- Receive a message
  PROCEDURE Receive
   (Self : MessengerSubclass;
   msg : OUT Message64.Message);
  -- Get HID device name string
  FUNCTION Name(Self : MessengerSubclass) RETURN String;
  -- Get HID device manufacturer string
  FUNCTION Manufacturer
   (Self : MessengerSubclass) RETURN String;
  -- Get HID device product string
  FUNCTION Product
   (Self : MessengerSubclass) RETURN String;
```

-- Get HID device serial number string

FUNCTION SerialNumber (Self : MessengerSubclass) RETURN String;

**PRIVATE** 

-- Implementation defined END HID.hidapi;

#### **RemoteIO.Client**

This package defines the client API for the Remote I/O Protocol. It defines a class type **DeviceClass** and a classwide access type **Device**. The **Create** function accepts an object instance of type **Message64.Messenger** (*e.g.* from **HID.hidapi.Create**) and returns an object instance of type **Device**. As usual, **Create** is *not* a primitive operation of **DeviceClass**. The four methods **Transaction**, **GetVersion**, **GetCapability**, and **GetAvailableChannels** *are* primitive operations of **DeviceClass**.

```
WITH Message64;
PACKAGE RemoteIO.Client IS
  -- Define a tagged type for remote I/O server devices
  TYPE DeviceClass IS TAGGED PRIVATE:
  -- Define an access type compatible with any subclass implementing
  -- DeviceClass
  TYPE Device IS ACCESS ALL DeviceClass'Class;
  -- Constructors
  FUNCTION Create(msg : Message64.Messenger) RETURN Device;
  -- Perform a Remote I/O operation
  PROCEDURE Transaction
   (Self : IN OUT DeviceClass;
    cmd : IN OUT Message64.Message;
    resp : OUT Message64.Message);
  -- Get the remote device version string
  FUNCTION GetVersion(Self : IN OUT DeviceClass) RETURN String;
  -- Get the remote device capability string
  FUNCTION GetCapability(Self : IN OUT DeviceClass) RETURN String;
  -- Get the available channels for a given service type
  FUNCTION GetAvailableChannels
         : IN OUT DeviceClass;
    service : ChannelTypes) RETURN ChannelSets.Set;
PRIVATE
  -- Implementation defined
END RemoteIO.Client;
```

#### RemotelO.LPC1114

This package specifies all of the resources available from the LPC1114 I/O Processor Remote I/O Server. Packages for other Remote I/O server devices (e.g. RemoteIO.FEZ) are available in libsimpleio/ada/remoteio/client/.

The first section (this page) defines constants for the normal Remote I/O resources (analog inputs, GPIO pins, and PWM outputs).

The second section (the three following pages) defines a Remote I/O abstract device binding to the SPI Agent firmware inside the LPC1114 I/O Processor. See the *Raspberry Pi LPC1114 I/O Processor Expansion Board User Guide* for more information about the services the SPI Agent firmware can provide:

http://git.munts.com/rpi-mcu/expansion/LPC1114/doc/UserGuide.pdf

```
WITH Interfaces; USE Interfaces;

WITH RemoteIO.Abstract_Device;
WITH RemoteIO.Client;

PACKAGE RemoteIO.LPC1114 IS

-- Analog inputs

AIN1 : CONSTANT RemoteIO.ChannelNumber := 1; -- aka LPC1114 P1.0 AIN2 : CONSTANT RemoteIO.ChannelNumber := 2; -- aka LPC1114 P1.1 AIN3 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.2 AIN4 : CONSTANT RemoteIO.ChannelNumber := 4; -- aka LPC1114 P1.3 AIN5 : CONSTANT RemoteIO.ChannelNumber := 5; -- aka LPC1114 P1.4

-- GPIO pins

LED : CONSTANT RemoteIO.ChannelNumber := 0; -- aka LPC1114 P1.4

-- GPIO0 : CONSTANT RemoteIO.ChannelNumber := 1; -- aka LPC1114 P1.0 GPIO1 : CONSTANT RemoteIO.ChannelNumber := 2; -- aka LPC1114 P1.1 GPIO2 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.2 GPIO3 : CONSTANT RemoteIO.ChannelNumber := 4; -- aka LPC1114 P1.2 GPIO3 : CONSTANT RemoteIO.ChannelNumber := 5; -- aka LPC1114 P1.5 GPIO6 : CONSTANT RemoteIO.ChannelNumber := 5; -- aka LPC1114 P1.5 GPIO6 : CONSTANT RemoteIO.ChannelNumber := 6; -- aka LPC1114 P1.5 GPIO6 : CONSTANT RemoteIO.ChannelNumber := 7; -- aka LPC1114 P1.5 GPIO6 : CONSTANT RemoteIO.ChannelNumber := 8; -- aka LPC1114 P1.5 GPIO6 : CONSTANT RemoteIO.ChannelNumber := 8; -- aka LPC1114 P1.8 GPIO7 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.9 PWM2 : CONSTANT RemoteIO.ChannelNumber := 2; -- aka LPC1114 P1.9 PWM3 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.1 PWM2 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.1 PWM3 : CONSTANT RemoteIO.ChannelNumber := 3; -- aka LPC1114 P1.1 PWM3 : CONSTANT RemoteIO.ChannelNumber := 4; -- aka LPC1114 P1.1 PWM3 : CONSTANT RemoteIO.ChannelNumber := 4; -- aka LPC1114 P1.1
```

```
-- LPC1114 I/O Processor Expansion Board Abstract Device services follow
-- See: http://qit.munts.com/rpi-mcu/expansion/LPC1114/doc/UserGuide.pdf
-- Naming of identifiers below matches UserGuide.pdf.
______
-- Raspberry Pi LPC1114 I/O Processor SPI Agent Firmware command structure
TYPE SPIAGENT_COMMAND_MSG_t IS RECORD
  command: Unsigned 32;
          : Unsigned_32;
  pin
          : Unsigned_32;
  data
END record;
-- Raspberry Pi LPC1114 I/O Processor SPI Agent Firmware response structure
TYPE SPIAGENT RESPONSE MSG t IS RECORD
  command: Unsigned 32;
          : Unsigned_32;
  pin
  data
          : Unsigned_32;
  error
          : Unsigned_32;
END record;
-- Raspberry Pi LPC1114 I/O Processor SPI Agent Firmware commands
SPIAGENT_CMD_NOP
                                             : CONSTANT Unsigned_32 := 0;
                                            : CONSTANT Unsigned_32 := 1;
SPIAGENT_CMD_LOOPBACK
SPIAGENT_CMD_CONFIGURE_ANALOG_INPUT : CONSTANT Unsigned_32 := 2;
SPIAGENT_CMD_CONFIGURE_GPIO_INPUT
                                            : CONSTANT Unsigned_32 := 3;
SPIAGENT_CMD_CONFIGURE_GPIO_OUTPUT
                                            : CONSTANT Unsigned_32 := 4;
                                            : CONSTANT Unsigned_32 := 5;
SPIAGENT_CMD_CONFIGURE_PWM_OUTPUT
SPIAGENT_CMD_GET_ANALOG
                                            : CONSTANT Unsigned_32 := 6;
SPIAGENT_CMD_GET_GPIO
                                            : CONSTANT Unsigned_32 := 7;
SPIAGENT_CMD_PUT_GPIO
                                            : CONSTANT Unsigned_32 := 8;
SPIAGENT_CMD_PUT_PWM
                                            : CONSTANT Unsigned_32 := 9;
SPIAGENT_CMD_CONFIGURE_GPIO_INTERRUPT
                                            : CONSTANT Unsigned_32 := 10;
SPIAGENT_CMD_CONFIGURE_GPIO
                                            : CONSTANT Unsigned_32 := 11;
SPIAGENT CMD PUT LEGORC
                                            : CONSTANT Unsigned 32 := 12;
SPIAGENT CMD GET SFR
                                            : CONSTANT Unsigned 32 := 13;
SPIAGENT CMD PUT SFR
                                            : CONSTANT Unsigned 32 := 14;
SPIAGENT CMD CONFIGURE TIMER MODE
                                            : CONSTANT Unsigned_32 := 15;
SPIAGENT_CMD_CONFIGURE_TIMER_PRESCALER : CONSTANT Unsigned_32 := 16;
SPIAGENT_CMD_CONFIGURE_TIMER_CAPTURE : CONSTANT Unsigned_32 := 17;
                                            : CONSTANT Unsigned_32 := 18;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH0
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH1
                                            : CONSTANT Unsigned_32 := 19;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH2 : CONSTANT Unsigned_32 := 20;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH3 : CONSTANT Unsigned_32 := 21;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCHO_VALUE : CONSTANT Unsigned_32 := 22;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH1_VALUE : CONSTANT Unsigned_32 := 23;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH2_VALUE : CONSTANT Unsigned_32 := 24;
SPIAGENT_CMD_CONFIGURE_TIMER_MATCH3_VALUE : CONSTANT Unsigned_32 := 25;
SPIAGENT_CMD_GET_TIMER_VALUE : CONSTANT Unsigned_32 := 26;
SPIAGENT_CMD_GET_TIMER_CAPTURE : CONSTANT Unsigned_32 := 27;
SPIAGENT_CMD_GET_TIMER_CAPTURE_DELTA : CONSTANT Unsigned_32 := 28;
SPIAGENT_CMD_INIT_TIMER
                                            : CONSTANT Unsigned_32 := 29;
SPIAGENT_CMD_INIT_TIMER
```

```
LPC1114_GPI00 : CONSTANT Unsigned_32 := 12; -- aka P1.0
LPC1114_GPI01 : CONSTANT Unsigned_32 := 13; -- aka P1.1
LPC1114_GPI02 : CONSTANT Unsigned_32 := 14; -- aka P1.2
LPC1114_GPI03 : CONSTANT Unsigned_32 := 15; -- aka P1.3
LPC1114_GPI04 : CONSTANT Unsigned_32 := 16; -- aka P1.4
LPC1114_GPI05 : CONSTANT Unsigned_32 := 17; -- aka P1.5
LPC1114_GPI06 : CONSTANT Unsigned_32 := 20; -- aka P1.8
LPC1114_GPI07 : CONSTANT Unsigned_32 := 21; -- aka P1.9
LPC1114_LED : CONSTANT Unsigned_32 := 7; -- aka P0.7
LPC1114 GPI00
                            : CONSTANT Unsigned_32 := 12; -- aka P1.0
 -- Raspberry Pi LPC1114 I/O Processor Analog input pins
                             : CONSTANT Unsigned_32 := LPC1114_GPI00;
LPC1114_AD1 : CONSTANT Unsigned_32 := LPC1114_GPI00;

LPC1114_AD2 : CONSTANT Unsigned_32 := LPC1114_GPI01;

LPC1114_AD3 : CONSTANT Unsigned_32 := LPC1114_GPI02;

LPC1114_AD4 : CONSTANT Unsigned_32 := LPC1114_GPI03;

LPC1114_AD5 : CONSTANT Unsigned_32 := LPC1114_GPI04;
LPC1114 AD1
 -- Raspberry Pi LPC1114 I/O Processor PWM output pins
LPC1114_PWM1 : CONSTANT Unsigned_32 := LPC1114_GPI01;

LPC1114_PWM2 : CONSTANT Unsigned_32 := LPC1114_GPI02;

LPC1114_PWM3 : CONSTANT Unsigned_32 := LPC1114_GPI03;

LPC1114_PWM4 : CONSTANT Unsigned_32 := LPC1114_GPI07;
-- Raspberry Pi LPC1114 I/O Processor Timer pins
LPC1114_CT32B1_CAP0 : CONSTANT Unsigned_32 := LPC1114_GPI00;
LPC1114_CT32B1_MAT0 : CONSTANT Unsigned 32 := LPC1114_GPI01;
LPC1114_CT32B1_MAT1 : CONSTANT Unsigned_32 := LPC1114_GPI02;
LPC1114_CT32B1_MAT2 : CONSTANT Unsigned_32 := LPC1114_GPI03;
LPC1114_CT32B1_MAT3 : CONSTANT Unsigned_32 := LPC1114_GPI04;
LPC1114_CT32B0_CAP0 : CONSTANT Unsigned_32 := LPC1114_GPI05;
-- LPC1114 special function registers
LPC1114_DEVICEID : CONSTANT Unsigned_32 := 16#400483F4#;
LPC1114_GPI01DATA : CONSTANT Unsigned_32 := 16#50010CFC#;
LPC1114_U0SCR : CONSTANT Unsigned_32 := 16#4000801C#;
-- LPC1114 timer identifiers
LPC1114 CT32B0
                            : CONSTANT Unsigned 32 := 0;
LPC1114_CT32B1
                            : CONSTANT Unsigned_32 := 1;
-- LPC1114 timer modes
LPC1114_TIMER_MODE_DISABLED : CONSTANT Unsigned_32 := 0;
LPC1114_TIMER_MODE_RESET : CONSTANT Unsigned_32 := 1;
LPC1114_TIMER_MODE_PCLK : CONSTANT Unsigned_32 := 2;
LPC1114_TIMER_MODE_CAP0_RISING : CONSTANT Unsigned_32 := 3;
LPC1114_TIMER_MODE_CAP0_FALLING : CONSTANT Unsigned_32 := 4;
LPC1114_TIMER_MODE_CAP0_BOTH : CONSTANT Unsigned_32 := 5;
-- LPC1114 timer capture edges
LPC1114_TIMER_CAPTURE_EDGE_DISABLED
                                                           : CONSTANT Unsigned_32 := 0;
LPC1114_TIMER_CAPTURE_EDGE_CAPO_RISING : CONSTANT Unsigned_32 := 1;
LPC1114_TIMER_CAPTURE_EDGE_CAP0_FALLING : CONSTANT Unsigned_32 := 2;
LPC1114_TIMER_CAPTURE_EDGE_CAP0_BOTH : CONSTANT Unsigned_32 := 3;
```

-- Raspberry Pi LPC1114 I/O Processor General Purpose Input/Output pins

```
-- LPC1114 timer match registers

LPC1114_TIMER_MATCH0 : CONSTANT Unsigned_32 := 0;
LPC1114_TIMER_MATCH1 : CONSTANT Unsigned_32 := 1;
LPC1114_TIMER_MATCH2 : CONSTANT Unsigned_32 := 2;
LPC1114_TIMER_MATCH2 : CONSTANT Unsigned_32 := 3;

-- LPC1114_TIMER_MATCH3 : CONSTANT Unsigned_32 := 3;

-- LPC1114_TIMER_MATCH_OUTPUT_DISABLED : CONSTANT Unsigned_32 := 0;
LPC1114_TIMER_MATCH_OUTPUT_CLEAR : CONSTANT Unsigned_32 := 1;
LPC1114_TIMER_MATCH_OUTPUT_SET : CONSTANT Unsigned_32 := 2;
LPC1114_TIMER_MATCH_OUTPUT_TOGGLE : CONSTANT Unsigned_32 := 3;

-- Instantiate RemoteIO.Abstract_Device

FUNCTION FromCommand(cmd : SPIAGENT_COMMAND_MSG_t) RETURN Message64.Message;
FUNCTION TOREsponse(msg : Message64.Message) RETURN SPIAGENT_RESPONSE_MSG_t;

PACKAGE Abstract_Device IS NEW RemoteIO.Abstract_Device
  (SPIAGENT_COMMAND_MSG_t, SPIAGENT_RESPONSE_MSG_t);

END RemoteIO.LPC1114;
```

#### **IO** Interfaces

This generic package must be instantiated with some type **Property**, which can be scalar or composite. The instantiated package will define three abstract interface types:

**InputInterface**, **InputOutputInterface**, and **OutputInterface**. Each abstract interface includes a classwide access type and **Get** and/or **Put** procedures. **IO\_Interfaces** is used extensively internally within **libsimpleio** but will seldom if ever be need to be referenced from an application program.

#### **GENERIC**

```
TYPE Property IS PRIVATE;
PACKAGE IO Interfaces IS
 -- Define an abstract input only interface
 TYPE InputInterface IS INTERFACE;
 -- Define a method for reading from an input
 FUNCTION Get(Self: IN OUT InputInterface) RETURN Property IS ABSTRACT;
 -- Define an abstract input/output interface
 TYPE InputOutputInterface IS INTERFACE;
 -- Define a method for reading from an input
 FUNCTION Get(Self: IN OUT InputOutputInterface) RETURN Property IS ABSTRACT;
 -- Define a method for writing to an output
 PROCEDURE Put(Self : IN OUT InputOutputInterface; value : Property) IS ABSTRACT;
  -----
 -- Define an abstract output only interface
 TYPE OutputInterface IS INTERFACE;
 -- Define a method for writing to an output
 PROCEDURE Put(Self : IN OUT OutputInterface; value : Property) IS ABSTRACT;
END IO_Interfaces;
```

#### **GPIO**

This package defines an abstract interface for all GPIO (General Purpose Input/Output) pins. It defines an exception **GPIO\_Error**, an abstract interface type **PinInterface**, and a classwide access type **Pin**.

```
WITH Ada. Text IO;
WITH IO_Interfaces;
PACKAGE GPIO IS
  -- Define an exception for GPIO errors
  GPIO_Error : EXCEPTION;
  -- Instantiate text I/O package
  PACKAGE Boolean_IO IS NEW Ada.Text_IO.Enumeration_IO(Boolean);
  -- Type definitions
  TYPE Direction IS (Input, Output);
  -- Instantiate I/O interfaces package for digital I/O
  PACKAGE Interfaces IS NEW IO_Interfaces(Boolean);
  -- Define an abstract interface for GPIO pins, derived from
  -- Interfaces.InputOutputInterface
  TYPE PinInterface IS INTERFACE AND Interfaces.InputOutputInterface;
  -- Define an access type compatible with any subclass implementing
  -- PinInterface
  TYPE Pin IS ACCESS ALL PinInterface'Class;
END GPIO;
```

#### **GPIO.RemoteIO**

This package provides GPIO pin services using the Remote I/O protocol. It defines a concrete subclass of **GPIO.PinInterface** called **GPIO.RemoteIO.PinSubclass**.

Note that the **Create** function returns a value of classwide access type **GPIO.Pin** and is *not* a primitive operation of **GPIO.RemoteIO.PinSubclass**. This is a pattern followed throughout **libsimpleio**.

```
WITH RemoteIO.Client;
PACKAGE GPIO.RemoteIO IS
  TYPE PinSubclass IS NEW PinInterface WITH PRIVATE;
  -- GPIO pin object constructor
  FUNCTION Create
   (dev : Standard.RemoteIO.Client.Device;
    num : Standard.RemoteIO.ChannelNumber;
    dir : Direction;
    state : Boolean := False) RETURN Pin;
  -- Read GPIO pin state
  FUNCTION Get(Self : IN OUT PinSubclass) RETURN Boolean;
  -- Write GPIO pin state
  PROCEDURE Put(Self : IN OUT PinSubclass; state : Boolean);
PRIVATE
  -- Implementation defined
END GPIO.RemoteIO;
```

### **Analog**

This package defines abstract interfaces for analog sampled data inputs, outputs, and input/outputs. Use **InputInterface** and **Input** for ADC (Analog to Digital Converter) inputs and **OutputInterface** and **Output** for DAC (Digital to Analog Converter) outputs.

**InputOutputInterface** and **InputOutput**) are provided for completeness. They might be useful for a DAC with readback capability, or for unusual devices that are configurable as either analog input or output.

Sampled analog data values (of type **Sample**) are 32-bit unsigned and right justified.

```
WITH Ada.Text_IO;
WITH IO_Interfaces;
PACKAGE Analog IS
  -- Define a type for sampled analog data
  MaxResolution : CONSTANT := 32; -- Bits
  TYPE Sample IS MOD 2**MaxResolution;
  -- Instantiate text I/O package
  PACKAGE Sample_IO IS NEW Ada.Text_IO.Modular_IO(Sample);
  -- Instantiate I/O interfaces package for digital I/O
  PACKAGE Interfaces IS NEW IO_Interfaces(Sample);
  -- Interfaces
  TYPE InputInterface IS INTERFACE AND Interfaces.InputInterface;
  TYPE OutputInterface IS INTERFACE AND Interfaces.OutputInterface;
  TYPE InputOutputInterface IS INTERFACE AND Interfaces.InputOutputInterface;
  -- Access types
  TYPE Input IS ACCESS ALL InputInterface'Class;
  TYPE Output IS ACCESS ALL OutputInterface 'Class;
  TYPE InputOutput IS ACCESS ALL InputOutputInterface'Class;
  -- Additional methods
  FUNCTION GetResolution(Self : IN OUT InputInterface) RETURN Positive IS ABSTRACT;
  FUNCTION GetResolution(Self : IN OUT InputOutputInterface) RETURN Positive IS
    ABSTRACT;
  FUNCTION GetResolution(Self: IN OUT OutputInterface) RETURN Positive IS ABSTRACT;
END Analog;
```

### **Voltage**

This package defines a type **Volts** to represent continuously variable voltage input and/or output devices. It is representative of all of the physical quantity packages.

```
WITH Ada. Text IO;
WITH IO_Interfaces;
PACKAGE Voltage IS
 TYPE Volts IS NEW Float;
  -- Instantiate text I/O package
  PACKAGE Volts_IO IS NEW Ada.Text_IO.Float_IO(Volts);
  -- Instantiate abstract interfaces package
  PACKAGE Interfaces IS NEW IO_Interfaces(Volts);
  -- Interfaces
  TYPE InputInterface IS INTERFACE AND Interfaces.InputInterface;
  TYPE OutputInterface IS INTERFACE AND Interfaces.OutputInterface;
  TYPE InputOutputInterface IS INTERFACE AND Interfaces.InputOutputInterface;
  -- Access types
  TYPE Input IS ACCESS ALL InputInterface 'Class;
  TYPE Output IS ACCESS ALL OutputInterface 'Class;
  TYPE InputOutput IS ACCESS ALL InputOutputInterface'Class;
END Voltage;
```

#### **ADC**

This package provides services for reading the scaled input voltage from ADC (Analog to Digital Converter) inputs. It defines a concrete subclass of **Volts.Interfaces.InputInterface** called **ADC.InputSubclass**.

The **Create** function accepts an analog input object instance (of type **Analog.Input**), a reference voltage value (of type **Voltage.Volts**), and a voltage gain value (also of type **Voltage.Volts**) and returns a voltage input object instance of type **Voltage.Interfaces.Input**.

As is usual throughout **libsimpleio**, **Create** is **not** a primitive operation of **ADC.InputSubclass**.

```
WITH Analog;
WITH Voltage;

PACKAGE ADC IS

ADC_Error : EXCEPTION;

TYPE InputSubclass IS NEW Voltage.InputInterface WITH PRIVATE;

-- Constructor

FUNCTION Create
(input : Analog.Input;
reference : Voltage.Volts;
gain : Voltage.Volts := 1.0) RETURN Voltage.Input;

-- Methods

FUNCTION Get(Self : IN OUT InputSubclass) RETURN Voltage.Volts;

PRIVATE
-- Implementation defined
END ADC;
```

#### **ADC.RemotelO**

This package provides analog input services using the Remote I/O protocol. It defines a concrete subclass of Analog.InputInterface called ADC.RemoteIO.InputSubclass.

The **Create** function returns an analog input object instance of type **Analog.Input**.

```
WITH Analog;
WITH RemoteIO.Client;

PACKAGE ADC.RemoteIO IS

TYPE InputSubclass IS NEW Analog.InputInterface WITH PRIVATE;

-- A/D input pin object constructor

FUNCTION Create
  (dev : Standard.RemoteIO.Client.Device;
   num : Standard.RemoteIO.ChannelNumber) RETURN Analog.Input;

-- Read A/D input pin

FUNCTION Get(Self : IN OUT InputSubclass) RETURN Analog.Sample;

-- Retrieve A/D input resolution

FUNCTION GetResolution(Self : IN OUT InputSubclass) RETURN Positive;

PRIVATE
  -- Implementation defined
END ADC.RemoteIO;
```