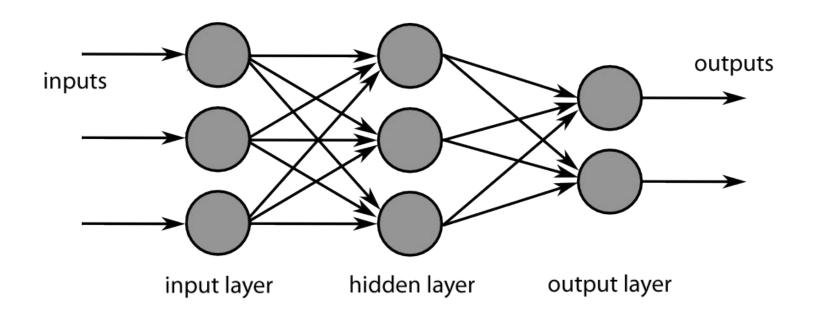
Multi-layer Perceptron

Neural Network:

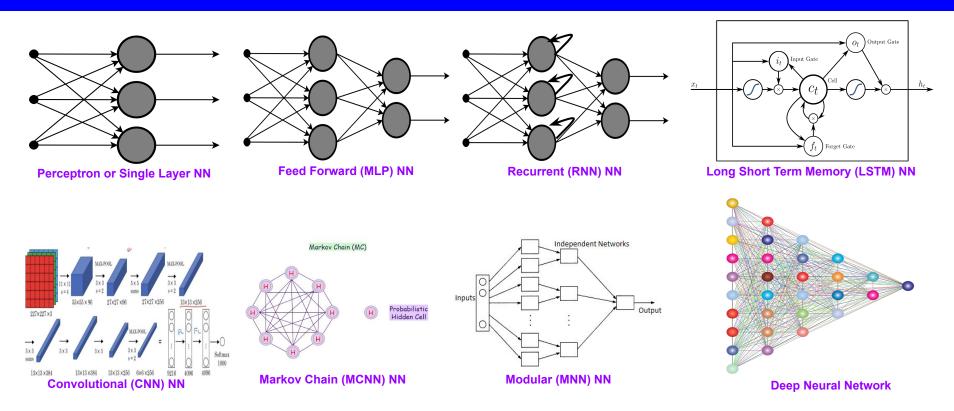
Introduction

- Robust approach to predict real, discrete or vector value
- Inspired from Biological learning system
- Solve both biological and non-biological problems
- Representation Element
 - Nodes
 - Edges
 - Edge Weights
 - Bias
- Instances are represented by many attribute-value pairs
- The training examples may contain errors
- Long training times are acceptable / required
- Fast evaluation of the learned target function may be required
- The ability of humans to understand the learned target function is not important

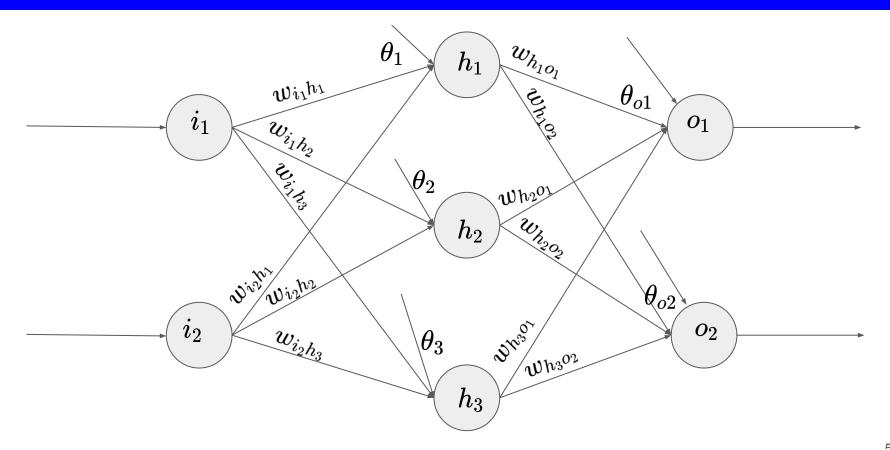
Introduction



Types of Neural Networks



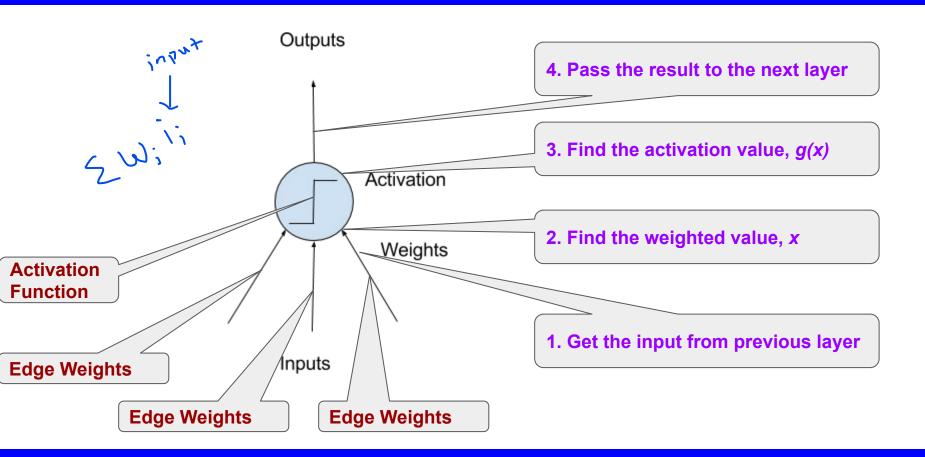
Multi-layer Perceptron



Multi-layer Perceptron NN

- The most useful type of neural network
- A perceptron is a single neuron model
- Investigates how simply biological brains can be modeled to solve difficult computational tasks
- Develop robust algorithms and data structures
- Power of the ability to learn the representation in training data
- Neurons are the building block
- Neurons are arranged into network of neurons
- Two layer learning and predicting methodologies:
 - Feed Forward
 - Backpropagation
- Activation Function needed on neuron

Neuron



Feedforward Algorithm

$$h_1 = \sum_{k=1}^2 i_k * w_{i_k h_1} + \theta_1$$

$$= i_1 * w_{i_1 h_1} + i_2 * w_{i_2 h_1} + \theta_1$$

$$ho_1 = g(h_1) = \int_{1+e^{-h_1}}^{1} \leftarrow$$

$$h_2 = \sum_{k=1}^2 i_k * w_{i_k h_2} + \theta_2$$

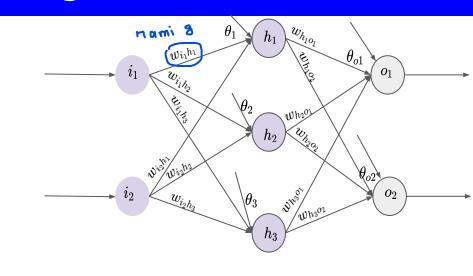
$$= i_1 * w_{i_1 h_2} + i_2 * w_{i_2 h_2} + \theta_2$$

$$ho_2 = g(h_2) = \frac{1}{1+e^{-h_2}}$$

$$h_3 = \sum_{k=1}^2 i_k * w_{i_k h_3} + \theta_3$$

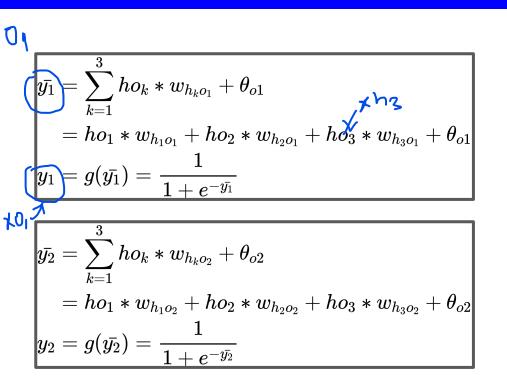
$$= i_1 * w_{i_1 h_3} + i_2 * w_{i_2 h_3} + \theta_3$$

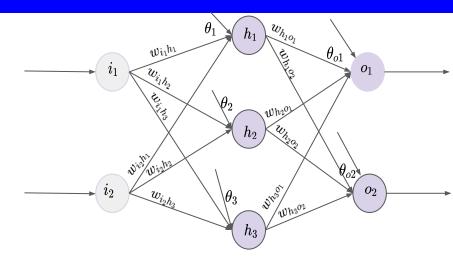
$$ho_3 = g(h_3) = \frac{1}{1+e^{-h_3}}$$



$$h_j = \sum_{k=1}^{|i|} i_k * w_{i_k h_j} + heta_j \ ho_j = g(h_j) = rac{1}{1+e^{-h_j}}$$

Feedforward Algorithm





$$egin{split} ar{y_j} &= \sum_{k=1}^{|h|} h_k * w_{h_k o_j} + heta_{oj} \ y_j &= g(ar{y_j}) = rac{1}{1 + e^{-ar{y_j}}} \end{split}$$

Backpropagation Algorithm

$$h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1, \ h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}} \ h_2=i_1*w_{i_1h_2}+i_2*w_{i_2h_2}+ heta_2, \ h_{o2}=g(h_2)=rac{1}{1+e^{-h_2}} \ h_3=i_1*w_{i_1h_3}+i_2*w_{i_2h_3}+ heta_3, \ h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}} \ w_{i_1h_3}+i_2*w_{i_2h_3}+ho_3*w_{h_3o_1}+ heta_{o1}, \ y_1=g(ar{y_1})=rac{1}{1+e^{-ar{y_1}}} \ w_{i_1h_3}+i_2*w_{i_2h_3}+ho_3*w_{h_3o_2}+ho_3*w_{h_3o_2}+ho_2, \ y_2=g(ar{y_2})=rac{1}{1+e^{-ar{y_2}}} \ w_{i_2h_3}+i_2*w_{i_2h_3}+i_3*w_{i_1h_3}+i_2*w_{i_2h_3}+i_3*w_{i_2h_3}+i_3*w_{i_1h_3}+i_2*w_{i_2h_3}+i_3*w_{i_2h_3}+i_3*w_{i_1h_3}+i_2*w_{i_2h_3}+i_3*w_{$$

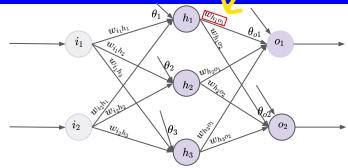
$$orall w_k, w_{k(new)} = w_{k(old)} - \Delta w_k ar{\Delta} w_k = rac{\partial E}{\partial w_k}$$

rondient descent

$$egin{align} \Delta w_{h_1o_1} &= rac{\partial E}{\partial w_{h_1o_1}} \ \Delta w_{h_1o_1} &= rac{\partial E}{\partial y_1} rac{\partial y_1}{\partial ar{y_1}} rac{\partial ar{y_1}}{\partial w_{h_1o_1}} \ \end{pmatrix}$$



$$egin{aligned} rac{\partial E}{\partial y_1} &= rac{\partial}{\partial y_1} igg(rac{1}{2} igg((y_1 - y_{ex_1})^2 + (y_2 - y_{ex_2})^2 igg) igg) \ &= rac{1}{2}.rac{\partial}{\partial y_1} igg((y_1 - y_{ex_1})^2 igg) \ &= rac{1}{2}.2.\, (y_1 - y_{ex_1}).\, rac{\partial}{\partial y_1} ((y_1 - y_{ex_1})) \ &= rac{1}{2}.2.\, (y_1 - y_{ex_1}).1 \ &= (y_1 - y_{ex_1}) \end{aligned}$$



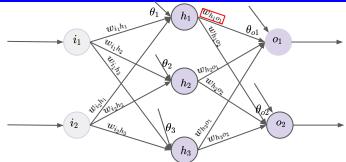
$$h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1,\,h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}}, h_{o2}=i_1*w_{i_1h_2}+i_2*w_{i_2h_2}+ heta_2,\,h_{o2}=g(h_2)=rac{1}{1+e^{-h_2}}, h_{o3}=i_1*w_{i_1h_3}+i_2*w_{i_2h_3}+ heta_3,\,h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}}, h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}}, h_{o3}=g(h_3)=\frac{1}{1+e^{-h_3}}, h_{o3$$

$$egin{aligned} ar{y_1} = ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_2} + ho_3 * w_{h_3o_2} + heta_{o2}, \ y_2 = g(ar{y_2}) = rac{1}{1 + e^{-ar{y_2}}} \end{aligned}$$

$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

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$$egin{aligned} rac{\partial y_1}{\partial ar{y_1}} &= rac{\partial}{\partial ar{y_1}}(g(ar{y_1})) \ &= g(ar{y_1})(1-g(ar{y_1})) \ &= y_1(1-y_1) \end{aligned}$$

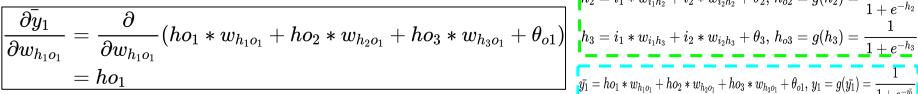


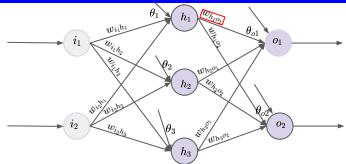
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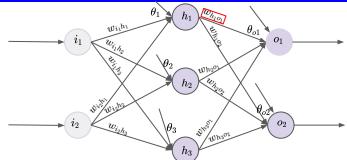
$$h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1,\, h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}}, h_{o2}=i_1*w_{i_1h_2}+i_2*w_{i_2h_2}+ heta_2,\, h_{o2}=g(h_2)=rac{1}{1+e^{-h_2}}, h_{o3}=i_1*w_{i_1h_3}+i_2*w_{i_2h_3}+ heta_3,\, h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}},$$

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$$egin{align} h_1 &= i_1 * w_{i_1h_1} + i_2 * w_{i_2h_1} + heta_1, \ h_{o1} &= g(h_1) = rac{1}{1 + e^{-h_1}} \ h_2 &= i_1 * w_{i_1h_2} + i_2 * w_{i_2h_2} + heta_2, \ h_{o2} &= g(h_2) = rac{1}{1 + e^{-h_2}} \ h_3 &= i_1 * w_{i_1h_3} + i_2 * w_{i_2h_3} + heta_3, \ h_{o3} &= g(h_3) = rac{1}{1 + e^{-h_3}} \ ar{y_1} &= ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_1} + ho_3 * w_{$$

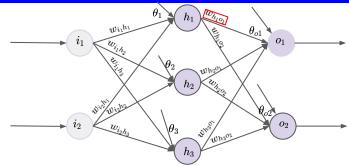
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$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

$$egin{aligned} \Delta w_{h_1o_1} &= (y_1 - y_{ex_1}).\,y_{1.}(1 - y_1).\,ho_1 \ \Delta w_{h_2o_1} &= (y_1 - y_{ex_1}).\,y_{1.}(1 - y_1).\,ho_2 \ \Delta w_{h_3o_1} &= (y_1 - y_{ex_1}).\,y_{1.}(1 - y_1).\,ho_3 \ \Delta w_{h_1o_2} &= (y_2 - y_{ex_2}).\,y_{2.}(1 - y_2).\,ho_1 \ \Delta w_{h_2o_2} &= (y_2 - y_{ex_2}).\,y_{2.}(1 - y_2).\,ho_2 \ \Delta w_{h_3o_2} &= (y_2 - y_{ex_2}).\,y_{2.}(1 - y_2).\,ho_3 \end{aligned}$$

Do Yourself ...





$$h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1,\, h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}}, h_{o2}=i_1*w_{i_1h_2}+i_2*w_{i_2h_2}+ heta_2,\, h_{o2}=g(h_2)=rac{1}{1+e^{-h_2}}, h_{o3}=i_1*w_{i_1h_3}+i_2*w_{i_2h_3}+ heta_3,\, h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}},$$

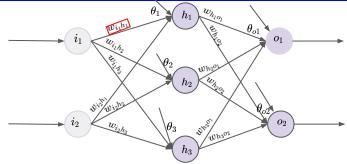
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$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
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$$\Delta w_{i_1h_1}=rac{\partial E}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}}$$

$$egin{aligned} rac{\partial h_1}{\partial w_{i_1h_1}} &= rac{\partial}{\partial w_{i_1h_1}} (i_1 * w_{i_1h_1} + i_2 * w_{i_2h_1} + heta_1) \ &= i_1 \end{aligned}$$



$$h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1,\ h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}}, h_{o2}=i_1*w_{i_1h_2}+i_2*w_{i_2h_2}+ heta_2,\ h_{o2}=g(h_2)=rac{1}{1+e^{-h_2}}, h_{o3}=i_1*w_{i_1h_3}+i_2*w_{i_2h_3}+ heta_3,\ h_{o3}=g(h_3)=rac{1}{1+e^{-h_3}}, h_{o3}=g(h_3)=\frac{1}{1+e^{-h_3}}, h_{o4}=g(h_3)=\frac{1}{1+e^{-h_3}}, h_{o5}=g(h_3)=\frac{1}{1+e^{-h_3}}, h_{o5}=g(h_5)=\frac{1}{1+e^{-h_5}}, h_{o5}=g(h_5)=\frac{1}{1+e^{-h_5}}, h_{o5}=g(h_5)=\frac{1}{1+e^{-h_5}}, h_{o5}=g$$

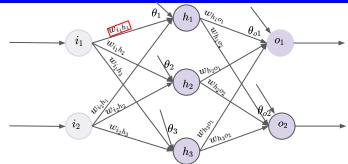
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$$egin{aligned} rac{\partial ho_1}{\partial h_1} &= rac{\partial}{\partial h_1} g(h_1) \ &= g(h_1).\left(1-g(h_1)
ight) \ &= ho_1.\left(1-ho_1
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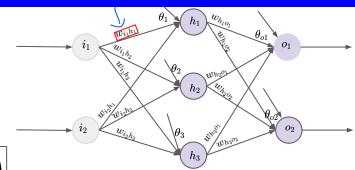
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$$\Delta w_{i_1h_1} = rac{\partial E}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}}$$

$$oxed{rac{\partial E}{\partial ho_1} = rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_1-y_{ex_1})^2igg) + rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_2-y_{ex_2})^2igg)}$$

$$egin{aligned} rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_1-y_{ex_1})^2igg) &= rac{1}{2}.2.\,(y_1-y_{ex_1}).\,rac{\partial}{\partial ho_1}(y_1-y_{ex_1}) \ &= (y_1-y_{ex_1}).\,rac{\partial}{\partial ho_1}(y_1) \ &= (y_1-y_{ex_1}).\,w_{h_1o_1} \end{aligned}$$



$$egin{align} h_1 &= i_1 * w_{i_1h_1} + i_2 * w_{i_2h_1} + heta_1, \ h_{o1} &= g(h_1) = rac{1}{1 + e^{-h_1}} \ h_2 &= i_1 * w_{i_1h_2} + i_2 * w_{i_2h_2} + heta_2, \ h_{o2} &= g(h_2) = rac{1}{1 + e^{-h_2}} \ h_3 &= i_1 * w_{i_1h_3} + i_2 * w_{i_2h_3} + heta_3, \ h_{o3} &= g(h_3) = rac{1}{1 + e^{-h_3}} \ \end{array}$$

$$egin{align*} ar{y_1} = ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 = g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} = ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_2} + ho_3 * w_{h_3o_2} + heta_{o2}, \ y_2 = g(ar{y_2}) = rac{1}{1 + e^{-ar{y_2}}} \end{split}$$

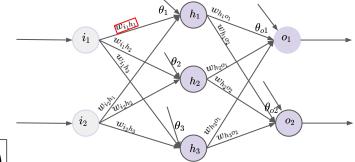
$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}}$$

$$oxed{rac{\partial E}{\partial ho_1} = rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_1-y_{ex_1})^2igg) + rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_2-y_{ex_2})^2igg)}$$

$$egin{aligned} rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_2-y_{ex_2})^2igg) &= rac{1}{2}.2.\,(y_2-y_{ex_2}).\,rac{\partial}{\partial ho_1}(y_2-y_{ex_2}) \ &= (y_2-y_{ex_2}).\,rac{\partial}{\partial ho_1}(y_2) \ &= (y_2-y_{ex_2}).\,w_{h_1o_2} \end{aligned}$$



$$egin{align} h_1 &= i_1 * w_{i_1h_1} + i_2 * w_{i_2h_1} + heta_1, \ h_{o1} &= g(h_1) = rac{1}{1 + e^{-h_1}} \ h_2 &= i_1 * w_{i_1h_2} + i_2 * w_{i_2h_2} + heta_2, \ h_{o2} &= g(h_2) = rac{1}{1 + e^{-h_2}} \ h_3 &= i_1 * w_{i_1h_3} + i_2 * w_{i_2h_3} + heta_3, \ h_{o3} &= g(h_3) = rac{1}{1 + e^{-h_3}} \ rac{1}{1 + e^{-h_3}} \ . \end{align}$$

$$egin{aligned} ar{y_1} &= ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 = g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}} \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_2} + ho_3 * w_{h_3o_2} + heta_{o2}, \ y_2 = g(ar{y_2}) = rac{1}{1 + e^{-ar{y_2}}} \end{aligned}$$

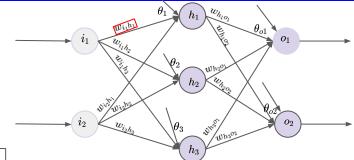
$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}}$$

$$rac{\partial E}{\partial ho_1} = rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_1-y_{ex_1})^2igg) + rac{\partial}{\partial ho_1}igg(rac{1}{2}(y_2-y_{ex_2})^2igg) }{\left[h_1=i_1*w_{i_1h_1}+i_2*w_{i_2h_1}+ heta_1,\,h_{o1}=g(h_1)=rac{1}{1+e^{-h_1}}
ight]}$$

$$egin{aligned} rac{\partial E}{\partial ho_1} &= rac{\partial}{\partial ho_1} igg(rac{1}{2} (y_1 - y_{ex_1})^2igg) + rac{\partial}{\partial ho_1} igg(rac{1}{2} (y_2 - y_{ex_2})^2igg) \ &= (y_1 - y_{ex_1}). \, w_{h_1o_1} + (y_2 - y_{ex_2}). \, w_{h_1o_2} \ &= \sum_{k=1}^{|Output|} w_{h_1o_k}. \, (y_k - y_{ex_k}) \end{aligned}$$



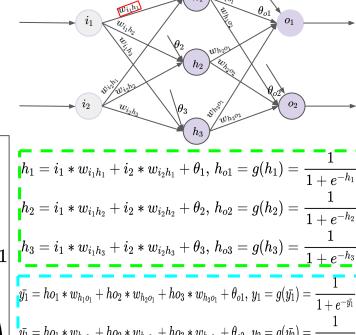
$$egin{aligned} h_2 &= i_1 * w_{i_1h_2} + i_2 * w_{i_2h_2} + heta_2, \ h_{o2} &= g(h_2) = rac{1}{1 + e^{-h_2}}, \ h_3 &= i_1 * w_{i_1h_3} + i_2 * w_{i_2h_3} + heta_3, \ h_{o3} &= g(h_3) = rac{1}{1 + e^{-h_3}}, \ ar{y_1} &= ho_1 * w_{h_1o_1} + ho_2 * w_{h_2o_1} + ho_3 * w_{h_3o_1} + heta_{o1}, \ y_1 &= g(ar{y_1}) = rac{1}{1 + e^{-ar{y_1}}}, \ ar{y_1} &= ho_1 * w_{h_1o_2} + ho_2 * w_{h_2o_2} + ho_3 * w_{h_3o_2} + heta_{o2}, \ y_2 &= g(ar{y_2}) = rac{1}{1 + e^{-ar{y_2}}}. \end{aligned}$$

$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}}$$

$$\Delta w_{i_1h_1} = rac{\partial E}{\partial ho_1} rac{\partial ho_1}{\partial h_1} rac{\partial h_1}{\partial w_{i_1h_1}} \ = \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight). \ ho_1. \ (1-ho_1). \ i_1 \ = i_1. \ ho_1. \ (1-ho_1). \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ = i_1. \ ho_1. \ (1-ho_1). \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ = i_1. \ ho_1. \ (1-ho_1). \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ = i_1. \ ho_1. \ (1-ho_1). \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ = i_1. \ ho_1. \ (1-ho_2). \ ho_1. \ (1-ho_2). \ ho_2. \ ho_3. \ ho_3$$



$$E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$$

$$egin{aligned} \Delta w_{i_1h_1} &= i_1.\,ho_1.\,(1-ho_1).\, \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ \Delta w_{i_1h_2} &= i_1.\,ho_2.\,(1-ho_2).\, \left(\sum_{k=1}^{|Output|} w_{h_2o_k.(y_k-y_{ex_k})}
ight) \ \Delta w_{i_1h_3} &= i_1.\,ho_3.\,(1-ho_3).\, \left(\sum_{k=1}^{|Output|} w_{h_3o_k.(y_k-y_{ex_k})}
ight) \ \Delta w_{i_2h_1} &= i_2.\,ho_1.\,(1-ho_1).\, \left(\sum_{k=1}^{|Output|} w_{h_1o_k.(y_k-y_{ex_k})}
ight) \ \Delta w_{i_2h_2} &= i_2.\,ho_2.\,(1-ho_2).\, \left(\sum_{k=1}^{|Output|} w_{h_2o_k.(y_k-y_{ex_k})}
ight) \ \Delta w_{i_2h_3} &= i_2.\,ho_3.\,(1-ho_3).\, \left(\sum_{k=1}^{|Output|} w_{h_3o_k.(y_k-y_{ex_k})}
ight) \end{aligned}$$

 $h_1 = i_1 * w_{i_1h_1} + i_2 * w_{i_2h_2} + heta_1, \, h_{o1} = g(h_1) = rac{1}{1 + e^{-h_1}} \ h_2 = i_1 * w_{i_1h_2} + i_2 * w_{i_2h_2} + heta_2, \, h_{o2} = g(h_2) = rac{1}{1 + e^{-h_2}}$

$$egin{aligned} h_3 &= i_1 * w_{i_1 h_3} + i_2 * w_{i_2 h_3} + heta_3, \ h_{o3} &= g(h_3) = rac{1}{1 + e^{-h_2}} \ &rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1 + e^{-h_3}} \ & rac{1}{1$$

 $E=rac{1}{2}\sum_{k=1}^{|Output|}\left(y_k-y_{ex_k}
ight)^2$

Do Yourself ...

Thank You

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