Build my own CNN

Practice - CNN

• Run "7.2. MyCNN.ipynb"



Build my own CNN model

```
class MyCNN(nn.Module):
 def init (self):
                                   Suppose input image size = 64 \times 64 \times 3
    super(MyCNN, self). init ()
    self.features = nn.Sequential(
                                     #Assume input image H/W=64
       nn.Conv2d(3, 32, 3, 1, 1), #feature map H/W=(64+2*1-3)/1+1=64
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                \#H/W=(64+2*0-2)/2+1 = 32
       nn.Conv2d(32, 8, 3, 1, 1), \#H/W=(32+2*1-3)/1+1=32
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                #H/W=(32+2*0-2)/2+1 = 16
    self.classifier = nn.Sequential(
       nn.Dropout(),
       nn.Linear(8 * 16 * 16, 500),
       nn.ReLU(inplace=True),
       nn.Dropout(),
       nn.Linear(500, 100),
       nn.ReLU(inplace=True),
       nn.Dropout(),
       nn.Linear(100, 2),
 def forward(self, x):
   x = self.features(x)
   x = torch.flatten(x, 1)
   x = self.classifier(x)
   return x
```

The MLP used in "4.2. Classification with CE loss"

```
MyNet = nn.Sequential(
    nn.Linear(2, 50),
    nn.ReLU(),
    nn.Linear(50, 100),
    nn.ReLU(),
    nn.Linear(100, 50),
    nn.ReLU(),
    nn.Linear(50, 2),
)
MyNet.to(device)
```

Practice: Draw the structure of MyCNN

```
Suppose input image size = 64 x 64x 3
model = MyCNN().to(device)
print(model)
MyCNN(
  (features): Sequential(
    (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mo
    (3): Conv2d(32, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (4): ReLU(inplace=True)
    (5): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mo-
  (classifier): Sequential(
    (0): Dropout(p=0.5, inplace=False)
    (1): Linear(in features=2048, out features=500, bias=True)
    (2): ReLU(inplace=True)
    (3): Dropout(p=0.5, inplace=False)
    (4): Linear(in_features=500, out_features=100, bias=True)
    (5): ReLU(inplace=True)
    (6): Dropout(p=0.5, inplace=False)
    (7): Linear(in features=100, out features=2, bias=True)
```

My own CNN

```
from torchsummary import summary
summary(model, input_size=(3, 64, 64))
```

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 32, 64, 64]	896
ReLU-2	[-1, 32, 64, 64]	0
MaxPool2d-3	[-1, 32, 32, 32]	0
Conv2d-4	[-1, 8, 32, 32]	2,312
ReLU-5	[-1, 8, 32, 32]	0
MaxPool2d-6	[-1, 8, 16, 16]	0
Dropout-7	[-1, 2048]	0
Linear-8	[-1, 500]	1,024,500
ReLU-9 Dropout-10	[-1, 500] [-1, 500]	0
Linear-11	[-1, 100]	50,100
ReLU-12	[-1, 100]	0
Dropout-13	[-1, 100]	0
Linear-14	[-1, 2]	202

Total params: 1,078,010
Trainable params: 1,078,810
Non-trainable params: 0

Input size (MB): 0.05

Forward/backward pass size (MB): 2.42

Params size (MB): 4.11

Estimated Total Size (MB): 6.58

MLP in "4.2. Classification with CE loss"

BATCH_SIZE = 30
summary(MyNet, input_size=(BATCH_SIZE, 2))

Layer (type)	Output Shape	Param #
Linear-1 ReLU-2 Linear-3 ReLU-4 Linear-5 ReLU-6 Linear-7	[-1, 30, 50] [-1, 30, 50] [-1, 30, 50] [-1, 30, 100] [-1, 30, 50] [-1, 30, 50] [-1, 30, 50]	5,100 0 5,100 0 5,050 0

Total params: 10,402
Trainable params: 10,402
Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.09

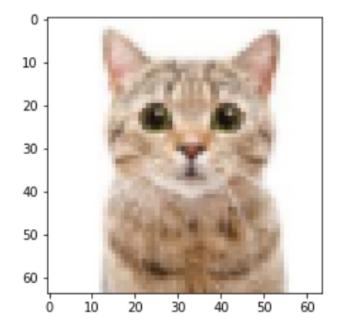
Params size (MB): 0.04

Estimated Total Size (MB): 0.13

Input image after pre-processing

```
In [13]: #visualize the image after pre-processing
    # Tensor is channel first, to plot, we need to convert to channel last
    import numpy as np
    PILImgArray = np.zeros((PILImg.shape[1], PILImg.shape[2], 3))
    PILImgArray[:,:,0] = PILImg[0, :, :]
    PILImgArray[:,:,1] = PILImg[1, :, :]
    PILImgArray[:,:,2] = PILImg[2, :, :]
    PILImgArray = PILImgArray*0.5+0.5 # change N(0, 1) to [0, 1]
    print(PILImgArray.shape, PILImgArray.min(), PILImgArray.max())
    plt.imshow(PILImgArray)
    plt.show()
```

(64, 64, 3) 0.027450978755950928 1.0



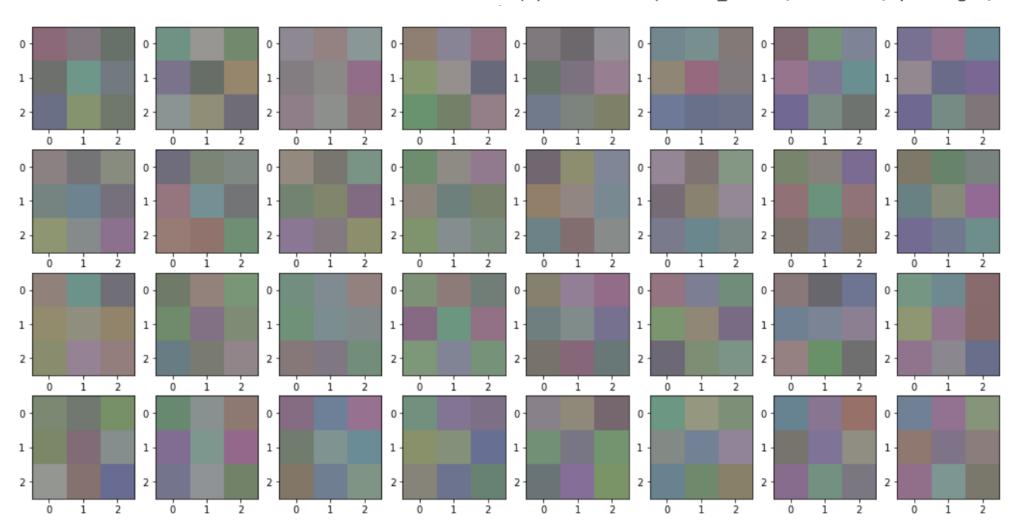
Input image size = $64 \times 64 \times 3$

Initial filter weights

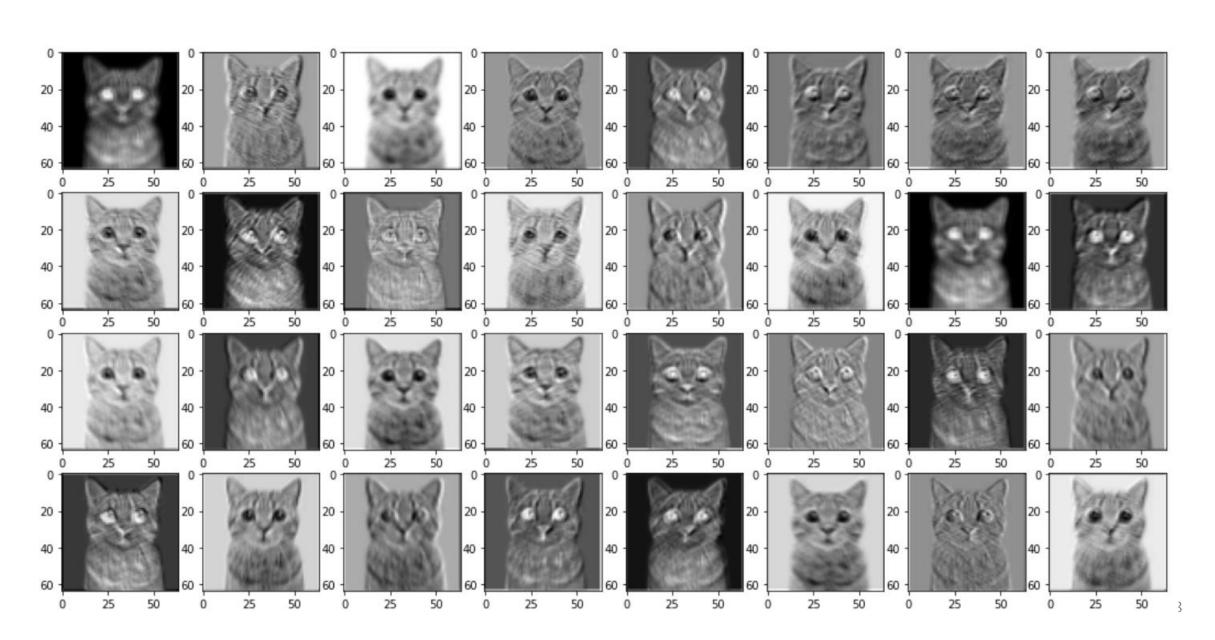
MyCNN(
 (features): Sequential(
 (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=
 (1): ReLU(inplace=True)
 (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1)
 (3): Conv2d(32, 8, kernel size=(3, 3), stride=(1, 1), padding=

(4): ReLU(inplace=True)

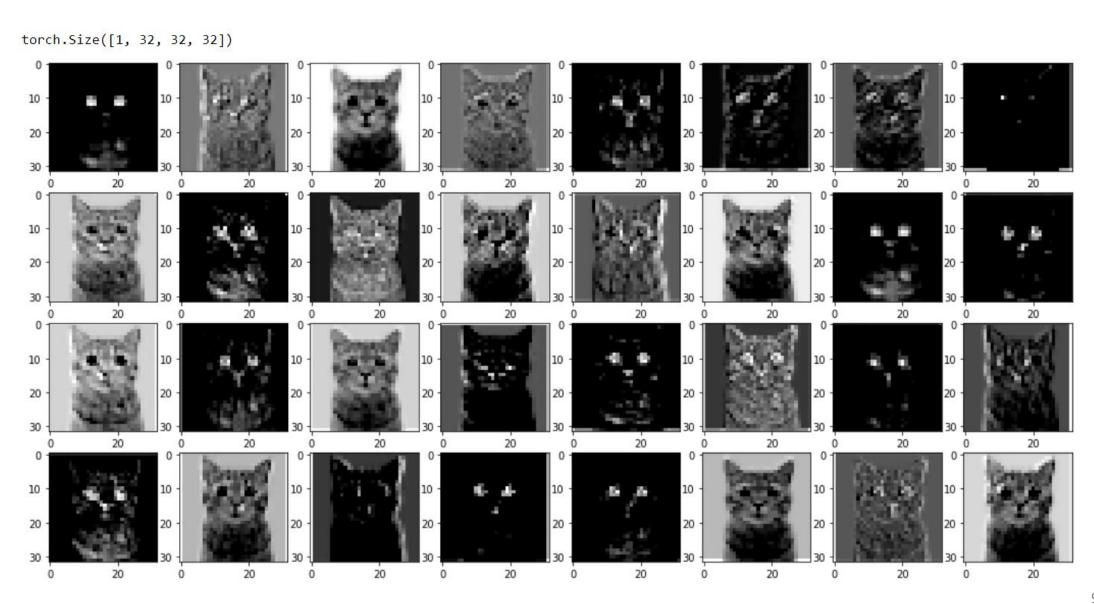
(5): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1



Output feature map, shape = 64x64x32



Feature map after max pooling, shape = 32x32x32



Flatten

```
class MyCNN(nn.Module):
  def init (self):
    super(MyCNN, self). init ()
    self.features = nn.Sequential(
                                     #Assume input image H/W=64
        nn.Conv2d(3, 32, 3, 1, 1), #feature map H/W=(64+2*1-3)/1+1=64
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                \#H/W=(64+2*0-2)/2+1 = 32
       nn.Conv2d(32, 8, 3, 1, 1), \#H/W=(32+2*1-3)/1+1=32
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                 \#H/W=(32+2*0-2)/2+1=16
    self.classifier = nn.Sequential(
        nn.Dropout ()
       nn.Linear (8 * 16 * 16, 500),
       nn.ReLU(nplace=True),
       nn.Dropout(),
       nn.Linear(500, 100),
       nn.ReLU(inplace=True),
       nn.Dropout(),
       nn.Linear(100, 2),
  def forward(self, x):
    x = self.features(x)
    x = torch.flatten(x, 1)
    x = self.classifier(x)
    return x
```

```
model = MyCNN().to(device)
print(model)
MyCNN(
  (features): Sequential(
    (0): Conv2d(3, 32, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mo
    (3): Conv2d(32, 8, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (4): ReLU(inplace=True)
    (5): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mo-
  (classifier): Sequential(
    (0): Dropout(p=0.5, inplace=ralse)
    (1): Linear(in features=2048, out features=500, bias=True)
    (2): ReLU(inplace=True)
    (3): Dropout(p=0.5, inplace=False)
    (4): Linear(in features=500, out features=100, bias=True)
    (5): ReLU(inplace=True)
    (6): Dropout(p=0.5, inplace=False)
    (7): Linear(in features=100, out features=2, bias=True)
In [22]: WholeConvLayers = model.features
         out1 = WholeConvLayers(imageTensor.to(device))
         print(out1.shape)
         torch.Size([1, 8, 16, 16])
In [23]: out2 = torch.flatten(out1, 1)
         print(out2.shape)
         torch.Size([1, 2048])
In [24]: ClassifierMLP = model.classifier
         out = ClassifierMLP(out2)
                                                                10
```

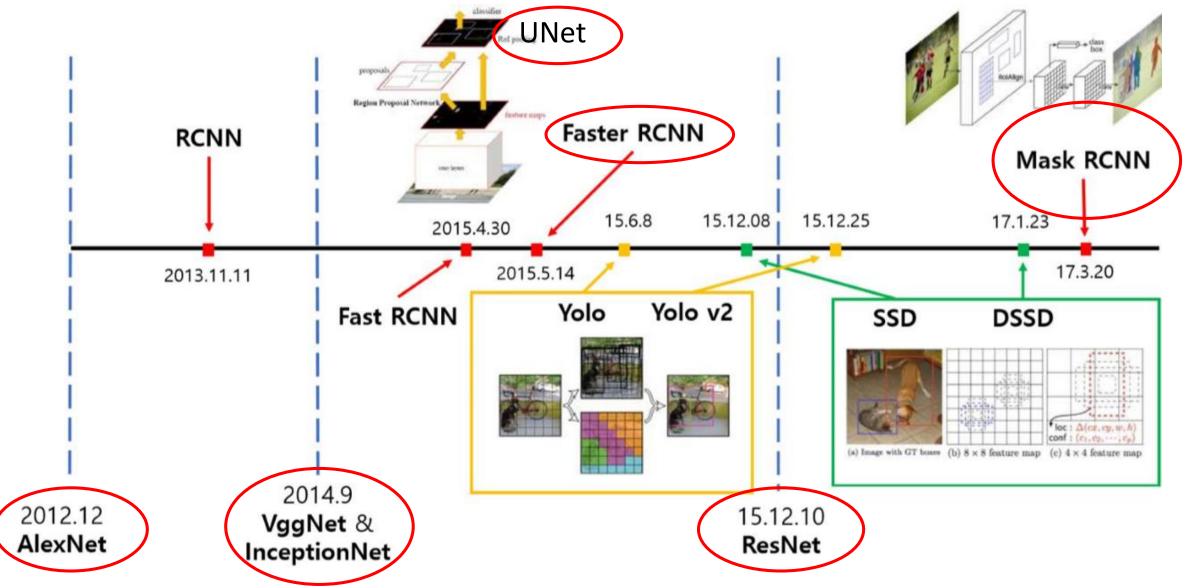
HW5 (1)

• Let the input image size be 224x224x3. Modify your CNN.

```
class MyCNN(nn.Module):
 def init (self):
    super(MyCNN, self). init ()
    self.features = nn.Sequential(
                                     #Assume input image H/W=64
       nn.Conv2d(3, 32, 3, 1, 1), #feature map H/W=(64+2*1-3)/1+1=64
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                 \#H/W=(64+2*0-2)/2+1=32
       nn.Conv2d(32, 8, 3, 1, 1), \#H/W=(32+2*1-3)/1+1=32
       nn.ReLU(inplace=True),
       nn.MaxPool2d(2, 2, 0),
                                 \#H/W=(32+2*0-2)/2+1=16
    self.classifier = nn.Sequential(
       nn.Dropout()
       nn.Linear (8 * 16 * 16, 500).
       nn.ReLU(nplace=True),
       nn.Dropout(),
       nn.Linear(500, 100),
       nn.ReLU(inplace=True),
       nn.Dropout(),
       nn.Linear(100, 2),
  def forward(self, x):
   x = self.features(x)
   x = torch.flatten(x, 1)
    x = self.classifier(x)
    return x
```

VGG16

CNN family



Practice – Load ImageNet pre-trained VGG

```
import torchvision
model = torchvision.models.vgg16(pretrained=True)

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth"
100%

528M/528M [00:10<00:00, 54.9MB/s]</pre>
```

Practice: Draw the structure of VGG16

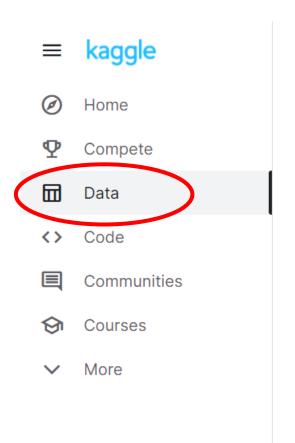
```
model.eval()
model. to (device)
VGG (
  (features): Sequential(
    (0): Conv2d(3, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace=True)
    (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (3): ReLU(inplace=True)
    (4): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (5): Conv2d(64, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (6): ReLU(inplace=True)
    (7): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU(inplace=True)
    (9): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (10): Conv2d(128, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU(inplace=True)
    (12): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (13): ReLU(inplace=True)
    (14): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (15): ReLU(inplace=True)
    (16): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
    (17): Conv2d(256, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU(inplace=True)
    (19): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (20): ReLU(inplace=True)
```

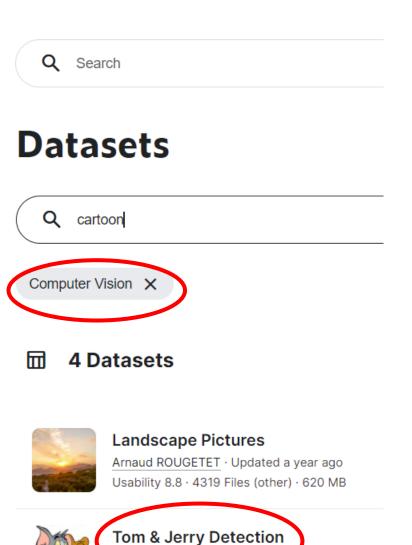
Practice: Draw the structure of VGG16

```
(21): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
  (22): ReLU(inplace=True)
 (23): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
 (24): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
 (25): ReLU(inplace=True)
 (26): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
 (27): ReLU(inplace=True)
 (28): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
  (29): ReLU(inplace=True)
 (30): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
(avgpool): AdaptiveAvgPool2d(output size=(7, 7))
(classifier): Sequential(
 (0): Linear(in features=25088, out features=4096, bias=True)
 (1): ReLU(inplace=True)
 (2): Dropout (p=0.5, inplace=False)
 (3): Linear(in features=4096, out features=4096, bias=True)
 (4): ReLU(inplace=True)
 (5): Dropout (p=0.5, inplace=False)
 (6): Linear(in features=4096, out features=1000, bias=True)
```

Transfer learning

Download images from Kaggle

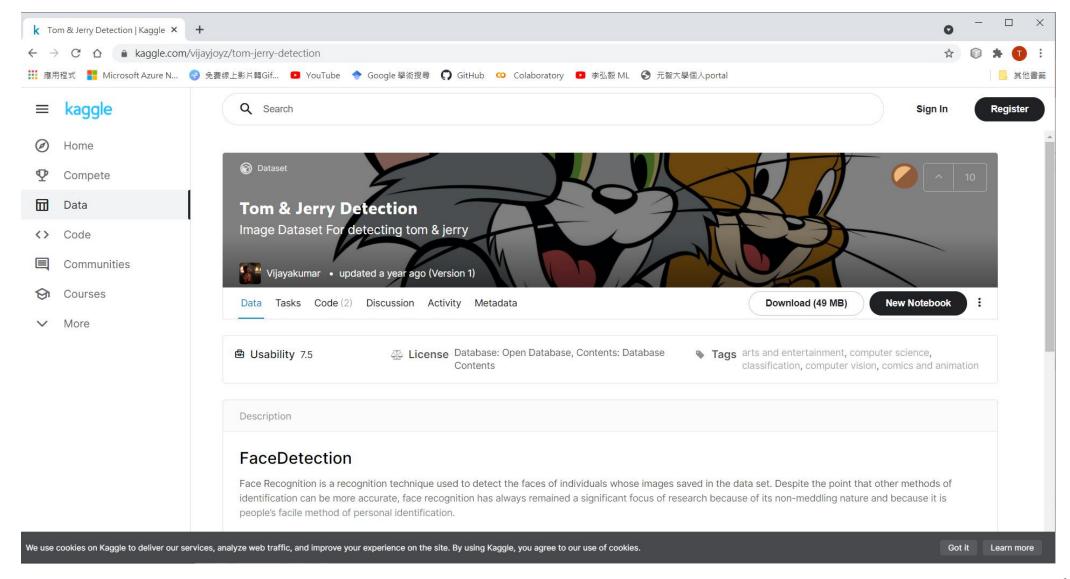




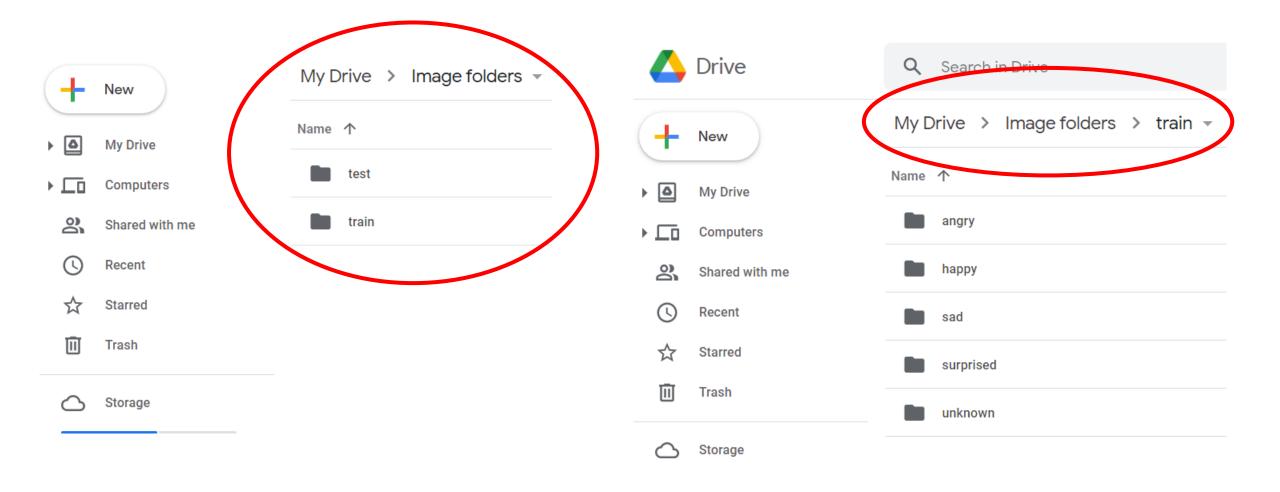
∕ijayakumar · Updated a year

Usability 7.5 484 Flies (other) · 47 MB

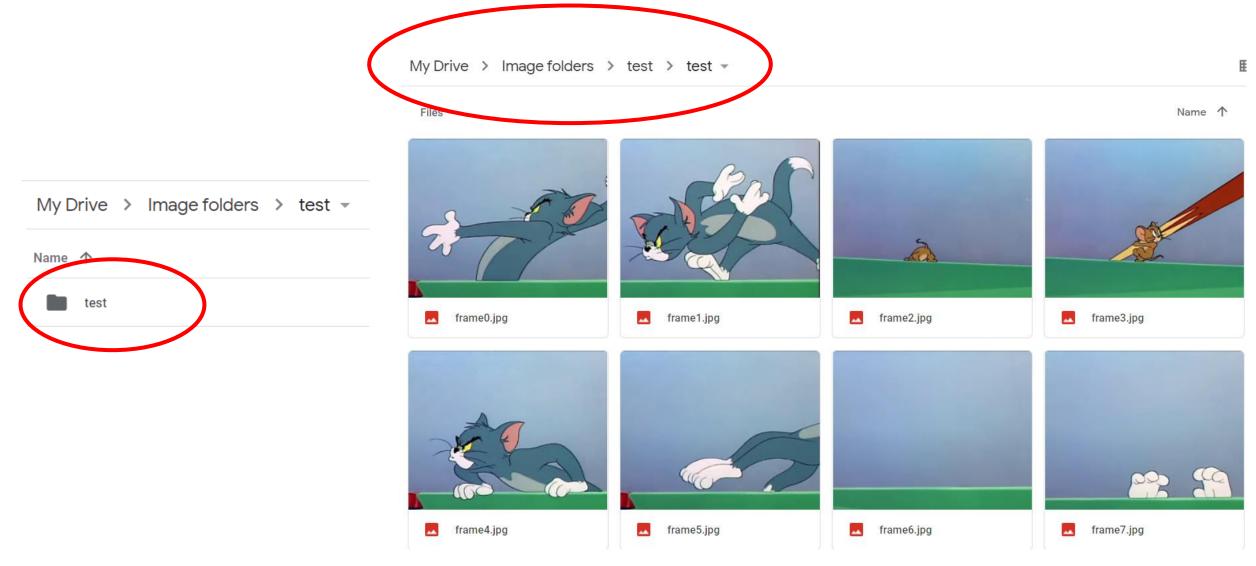
Tom & Jerry



Save images in your Google drive



Save images in your Google drive



Practice

• Run "7.3. Transfer learning.ipynb"



Build our own image classifier

- Suppose input image size = (224, 224, 3)
- Output has 5 classes: Angry, Happy, Sad, Surprised, Unknown

```
In [3]: import torch.nn as nn
        # fix the weight of convolution layers
        model.features.eval()
        # modify classifier
        model.classifier = torch.nn.Sequential(
          nn.Linear(25088, 4096),
          nn.ReLU(inplace=True),
          nn.Dropout(p=0.5, inplace=False),
          nn.Linear(4096, 4096),
          nn.ReLU(inplace=True),
          nn.Dropout(p=0.5, inplace=False),
          torch.nn.Linear(4096, (5)
```

Summary of parameters

```
Total params: 139,590,725
Trainable params: 139,590,725
Non-trainable params: 0
Input size (MB): 0.57
Forward/backward pass size (MB): 238.68
Params size (MB): 532.50
Estimated Total Size (MB): 771.75
```

MLP in "4.2. Classification with CE loss"

```
BATCH_SIZE = 30
summary(MyNet, input_size=(BATCH_SIZE, 2))
```

Layer (type)	Output Shape	Param #
Linear-1	[-1, 30, 50]	150
ReLU-2	[-1, 30, 50]	0
Linear-3	[-1, 30, 100]	5,100
ReLU-4	[-1, 30, 100]	0
Linear-5	[-1, 30, 50]	5,050
ReLU-6	[-1, 30, 50]	0
Linear-7	[-1, 30, 2]	102

Total params: 10,402
Trainable params: 10.402
Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.09

Params size (MB): 0.04

Estimated Total Size (MB): 0.13

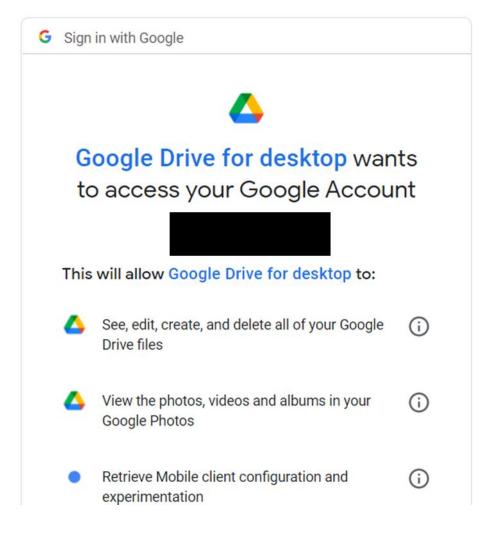
Connect to Google drive

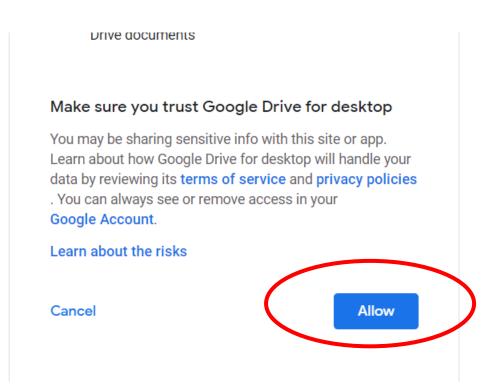




繁體中文 ▼ 説明 隱私權 條款

Connect to Google drive





Connect to Google drive



Sign in

Please copy this code, switch to your application and paste it there:

4/1AY0e-

g4roX6ceHqek0M4JnYfPrHwEJCdrz8DP6nsD5ylm7UNZB



[7] from google.colab import drive drive.mount("/content/gdrive")

Mounted at /content/gdrive

Batch training using Image Folder

```
In [8]: from torchvision import transforms
        transformer = transforms.Compose([
             transforms.Resize((224, 224)),
             transforms.ToTensor(),
             transforms.Normalize(mean=[0.5, 0.5, 0.5], std=[0.5, 0.5, 0.5])
        from torchvision import datasets
In [9]:
        train dataset = datasets.ImageFolder(noot = "/content/gdrive/MyDrive/Image folders/train", transform = transformer)
n [10]: classes = train dataset.classes
        classes index = train dataset.class to idx
        print(classes)
        print(classes index)
        ['angry', 'happy', 'sad', 'surprised', 'unknown']
        {'angry': 0, 'happy': 1, 'sad': 2, 'surprised': 3, 'unknown': 4}
n [11]: import torch.utils.data as Data
        loader = Data.DataLoader(dataset=train dataset, batch size=4, shuffle=True)
```

Batch training using data in RAM

```
In [9]: tensorX = torch.FloatTensor(trainX).to(device)
         tensorY hat = torch.LongTensor(trainY hat).to(device)
         print(tensorX.shape, tensorY hat.shape)
         torch.Size([128, 2]) torch.Size([128])
In [10]: torch dataset = Data.TensorDataset(tensorX, tensorY hat)
In [11]: loader = Data.DataLoader(
             dataset=torch dataset,
             batch size=5,
             shuffle=True,
             num workers=0, # subprocesses for loading data
In [12]: for (batchX, batchY hat) in loader:
             break
         print(batchX.shape, batchY hat)
         torch.Size([5, 2]) tensor([0, 0, 0, 1, 1], device='cuda:0')
```

One batch has 4 images

```
[12]: for batchX, batchY hat in loader:
        break;
      print(batchX.shape, batchY hat.shape, batchY hat)
      torch.Size([4, 3, 224, 224]) torch.Size([4]) tensor([3, 2, 3, 2])
[13]: import numpy as np
      import matplotlib.pyplot as plt
      imgTensor = torchvision.utils.make grid(batchX)
      imgArray = imgTensor.numpy()
      imgArray1 = np.zeros((imgArray.shape[1], imgArray.shape[2], 3))
      imgArray1[:,:,0] = imgArray[0, :, :]
      imgArray1[:,:,1] = imgArray[1,:,:]
      imgArray1[:,:,2] = imgArray[2, :, :]
      imgArray1 = imgArray1*0.5+0.5
      plt.figure(figsize=(12, 6))
      plt.imshow(imgArray1)
      plt.show()
      print([classes[i] for i in batchY_hat])
```



['surprised', 'sad', 'surprised', 'sad']

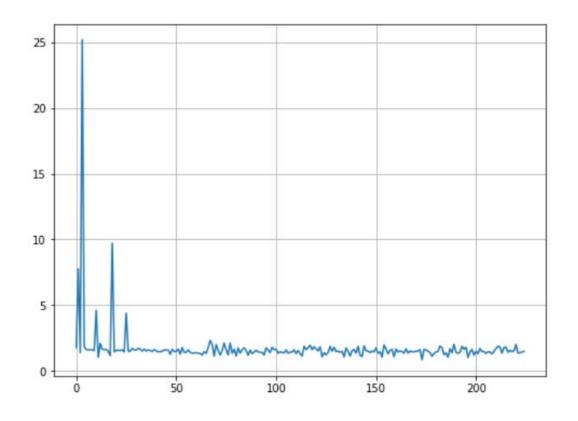
Batch training loop

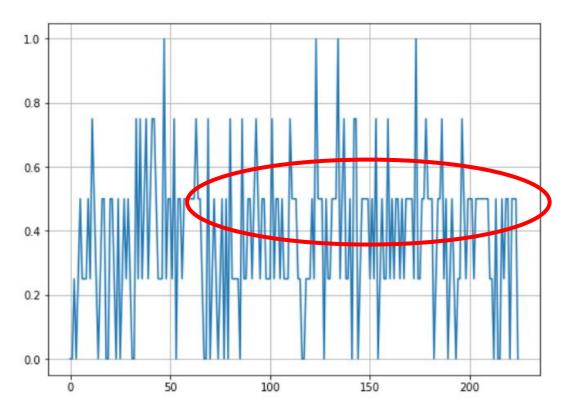
```
[16]: lossLst = []
      accuracyLst = []
      for epoch in range(1, 4):
        print("\nepoch = ", epoch, end = ", ")
        print("batch: ", end="")
        for step, (batch x, batchY hat) in enumerate(loader):
          if(step%5==0):
            print(step, end = ", ")
          tensorY = model(batch x.to(device))
          loss = loss func(tensorY, batchY hat.to(device))
          lossLst.append(float(loss))
          optimizer.zero grad()
          loss.backward()
          optimizer.step()
          correct = 0
          tensorY = torch.softmax(tensorY, 1)
          MaxIdxOfEachRow = torch.max(tensorY, 1)[1]
          for i in range(batchY hat.shape[0]):
            if (int(MaxIdxOfEachRow[i]) == int(batchY hat[i])):
              correct += 1
          accuracy = correct/batchY hat.shape[0]
          accuracyLst.append(accuracy)
      epoch = 1, batch: 0, 5, 10, 15, 20, 25, 30, 35, 40, 45, !
```


MLP in "4.2. Classification with CE loss"

```
lossLst = []
accuracyLst = []
for epoch in range(1, 500):
  for (batchX, batchY hat) in loader:
    tensorY = MyNet(batchX)
    loss = loss func(tensorY, batchY hat)
    lossLst.append(float(loss))
    optimizer.zero grad()
    loss.backward()
    optimizer.step()
    correct = 0
    tensorY = torch.softmax(tensorY, 1)
    MaxIdxOfEachRow = torch.max(tensorY, 1)[1]
    for i in range(batchY hat.shape[0]):
      if (int(MaxIdxOfEachRow[i]) == int(batchY hat[i])):
        correct += 1
    accuracy = correct/batchY hat.shape[0]
    accuracyLst.append(accuracy)
```

Why training is not good?





Biased prediction, why?

Transfer learning design 2

Use first 10 layers in convolution section

Let input image size = (224, 224, 3), Output has 5 classes: Angry, Happy, Sad, Surprised, Unknown

```
[3] import torch.nn as nn
     class MyCNN (nn. Module):
         def init (self):
             super(MyCNN, self).__init__()
             self. features = vgg19. features[0:10] #layer 0-9
             self. classifier = nn. Sequential (
                 nn. Dropout ().
                 nn. Linear (56*56*128, \ \ 4096),
                 nn. ReLU (inplace=True)
                 nn.Dropout(p 0.5, inplace=False),
                 nn. Linear (4096, 4096),
                 nn. ReLU (inplace=True),
                 nn. Dropout (p=0.5, inplace=False),
                 nn. Linear (4096, 5),
         def forward(self, x):
             x = self. features(x)
             x = torch. flatten(x, 1)
             x = self. classifier(x)
             return x
```

1,661M parameters!

from torchsummary import summary summary (model, input_size=(3, 224, 224))

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 64, 224, 224]	1, 792
ReLU-2	[-1, 64, 224, 224]	0
Conv2d-3	[-1, 64, 224, 224]	36, 928
ReLU-4	[-1, 64, 224, 224]	0
MaxPool2d-5	[-1, 64, 112, 112]	0
Conv2d-6	[-1, 128, 112, 112]	73, 856
ReLU-7	[-1, 128, 112, 112]	0
Conv2d-8	[-1, 128, 112, 112]	147, 584
ReLU-9	[-1, 128, 112, 112]	0
MaxPool2d-10	[-1, 128, 56, 56]	0
Dropout-11	[-1, 401408]	0
Linear-12	[-1, 4096]	1, 644, 171, 264
ReLU-13	[-1, 4096]	0
Dropout-14	[-1, 4096]	0
Linear-15	[-1, 4096]	16, 781, 312
ReLU-16	[-1, 4096]	0
Dropout-17	[-1, 4096]	0
Inear-18	[-1, 5]	20, 485

Total params: 1,661,233,221 Trainable params: 1,661,233,223

Non-trainable params: 0

Total params: 139,590,725
Trainable params: 139,590,725
Non-trainable params: 0
-----Input size (MB): 0.57
Forward/backward pass size (MB): 238.68
Params size (MB): 532.50
Estimated Total Size (MB): 771.75

CUDA out of memory!

```
epoch = 1, batch: 0,
RuntimeError
                                         Traceback (most recent call last)
<ipython-input-17-94eca5998520> in <module>()
           lossLst.append(float(loss))
    11
           optimizer.zero grad()
    12
          loss.backward()
---> 13
           optimizer.step()
    14
    15
                                  1 frames
/usr/local/lib/python3.7/dist-packages/torch/autograd/ init .py in backward(tensors,
grad tensors, retain graph, create graph, grad variables, inputs)
           Variable. execution engine.run backward(
   145
               tensors, grad tensors, retain graph, create graph, inputs,
   146
               allow unreachable=True, accumulate grad=True) # allow unreachable flag
--> 147
   148
   149
RuntimeError: CUDA out of memory. Tried to allocate 6.12 GiB (GPU 0; 11.17 GiB total
capacity; 6.46 GiB already allocated; 4.27 GiB free; 6.47 GiB reserved in total by PyTorch)
```

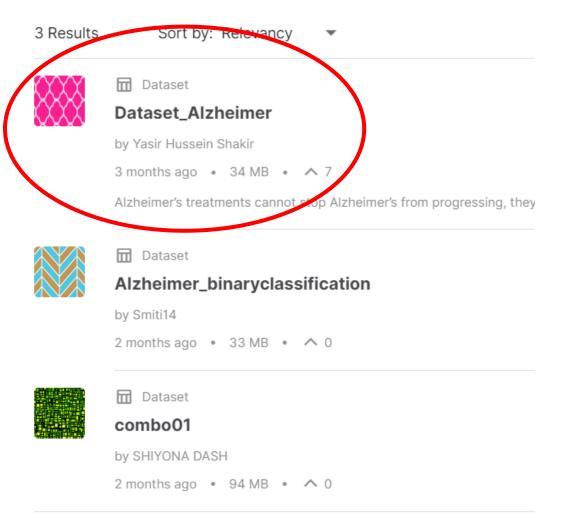
HW5 (2) – Can CNN recognize your facial expression?

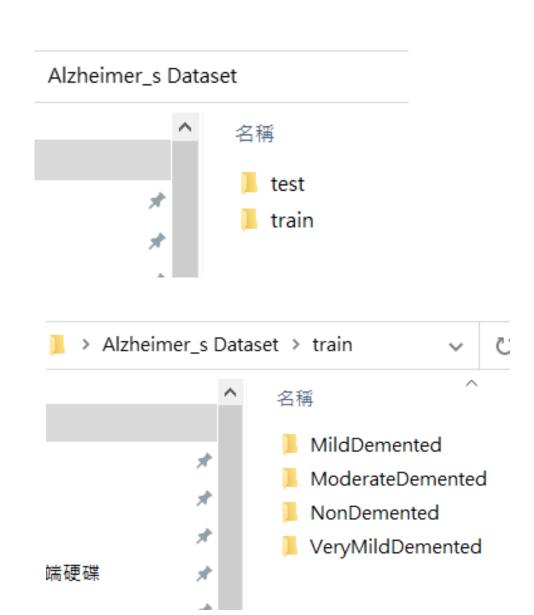
• Use transfer learning to train an image classifier to recognize happy and angry faces.



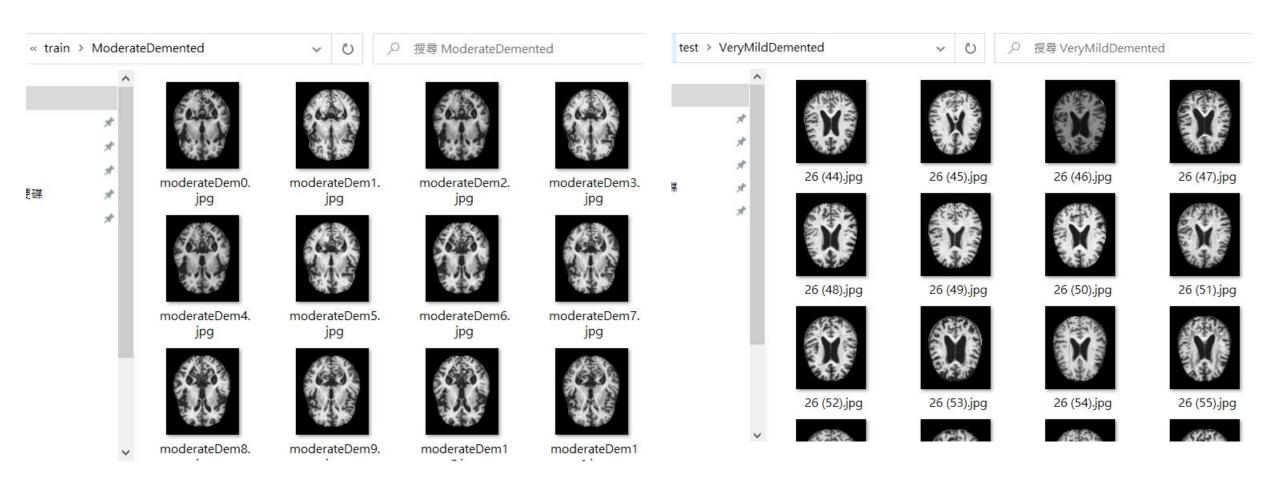
HW5 (2) – Recognize Alzheimer disease from MRI

Results by searching "dementia" in Kaggle

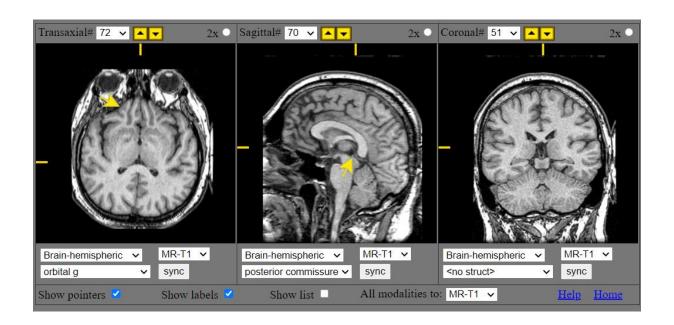




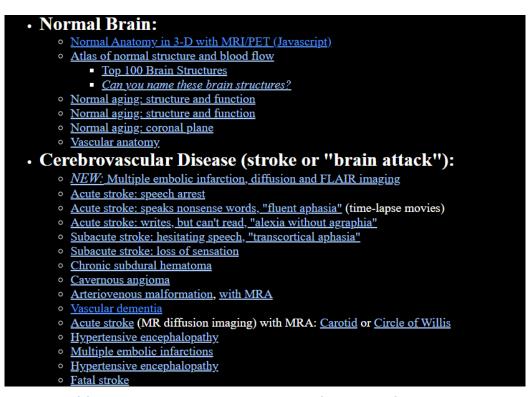
HW5 (2) – Recognize Alzheimer disease from MRI



If you want to understand more about MRI brain scan images



https://www.med.harvard.edu/aANliB/cases/caseNA/pb9.htm



https://www.med.harvard.edu/aANliB/home.html

HW5 (2) – Can we recognize dementia disease from facial expression ?

Facial expressions can detect Parkinson's disease: preliminary evidence from videos collected online

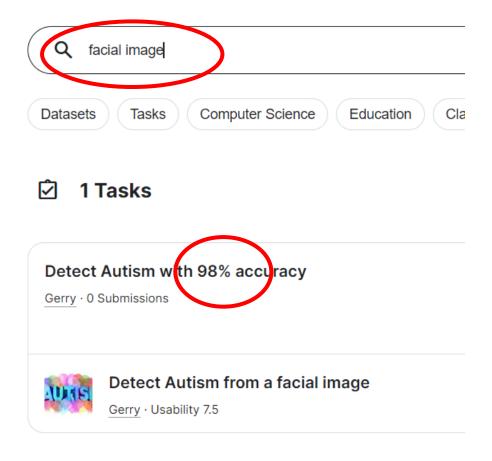
Mohammad Rafayet Ali, Taylor Myers, Ellen Wagner, Harshil Ratnu, E. Ray Dorsey, Ehsan Hoque



https://arxiv.org/abs/2012.05373

HW5 (2) – Can CNN detect Autism from a facial image?

Datasets



consolidated
test
train
valid
autism-2
autism-S-224-89.33.h5

