

UESTC3001 Dynamics & Control  
Lecture 2

# Basics of Control System Analysis

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# Outline

- Introduction to Control Systems
- Block Diagram Representation

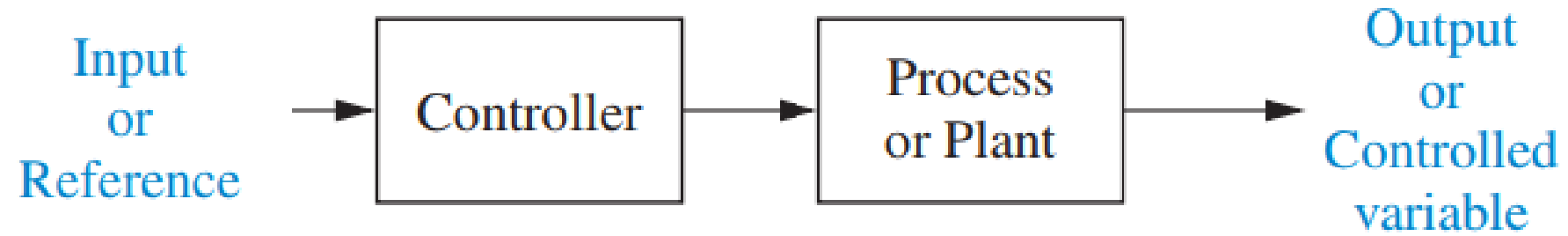
# Introduction to Control System



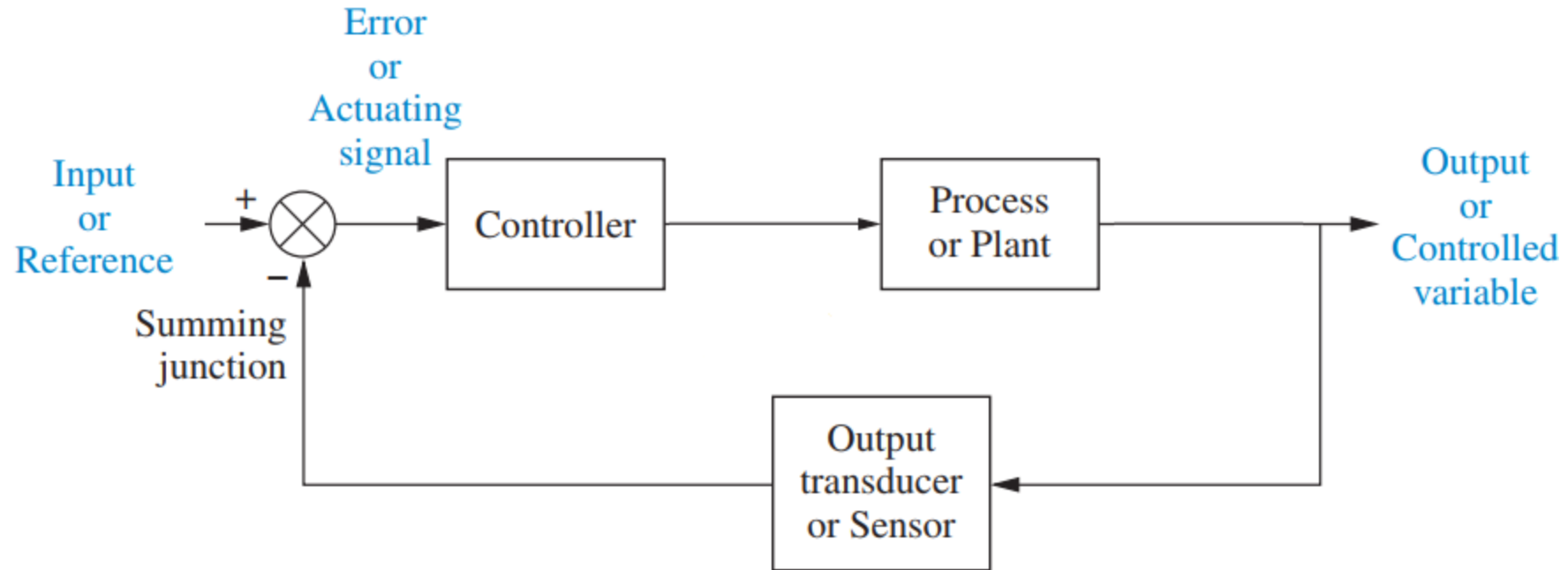
# Advantages of Control Systems

- Power amplification
- Remote control
- Convenience of input form
- Compensation for disturbances

# Open-loop Control

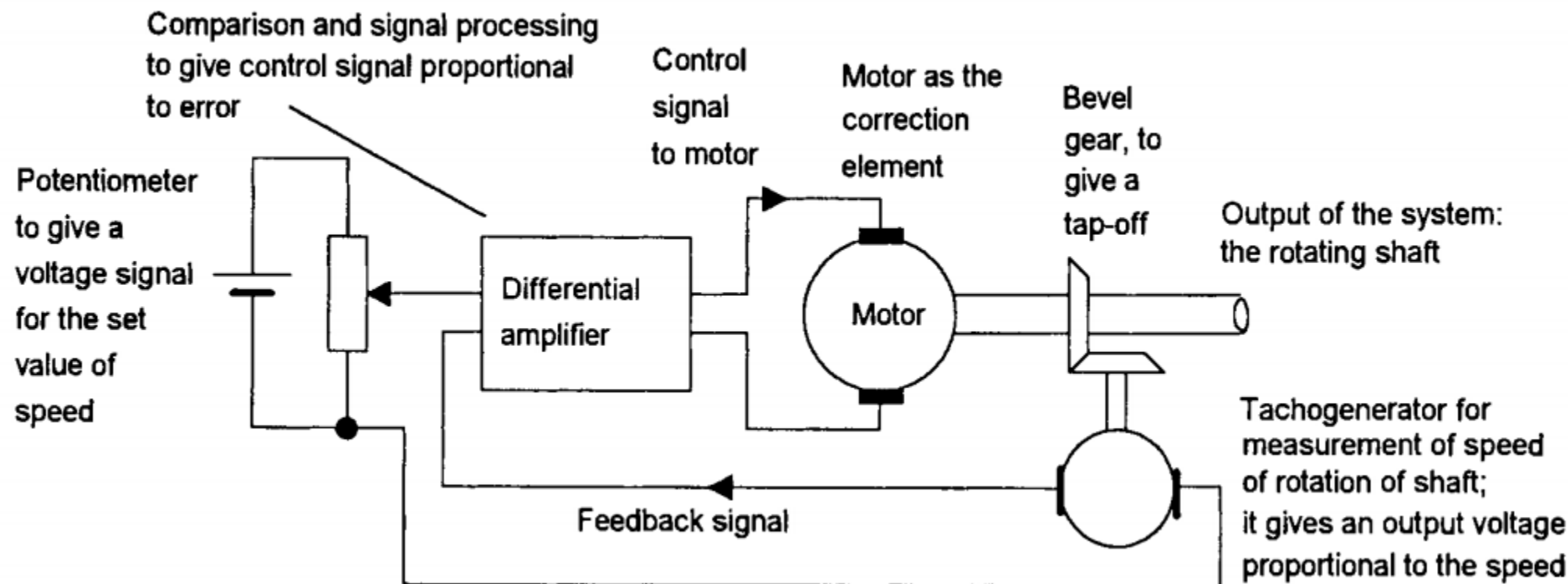


# Closed-loop Control

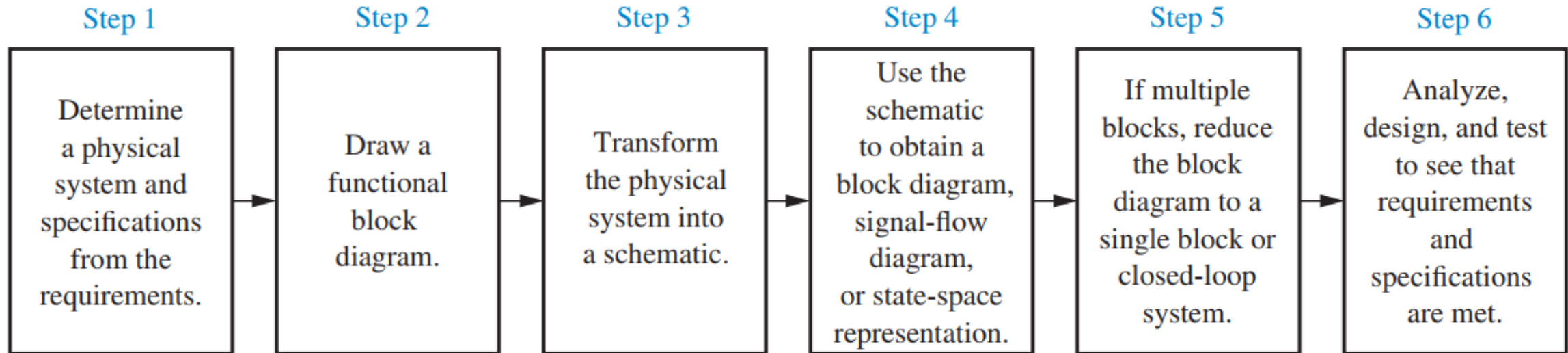


# Example

## Control of the speed of rotation of a motor shaft



# The Design Process



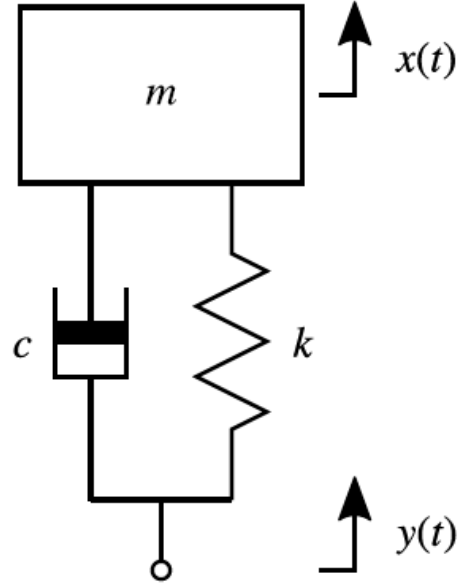


# Introduction to Block Diagrams

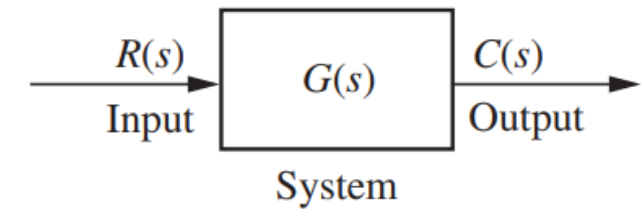
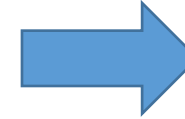
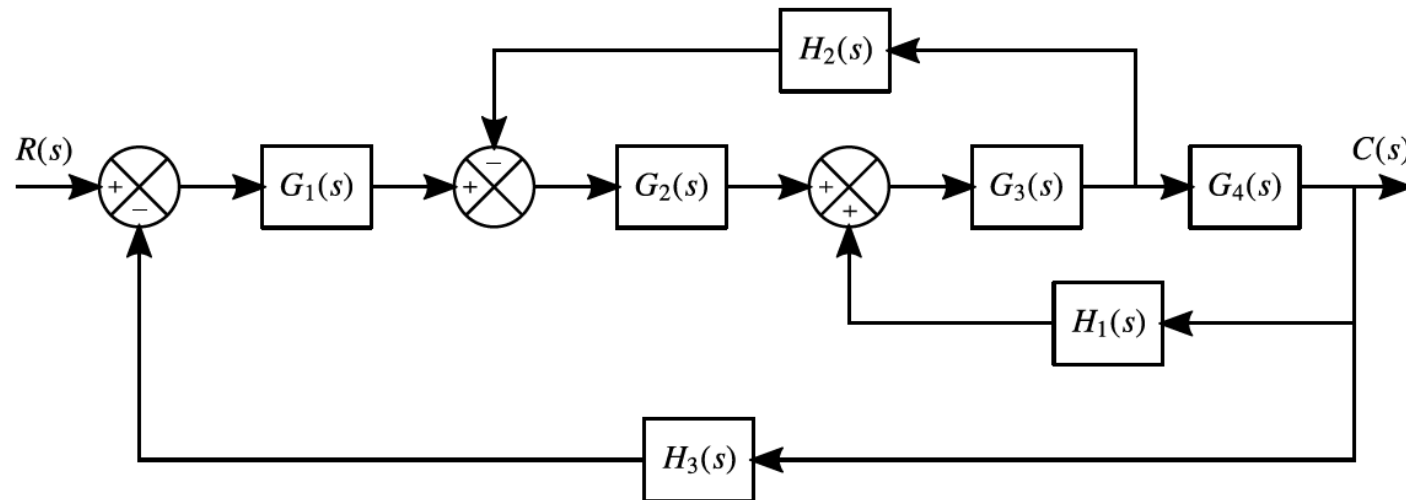
- Use for frequency-domain analysis and design
- Graphical representation of the interconnections between the components of the system and the flow of signals
- Diagram is composed of functional blocks

# Example:

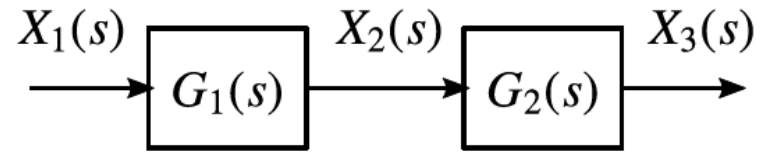
## Block Diagram Representation of Control Systems



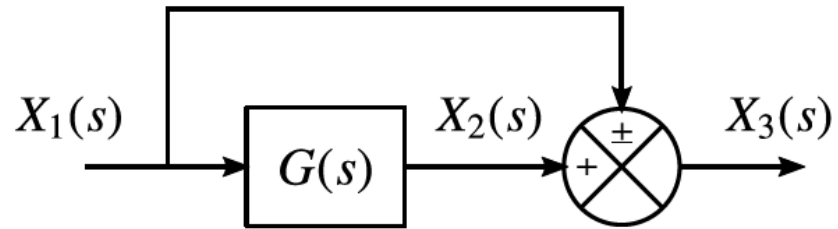
# Block Diagram Reduction



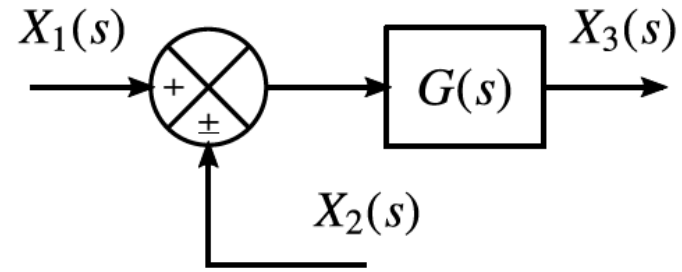
# 1: Cascaded Blocks



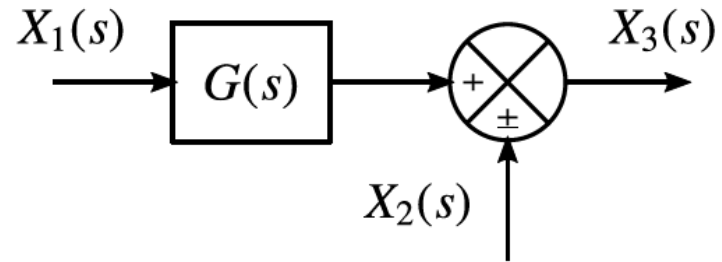
## 2: Summing Two Signals



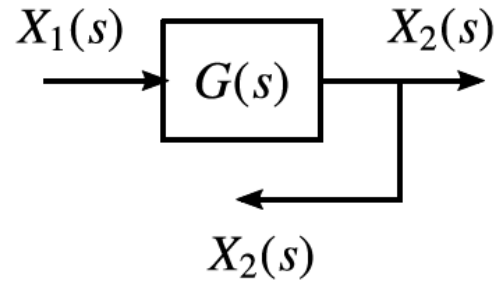
### 3: Moving a Summing Point Behind a Block



## 4: Moving a Summing Point Ahead of a Block

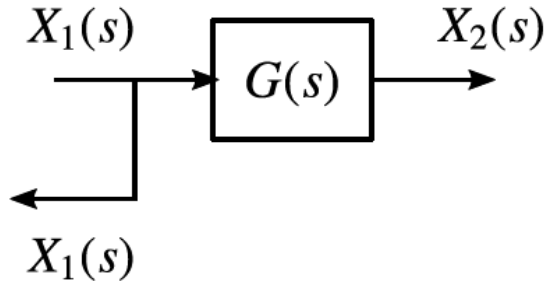


## 5: Moving a Branch Point Ahead of a Block

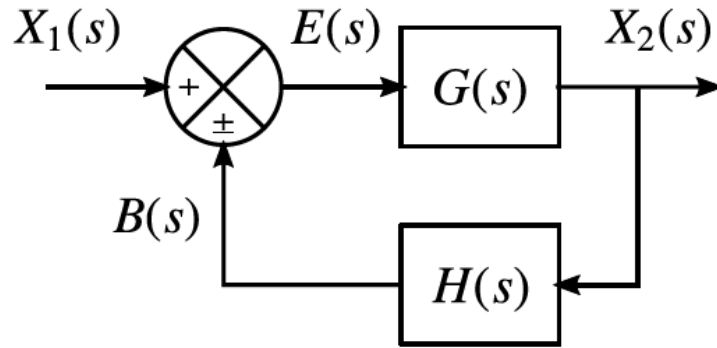




## 6: Moving a Branch Point Behind a Block



# 7: Eliminating a Feedback Loop



# Summary

- Overview to Control Systems
- Block Diagram Representation of Control Systems
- Block Diagram Reduction
- Block Diagram Reduction Rules

**Reference:**

-Control Systems Engineering, 7th Edition, N.S. Nise  
-UESTC3001 2019/20 Notes, J. Le Kernec