## Formalism for autocorrelation derivations

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Let  $x_{(1)}, \ldots, x_{(|s|)}$  denote the (independent) realizations of the random signal x in the observation y, starting at (deterministic) positions  $s_{(1)}, \ldots, s_{(|s|)}$ . Let  $I_{ij}$  be the indicator variable for whether position i is in the support of occurrence j, that is, it is one if i is in  $\{s_{(j)}, \ldots, s_{(j)} + L - 1\}$ , and zero otherwise. Then,

$$y[i] = \sum_{j=1}^{|s|} I_{ij} x_{(j)} [i - s_{(j)}] + \varepsilon[i].$$

This gives a simple expression for the first autocorrelation of y:

$$a_y^1 = \mathbb{E}_y \left\{ \frac{1}{N} \sum_{i=0}^{N-1} y[i] \right\}$$
 (1)

$$= \frac{1}{N} \mathbb{E}_{x_{(1)},\dots,x_{(|s|)},\varepsilon} \left\{ \sum_{i=0}^{N-1} \sum_{j=1}^{|s|} I_{ij} x_{(j)} [i - s_{(j)}] + \varepsilon[i] \right\}. \tag{2}$$

Now switch the sums over i and j, and observe that  $I_{ij}$  is zero unless  $i = s_{(j)} + t$  for t in the range  $0, \ldots, L-1$ . Hence,

$$a_y^1 = \frac{1}{N} \sum_{j=1}^{|s|} \mathbb{E}_{x_{(j)}} \left\{ \sum_{t=0}^{L-1} x_{(j)}[t] \right\} + \frac{1}{N} \mathbb{E}_{\varepsilon} \left\{ \sum_{i=0}^{N-1} \varepsilon[i] \right\}.$$
 (3)

Since the noise has zero mean and  $x_{(1)}, \ldots, x_{(|s|)}$  are independent and all distributed as x, we further find:

$$a_y^1 = \frac{|s|}{N} L a_x^1 = \gamma a_x^1. \tag{4}$$

To address the second-order moments, we resort to the separation conditions. In-

deed, consider this expression:

$$a_{y}^{2}[\ell] = \mathbb{E}_{y} \left\{ \frac{1}{N} \sum_{i=0}^{N-1} y[i]y[i+\ell] \right\}$$

$$= \frac{1}{N} \mathbb{E}_{x_{(1)},\dots,x_{(|s|)},\varepsilon} \left\{ \left( \sum_{j=1}^{|s|} I_{ij}x_{(j)}[i-s_{(j)}] + \varepsilon[i] \right) \left( \sum_{j'=1}^{|s|} I_{i+\ell,j'}x_{(j')}[i+\ell-s_{(j')}] + \varepsilon[i+\ell] \right) \right\}.$$
(6)