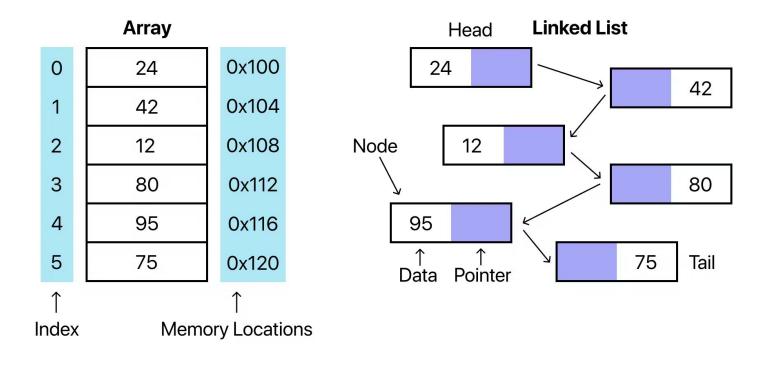
Heap (Priority Queue) & Heap Sort

CSE-215
Data Structure & Algorithm II

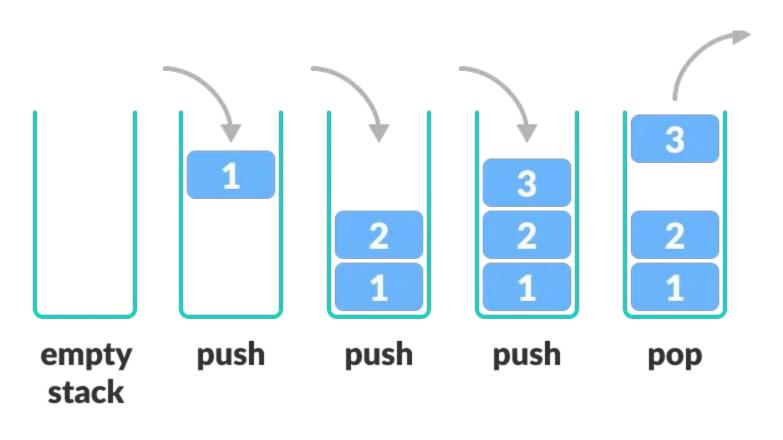
Linked List

• Linked list is a fundamental data structure in computer science. It mainly allows efficient insertion and deletion operations compared to arrays.



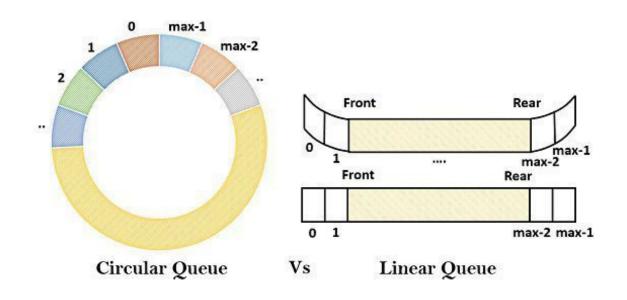
Stack

• Stack is a linear data structure that follows a particular order (LIFO or Last In First Out) in which the operations are performed.



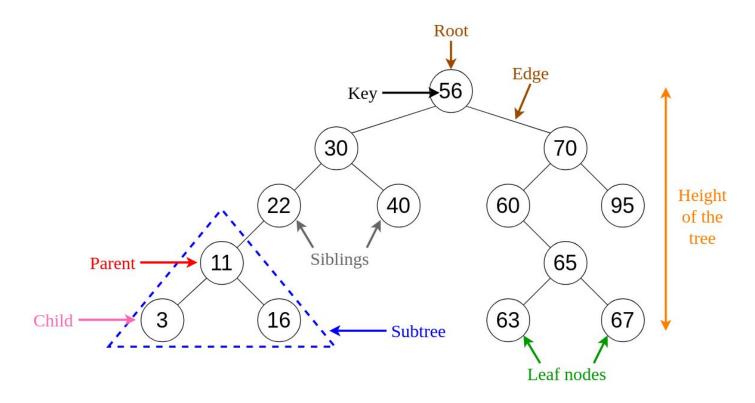
Queue

• Queue is a linear data structure that follows a particular order (FIFO or Fast In First Out) in which the operations are performed.



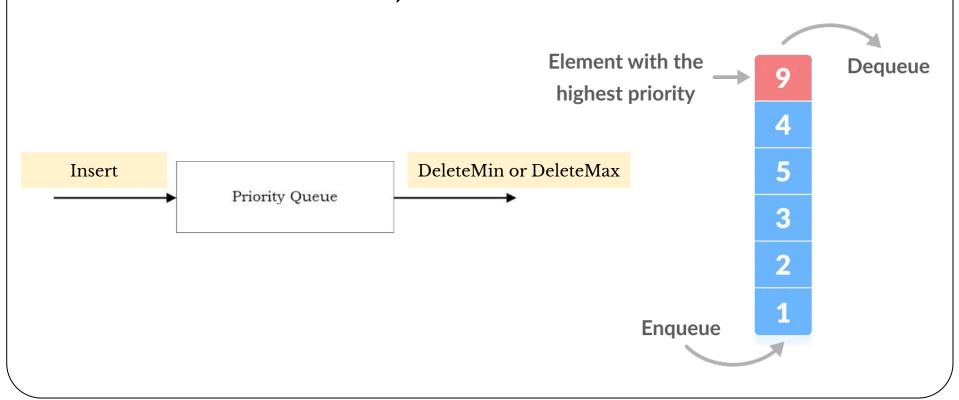
Binary Search Tree

• Binary Search Tree is a binary tree that additionally satisfies the binary search property. The number of elements to compare decreases every time the search progresses.



Priority Queue

• Priority Queue is a data structure that supports the operations Insert and DeleteMin (which returns and removes the minimum element) or DeleteMax (which returns and removes the maximum element).



Priority Queue: Main Operations

- A priority queue is a container of elements, each having an associated key.
 - Insert (key, data): Inserts data with key to the priority queue. Elements are ordered based on key.
 - <u>DeleteMin/DeleteMax:</u> Remove and return the element with the smallest/largest key.
 - GetMinimum/GetMaximum: Return the element with the smallest/largest key without deleting it.
 - Increase-Key (data, newkey): Increases the value of data's key to the newkey.

Comparing Implementations

Comparison based on the operations:

Implementation	Insertion	Deletion (DeleteMin)	Find Min
Unordered array	1	n	n
Unordered list	1	n	n
Ordered array	n	1	1
Ordered list	n	1	1
Binary Search Trees	logn (average)	logn (average)	logn (average)
Balanced Binary Search Trees	logn	logn	logn

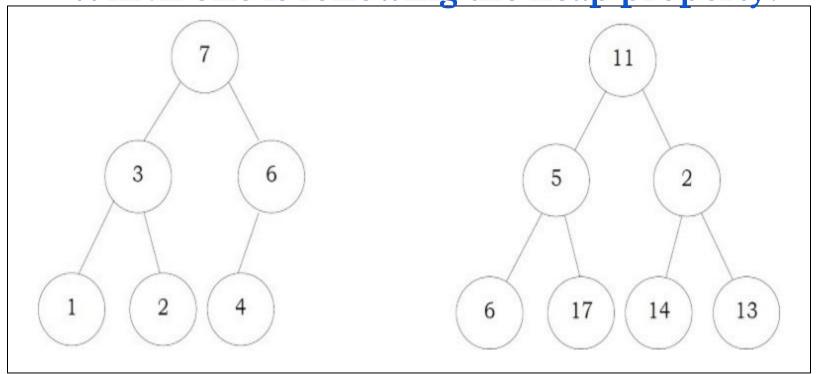
Comparing Implementations

Comparison based on the operations:

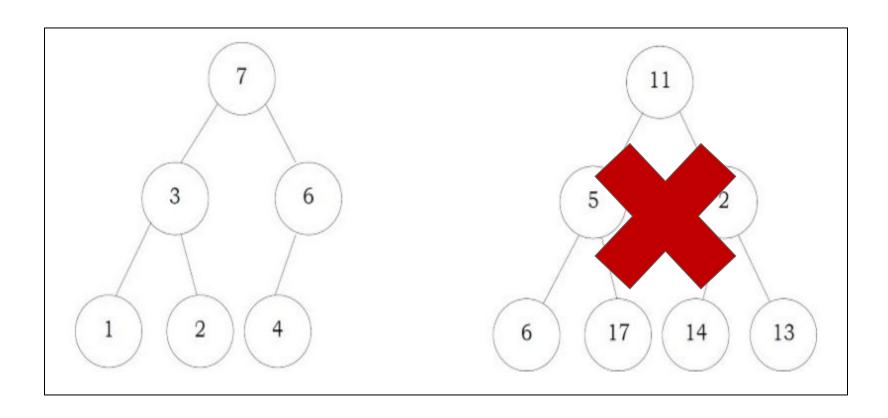
Implementation	Insertion	Deletion (DeleteMin)	Find Min
Unordered array	1	n	n
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Ordered array	n	1	1
Ordered list	n	1	1
Binary Search Trees	logn (average)	logn (average)	logn (average)
Balanced Binary Search Trees	logn	logn	logn
Binary Heaps	logn	logn	1

• Heap Property: The basic requirement of a heap is that the value of a node must be \geq (or \leq) than the values of its children.

Which one is following the heap property?

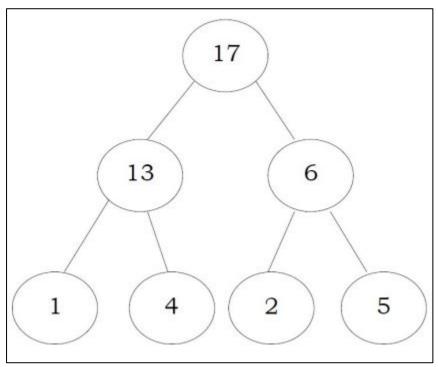


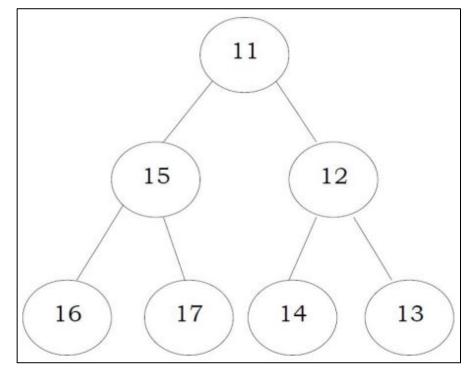
• Heap Property: The basic requirement of a heap is that the value of a node must be \geq (or \leq) than the values of its children.



Types of Heaps:

- Min heap: The value of a node must be less than or equal to the values of its children
- Max heap: The value of a node must be greater than or equal to the values of its children

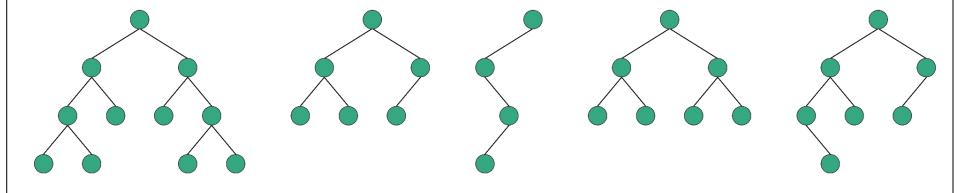




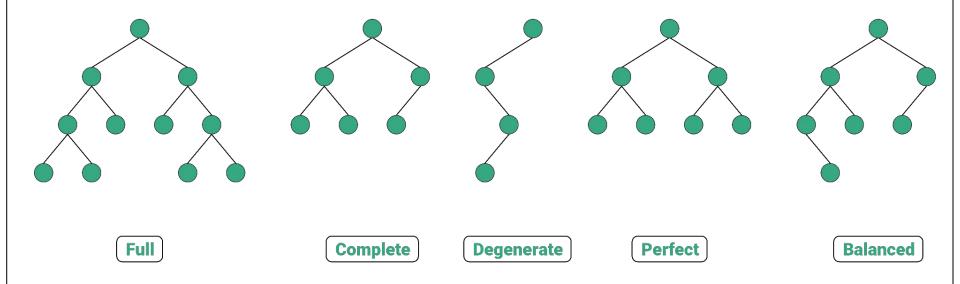
Max Heap

Min Heap

• Complete Binary Tree: Heap has the additional property that all leaves should be at h or h – 1 levels (where h is the height of the tree).



• Complete Binary Tree: Heap has the additional property that all leaves should be at h or h-1 levels (where h is the height of the tree).



^{*}A complete binary tree is a binary tree in which every level, except possibly the last, is completely filled, and all nodes in the last level are as far left as possible.

- Representing Heaps: One possibility is using arrays. Since heaps are forming complete binary trees, there will not be any wastage of locations.
- Why Heap can be represent using an Array but BST can not?
- To represent a complete binary tree as an array:
 - The root node is A[1]
 - The root stores the largest/smallest value (key)
 - Node i is A[i]
 - The parent of node i is A[i/2]
 - The left child of node i is A[2i]
 - The right child of node i is A[2i + 1]

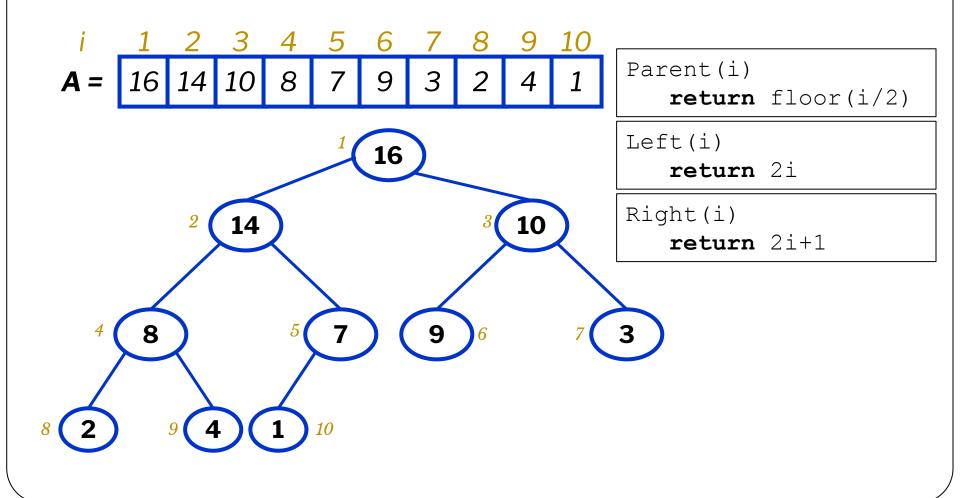
Draw the tree (*Complete Binary Tree) where

```
Parent(i)
return floor(i/2)

Left(i)
return 2i

Right(i)
return 2i+1
```

• Represent the complete binary tree as an array:



- Heap Property (Representing using an array)
 - Max-Heaps satisfy the heap property:

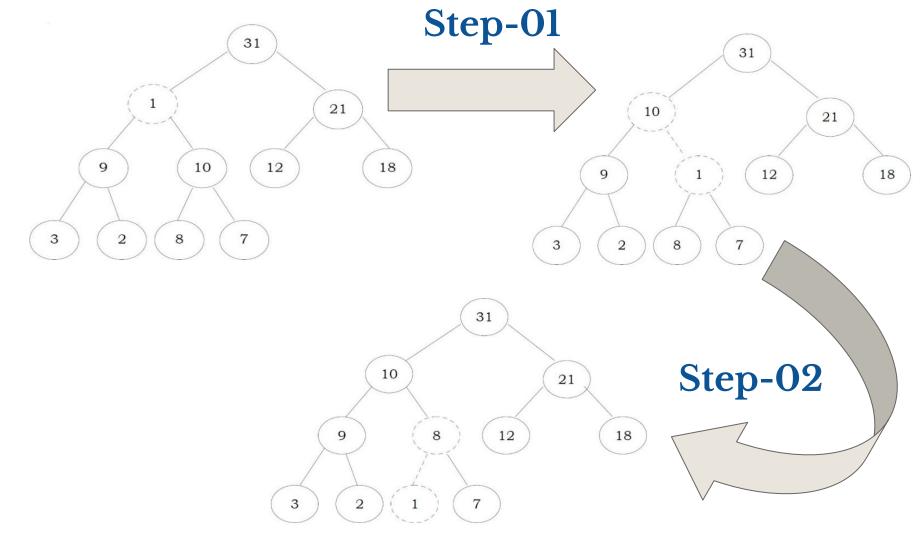
```
A[Parent(i)] \ge A[i] for all nodes i > 1
```

- In other words, the value of a node is at most the value of its parent
- The largest element is stored at the index 1 or root
- Min-Heaps satisfy the heap property:

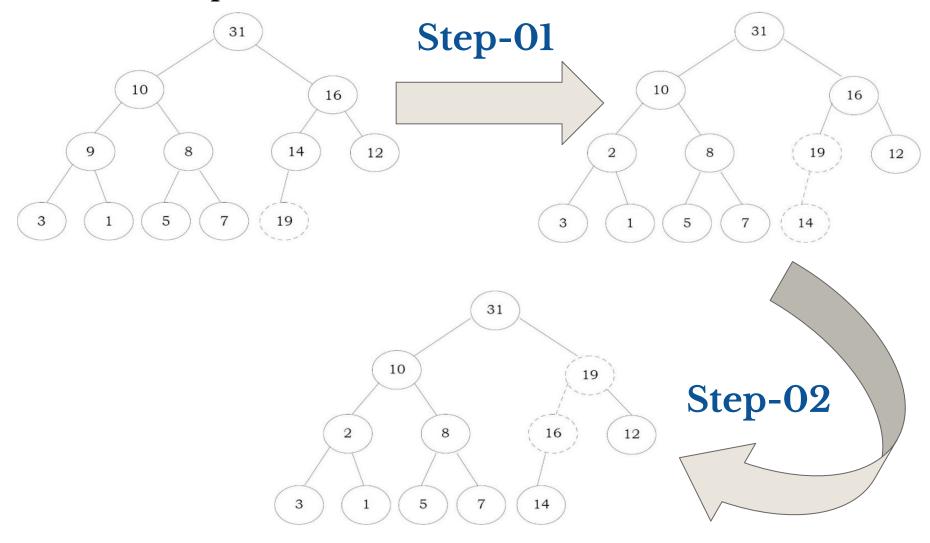
```
A[Parent(i)] \le A[i] for all nodes i > 1
```

- In other words, the value of a node is at least the value of its parent
- The smallest element is stored at the index 1 or root

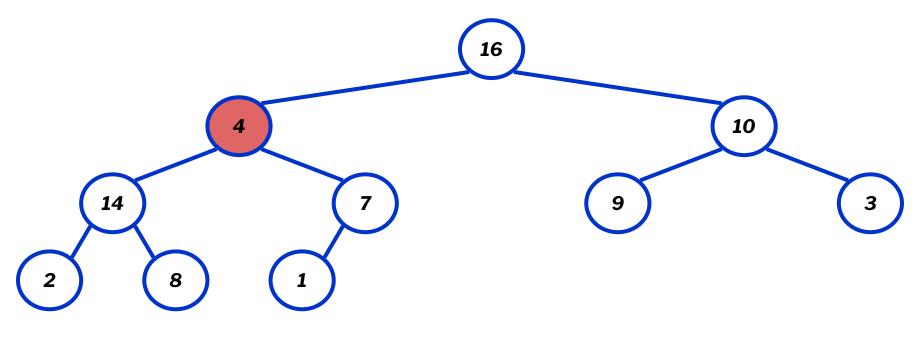
- Heapifying an Element (maintain the heap property)
 - After inserting an element into heap or deleting the root (minimum/ maximum) from heap, it may not satisfy the heap property.
 - In that case we need to adjust the locations of the heap to make it heap again. This process is called heapifying.
 - PercolateDown: Compare Parent and Children towards Leaf
 - PercolateUp: Compare Parent and Children towards Root
 - Time Complexity:
 - Height of the tree (*Complete Binary Tree) = O(logn)

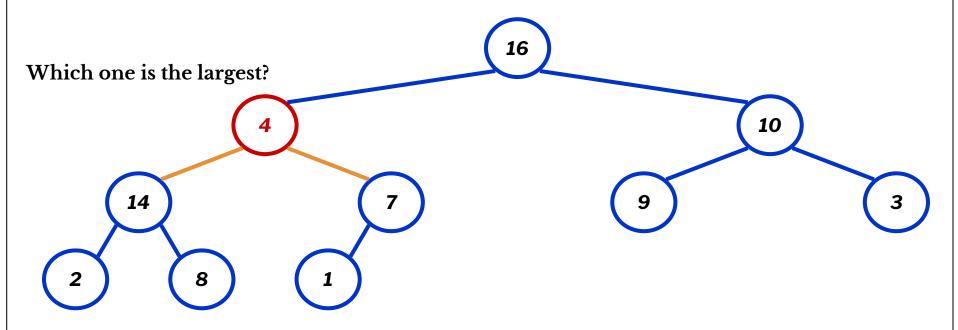


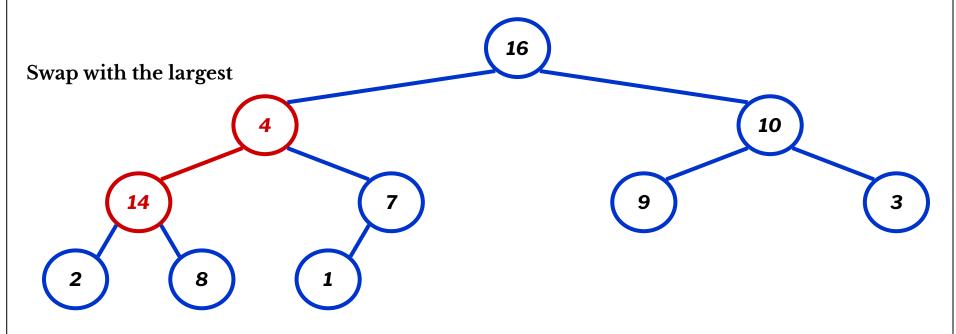
PercolateUp

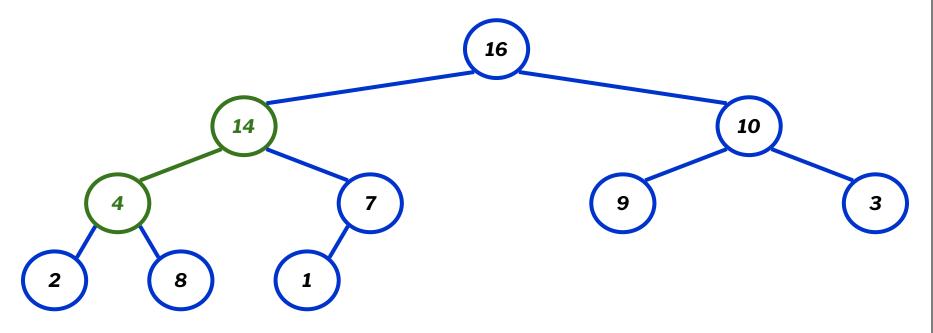


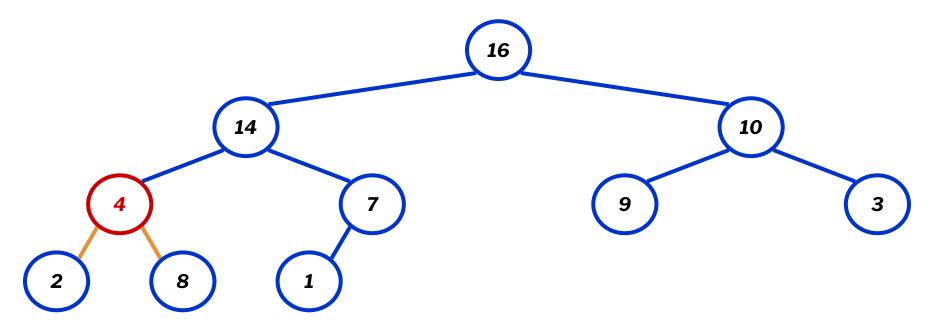
• PercolateDown the value at index 2 (4)

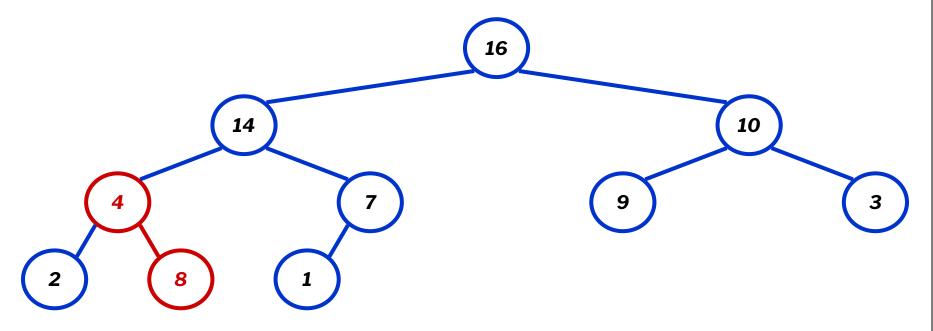


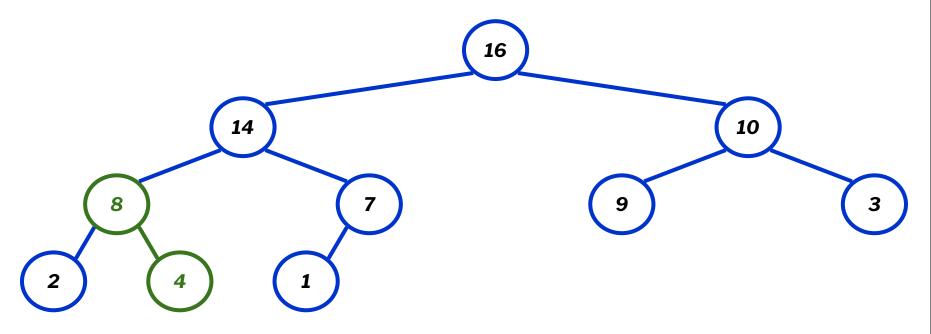


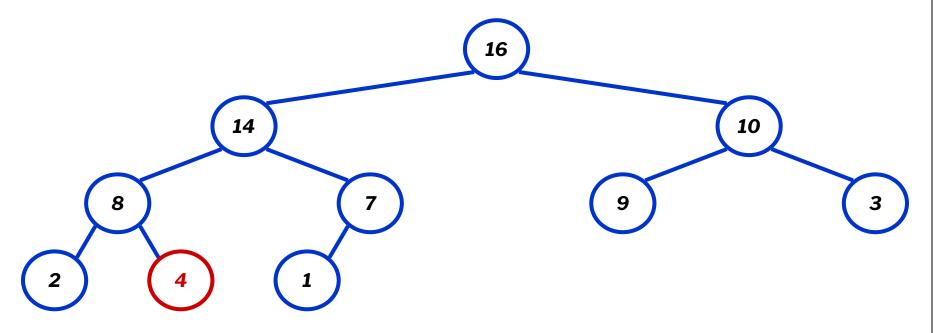


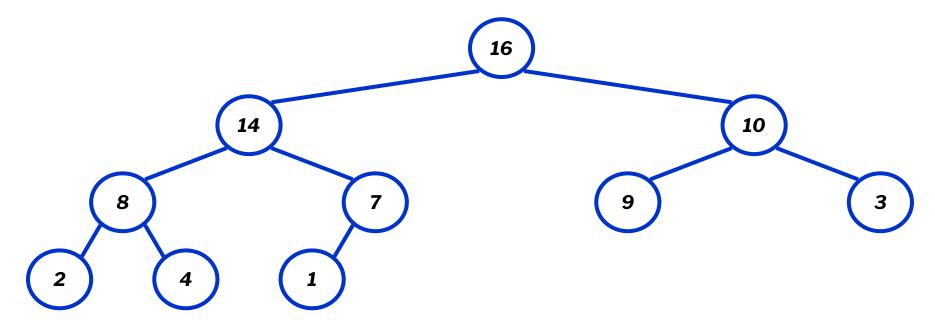












PercolateDown

Assume that the binary trees rooted at LEFT(i) and RIGHT(i) are already max-heaps.

```
PercolateDown (A, i)
     l \leftarrow \text{LEFT}(i)
 2 r \leftarrow RIGHT(i)
 3 if l \le heap\text{-}size[A] and A[l] > A[i]
         then largest \leftarrow l
         else largest \leftarrow i
     if r \leq heap\text{-size}[A] and A[r] > A[largest]
         then largest \leftarrow r
     if largest \neq i
         then exchange A[i] \leftrightarrow A[largest]
10
               PercolateDown (A, largest)
```

Binary Heaps: DeleteMax/ DeleteMin

- Steps:
 - Copy the first element into some variable
 - Copy the last element into first element location
 - Reduce the heap size
 - PercolateDown the first element

```
DeleteMax (A)

1 if heap-size[A] < 1

2 then error "heap underflow"

3 max \leftarrow A[1]

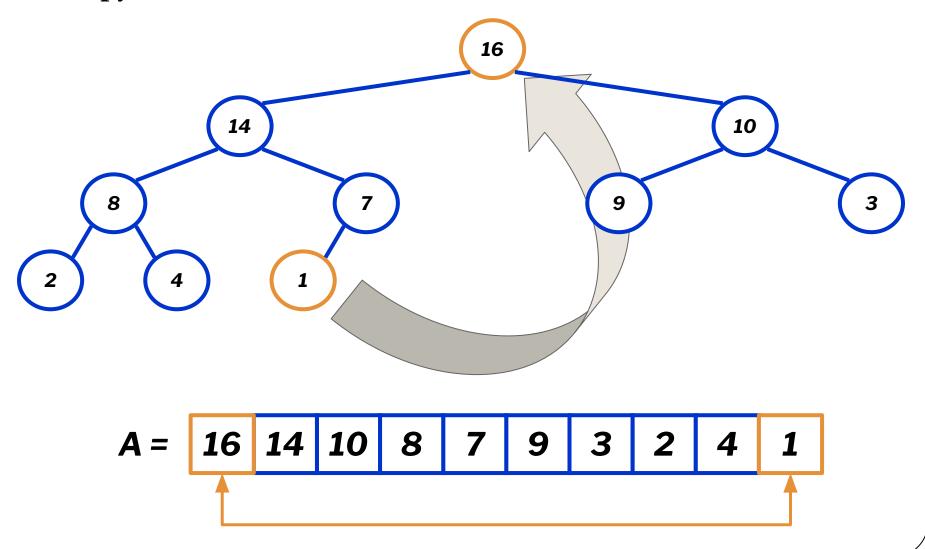
4 A[1] \leftarrow A[heap-size[A]]

5 heap-size[A] \leftarrow heap-size[A] - 1

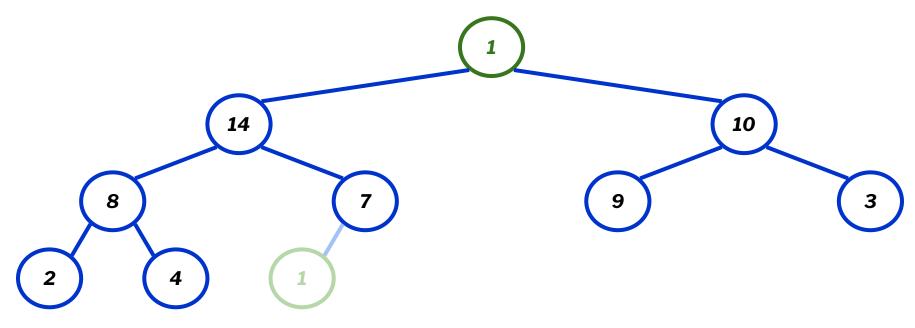
6 PercolateDown (A, 1)

7 return max
```

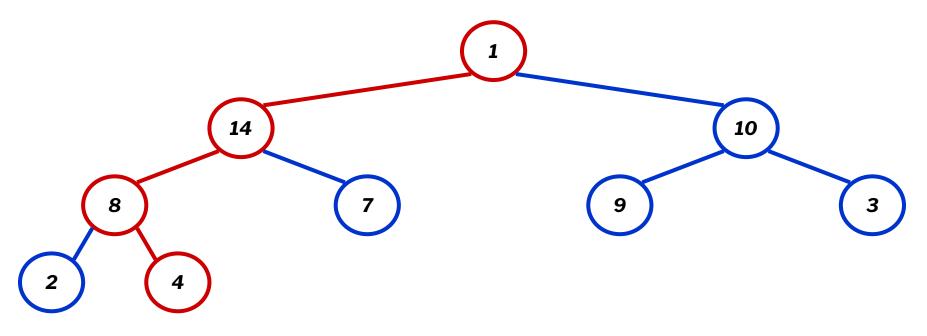
Copy the last element into first element location



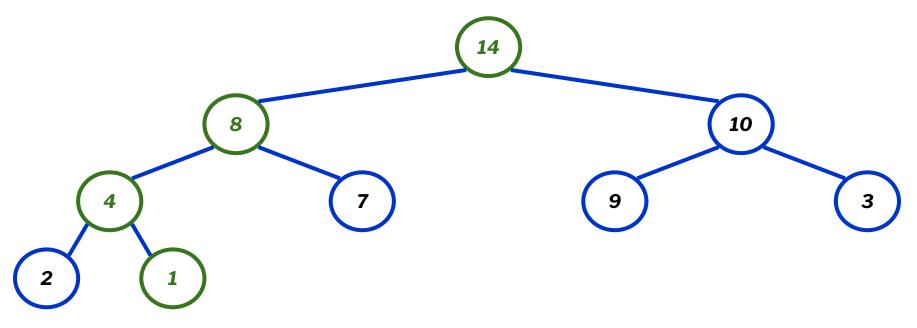
Reduce the heap size



• PercolateDown the first element



Satisfy the Heap property



Binary Heaps: Increase Key

- Steps:
 - Update the value/ key
 - PercolateUp the first element

```
HEAP-INCREASE-KEY(A, i, key)

1 if key < A[i]

2 then error "new key is smaller than current key"

3 A[i] \leftarrow key

4 while i > 1 and A[PARENT(i)] < A[i]

5 do exchange A[i] \leftrightarrow A[PARENT(i)]

6 i \leftarrow PARENT(i)
```



Binary Heaps: Increase Key

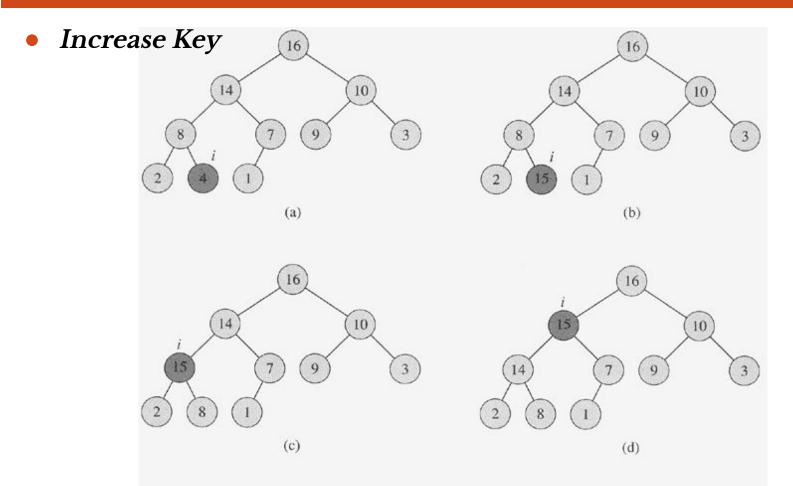


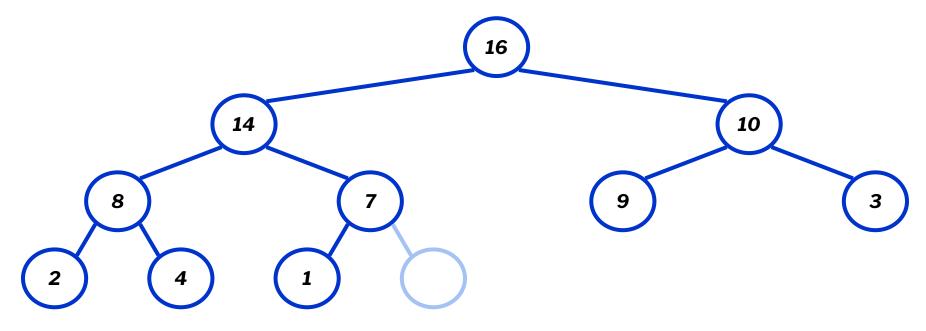
Figure 6.5 The operation of HEAP-INCREASE-KEY. (a) The max-heap of Figure 6.4(a) with a node whose index is i heavily shaded. (b) This node has its key increased to 15. (c) After one iteration of the while loop of lines 4–6, the node and its parent have exchanged keys, and the index i moves up to the parent. (d) The max-heap after one more iteration of the while loop. At this point, $A[PARENT(i)] \ge A[i]$. The max-heap property now holds and the procedure terminates.

- Steps:
 - Increase the heap size
 - Keep the new element at the end of the heap (tree)
 - PercolateUp the new element from bottom to top (root)

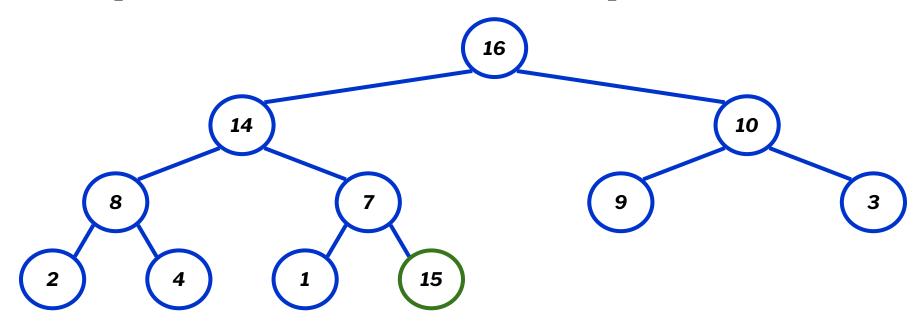
MAX-HEAP-INSERT(A, key)

- 1 heap-size $[A] \leftarrow heap$ -size[A] + 1
- 2 $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY (A, heap-size[A], key)

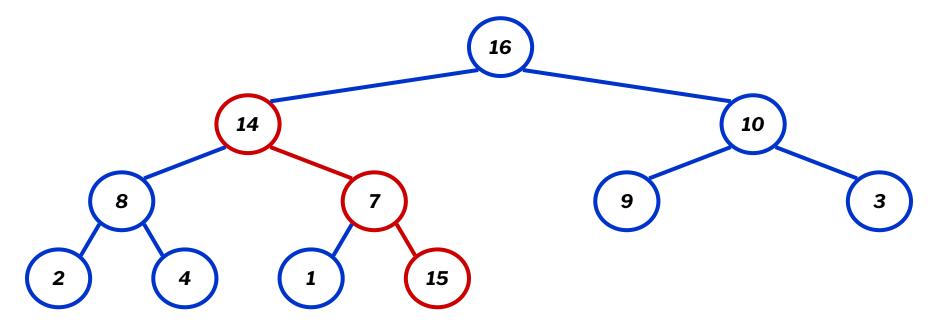
• Increase the heap size



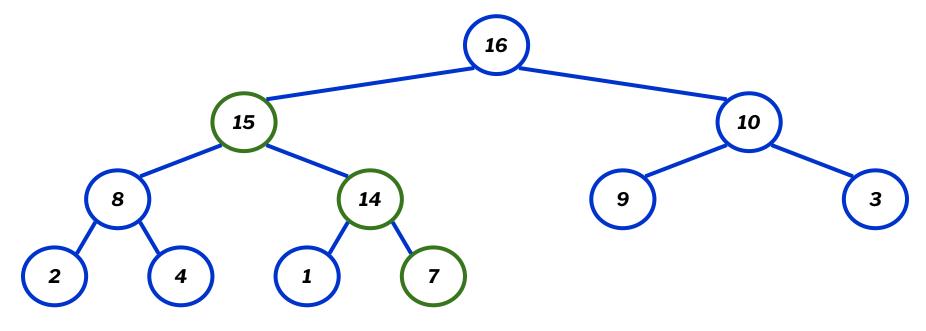
Keep the new element at the end of the heap (tree)



PercolateDown



• Satisfy the Heap property



- Steps:
 - Walk backwards through the array from n/2 to 1, calling *PercolateDown* on each node.
- *Order of processing guarantees that the children of node i are heaps when i is processed.

```
BUILD-MAX-HEAP(A)

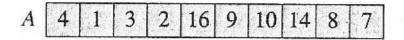
1 heap-size[A] \leftarrow length[A]

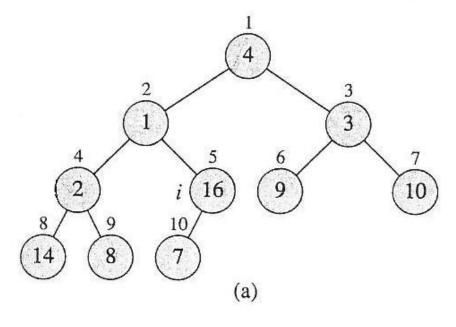
2 for i \leftarrow \lfloor length[A]/2 \rfloor downto 1

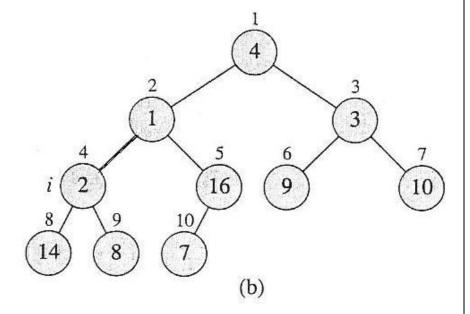
3 do PercolateDown (A, i)
```

Converts an unorganized array A into a max-heap.

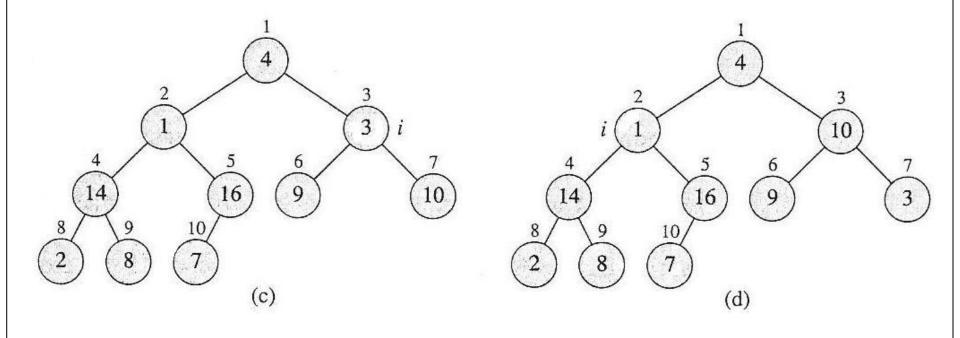
- Work through example:
 - A = {4, 1, 3, 2, 16, 9, 10, 14, 8, 7}



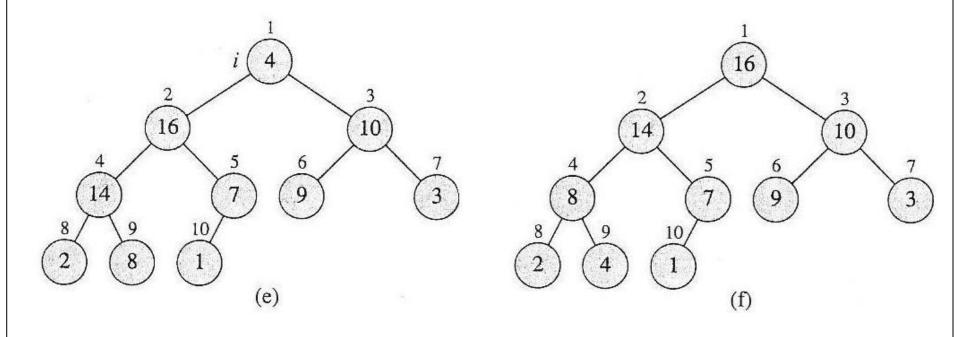




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 - A = {4, 1, 3, 2, 16, 9, 10, 14, 8, 7}



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 - A = {4, 1, 3, 2, 16, 9, 10, 14, 8, 7}



- Show that the height of a heap with n elements is logn.
 - A heap is a complete binary tree.
 - All the levels, except the lowest, are completely full.
 - A heap has at least 2^h elements ((if the lowest level has just 1 element and all the other levels are complete)
 - A heap has at most elements $2^{h+1} 1$.
 - Hence, $2^h \le n \le 2^{h+1} 1$
 - This implies, $h \le logn \le h + 1$.
 - Since h is an integer, h = logn.

- Analyzing BuildHeap
 - Each call to PercolateDown takes O(log n) time
 - There are O(n) such calls (specifically, [n/2])
 - Thus the running time is O(n log n)
 - Is this a correct asymptotic upper bound?
 - Is this an asymptotically tight bound?
 - A tighter bound is O(n)
 - How can this be? Is there a flaw in the above reasoning?

- Prove that, for a complete binary tree of height h the sum of the height of all nodes is O(n - h)
 - A complete binary tree has 2i nodes on level i.
 - \circ A node on level i has depth i and height h i.
 - Let us assume that S denotes the sum of the heights of all these nodes and S can be calculated as:

$$S = \sum_{i=0}^{h} 2^{i}(h-i)$$

$$S = h + 2(h-1) + 4(h-2) + \dots + 2^{h-1}$$

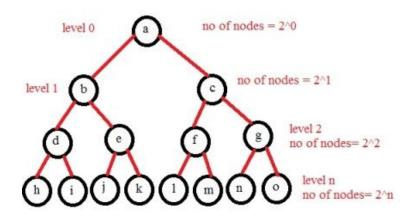
$$2S = 2h + 4(h-1) + 8(h-2) + \dots + 2h$$

$$2S - S = -h + 2 + 4 + \dots + 2h$$

$$\Rightarrow S = (2^{h+1} - 1) - (h-1)$$

$$\Rightarrow S = (2^{h+1} - 1) - (h-1) = n - (h-1) = n - h + 1$$

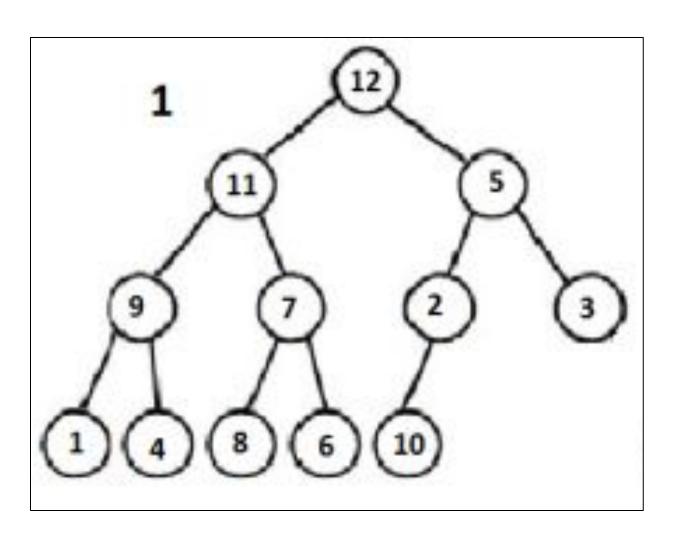
$$\Rightarrow O(n-h)$$

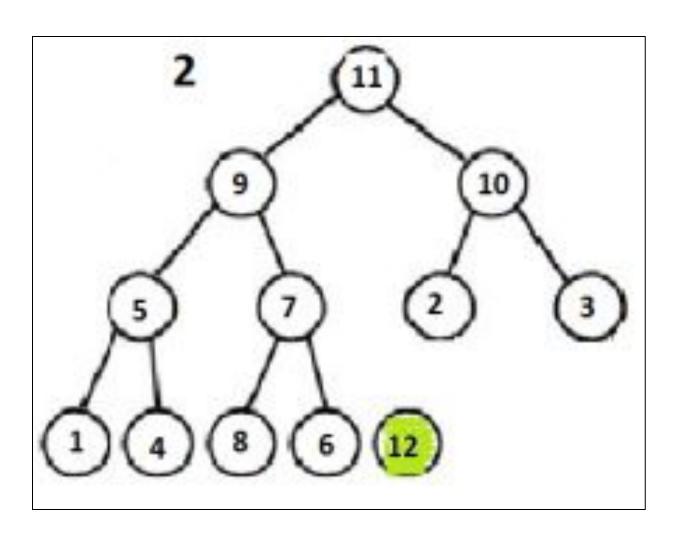


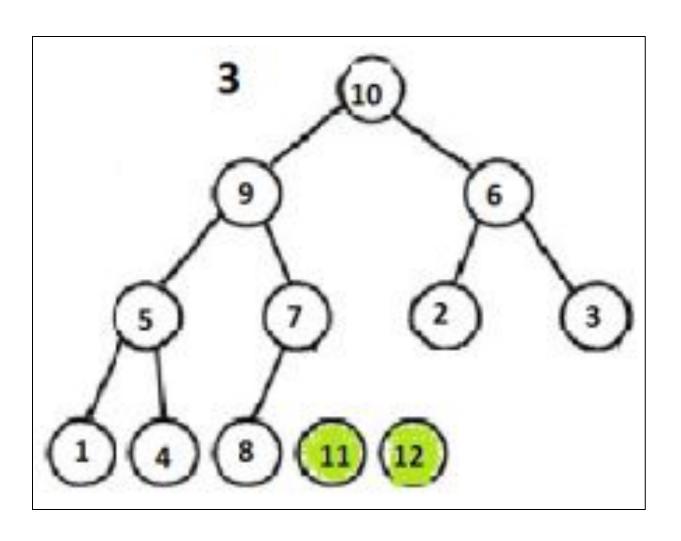
- Time Complexity:
 - The linear time bound of building heap can be shown by computing the sum of the heights of all the nodes.
 - For a complete binary tree of height h containing $n = 2^{h+l} 1$ nodes, the sum of the heights of the nodes is $n h 1 = n \log n 1$
 - That means, building the heap operation can be done in linear time (O(n)) by applying a *PercolateDown* function to the nodes in reverse level order.

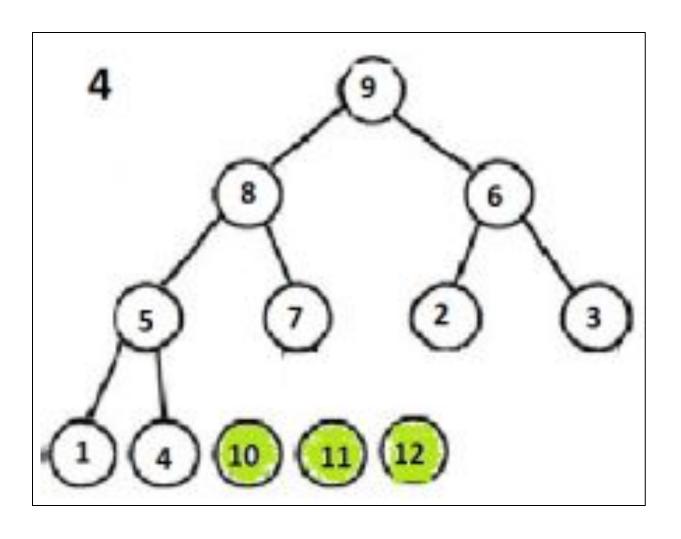
- Steps:
 - Maximum element is at A[1]
 - Discard by swapping with element at A[n]
 - Decrement heap_size[A]
 - \blacksquare A[n] now contains maximum
- Restore heap property at A[1] by calling Heapify [PercolateDown]
- Repeat, always swapping A[1] for A[heap size(A)]

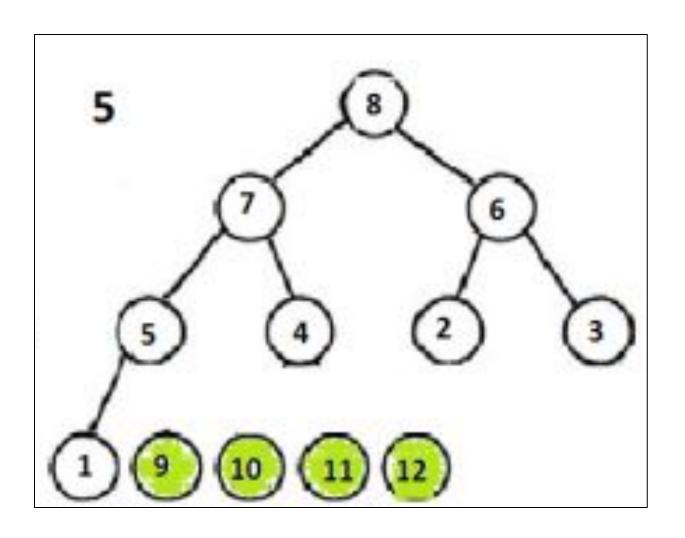
```
Heapsort(A) {
    BuildHeap(A)
    for i <- length(A) downto 2 {
       exchange A[1] <-> A[i]
       heapsize <- heapsize -1
       Heapify(A, 1)
}</pre>
```

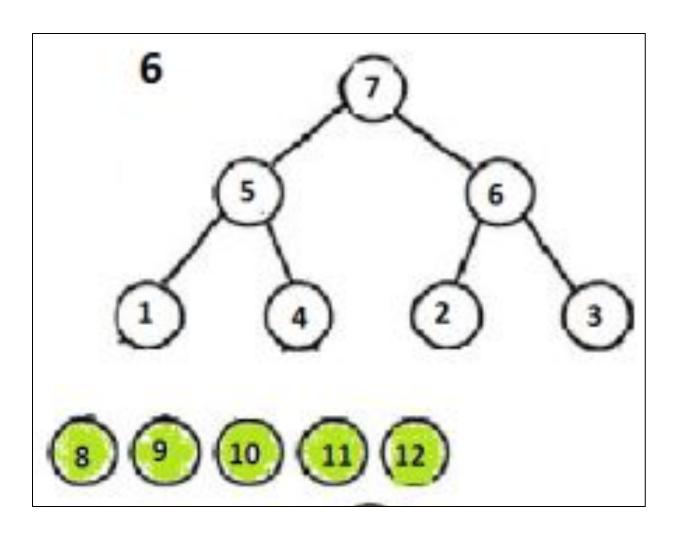


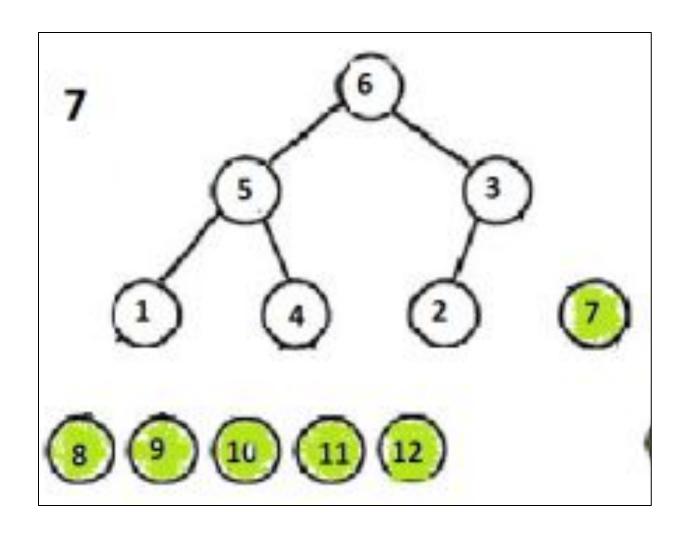


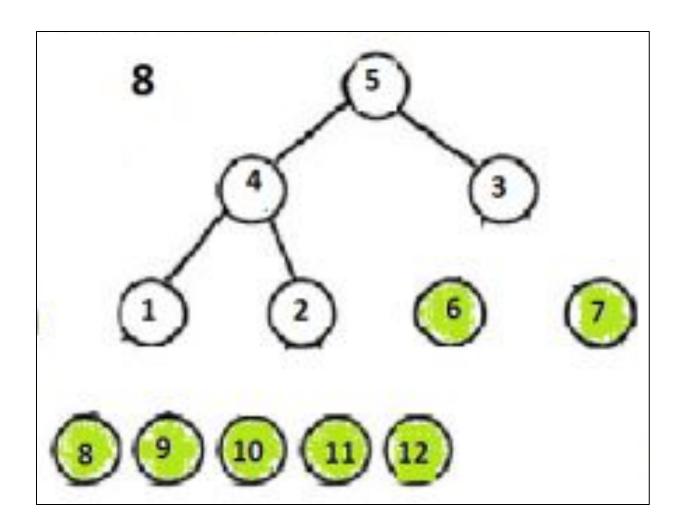


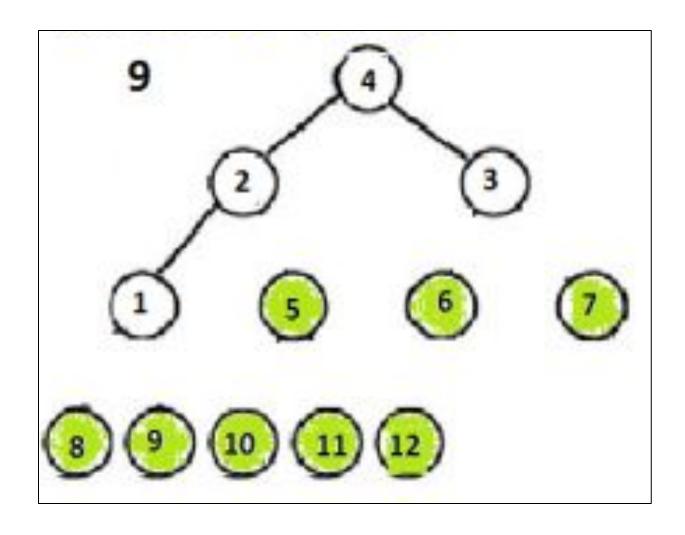


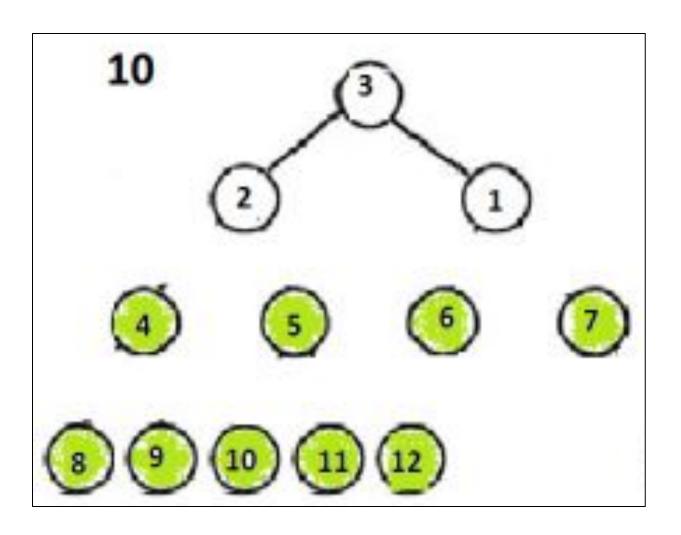


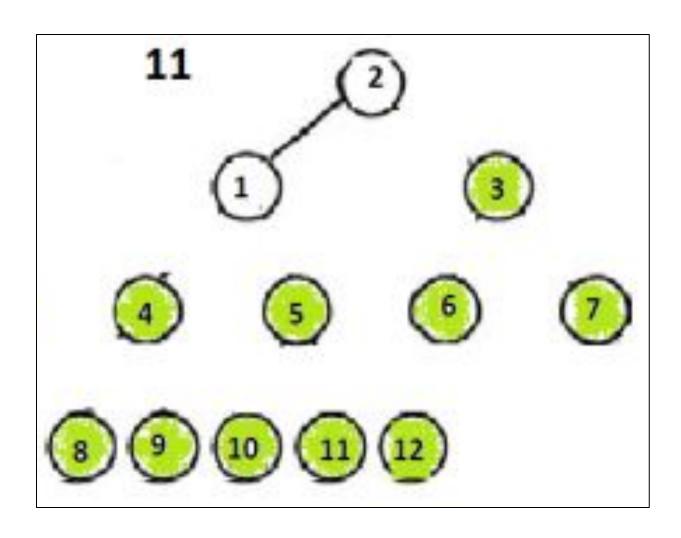


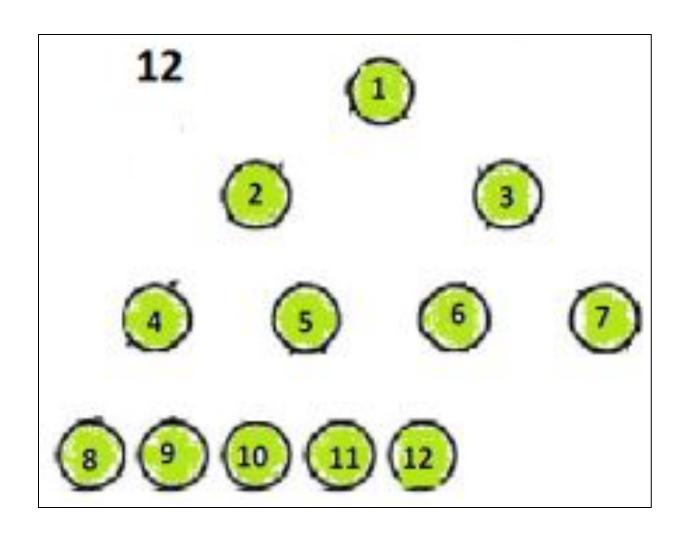












- Analyzing Heap Sort:
 - The call to BuildHeap() takes O(n) time
 - \circ Each of the n 1 calls to Heapify() takes O(log n) time
 - Thus the total time taken by HeapSort()
 - $= O(n) + (n-1) O(\log n)$
 - $= O(n) + O(n \log n)$
 - $= O(n \log n)$