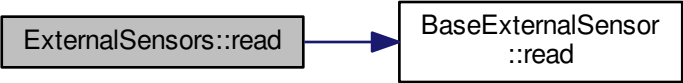


ExternalSensors::read



```
graph LR; A[ExternalSensors::read] --> B[BaseExternalSensor::read]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ExternalSensors::read'. The right box is white and contains the text 'BaseExternalSensor::read'. A blue arrow points from the right side of the gray box to the left side of the white box.

BaseExternalSensor
::read