

Lecture 21 announcements

- Groups have been created on D2L
 - Each project team is a group (already created)
 - All students working on the collaborative Kaggle topic are 1 group - you need to sign yourself up to be included
- Next Homework will be HW 12, to be posted next week.
- Discussion 12 will be pre-recorded today at 5:00 PM in OHE 100C, and played back next week at the usual time and place. Also will be posted on D2L as usual.

Lecture 21 outline

- Finish Random Forest
- Start Boosting

RANDOM FOREST ALGORITHM

[Based on Hastie, et al., 2nd Ed, Alg. 15.1].

1. For $b = 1$ to B

(a) DRAW A SAMPLE DATASET \mathcal{D}^* AT RANDOM, WITH REPLACEMENT, OF SIZE N^* , FROM \mathcal{D}_{Tr} . TYPICALLY, $N^* = N_{Tr}$.

(b) GROW A RANDOM-FOREST TREE T_b , USING \mathcal{D}^* :

CYCLE THROUGH EACH REGION R_m ;

FOR EACH R_m :

(i) SELECT d FEATURES AT RANDOM (~~FOR~~ FROM ALL D FEATURES)

• COMMON VALUES:

$$d \approx \sqrt{D}, \text{ or } d = \lfloor \sqrt{D} \rfloor$$

(ii) USE CART APPROACH TO SPLIT R_m BY FINDING OPTIMAL

j, t_k, w

(iii) SPLIT THE TREE NODE INTO TWO DAUGHTER NODES.

~~tree~~

(iv) ITERATE UNTIL A HALTING
CONDITION IS REACHED

• SEE CART HALTING CONDITIONS

2. OUTPUT THE SET OF TREES $\{T_b, b=1, 2, \dots, B\}$.

3. TO USE RESULTING SET FOR PREDICTION:

REGRESSION -

$$\hat{f}(x) = \frac{1}{B} \sum_{b=1}^B \hat{f}_b(x)$$

PREDICTION FROM TREE

$$= \frac{1}{B} \sum_{b=1}^B \sum_{m=1}^M w_m^{(b)} \mathbb{I}(x \in R_m^{(b)})$$

$$= \frac{1}{B} \sum_{b=1}^B \sum_{m=1}^M w_m^{(b)} \phi(x, \gamma_m^{(b)})$$

STILL PIECEWISE CONSTANT, BUT A LOT MORE
"PIECES" OR REGIONS THAN FOR 1 CART TREE.

CLASSIFICATION —

CLASS PREDICTION:

IF $\hat{y}^{(b)}(\underline{x})$ IS CLASS ASSIGNMENT FROM TREE T_b , THEN

$$\hat{y}(\underline{x}) = \arg \max_c \sum_{b=1}^B \mathbb{I} [\hat{y}^{(b)}(\underline{x}) = c]$$

(\Rightarrow) TAKE VOTE, \hat{y} = WINNING CLASS)

CAN ALSO ESTIMATE CLASS POSTERIOR PROBABILITIES $p(\hat{y} = c | \underline{x}, \mathcal{D})$, BY:

LET $p_c^{(b)}(\underline{x})$ = FREQ. OF OCCURRENCE OF DATA POINTS $y_i = c$ IN $R_m^{(b)}$ THAT CONTAINS \underline{x} , FROM TREE T_b .

AT EACH POINT \underline{x} , TAKE AVE:

$$p(\hat{y} = c | \underline{x}, \mathcal{D}) \approx \frac{1}{B} \sum_{b=1}^B p_c^{(b)}(\underline{x}).$$

— [FIG. 15.1, HASTIE] —

BOOSTING [MURPHY 16.4.0-16.4.4]

[ALSO - HASTIE et al., ch. 10]

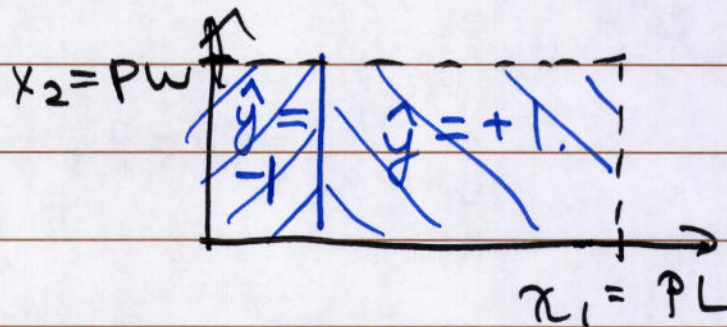
IS ALSO AN ADPTIVE BASIS FCN. MODEL:

$$(1) \quad \hat{f}(x) = w_0 + \sum_{m=1}^M w_m \phi(x; \gamma_m)$$

EACH $\phi(x, \gamma_m)$:

- IS A SIMPLE CLASSIFIER THAT CAN CLASSIFY THE ~~ENTIRE~~ ENTIRE FEATURE SPACE.
- IS A "WEAK LEARNER" THAT IS ONLY REQUIRED TO DO BETTER THAN CHANCE.

e.g., WEAK LEARNER IS TYPICALLY A "DECISION STUMP" - A 1-STAGE CART RESULTING IN 1 NODE AND 2 LEAVES (OR VARIANTS WITH >2 LEAVES).



$\phi_m(x)$ ARE FOUND SEQUENTIALLY.

NOTATION

FOR 2-CLASS PROBLEM, LET CLASS LABELS BE ± 1 .

$$(2) \hat{f}(x) = f_0 + \sum_{m=1}^M \beta_m \phi_m(x)$$

"WEIGHT" OR
IMPORTANCE OF
 m^{th}
CLASSIFIER
($\beta_m \in \mathbb{R}$)

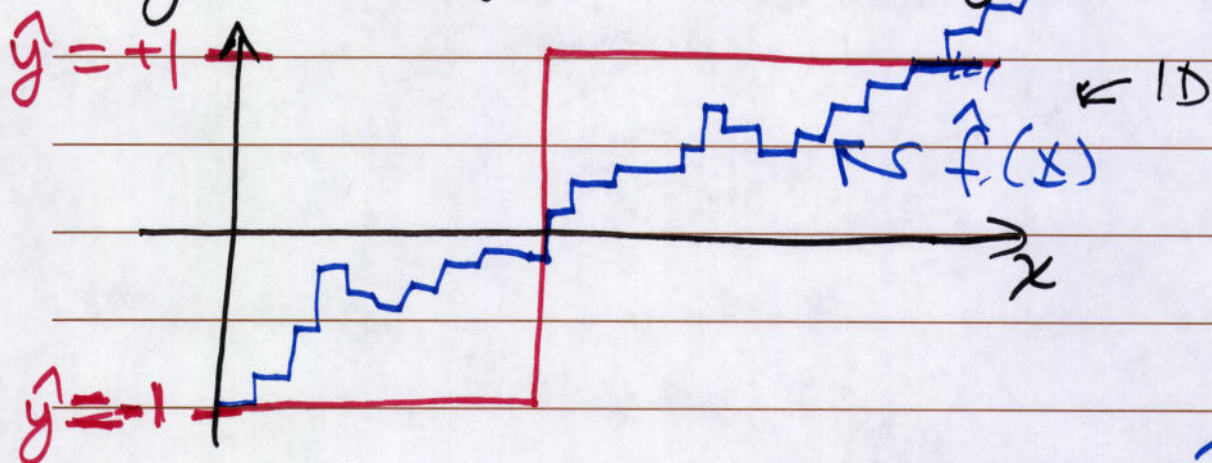
$$= f_0 + \sum_{m=1}^M \beta_m \phi(x; \gamma_m)$$

SIMPLE BASE CLASSIFIER

$$\phi_m \in \{-1, +1\}$$

FINAL CLASSIFIER:

$$\hat{y}(x) = \text{sign} \{ \hat{f}(x) \}, \quad \hat{y} \in \{-1, +1\}$$



$\hat{f}(x)$ CARRIES MORE INFO THAN $\hat{y}(x)$.

$|\hat{f}(x)|$ PROVIDES A MEASURE OF CONFIDENCE.

INTERMEDIATE EXPRESSIONS FOR \hat{f} :

$$(3) \quad \hat{f}_m(x) = f_0 + \sum_{m'=1}^m \beta_{m'} \phi_{m'}(x)$$

DATA POINTS: (x_i, \tilde{y}_i) , $\tilde{y}_i \in \{-1, +1\}$.

TO FIND EACH $\phi_m(x)$,

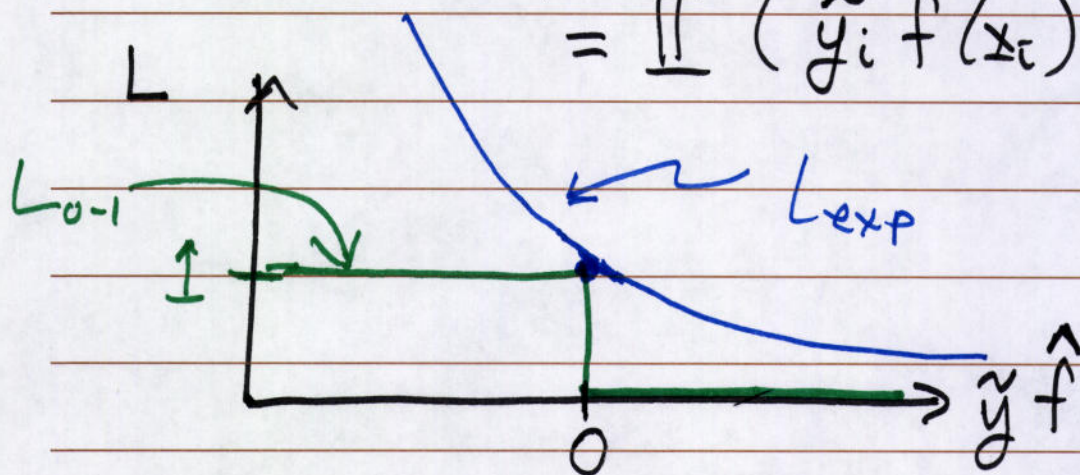
$$f_{obj} \left[\{ \beta_m, m=1, \dots, M \}, \{ \underline{x}_m, m=1, \dots, M \}, \phi(x) \right]$$

$$= \frac{1}{N} \sum_{i=1}^N L(\tilde{y}_i, \hat{f}(x_i))$$

LOSS FUNCTION.

$$0-1 \text{ Loss: } L_{0-1} = \mathbb{I}(\tilde{y}_i \neq \text{sign}\{\hat{f}(x_i)\})$$

$$= \mathbb{I}(\tilde{y}_i \hat{f}(x_i) < 0)$$



~~Ex~~ f_{obj} using L_{0-1} : - NOT CONVEX
- NOT AMENABLE TO GRADIENT TECHNIQUES.

\Rightarrow (4) EXPONENTIAL LOSS: $L_{\text{exp}} = \exp\{-\tilde{y}_i \hat{f}(x_i)\}$

(\exists OTHER L FCNS.)

\rightarrow - CONVEX

- DIFFERENTIABLE

- PROVIDES CONFIDENCE MEASURE.