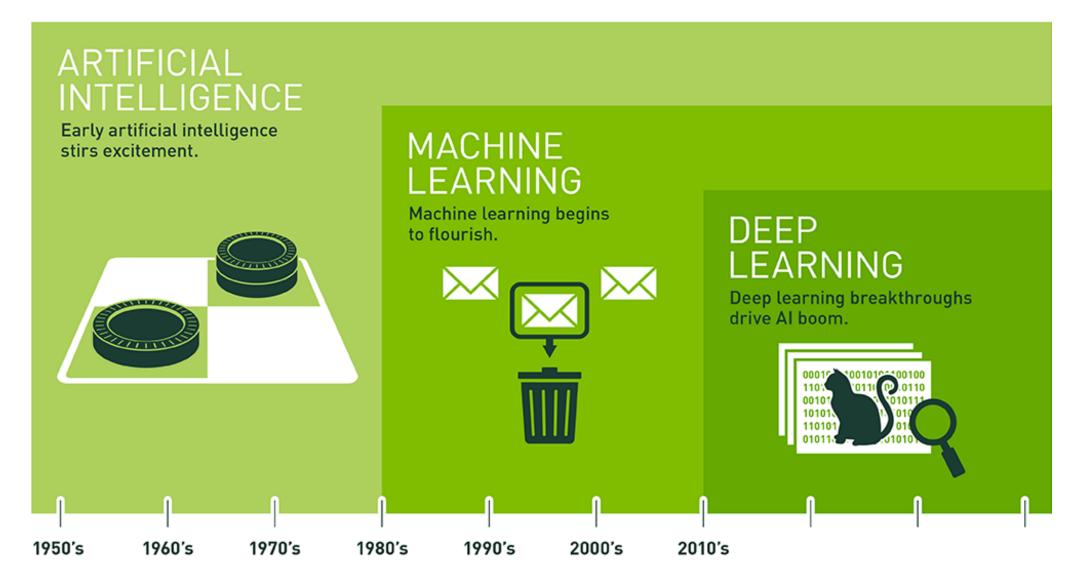
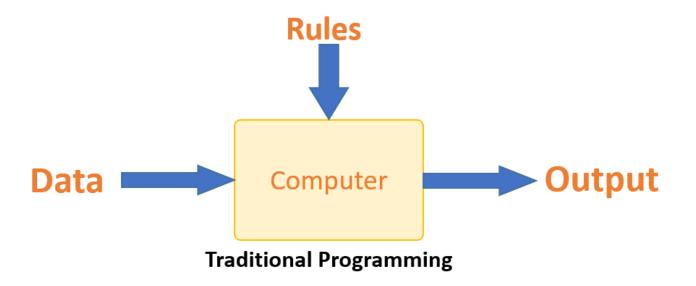
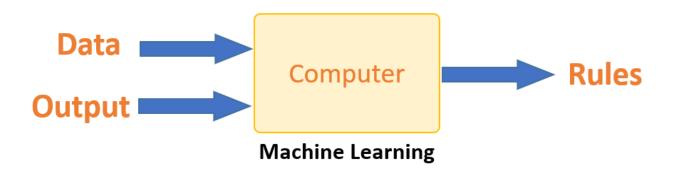
### What is Al?



## Traditional programming vs Al

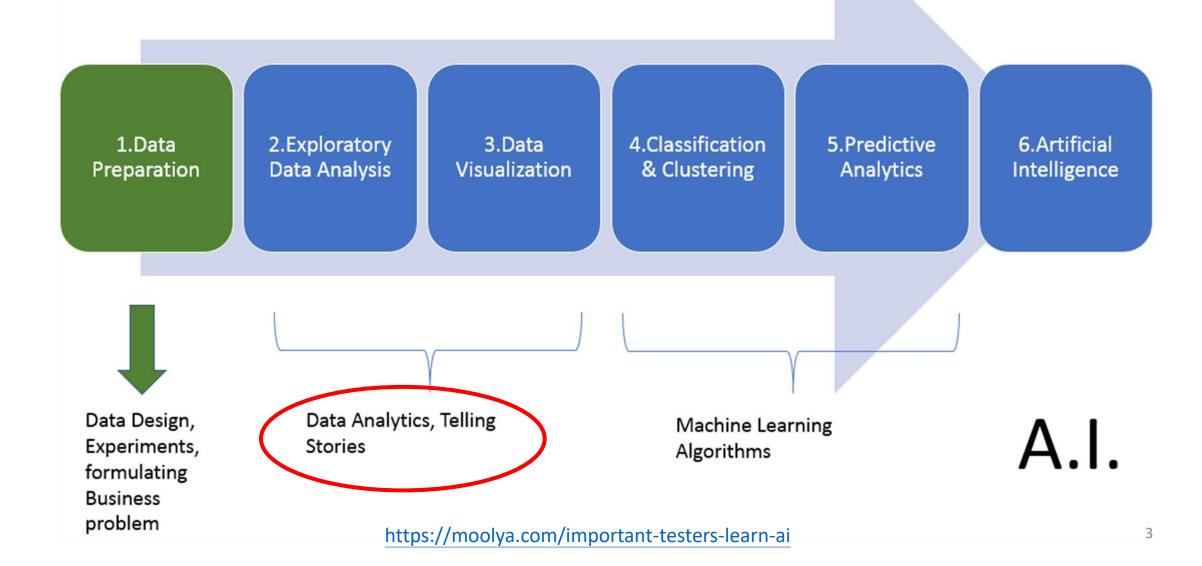




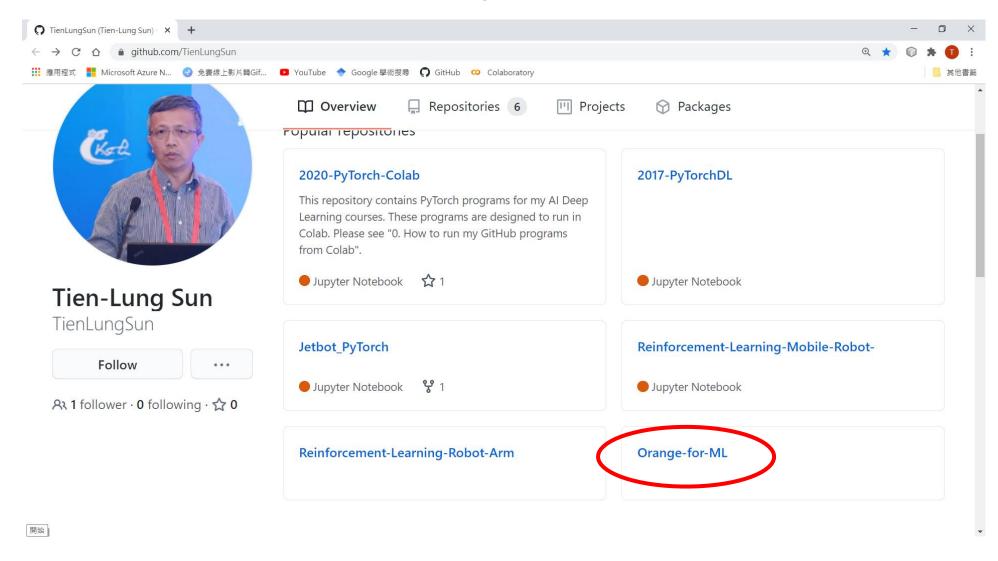
The practice of using algorithms to parse data, learn from it, and then make a determination or prediction about something in the world.

### HI before Al

Interactively visualize and explore your data before Al



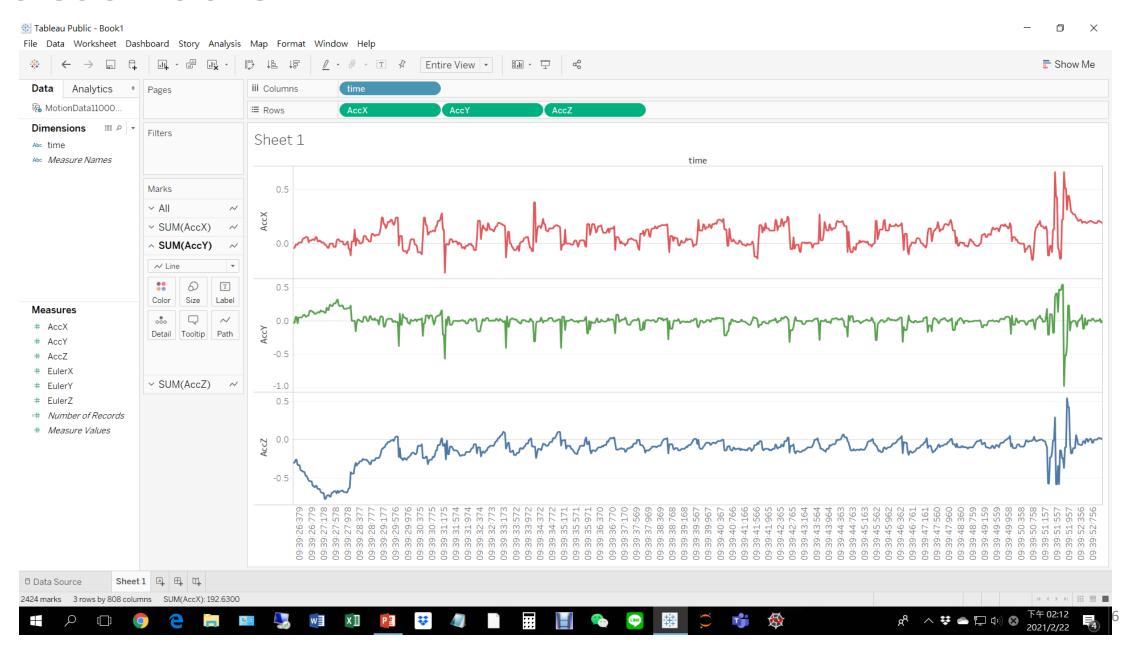
## Download data files from my GitHub



## Interactively visual exploration – (1) Tableau Public



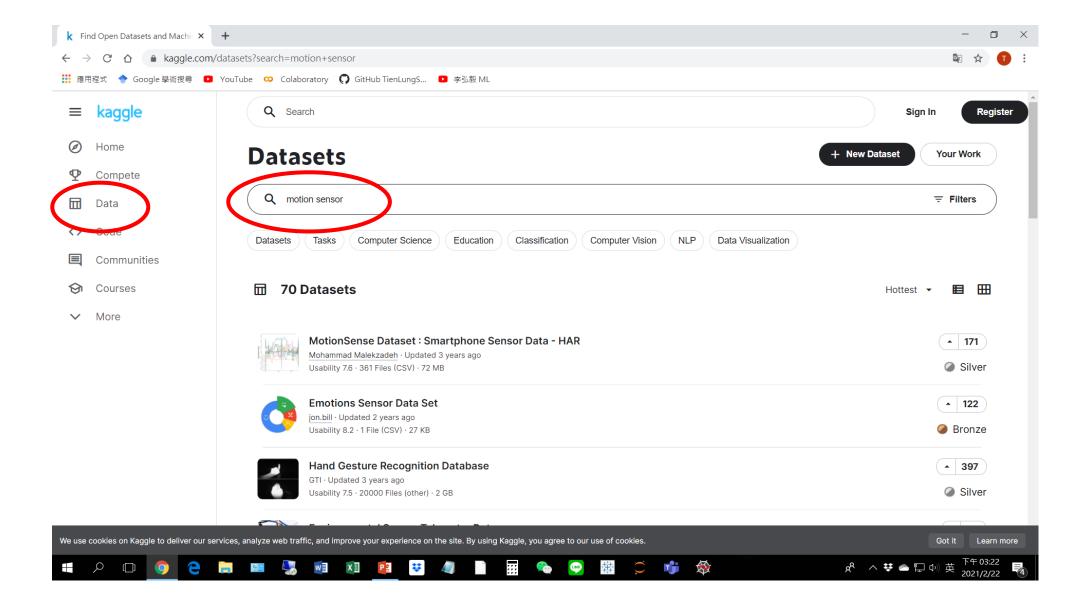
### Tableau Public



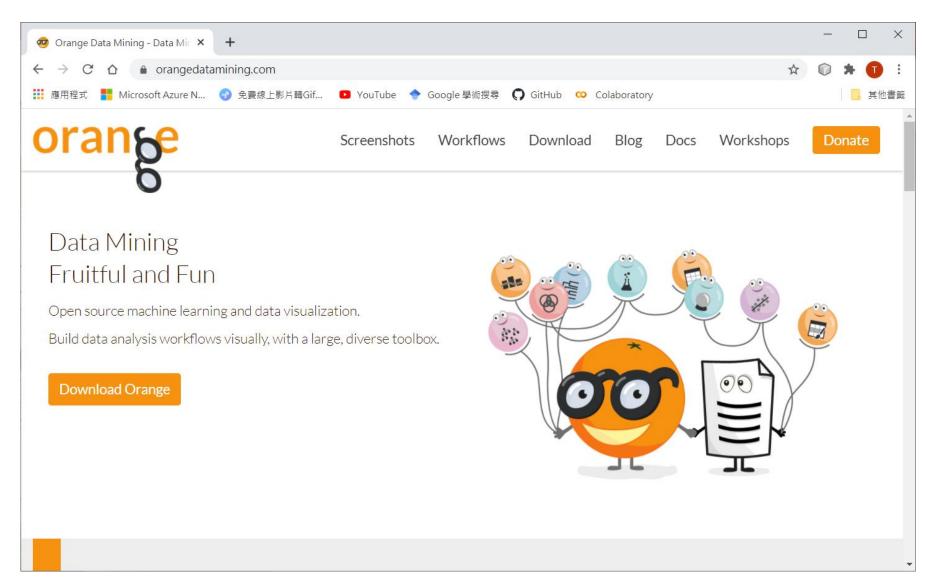
### Practice – Tableau public

- 1. Download and install Tableau Public
- 2. Visualize the motion data file
- 3. Search Kaggle (<a href="https://www.kaggle.com/">https://www.kaggle.com/</a>) to find a sensor data file (see next slide)
- 4. Use Tableau public to visualize the data file

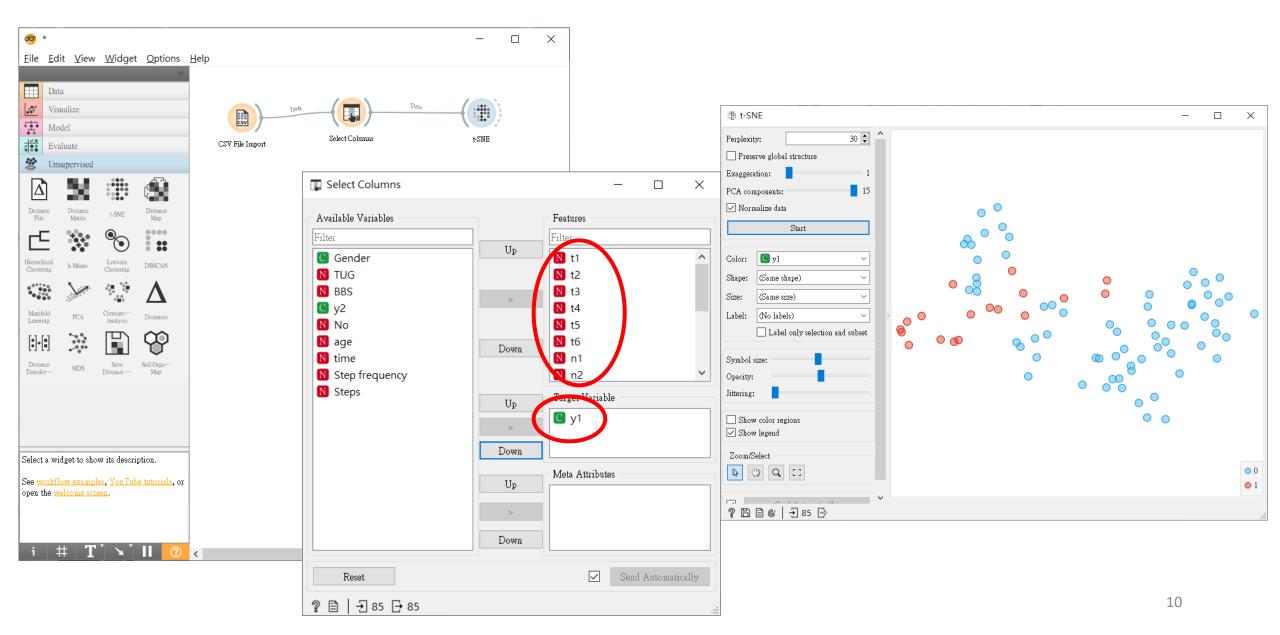
### Kaggle



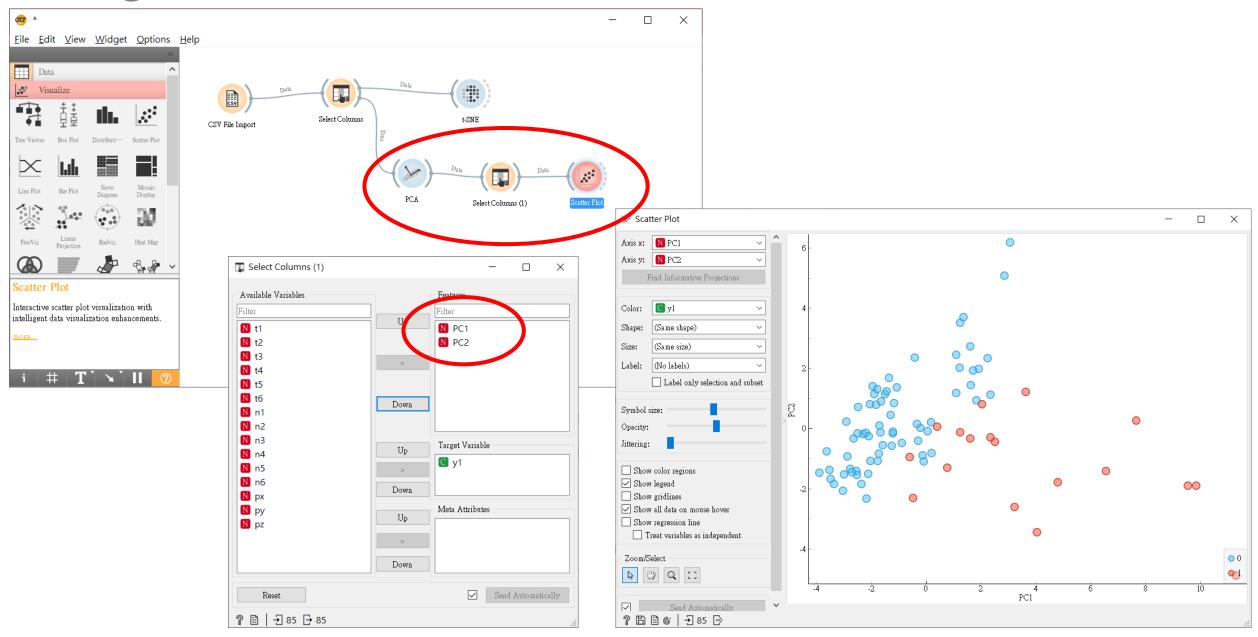
## Interactively visual exploration – (2) Orange



# Orange



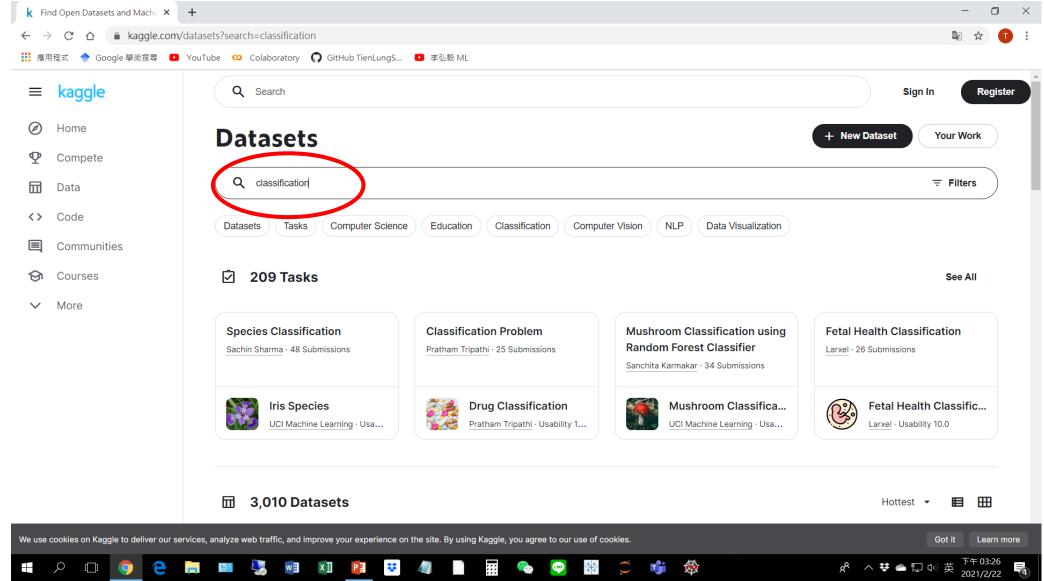
### Orange



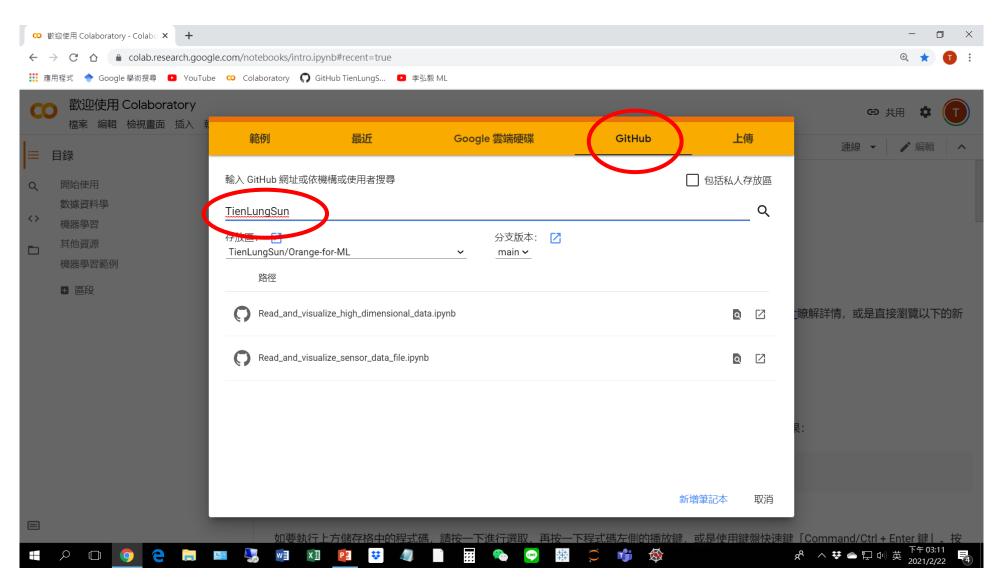
### Practice – Orange

- 1. Download and install Orange
- 2. Visualize the 3M TUG data file
- 3. Search Kaggle to find a classification data file
- 4. Use Orange to visualize the high dimensional data

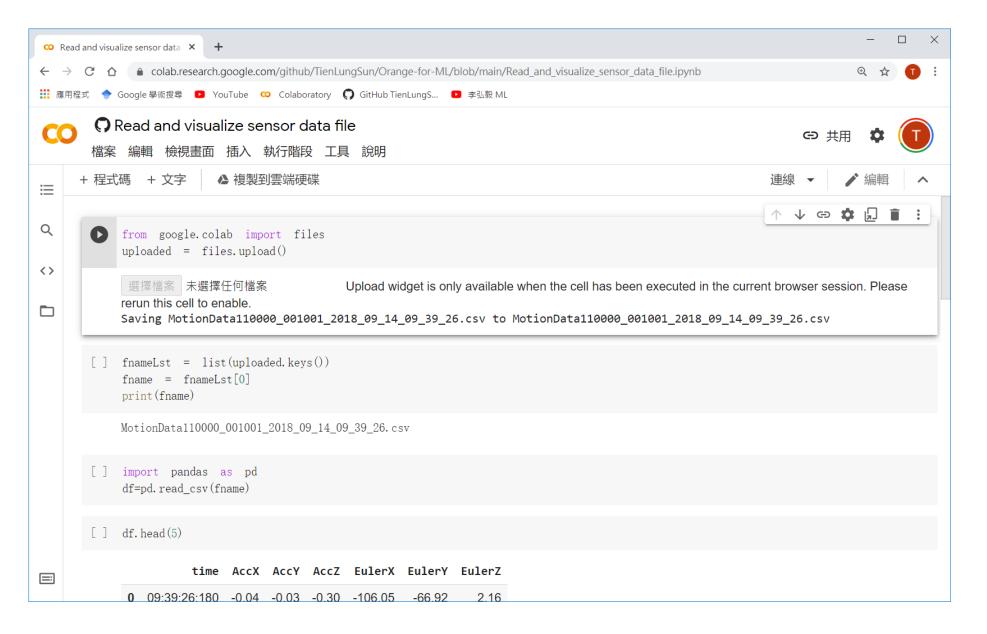
## Kaggle



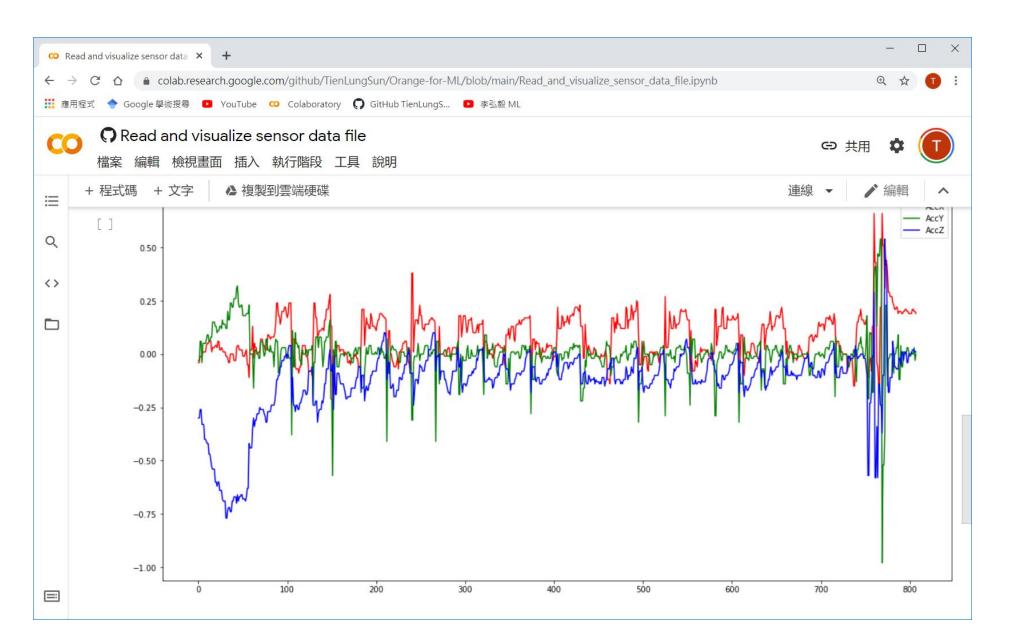
## Data visualization – (3) Python coding



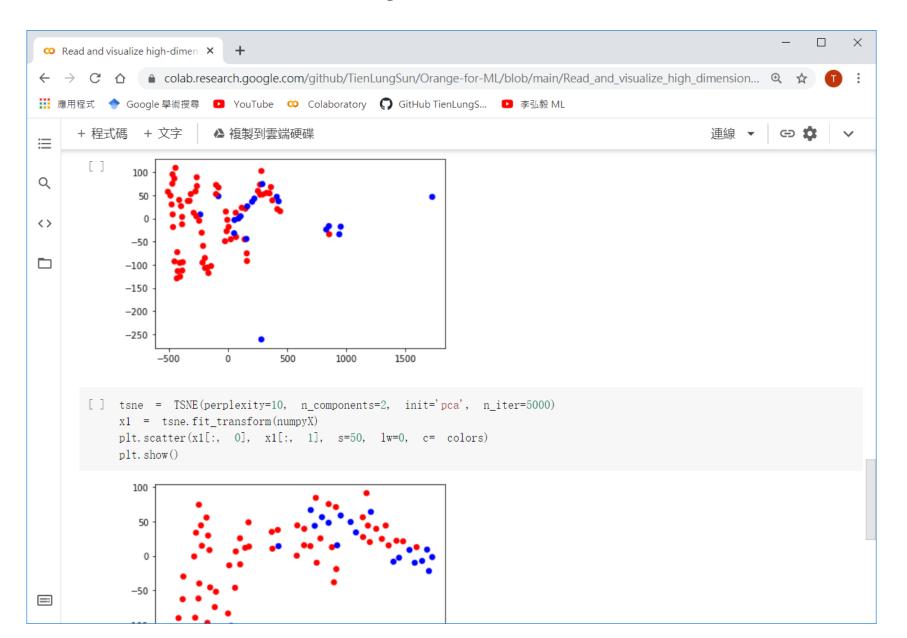
## Data visualization with Python



### Data visualization with Python



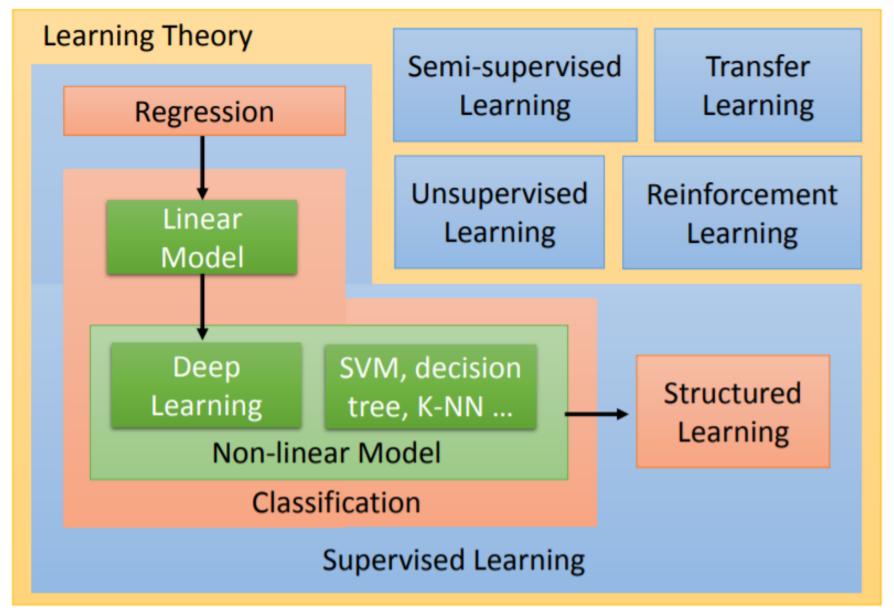
### Data visualization with Python

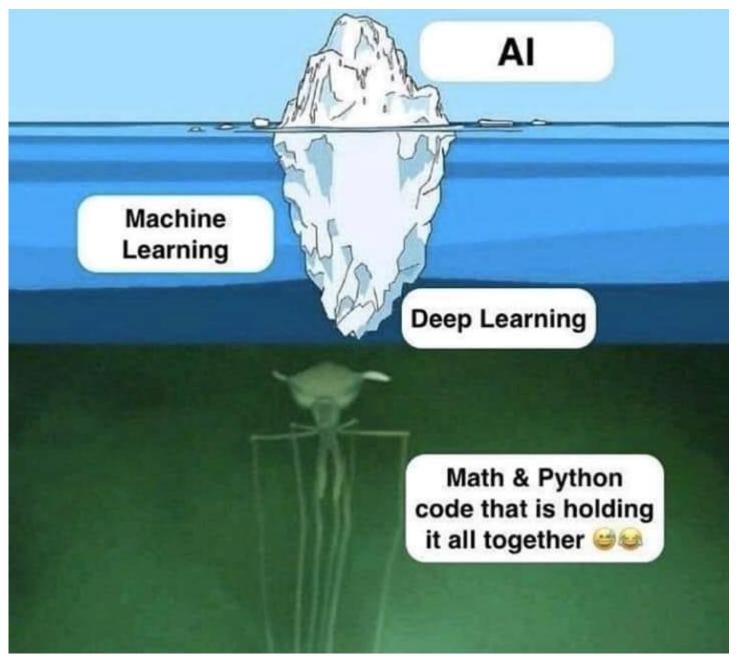


## Practice – Python coding

- 1. Log in to Colab
- 2. Run python code to visualize the motion sensor data file
- 3. Run python code to visualize the 3M TUG data file
- 4. Run python code to visualize the two data files you download from Kaggle

### Al Learning map





Theory is when you know everything, but nothing works.

Practice is when you don't know anything, yet everything works.

In Programming we combine theory and practice; nothing works, and we don't know why.

## Python development tools





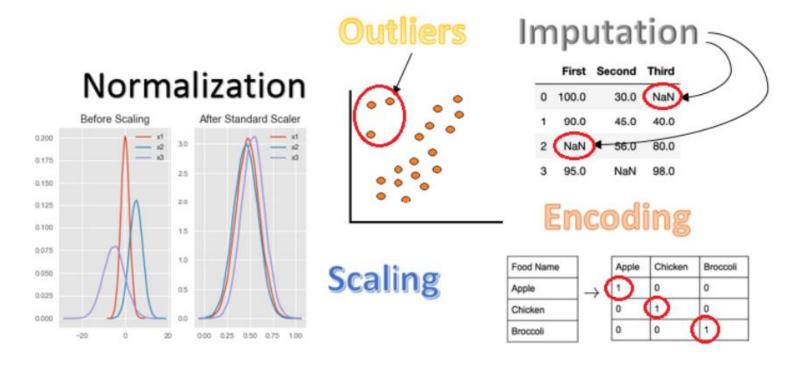




# Data preprocessing

#### Topics to be covered:

- 1. Standardization
- 2. Scaling with sparse data and outliers
- 3. Normalization
- 4. Categorical Encoding
- 5. Imputation



### Data preprocessing in Python

#### Steps involved in data preprocessing:

- 1. Importing the required Libraries
- 2. Importing the data set
- 3. Handling the Missing Data.
- 4. Encoding Categorical Data.
- 5. Splitting the data set into test set and training set.
- 6. Feature Scaling.

https://aaaanchakure.medium.com/data-preprocessing-3cd01eefd438

#### Steps in Data Preprocessing in Machine Learning

- 1. Acquire the dataset
- 2. Import all the crucial libraries
- 3. Import the dataset
- 4. Identifying and handling the missing values
- 5. Encoding the categorical data
- 6. Splitting the dataset
- 7. Feature scaling

https://www.upgrad.com/blog/data-preprocessing-in-machine-learning/

### Why Data Preprocessing?

#### Data in the real world is not clean

- incomplete: lacking attribute values, lacking certain attributes of interest, or containing only aggregate data, e.g., occupation="""
- noisy: containing errors or outliers, e.g., Salary="-10"
- inconsistent: containing discrepancies in codes or names, e.g., Age="42" Birthday="03/07/1997"
- No quality data, no quality mining results!
- Quality decisions must be based on quality data
  - Duplicates or missing data may cause incorrect or misleading analyses.

### **Data Preprocessing: Major Tasks**

#### Data cleaning

 Fill in missing values, smooth noisy data, identify or remove outliers, and resolve inconsistencies

#### Data integration

Integration of multiple databases, data cubes, or files

#### Data transformation

Normalization and aggregation

#### Data reduction

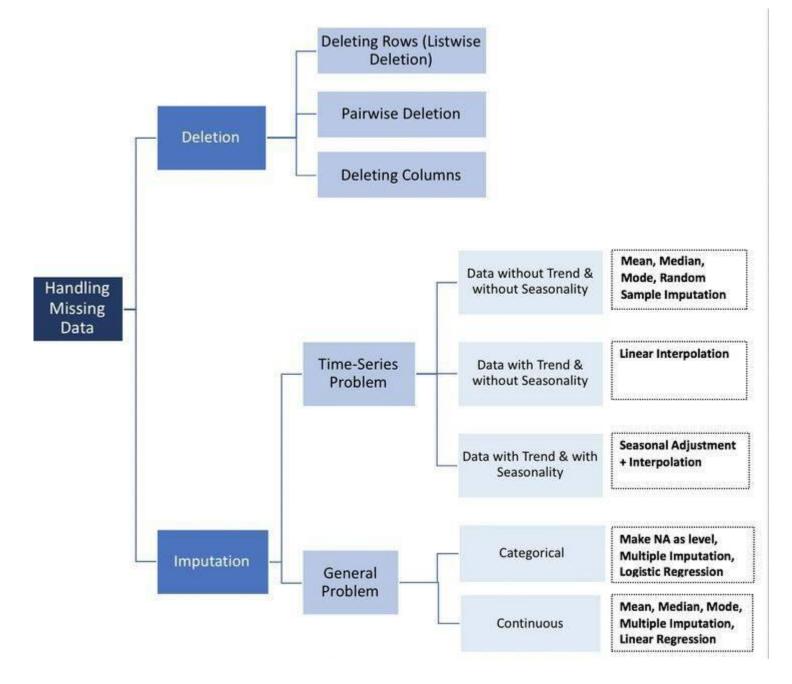
 Obtains reduced representation in volume but produces the same or similar analytical results

#### Data discretization

 Part of data reduction but with particular importance, especially for numerical data

### **Data Cleaning Tasks**

- Fill in missing values
- Identify outliers and smooth out noisy data
- Correct inconsistent data
- Resolve redundancy caused by data integration

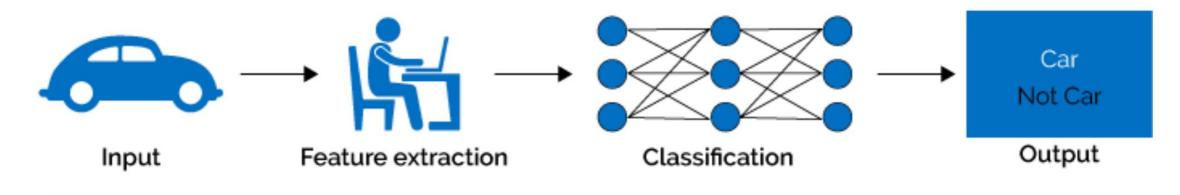


### **Data Transformation**

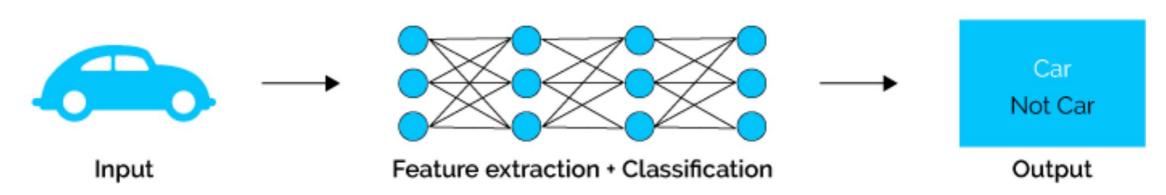
- Smoothing: remove noise from data
- Aggregation: summarization, data cube construction
- Generalization: concept hierarchy climbing
- Normalization: scaled to fall within a small, specified range
  - min-max normalization
  - z-score normalization
  - normalization by decimal scaling
- Attribute/feature construction
  - New attributes constructed from the given ones

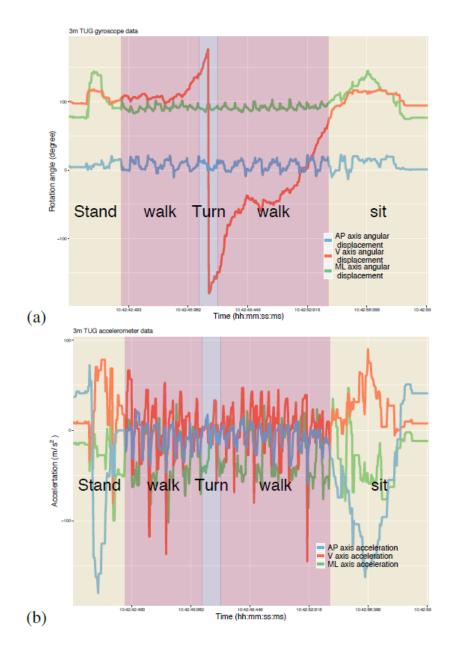
# Feature engineering

### Machine Learning



## Deep Learning





#### TABLE II SUMMARY OF FEATURES

TUG sensor-based features		
Feature name	Direction	Unit
Sit to stand		
Angle range	ML	deg
Acceleration range	V, AP	$m/s^2$
Completion time		S
Walking	-	
Acceleration CV	V, AP, ML	
Acceleration range	V, AP, ML	$m/s^2$
Acceleration median	V, AP, ML	$m/s^2$
Acceleration RMS	V, AP, ML	$m/s^2$
Angular velocity CV	V, AP, ML	
Angular velocity range	V, AP, ML	deg/s
Angular velocity median	V, AP, ML	deg/s
Angular velocity RMS	V, AP, ML	deg/s
Speed		m/s
Turning		·
Acceleration CV	V, AP, ML	
Acceleration range	V, AP, ML	$m/s^2$
Acceleration median	V, AP, ML	$m/s^2$
Acceleration RMS	V, AP, ML	$m/s^2$
Angular velocity CV	V, AP, ML	
	1	

Hsu, Y. C., Zhao, Y., Huang, K. H., Wu, Y. T., Cabrera, J., Sun, T. L., & Tsui, K. L. (2020). A novel approach for fall risk prediction using the inertial sensor data from the timed-up-and-go test in a community setting. IEEE Sensors Journal, 20(16), 9339-9350.

- > Supervised Feature Selection Methods
  - > Wrapper Feature Selection Methods
  - > Filter Feature Selection Methods
  - > Embedded or Intrinsic Feature Selection Methods
- > Feature Selection with Statistical Measures
  - > Univariate Feature Selection
- > Feature Selection Strategies
  - > Selection Method
  - > Transform Variables
- > Which Feature Selection Method is the Best?
- > Feature Selection Implementations
  - > Feature Selection For Regression models
  - Classification Feature Selection