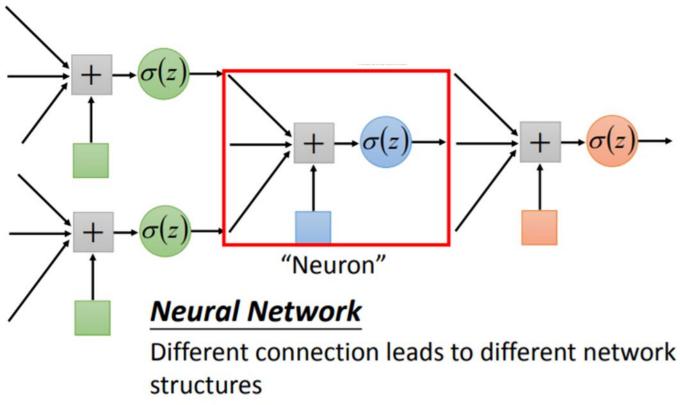
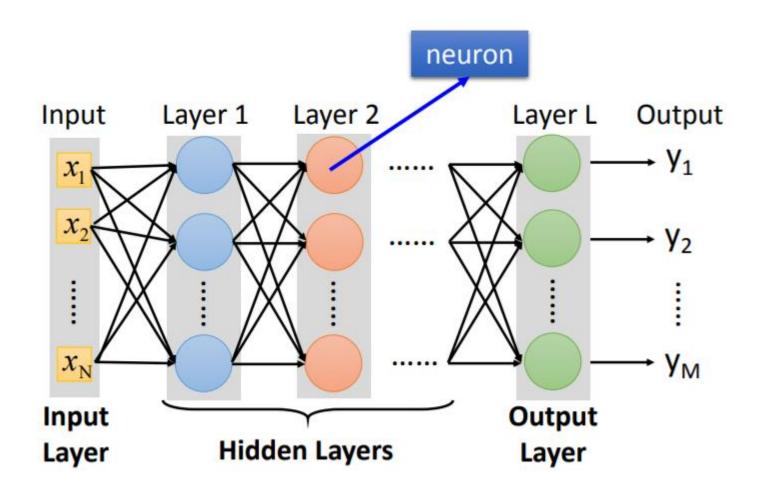
Neural network



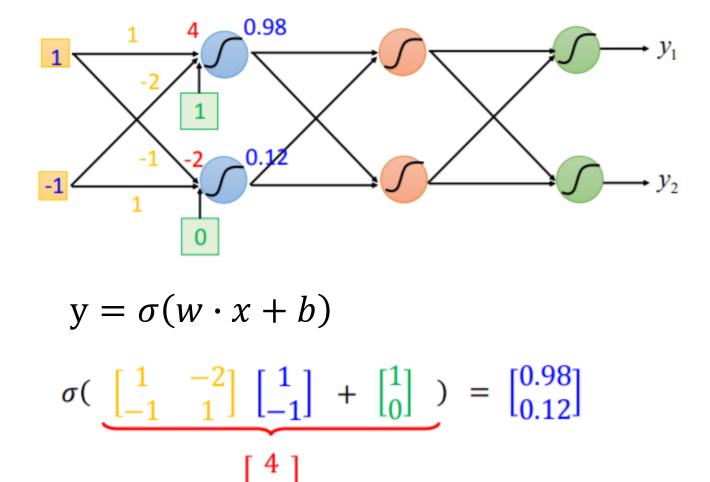
heta Network parameter heta: all the weights and biases in the "neurons"

Each neuron is a classifier

MLP is a fully connected feedforward network



Fully connected feed forward network is implemented as matrix operation



Reference: 李弘毅 ML Lecture 6 https://youtu.be/Dr-WRIEFefw

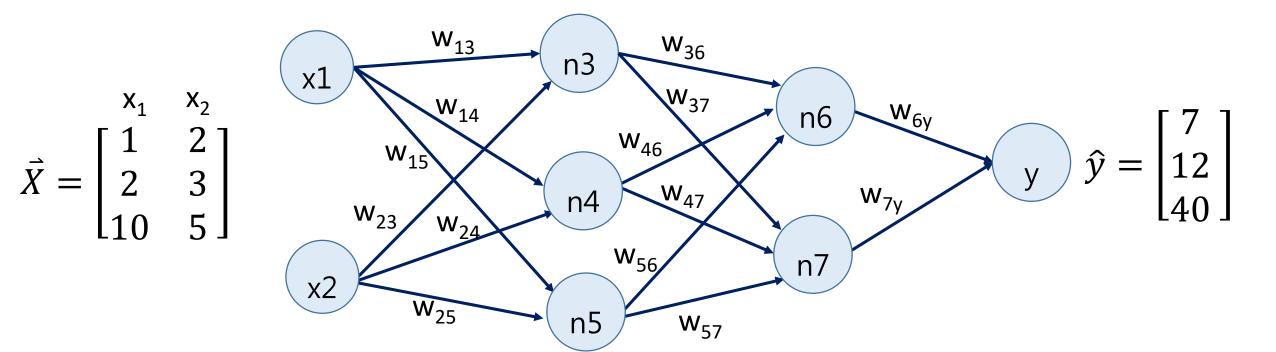
Practice

• Run "6. Matrix operation.ipynb"



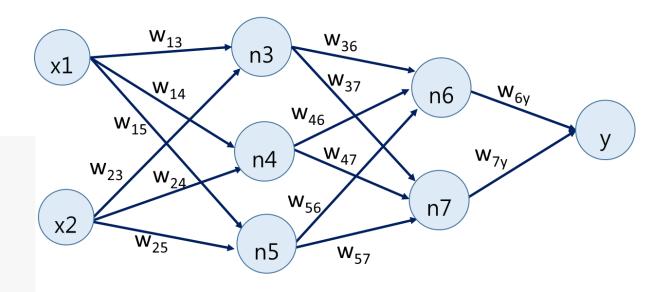
Matrix operation

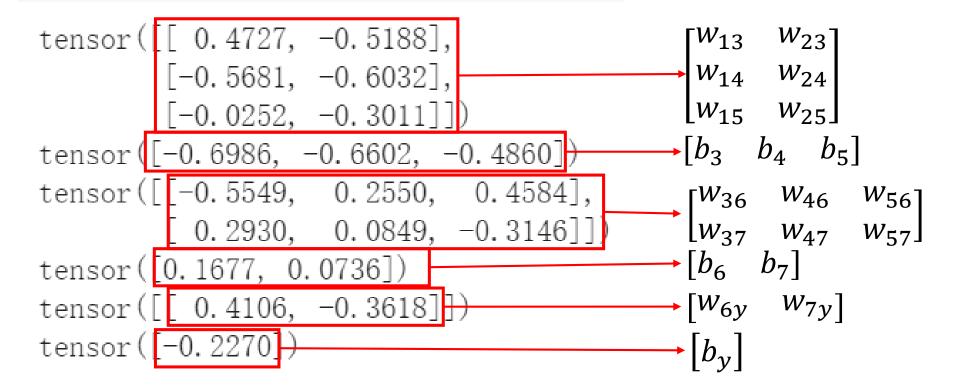
```
MyNet = nn. Sequential(
    nn. Linear(2, 3),
    nn. Linear(3, 2),
    nn. Linear(2, 1)
)
```



Matrix operation

```
for param in MyNet.parameters():
    if param.requires_grad:
        print(param.data)
```





$$\vec{X} = \begin{bmatrix} x_1 & x_2 \\ 1 & 2 \\ 2 & 3 \\ 10 & 5 \end{bmatrix} \qquad \begin{array}{c} x_1 \\ w_{15} \\ w_{23} \\ w_{24} \\ \end{array}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \\ 10 & 5 \end{bmatrix} \begin{bmatrix} w_{13} & w_{14} & w_{15} \\ w_{23} & w_{24} & w_{25} \end{bmatrix} + [b_3 \quad b_4 \quad b_5]$$

$$\begin{bmatrix} k_3^1 & k_4^1 & k_5^1 \\ k_3^2 & k_4^2 & k_5^2 \\ k_3^3 & k_4^3 & k_5^3 \end{bmatrix} + \begin{bmatrix} b_3 & b_4 & b_5 \\ b_3 & b_4 & b_5 \\ b_3 & b_4 & b_5 \end{bmatrix}$$

 W_{13}

n3

n4

n5

```
\begin{bmatrix} n_3^1 & n_4^1 & n_5^1 \\ n_3^2 & n_4^2 & n_5^2 \\ n_3^3 & n_4^3 & n_5^3 \end{bmatrix}
```

Use Excel to verify

```
W1 = MyNet[0].weight
b1 = MyNet[0].bias
print(W1, W1.shape, b1)
```

```
#Calculate n3, n4, n5
HiddenLayer1 = MyNet[0](tensorX)
print(HiddenLayer1)
```

```
tensor([[-1.2635, -2.4348, -1.1135], [-1.3097, -3.6061, -1.4398], [ 1.4340, -9.3577, -2.2441]],
```

```
#Calculate n3, n4, n5 using Pytorch matrix operation

HiddenLayer1 = tensorX.mm(torch.transpose(W1, 1, 0)) + b1

print(HiddenLayer1)
```

```
tensor ([[-1.2635, -2.4348, -1.1135],

[-1.3097, -3.6061, -1.4398],

[ 1.4340, -9.3577, -2.2441]], grad_fn=<AddBackward0>)
```

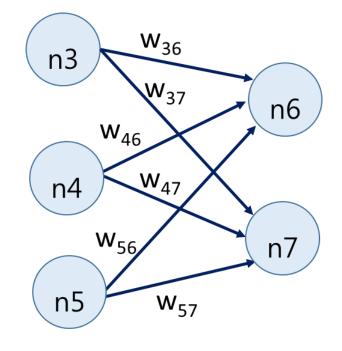
```
#Calculate n6, n7 using PyTorch matrix operation
W2 = MyNet[1].weight
b2 = MyNet[1].bias
HiddenLayer2 = HiddenLayer1. mm(torch. transpose(W2, 1, 0)) +b2
print(HiddenLayer2)
```

$$\begin{bmatrix} n_3^1 & n_4^1 & n_5^1 \\ n_3^2 & n_4^2 & n_5^2 \\ n_3^3 & n_4^3 & n_5^3 \end{bmatrix}$$

[-4.0429, 0.4054]], grad_fn=<AddBackward0>)

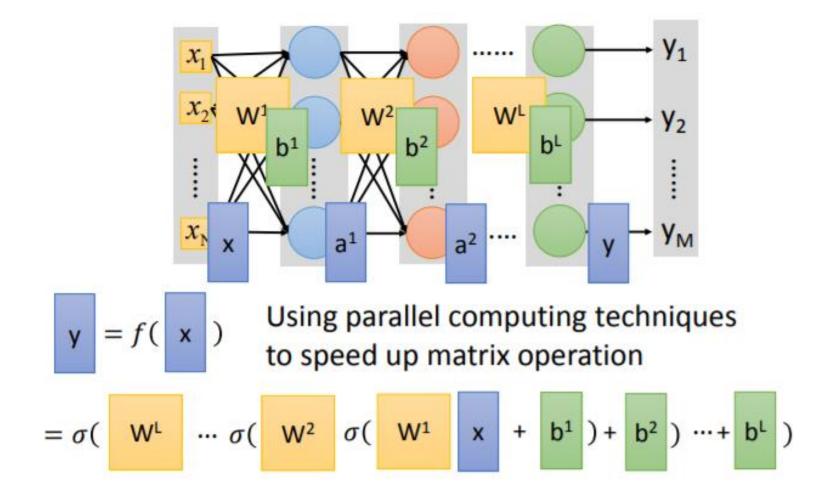
$$\begin{bmatrix} -1.2635 & -2.4348 & -1.1135 \\ -1.3097 & -3.6061 & -1.4398 \\ 1.4340 & -9.3577 & -2.2441 \end{bmatrix} \begin{bmatrix} w_{36} & w_{37} \\ w_{46} & w_{47} \\ w_{56} & w_{57} \end{bmatrix} + \begin{bmatrix} b_6 & b_7 \end{bmatrix}$$

$$\begin{array}{ccc}
k_6^1 & k_7^1 \\
k_6^2 & k_7^2 \\
k_6^3 & k_7^3
\end{array} +
\begin{bmatrix}
b_6 & b_7 \\
b_6 & b_7 \\
b_6 & b_7
\end{bmatrix}$$



$$\begin{bmatrix} n_6^1 & n_7^1 \\ n_6^2 & n_7^2 \\ n_6^3 & n_7^3 \end{bmatrix} \quad \begin{array}{c} \text{Use Excel to} \\ \text{verify} \end{array}$$

Use parallel computing to speed up matrix operation



Use parallel computing to speed up matrix operation

```
In [2]: if(torch.cuda.is_available()):
    device = torch.device("cuda")
    print(device, torch.cuda.get_device_name(0))
else:
    device= torch.device("cpu")
    print(device)

cuda Tesla P100-PCIE-16GB
```

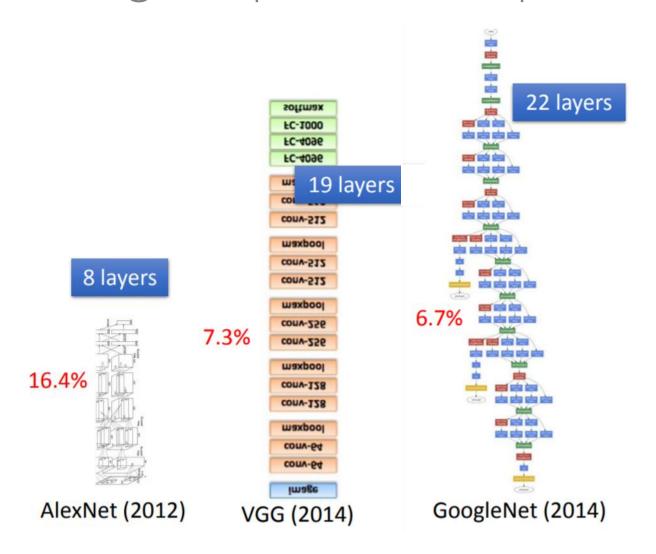
tensorX = torch.FloatTensor(trainX).to(device)
tensorY_hat = torch.FloatTensor(trainY_hat).to(device)
print(tensorX.shape, tensorY_hat.shape)

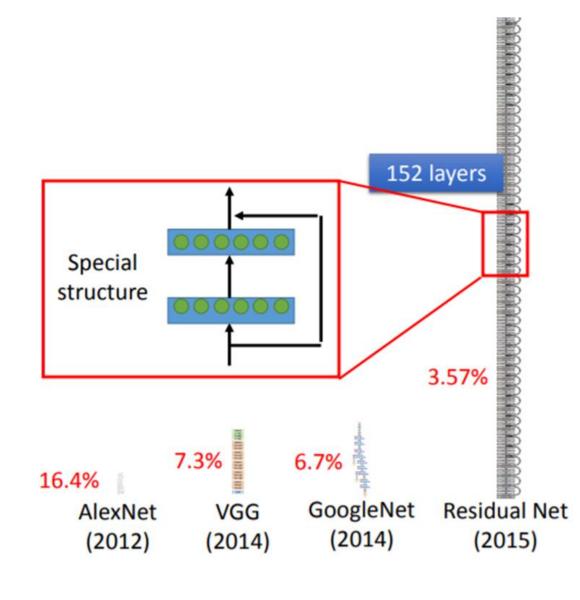
```
torch.Size([128, 2]) torch.Size([128, 1])
```

```
conv1_out = conv1(imageTensor.to(device))
conv1_out.shape
#output image (feature map) has 64 channels
torch.Size([1, 64, 55, 55])
```

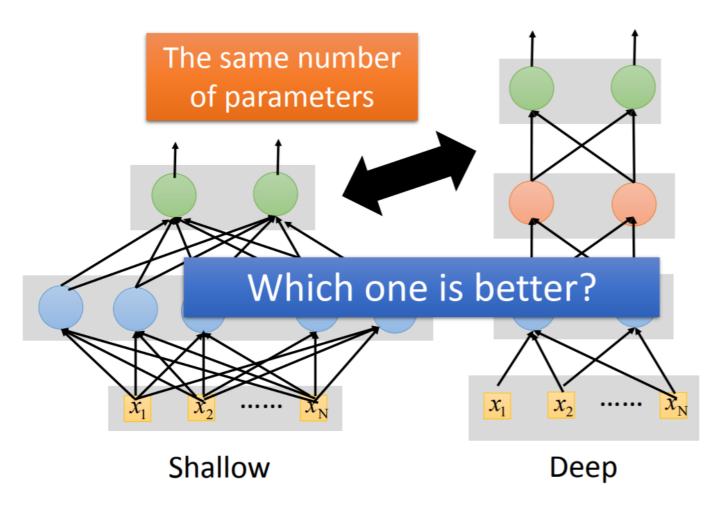
Why deep?

Going deeper and deeper...





With same number of parameters, which NN is better?



Deep is better

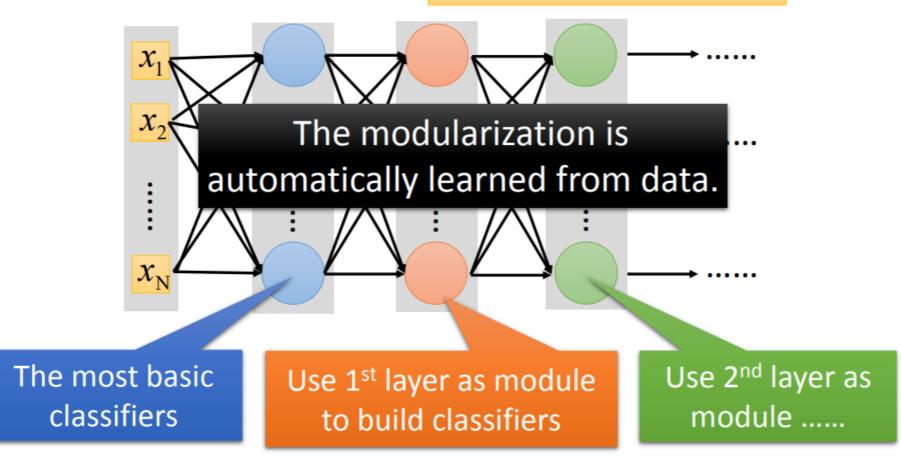
| Layer X Size | Word Error Rate (%) | Layer X Size | Word Error Rate (%) | |
|--------------|------------------------|--------------|------------------------|--|
| 1 X 2k | 24.2 | | | |
| 2 X 2k | 20.4 | \// | Why? | |
| 3 X 2k | 18.4 | | | |
| 4 X 2k | 17.8 | | | |
| 5 X 2k | 17.2 | →1 X 3772 | 22.5 | |
| 7 X 2k | 17.1 | → 1 X 4634 | 22.6 | |
| | | 1 X 16k | 22.1 | |

deep + thin

Seide, Frank, Gang Li, and Dong Yu. "Conversational Speech Transcription Using Context-Dependent Deep Neural Networks." *Interspeech*. 2011.

Reason 1 – Modularization

Deep → Modularization → Less training data?



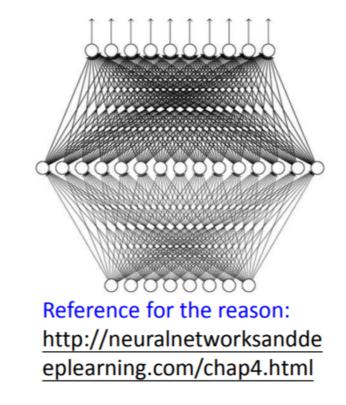
Universality theorem

Any continuous function f

$$f: \mathbb{R}^N \to \mathbb{R}^M$$

Can be realized by a network with one hidden layer

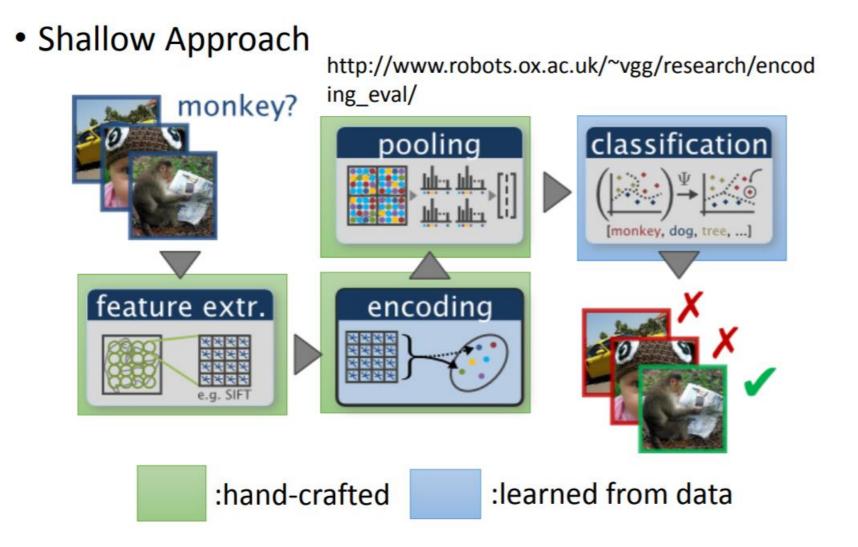
(given **enough** hidden neurons)



Yes, shallow network can represent any function.

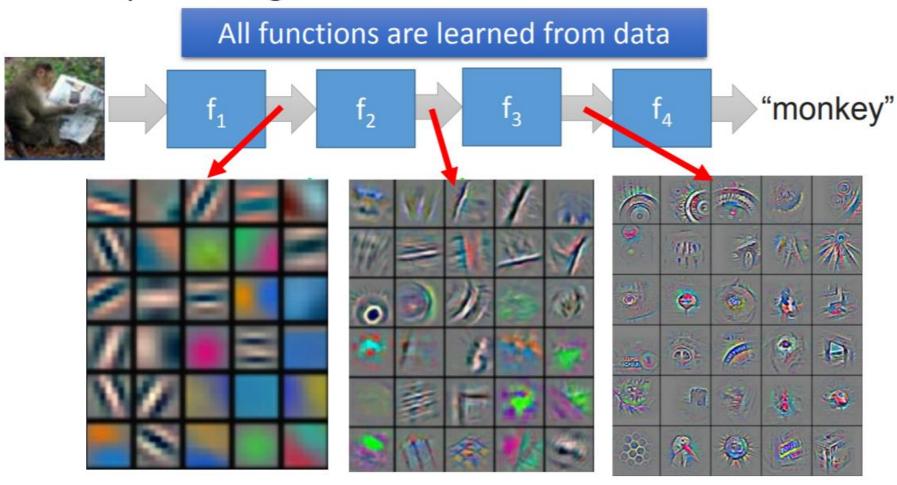
However, using deep structure is more effective.

Reason 2: End-to-end learning



End-to-end learning

Deep Learning



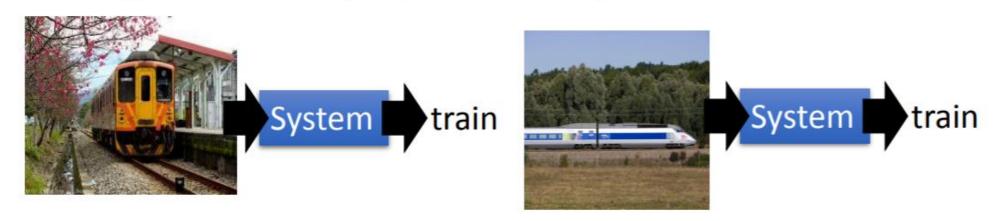
Reference: 李弘毅 ML Lecture 11 https://youtu.be/XsC9byQkUH8

Reason 3 - Easier to handle complex task

Very similar input, different output



Very different input, similar output

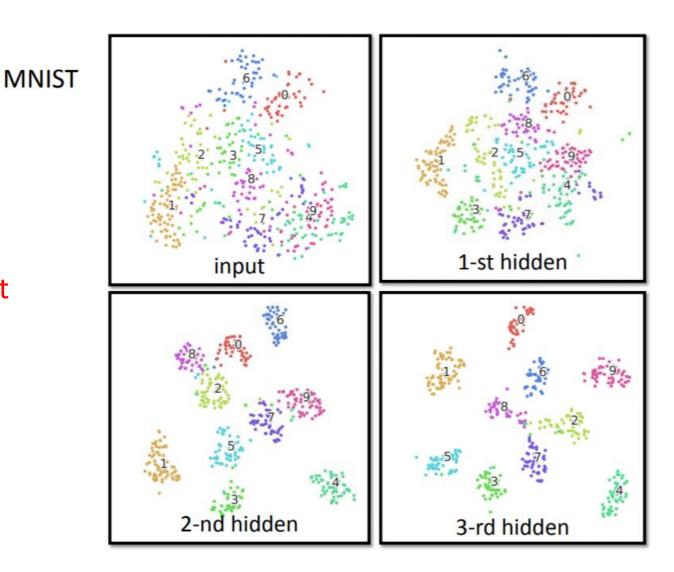


Reference: 李弘毅 ML Lecture 11 https://youtu.be/XsC9byQkUH8

Easier to handle complex task with DL

How to implement

this in PyTorch?



Reference: 李弘毅 ML Lecture 11 https://youtu.be/XsC9byQkUH8