7/8/2021 Lecture_Lab

```
# sample graph implemented as a dictionary
In [14]:
          graph = {'A': ['B', 'C', 'E'],
                    'B': ['A','D', 'E'],
                    'C': ['A', 'F', 'G'],
                    'D': ['B'],
                    'E': ['A', 'B','D'],
                    'F': ['C'],
                    'G': ['C']}
In [17]:
          # finds shortest path between 2 nodes of a graph using BFS
          def bfs_shortest_path(graph, start, goal):
              # keep track of explored nodes
              explored = []
              # keep track of all the paths to be checked
              queue = [[start]]
              # return path if start is goal
              if start == goal:
                  return "That was easy! Start = goal"
              # keeps looping until all possible paths have been checked
              while queue:
                  # pop the first path from the queue
                  path = queue.pop(0)
                  # get the last node from the path
                  node = path[-1]
                  if node not in explored:
                       neighbours = graph[node]
                       # go through all neighbour nodes, construct a new path and
                       # push it into the queue
                       for neighbour in neighbours:
                           new path = list(path)
                          new_path.append(neighbour)
                           queue.append(new path)
                           # return path if neighbour is goal
                           if neighbour == goal:
                               return new path
                       # mark node as explored
                       explored.append(node)
              # in case there's no path between the 2 nodes
              return "So sorry, but a connecting path doesn't exist :("
          bfs_shortest_path(graph, 'G', 'D') # returns ['G', 'C', 'A', 'B', 'D']
In [18]:
         <class 'list'>
Out[18]: ['G', 'C', 'A', 'B', 'D']
```

DFS

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```
'E' : ['F'],
    'F' : []
}
#visited = [] # Set to keep track of visited nodes.
#visited = set() # Lab work
def dfs(visited, graphs, node):
    if node not in visited:
        # print(node)
        #visited.add(node)
        visited.append(node)
        for neighbour in graphs[node]:
            dfs(visited, graphs, neighbour)
    return visited
# Driver Code
visit = dfs([], graphs, 'A')
print(visit)
```

['A', 'B', 'D', 'E', 'F', 'C']

UCS

```
In [44]:
          Uniform Cost Search Implementation using PriorityQueue
          Map and input taken from
          http://www.massey.ac.nz/~mjjohnso/notes/59302/104.html
          Author: Jayesh Chandrapal
          Version: 1.0
          import queue as Q
          def search(graph, start, end):
              if start not in graph:
                  raise TypeError(str(start) + ' not found in graph !')
              if end not in graph:
                   raise TypeError(str(end) + ' not found in graph !')
                  return
              queue = Q.PriorityQueue()
              queue.put((0, [start]))
              while not queue.empty():
                  node = queue.get()
                  current = node[1][len(node[1]) - 1]
                   if end in node[1]:
                       print("Path found: " + str(node[1]) + ", Cost = " + str(node[0]))
                       break
                   cost = node[0]
                   for neighbor in graph[current]:
                       temp = node[1][:]
                       temp.append(neighbor)
                       queue.put((cost + graph[current][neighbor], temp))
```

```
def readGraph():
    lines = int( input() )
    graph = \{\}
    for line in range(lines):
        line = input()
        tokens = line.split()
        node = tokens[0]
        graph[node] = {}
        print
        for i in range(1, len(tokens) - 1, 2):
            print(node, tokens[i], tokens[i + 1])
            #graph.addEdge(node, tokens[i], int(tokens[i + 1]))
            #graph[node][tokens[i]] = int(tokens[i + 1])
    return graph
....
Sample Map Input:
14
Arad Zerind 75 Timisoara 118 Sibiu 140
Zerind Oradea 71 Arad 75
Timisoara Arad 118 Lugoj 111
Sibiu Arad 140 Oradea 151 Fagaras 99 RimnicuVilcea 80
Oradea Zerind 71 Sibiu 151
Lugoj Timisoara 111 Mehadia 70
RimnicuVilcea Sibiu 80 Pitesti 97 Craiova 146
Mehadia Lugoj 70 Dobreta 75
Craiova Dobreta 120 RimnicuVilcea 146 Pitesti 138
Pitesti RimnicuVilcea 97 Craiova 138 Bucharest 101
Fagaras Sibiu 99 Bucharest 211
Dobreta Mehadia 75 Craiova 120
Bucharest Fagaras 211 Pitesti 101 Giurgiu 90
Giurgiu Bucharest 90
```

Out[44]: '\nSample Map Input:\n\n14\nArad Zerind 75 Timisoara 118 Sibiu 140\nZerind Oradea 71 Ara d 75\nTimisoara Arad 118 Lugoj 111\nSibiu Arad 140 Oradea 151 Fagaras 99 RimnicuVilcea 8 0\nOradea Zerind 71 Sibiu 151\nLugoj Timisoara 111 Mehadia 70\nRimnicuVilcea Sibiu 80 Pi testi 97 Craiova 146\nMehadia Lugoj 70 Dobreta 75\nCraiova Dobreta 120 RimnicuVilcea 146 Pitesti 138\nPitesti RimnicuVilcea 97 Craiova 138 Bucharest 101\nFagaras Sibiu 99 Buchar est 211\nDobreta Mehadia 75 Craiova 120\nBucharest Fagaras 211 Pitesti 101 Giurgiu 90\nG iurgiu Bucharest 90\n'

In []: