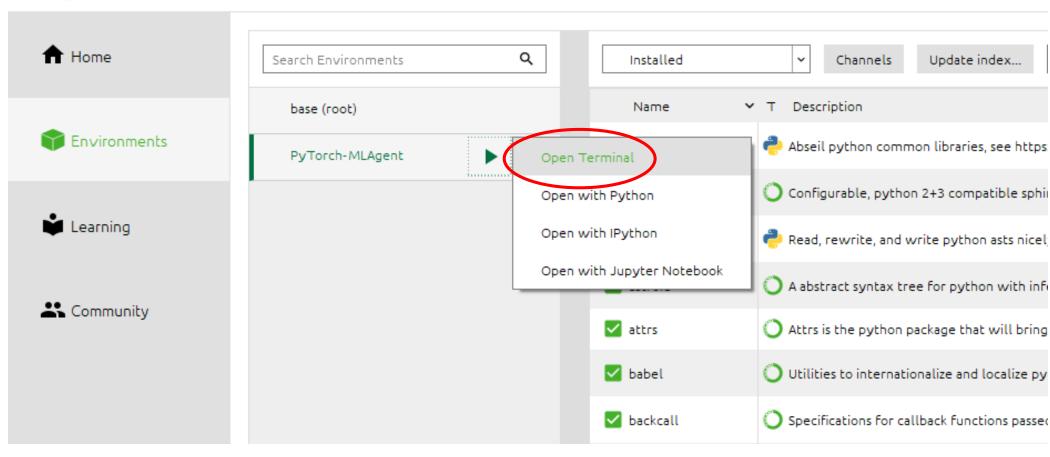
1. Install ML Agent to Anaconda

Anaconda Navigator

File Help

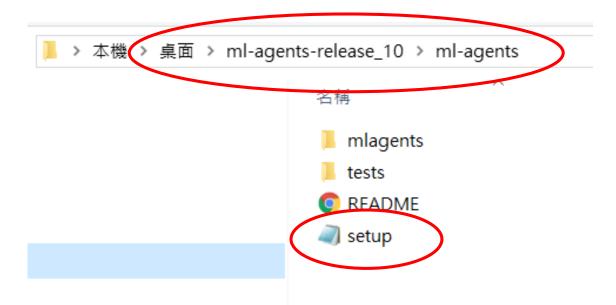
ANACONDA NAVIGATOR



1. Install ML Agent to Anaconda

```
(PyTorch-MLAgent) C:\Users\admin>cd C:\Users\admin\Desktop\ml-agents-release_10\ml-agents
(PyTorch-MLAgent) C:\Users\admin\Desktop\ml-agents-release_10\ml-agents>pip install .

1. cd to the directory where the setup.py is located 2. pip install .
```



1. Install ML Agent to Anaconda

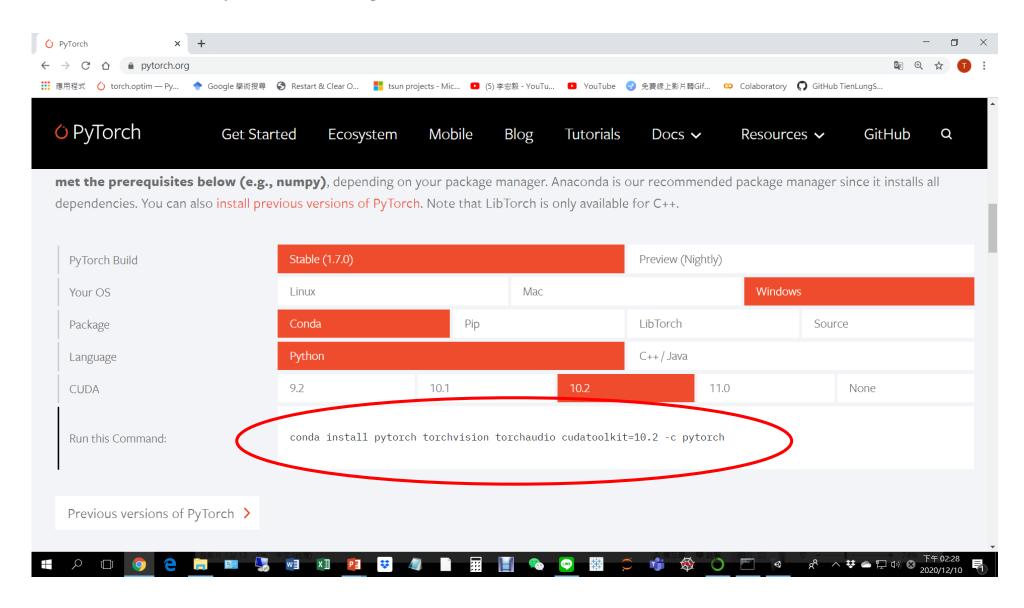
Type "pip freeze" to confirm

```
(PyTorch-MLAgent) C:\Users\admin\Desktop\ml-agents-release_10\ml_agents>pip freeze absl-py==0.9.0 alabaster==0.7.12 astor==0.8.1 astroid==2.4.2 attrs==19.3.0 Babel==2.8.0 backcall==0.1.0 bleach==3.1.1 boto3==1.14.33 botocore==1.17.33 brotlipy==0.7.0 cachetools==4.0.0 cattrs==1.0.0
```

C:\WINDOWS\system32\cmd.exe

```
Keras-Applications==1.0.8
Keras-Preprocessing==1.1.0
keyring==21.2.1
kiwisolver==1.1.0
lazy-object-proxy==1.4.3
xm1 = 4.5.2
Markdown==3.2.1
MarkupSafe==1.1.1
matplotlib==3.1.3
mccabe==0.6.1
mistune==0.8.4
mkl-fft==1.0.15
mkl-random==<del>1.1.0</del>
mki-service==2.3.0
mlagents==0.22.0
mlagents-envs==0.22.0
nbsonvert==5.6.1
nbformat==5.0.4
```

```
toml==0.10.1
torch==1.7.0
torchaudio==0.7.0
torchvision==0.8.1
tornado==6.0.3
tqdm==4.47.0
traitlets==4.3.3
```



```
C:\WINDOWS\system32\cmd.exe - conda install pytorch torchvision torchaudio cudatoolkit=10.2 -c pytorch
 PyTorch-MLAgent) C:\>
(PyTorch-MLAgent) C:\>
PyTorch-MLAgent) C:\>
 PyTorch-MLAgent) C:\>
(PyTorch-MLAgent) C:\>conda install pytorch torchvision torchaudio cudatoolkit=10.2 -c pytorch Collecting package metadata (repodata.json): done
Solving environment: done
==> WARNING: A newer version of conda exists. <==
  current version: 4.8.2
  latest version: 4.9.2
Please update conda by running
    $ conda update -n base -c defaults conda
## Package Plan ##
  environment location: C:\Users\admin\Anaconda3\envs\PyTorch-MLAgent
  added / updated specs:
    - cudatoolkit=10.2
    - pytorch
    - torchaudio
    - torchvision
```

```
C:\WINDOWS\system32\cmd.exe - conda install pytorch torchvision torchaudio cudatoolkit=10.2 -c pytorch
The following NEW packages will be INSTALLED:
                          pkgs/main/win-64::dataclasses-0.7-py36_0
pkgs/main/win-64::libuv-1.40.0-he774522_0
pytorch/win-64::torchaudio-0.7.0-py36
  dataclasses
  1 i buv
  torchaudio
  typing_extensions pkgs/main/noarch::typing_extensions-3.7.4.3-py 0
The following packages will be UPDATED:
  ca-certificates
                                                               2020.6.24-0 --> 2020.12.8-haa95532 0
                                                    2020.6.20-py36_0 --> 2020.12.5-py36haa95532_0 10.1.243-h74a9793_0 --> 10.2.89-h74a9793_1
  certifi
  cudatoolkit
                                        1.1.1g-he774522_1 --> 1.1.1i-h2bbff1b_0
1.4.0-py3.6_cuda101_cudnn7_0 --> 1.7.0-py3.6_cuda102_cudnn7_0
0.5.0-py36_cu101 --> 0.8.1-py36_cu102
  openss1
  pytorch
  torchvision
The following packages will be DOWNGRADED:
                                                        7.6.5-cuda10.1 0 --> 7.6.5-cuda10.2 0
  cudnn
Proceed ([y]/n)? y
Downloading and Extracting Packages
torchaudio-0.7.0
                              2.7~\mathrm{MB}
                                                                                                                                                     100%
torchvision-0.8.1
                              7.2 MB
dataclasses-0.7
                             31 KB
pytorch-1.7.0
                                              ###7
```

2. Prepare training configure file

RL-Mobile-Robot / ReachGoalAvoidObstacles / ழ main ▼ TienLungSun Delete test env.unitypackage 2020.12.19 PPO.unitypackage Add files via upload 2021.4.28 Test scene.unitypackage Add files via upload Car_Agent_s7.cs Add files via upload Car_Agent_s8.cs Add files via upload HW1 Build a training VE in Unity Update HW1 Build a training VE in Unity HW2 ML Agent Update HW2 ML Agent HW3 Train and test ML Agent Update HW3 Train and test ML Agent MobileRobot.yaml Add files via upload ReadMe Update ReadMe

2. Prepare training configure file

```
26 lines (26 sloc) 593 Bytes
       behaviors:
         MobileRobot:
          trainer_type: ppo
  4
           hyperparameters:
            batch size: 2048
            buffer size: 20480
             learning rate: 0.0003
             beta: 0.005
             epsilon: 0.2
             lambd: 0.95
            num_epoch: 3
 11
            learning rate schedule: linear
 13
           network_settings:
             normalize: true
 14
            hidden units: 512
            num_layers: 3
 16
            vis_encode_type: simple
 17
 18
           reward signals:
 19
             extrinsic:
              gamma: 0.995
 21
              strength: 1.0
          keep_checkpoints: 5
 22
           max_steps: 5000000
 23
          time_horizon: 1000
 24
           summary freq: 30000
  25
  26
           threaded: true
```

Copy to a text file and rename the text file as "MobileRobot.yaml"

2. Prepare training configure file

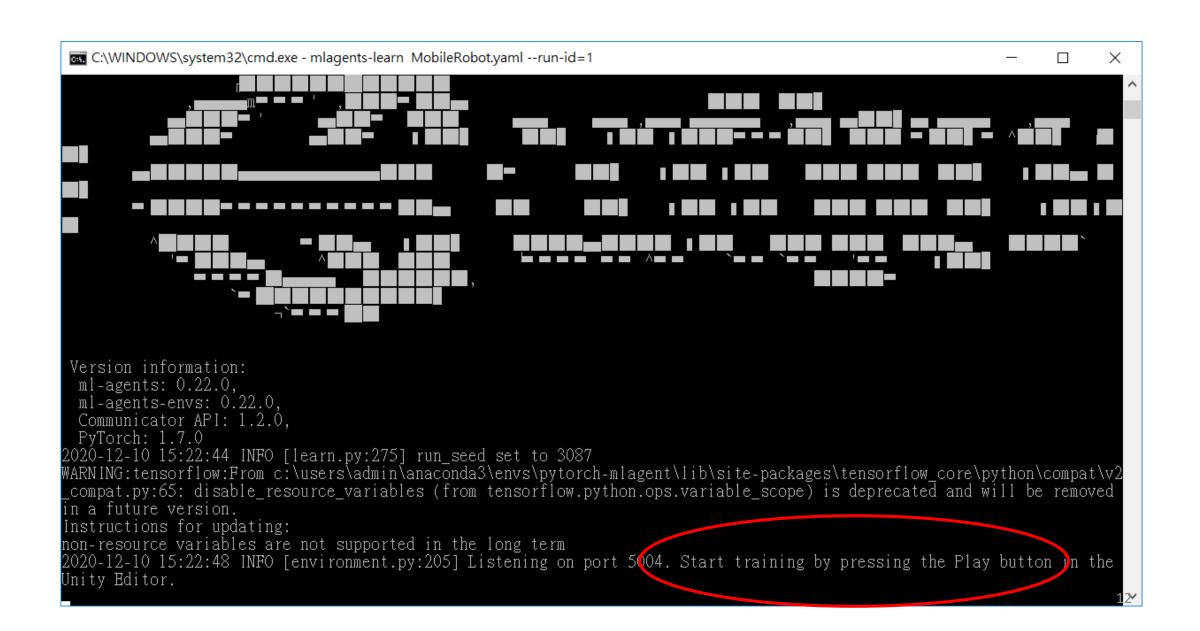
| > 本機 > 桌面 / ml-agents-release_10 > config > ppo | | | |
|---|--------------------------------|------------------------|----------------------|
| 名和 |) | 修改日期 | 類型 |
| A | 3DBall | 2020/11/20 上午 | YAML 檔案 |
| A | 3DBall_randomize | 2020/11/20 上午 | YAML 檔案 |
| A- | 3DBallHard | 2020/11/20 上午 | YAML 檔案 |
| A | Basic | 2020/11/20 上午 | YAML 檔案 |
| A | Bouncer | 2020/11/20 上午 | YAML 檔案 |
| A | CrawlerDynamic | 2020/11/20 上午 | YAML 檔案 |
| A | Crawler Dynamic Variable Speed | 2020/11/20 上午 | YAML 檔案 |
| A | CrawlerStatic | 2020/11/20 上午 | YAML 檔案 |
| A | CrawlerStaticVariableSpeed | 2020/11/20 上午 | YAML 檔案 |
| A | FoodCollector | 2020/11/20 上午 | YAML 檔案 |
| A | GridFoodCollector | 2020/11/20 上午 | YAML 檔案 |
| A | GridWorld | 2020/11/20 上午 | YAML 檔案 |
| A | Hallway | 2020/11/20 上午 | YAML 檔案 |
| A | Match3 | 4 - l- :l - D - l- | |
| | MobileRobot Place N | /IODIIEKOD | ot.yaml" to ML agent |
| A | PushBlock foldor/c | onfig/ppg | |
| A | Pyramids 1010e1/C | onfig/ppc |) |
| A- | PyramidsRND | 2020/11/20 上午 | YAML 檔案 |
| A | Reacher | 2020/11/20 上午 | YAML 檔案 |
| A- | SoccerTwos | 2020/11/20 上午 | YAML 檔案 |

3. Start train

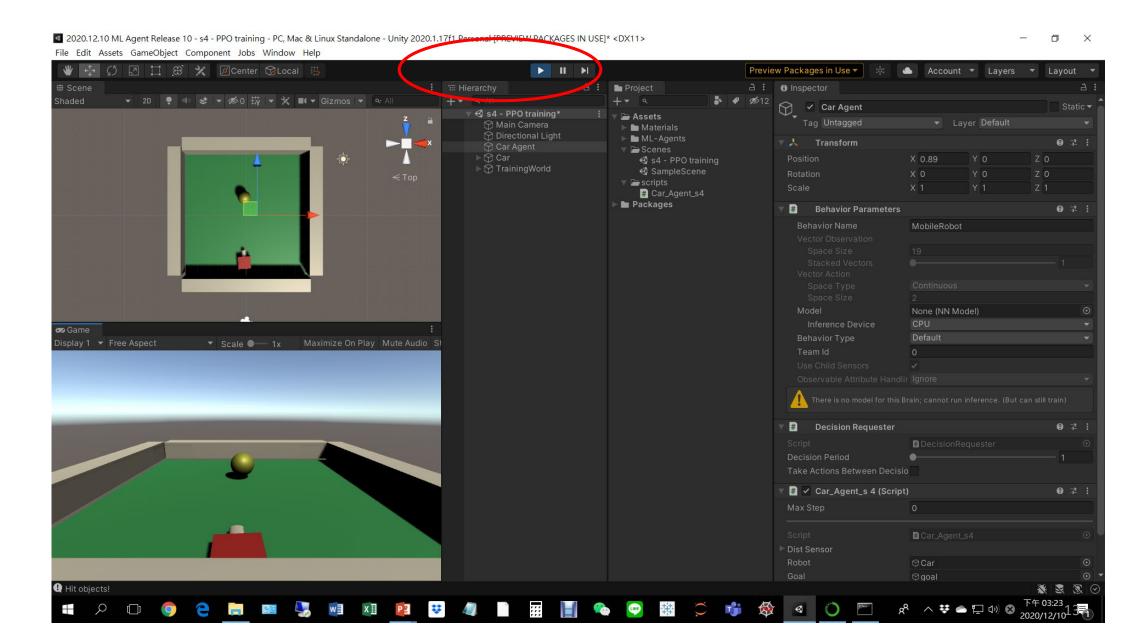
- 1. cd C:\...\ml-agents-release_10\config\ppo (the folder of your configuration file)
- 2. mlagents-learn MobilRobot.yaml --run-id=1 --force

```
C:\WINDOWS\system32\cmd.exe
(PyTorch-MLAgent) C:\>
(PyTorch-MLAgent) C:\>cd C:\Users\admin\Desktop\ml-agents-release 10\config\ppo
(PyTorch-MLAgent) C:\Users\admin\Desktop\ml-agents-release 10\config\ppo>mlagents-learn MobileRobot.yaml -run-id=1
```

3. Start train



3. Start train

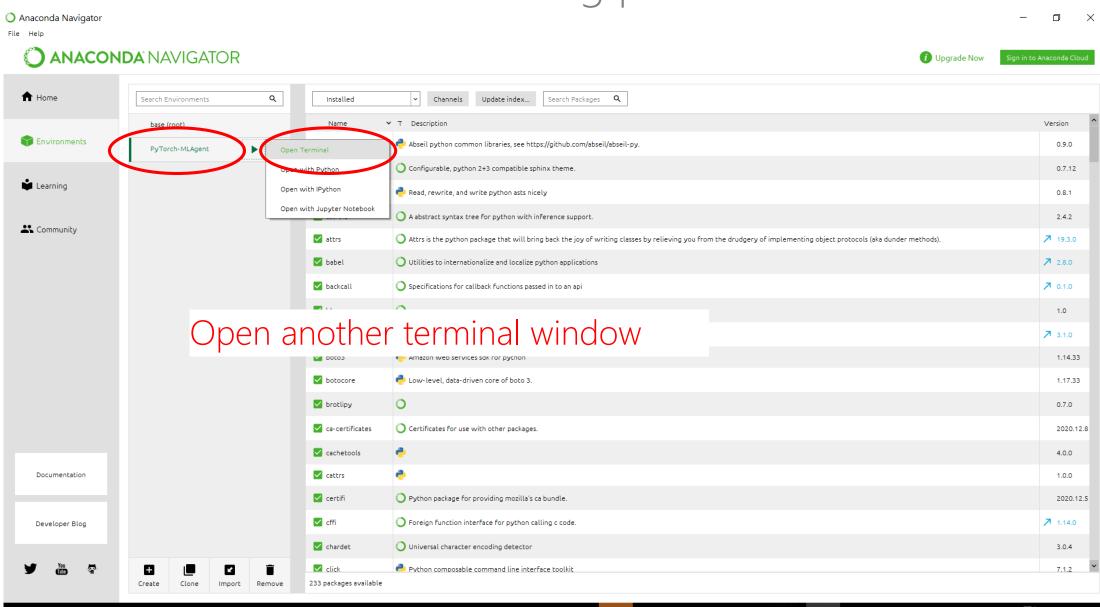


(You might need to download MS VC redistributable)

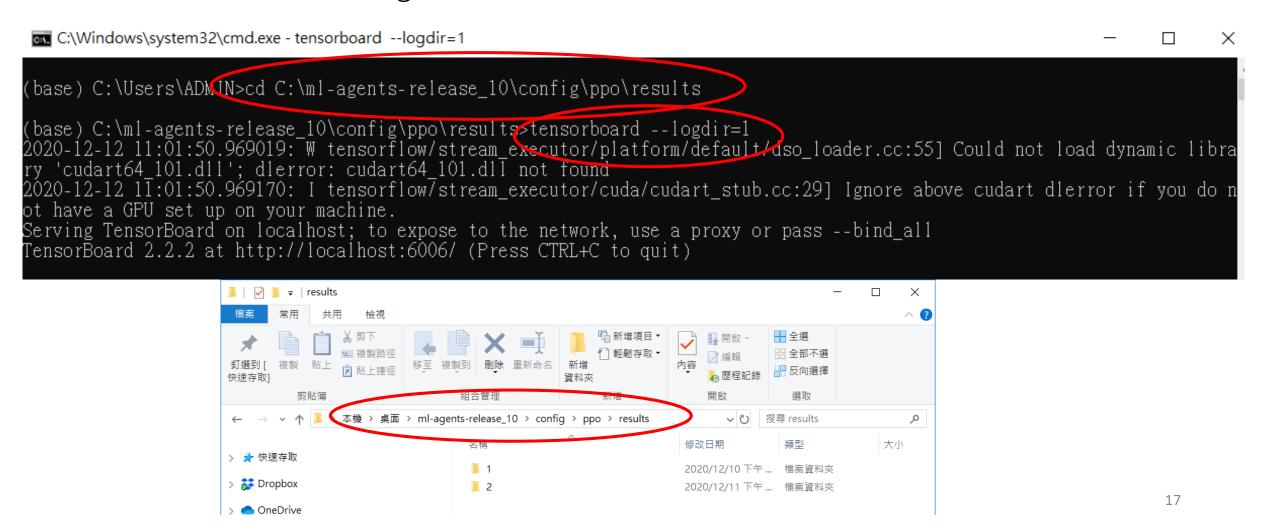
```
C:\WINDOWS\system32\cmd.exe
                                                                                                                                                ×
(PyTorch-MLAgent) C:\Users\admin>cd C:\Users\admin\Dockton\ml agents release 10\config\ppo
(Tylorch-MLAgent) C:\Users\admin\Desktop\ml-agents-release_10\config\ppo>mlagents-learn MobileRobot.yami run-id=1
Microsoft Visual C++ Redistributable is not installed, this may lead to the DLL load failure.
                    It can be downloaded at https://aka.ms/vs/16/release/vc_redist.x64.exe
Traceback (most recent call last):
File "c:\users\aumin\anacendo3\envg\nytorch-mlagent\lib\runny ny", line 193, in _run_module_as_main
     "__main__", mod_spec)
  File "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\runpy.py", line 85, in _run_code
    exec(code, run globals)
  File "C:\Users\admin\Anaconda3\envs\PyTorch-MLAgent\Scripts\mlagents-learn.exe\__main__.py", line 4, in <module>
File "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\site-packages\mlagents\trainers\learn.py", line 2, in <module>
    from mlagents import torch utils
  File "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\site-packages\mlagents\torch_utils\__init__.py", line 1, in <m
odule>
     from mlagents.torch_utils.torch import torch as torch # noqa
  File "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\site-packages\mlagents\torch utils\torch.py", line 29, in <mod
ule>
     import torch # noga I201
  File "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\site-packages\torch\__init__.py", line 128, in <module>
     raise err
OSError: [WinError 126] 找不到指定的模組。 Error loading "c:\users\admin\anaconda3\envs\pytorch-mlagent\lib\site-package
s\torch\lib\asmjit.dll" or one of its dependencies.
(PyTorch-MLAgent) C:\Users\admin\Desktop\ml-agents-release 10\config\ppo>
```

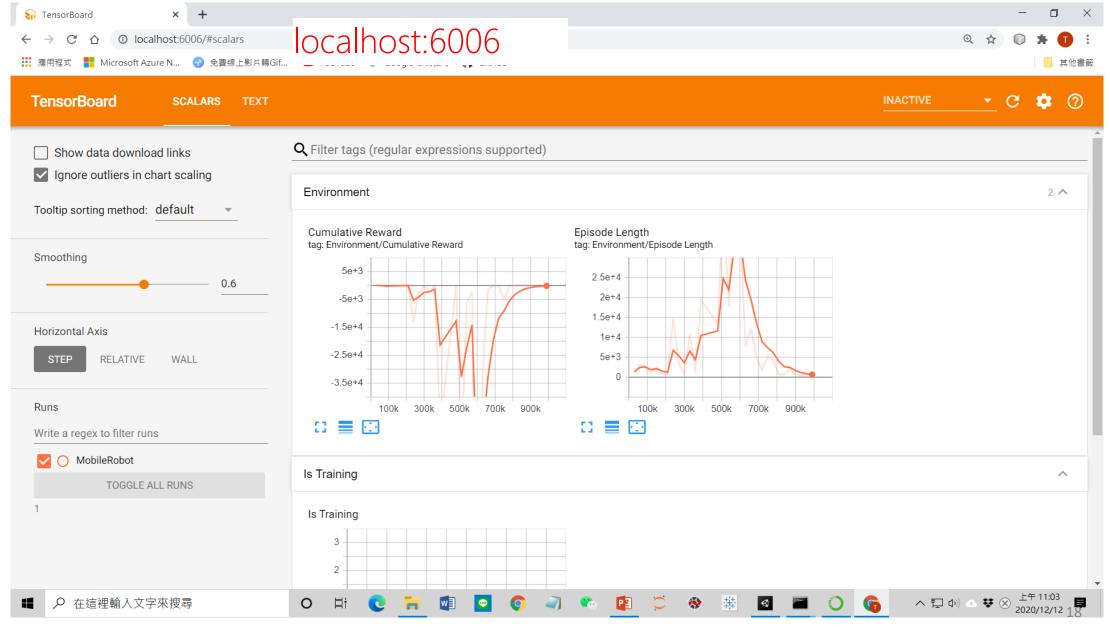
4. Training

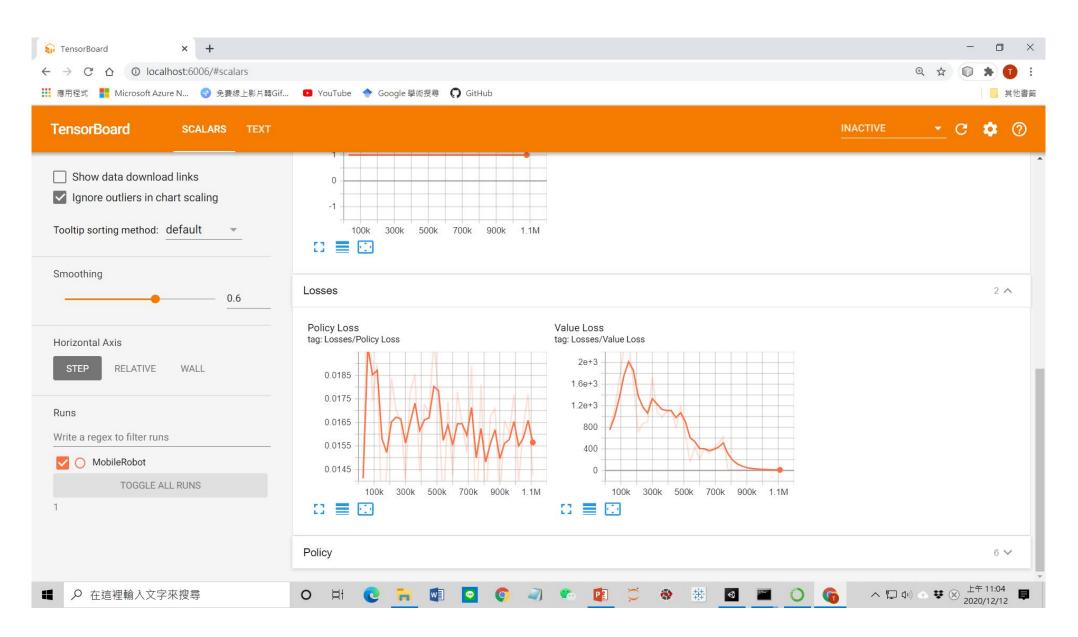
```
C:\Windows\system32\cmd.exe - mlagents-learn MobileRobot.yaml --run-id=2
                                                                                                                      X
          beta: 0.005
          epsilon:
                        0.2
                        0.95
          lambd:
                                                                                       vis encode type: simple
          num epoch:
          learning rate schedule:
                                         linear
                                                                                      reward signals:
        network_settings:
          normalize:
                        True
                                                                                       extrinsic:
          hidden_units: 512
                                                                                         gamma: 0.995
          num layers:
          vis encode type:
                                 simple
                                                                                         strength: 1.0
         memory:
                        None
        reward signals:
                                                                                      keep checkpoints: 5
          extrinsic:
                                                                                      max_steps: 7000000
                        0.995
            gamma:
            strength:
                        1.0
                                                                                      time horizon: 1000
        init path:
                        None
        keep checkpoints:
                                                                                      summary_freq: 30000
                                 500000
        checkpoint interval:
                                                                                      threaded: true
                        7000000
                        1000
        time horizon:
       summary_freq:
threaded:
                        30000
        self play:
                        None
        behavioral cloning:
                                None
                        pytorch
        framework:
2020–12–12 11:39:12 INFO [stats.py:139] MobileRobot. Step: 30000. 🖊ime Elapsed: 56.278 s. No episode was completed since
last summary. Training.
2020–12–12 11:39:49 INFO [stats.py:139] MobileRobot. Step: 60000. Time Elapsed: 93.340 s. Mean Reward: -14.130. Std of Re
ward: 10.538. Training.
```



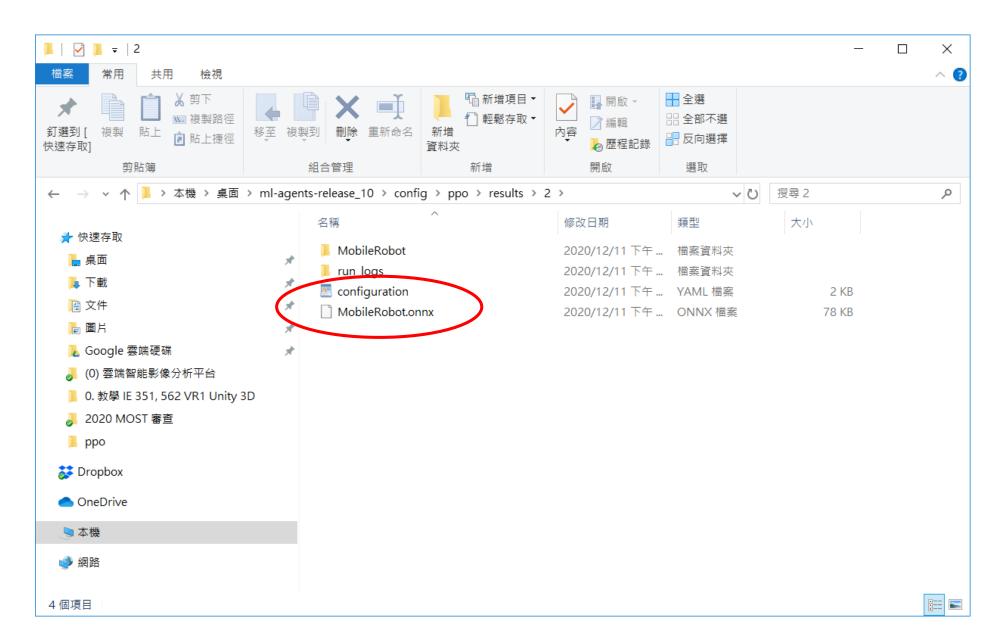
- 1. cd C:\ml-agents-release-10\config\ppo\results (The results folder)
- 2. tensorboard --logdir=1



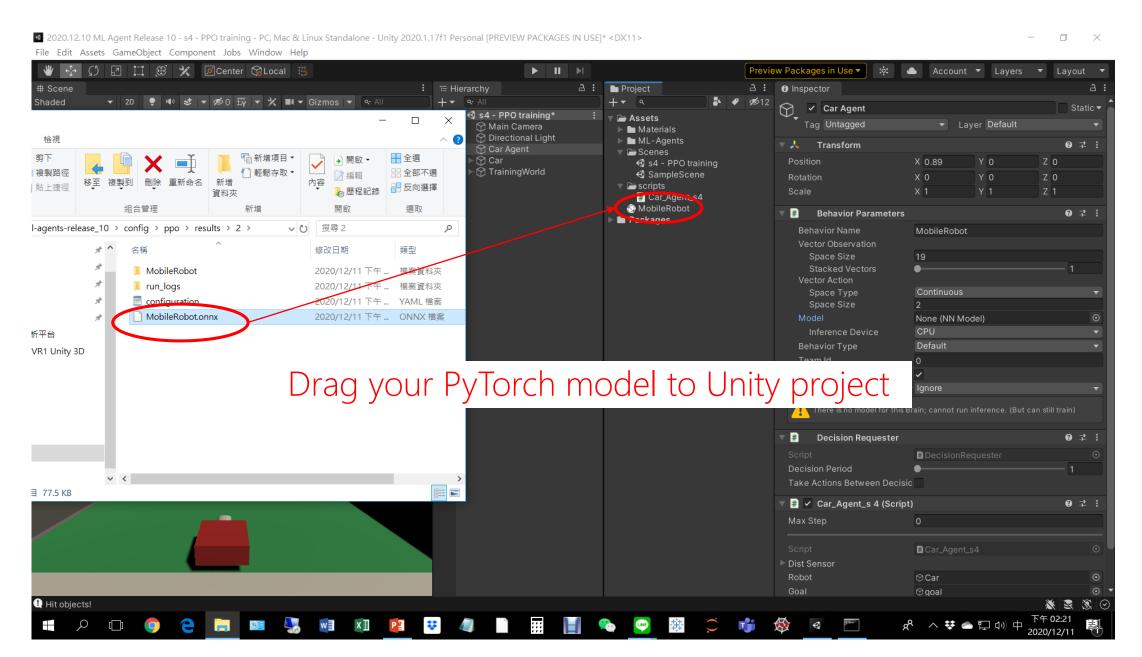




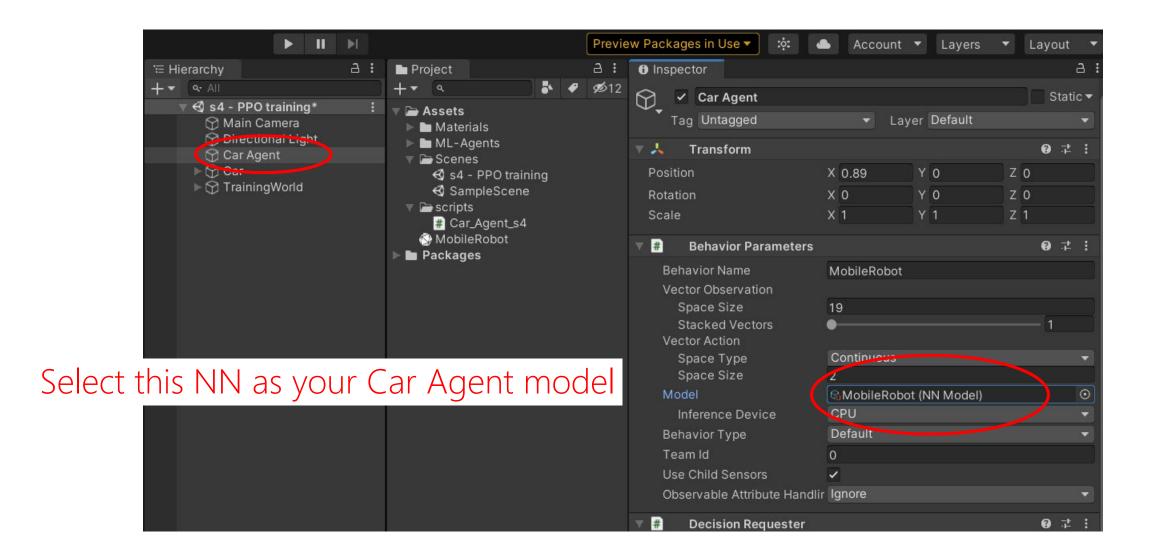
6. Finish training



7. Test



7. Test



7. Test

