## The autocorrelation functions in cryo-EM

Tamir Bendory, Nicolas Boumal, William Leeb and Amit Singer

May 25, 2018

The 3-D Fourier transform of an L-bandlimited 3-D volume (e.g., particle) can be expanded into spherical harmonics:

$$\hat{V}(k,\theta,\phi) = \sum_{\ell=0}^{L} \sum_{m=-\ell}^{\ell} A_{\ell,m}(k) Y_{\ell}^{m}(\theta,\phi),$$
(1)

where  $\theta \in [0, \pi)$  is the polar angle,  $\phi \in [0, 2\pi)$  is the azimuthal angle, k is the radial coordinate,  $Y_{\ell}^{m}(\theta, \phi)$  is the spherical harmonic of degree  $\ell$  and order m and  $A_{\ell,m}(k)$  are the associated spherical harmonics coefficients. The goal is to estimate the functions  $A_{\ell,m}$ . A rotation of the volume by  $\omega \in SO(3)$  can be described using the Wigner D-function  $D_{m,m'}^{\ell}$ :

$$(R_{\omega}\hat{V})(k,\theta,\phi) = \sum_{\ell=0}^{L} \sum_{m=-\ell}^{\ell} A_{\ell,m}(k) (R_{\omega}Y_{\ell}^{m})(\theta,\phi)$$

$$= \sum_{\ell=0}^{L} \sum_{m=-\ell}^{\ell} A_{\ell,m}(k) \sum_{m'=-\ell}^{\ell} D_{m,m'}^{\ell}(\omega) Y_{\ell}^{m'}(\theta,\phi).$$
(2)

By the Fourier slice theorem, the Fourier transform of each cryo-EM measurement (that is, each projection) is a slice of  $\hat{V}$ , associated with  $\theta = \pi/2$ , after  $\hat{V}$  was rotated by  $\omega \in SO(3)$ . Explicitly, the Fourier transform of a projection from the viewing direction  $\omega$  is related to the spherical harmonic coefficients of the object through:

$$\hat{P}_{\omega}(k,\phi) = \sum_{\ell=0}^{L} \sum_{m=-\ell}^{\ell} A_{\ell,m}(k) \sum_{m'=-\ell}^{\ell} D_{m,m'}^{\ell}(\omega) Y_{\ell}^{m'}(\pi/2,\phi).$$
(3)

Next, we relate the projections  $P_{\omega}$  to the mean and the autocorrelation functions, both computable from the observed micrographs. The mean of the micrograph is proportional to

$$M_1 \propto \sum_{n=1}^{N} \sum_{x,y} P_{\omega_n}(x,y), \tag{4}$$

where  $\omega_n$  denotes the viewing direction of the nth projection. By taking  $n \to \infty$ , we get

$$M_1 \propto \sum_{x,y} \int_{\omega} P_{\omega}(x,y) \rho(\omega) d\omega,$$
 (5)

where  $\rho(\omega)$  denotes the (possibly unknown) viewing direction distribution over SO(3).

We assume the projections are sufficiently separated so that, in the limit  $n \to \infty$ , the  $(\Delta_x, \Delta_y)$  entry of the second-order autocorrelation of the micrograph is proportional to:

$$M_2(\Delta_x, \Delta_y) \propto \sum_{x,y} \int_{\omega} P_{\omega}(x, y) P_{\omega}(x + \Delta_x, y + \Delta_y) \rho(\omega) d\omega + \text{bias.}$$
 (6)

The assumption here is that  $(\Delta_x, \Delta_y)$  are small enough so that, in computing the autocorrelation, points (x, y) and  $(x + \Delta_x, y + \Delta_y)$  do not touch distinct particles. In the same way and under the same conditions, the third moment is given by

$$M_3(\Delta_x^1, \Delta_y^1; \Delta_x^2, \Delta_y^2) \propto \sum_{x,y} \int_{\omega} P_{\omega}(x, y) P_{\omega}(x + \Delta_x^1, y + \Delta_y^1) P_{\omega}(x + \Delta_x^2, y + \Delta_y^2) \rho(\omega) d\omega + \text{bias.}$$
 (7)

In order to determine the particle, by (1) one needs to estimate order of  $L^3$  spherical harmonics coefficients. If the pixel size is proportional to 1/L (to match the volume's resolution), then  $M_3$  provides order of  $L^4$  equations involving triple products of  $P_{\omega}$ . However, since the in-plane rotation of each particle image is usually uniformly distributed,  $M_3$  depends on only three parameters: the length of the vector  $(\Delta_x^1, \Delta_y^1)$ , the length of the vector  $(\Delta_x^2, \Delta_y^2)$  and the angle between the two vectors. Therefore,  $M_3$  provides only  $\sim L^3$  equations. Since  $P_{\omega}$  depends (after coordinate transformation) linearly on the spherical harmonic coefficients through (3), this means we have a system of  $\sim L^3$  cubic equations in the  $\sim L^3$  sought parameters. Importantly, the coefficients of these equations can be estimated from the micrographs directly, without particle picking.