

Random Process

Jianbin Tan

1 Gaussian Processes

Definition. T is a index set and (Ω, \mathcal{F}, P) is a probability space, $(X_t)_{t \in T}$ is called a random process if $X_t \in \mathcal{F}, \forall t \in T$.

Note. (1) If X_t is measurable on $(\Omega_t, \mathcal{F}_t, P_t)$, we can assume that exist a new probability space (Ω, \mathcal{F}, P) and $X'_t \in \mathcal{F}$ s.t. $X'_t \stackrel{d}{=} X_t$ by Kolmogorov extension theorem.

(2) The distribution of $(X_t)_{t \in T}$ is uniquely determined by all the distributions of $(X_t)_{t \in T_0}$. T_0 is a finite subset of T .

(3) Normally, the index set T is some compact metric space with order. One may define a measurable structure on $E: (T, \mathcal{B}(T), \mu), \mu(T) < \infty$, if you are interesting in the stochastic integral $\int_T X_t f(t) \mu(dt)$.

Example. Random vector, random matrix and random field.

Example. Random walk: Z_i are independent, mean zero and $X_n = \sum_{k \leq n} Z_k$.

Example. Brownian motion: $T = [0, \infty), X_0 = 0$:

- (a) $t_0 < t_1 < \dots < t_n, X_{t_0}, X_{t_1} - X_{t_0}, \dots, X_{t_n} - X_{t_{n-1}}$ are independent.
- (b) $t > s, X_t - X_s \sim N(0, t - s)$.
- (c) $X_t \in C([0, \infty))$ a.s. P .

Definition. A random process $(X_t)_{t \in T}$ is called a Gaussian process if for \forall finite $T_0 \subset T$, $(X_t)_{t \in T_0}$ has a normal distribution.

Note. Noticed that if $(X_t)_{t \in T}$ is a mean zero Gaussian process, then it's completely determined by $EX_s X_t := K(s, t)$.

Example. If $(X_t)_{t \in T}$ is a Brownian motion, $EX_s X_t = EX_s(X_t - X_s) + EX_s^2 = s$ if $t > s \Rightarrow K(s, t) = \min(s, t)$. We can alternatively define the Brownian motion:

- (a) $(X_t)_{t \in T}$ is a mean zero Gaussian process.
- (b) $X_0 = 0, K(s, t) = \min(s, t)$.
- (c) $X_t \in C([0, \infty))$ a.s..

Definition. $(X_t)_{t \in T}$ is a mean zero Gaussian process with $K(s, t)$, then we can define a canonical metric on T : $d_X(s, t) = \|X_t - X_s\|_2 = (E(X_t - X_s)^2)^{1/2}$.

Note. (1) The canonical metric may not be a metric since $d_X(s, t) = 0 \nrightarrow s = t$.

(2) Assume that $X_p = 0$, d can determine the covariance function K since $K(s, t) = \frac{d^2(t, p) + d^2(s, p) - d^2(s, t)}{2}$. Then the canonical metric completely determines the mean zero Gaussian process.

Example. Let $T \subset \mathcal{R}^n$ and $g \sim N(0, I_n)$, $X_t = \langle g, t \rangle$, $t \in T$. $(X_t)_{t \in T}$ is called canonical Gaussian processes and $d_X(s, t) = \|s - t\|_2$.

2 Slepian's Inequality

Lemma 1. Let $X \sim N(0, 1)$ and f is a differentiable function on \mathcal{R} s.t. $E|f'(X)| < \infty$ and $E|Xf(X)| < \infty$, we have $Ef'(X) = EXf(X)$.

Proof. Let $f_n = fI_{[-n, n]}$, then $f_n(x) \rightarrow f(x)$.

$$Ef'_n(X) = \int_{\mathcal{R}} f'_n(x)p(x)dx = - \int_{\mathcal{R}} f_n(x)p'(x)dx = \int_{\mathcal{R}} f_n(x)p(x)xdx = EXf_n(X)$$

Let $n \rightarrow \infty$ and apply dominated convergence theorem. □

Lemma 2. Let $X \sim N(0, \Sigma)$, $f : \mathcal{R}^n \rightarrow \mathcal{R}$ and ∇f exist, then $\Sigma E\nabla f(X) = EXf(X)$.

Proof. Let $\Sigma = I$, then

$$E\partial f(X)/\partial X_i = EX_i f(X) \Rightarrow E\nabla f(X) = EXf(X)$$

Let $Z = \Sigma^{-1/2}X$, then

$$EXf(X) = E \Sigma^{1/2} Zf(X) = \Sigma^{1/2} E \Sigma^{1/2} \nabla f(X) = \Sigma E\nabla f(X)$$

□

Note. $EX\nabla f(X)^T = \Sigma E\nabla^2 f(X)$ since $EX \frac{\partial f(X)}{\partial X_i} = \Sigma E(X \frac{\partial^2 f(X)}{\partial X_i \partial X_j})_j$.

Definition. X, Y are two Gaussian random vector valued in \mathcal{R}^n , we define a continuous interpolates: $Z(u) = \sqrt{u} X + \sqrt{1-u} Y$, $u \in [0, 1]$.

Lemma 3. Let $X \sim N(0, \Sigma)$, $Y \sim N(0, \Lambda)$ are independent, then for all twice-differentiable $f : \mathcal{R}^n \rightarrow \mathcal{R}$, we have $\frac{d}{du}Ef(Z(u)) = \frac{1}{2}tr((\Sigma - \Lambda) E\nabla^2 f(Z))$.

Proof.

$$\frac{d}{du}Ef(Z(u)) = E\nabla f(Z)^T \frac{dZ}{du}(u) = \frac{1}{2}E\nabla f(Z)^T \left(\frac{X}{\sqrt{u}} - \frac{Y}{\sqrt{1-u}} \right)$$

And $E\nabla f(Z)^T X$ and $E\nabla f(Z)^T Y$ can be represented as:

$$\begin{aligned} E\nabla f(Z)^T X &= E \operatorname{tr}(X \nabla f(Z)^T) = \operatorname{tr}(E_Y E_X X \nabla f(Z)^T) = \sqrt{u} \operatorname{tr}(\Sigma E\nabla^2 f(Z)) \\ E\nabla f(Z)^T Y &= E \operatorname{tr}(Y \nabla f(Z)^T) = \operatorname{tr}(E_X E_Y Y \nabla f(Z)^T) = \sqrt{1-u} \operatorname{tr}(\Lambda E\nabla^2 f(Z)) \end{aligned}$$

□

Theorem 1. (Slepian's Inequality, functional form) Consider two mean zero Gaussian random vectors X and Y in \mathcal{R}^n , $X \sim N(0, \Sigma)$, $Y \sim N(0, \Lambda)$. Then $Ef(X) \geq Ef(Y)$ if:

- (a) $\|X_i\|_2 = \|Y_i\|_2$ and $\|X_i - X_j\|_2 \leq \|Y_i - Y_j\|_2$;
- (b) $f : \mathbb{R}^n \rightarrow \mathcal{R}$ s.t. $\frac{\partial^2 f}{\partial x_i \partial x_j} \geq 0$ for all $i \neq j$.

Proof. We can supposed that X and Y are independent, if not, we can create another independent X', Y' s.t. $X \stackrel{d}{=} X'$ and $Y \stackrel{d}{=} Y'$. Let $Z(u) = \sqrt{u} X + \sqrt{1-u} Y$, noticed that:

$$\frac{d}{du} Ef(Z(u)) = \frac{1}{2} \text{tr}((\Sigma - \Lambda) E \nabla^2 f(Z)) \geq 0 \Rightarrow Ef(X) \geq Ef(Y)$$

□

Corollary 1. (Slepian's Inequality) $P(\max_i X_i \geq \tau) \leq P(\max_i Y_i \geq \tau)$.

Proof. Let $h_n(x) \geq 0$ is some smooth and non-increasing functions s.t. $h_n(x) \rightarrow I_{(-\infty, \tau)}(x)$. Let $f_n(x) = \prod_i h_n(x_i) \rightarrow \prod_i I_{(-\infty, \tau)}(x_i) = I_{(-\infty, \tau)}(\max_i x_i)$. Noticed that:

$$\frac{\partial^2 f_n}{\partial x_i \partial x_j} \geq 0 \Rightarrow Ef_n(X) \geq Ef_n(Y) \Rightarrow P(\max_i X_i < \tau) \geq P(\max_i Y_i < \tau)$$

□

Note. $EX = \int_0^\infty P(X > t)dt - \int_{-\infty}^0 P(X < t)dt \Rightarrow E \max_i X_i \leq E \max_i Y_i$. For two Gaussian Processes $(X_t)_{t \in T}$ and $(Y_t)_{t \in T}$, $E \sup X_t \leq E \sup Y_t$ also achieves.

Theorem 2. (Sudakov-Fernique Inequality) We drop the condition: $\|X_t\|_2 = \|Y_t\|_2$, which means that if two pseudo-metric d_X and d_Y defined on T s.t. $d_X(s, t) \leq d_Y(s, t)$, then $E \sup X_t \leq E \sup Y_t$ holds.

Proof. Similarly, we just prove $E \max_i X_i \leq E \max_i Y_i$, $X \sim N(0, \Sigma)$, $Y \sim N(0, \Lambda)$. Let $f(z) = \frac{1}{\beta} \log(\sum_i e^{\beta z_i})$, it's easy to show that $f(x) \rightarrow \max_i x_i$, if $\beta \rightarrow \infty$.

Let $\frac{\partial f}{\partial Z_i}(Z) = \frac{e^{\beta Z_i}}{\sum_m e^{\beta Z_m}} := P_i$ and $\frac{\partial^2 f}{\partial Z_i \partial Z_j}(Z) = \beta(\delta_{ij} P_i - P_i P_j)$. The next step is to show $\text{tr}((\Sigma - \Lambda) E \nabla^2 f(Z)) \geq 0$:

Since $\sum_{i,j} (EX_i^2 + EX_j^2 - EY_i^2 - EY_j^2)(\delta_{ij} P_i - P_i P_j) = \sum_{i,j} (EX_i^2 - EY_i^2 + EX_j^2 - EY_j^2) \delta_{ij} P_i - \sum_{i,j} (EX_i^2 - EY_i^2 + EX_j^2 - EY_j^2) P_i P_j = 0$

$$\begin{aligned} \sum_{i,j} (\Sigma_{ij} - \Lambda_{ij})(\delta_{ij} P_i - P_i P_j) &= \sum_{i,j} (EY_i Y_j - EX_i X_j)(\delta_{ij} P_i - P_i P_j) \\ &= \frac{1}{2} \left(\sum_{i,j} (E(X_i - X_j)^2 - E(Y_i - Y_j)^2)(\delta_{ij} P_i - P_i P_j) - \right. \\ &\quad \left. \sum_{i,j} (EX_i^2 + EX_j^2 - EY_i^2 - EY_j^2)(\delta_{ij} P_i - P_i P_j) \right) \\ &= -\frac{1}{2} \left(\sum_{i \neq j} (E(X_i - X_j)^2 - E(Y_i - Y_j)^2) P_i P_j \right) \geq 0 \end{aligned}$$

□

Corollary 2. (Norms of Gaussian random matrices) Let $A \in M_{m \times n}(\mathcal{R})$ with iid $N(0, 1)$, then $E\|A\|_2 \leq \sqrt{m} + \sqrt{n}$.

Proof. Note that $\|A\|_2 = \max_{u \in S^{n-1}, v \in S^{m-1}} \langle Au, v \rangle_2$ and $\langle Au, v \rangle_2 = v^T Au = \sum_{i,j} v_i A_{ij} u_j$ is Gaussian distribution, which mean is 0 and variance is 1. We can view $\|A\|_2$ is a Gaussian process $\{X_{uv}\}$ in $S^{n-1} \times S^{m-1}$ and

$$\begin{aligned} E(X_{uv} - X_{wz})^2 &= E\left(\sum_{i,j} A_{ij}(v_i u_j - z_i w_j)\right)^2 = \sum_{i,j} (v_i u_j - z_i w_j)^2 = \|uv^T - wz^T\|_F^2 \\ &= \|(u - w)v^T + w(v - z)^T\|_F^2 \end{aligned}$$

And $\|\alpha \beta^T\|_F^2 = \text{tr}(\alpha \beta^T \beta \alpha^T) = \beta^T \beta \alpha^T \alpha \Rightarrow \|(u - w)v^T + w(v - z)^T\|_F^2 = \|u - w\|_2^2 + \|v - z\|_2^2 + 2(1 - v^T z)(w^T u - 1) \leq \|u - w\|_2^2 + \|v - z\|_2^2$.

Let $Y_{uv} = \langle g, u \rangle_2 + \langle h, v \rangle_2$, $g \sim N(0, I_n)$, $h \sim N(0, I_m)$ independent. Then

$$\begin{aligned} E(Y_{uv} - Y_{wz})^2 &= \|u - w\|_2^2 + \|v - z\|_2^2 \Rightarrow E\|A\|_2 \leq E \sup \{\langle g, u \rangle_2 + \langle h, v \rangle_2\} \\ &\leq E\|g\|_2 + E\|h\|_2 = (E\|g\|_2^2)^{1/2} + (E\|h\|_2^2)^{1/2} = \sqrt{n} + \sqrt{m} \end{aligned}$$

□

Lemma 4. $\{X_n\}_{n \leq N}$ iid standard normal distribution, then $E \max_n X_n \asymp \sqrt{\log N}$.

Corollary 3. (Sudakov's Minoration Inequality) $(X_t)_{t \in T}$ is a mean zero Gaussian process and recall $\mathcal{N}(E, d, \varepsilon)$ is the smallest covering number of T by ε -net. Then

$$E \sup X_t \geq c\varepsilon \sqrt{\log \mathcal{N}(T, d, \varepsilon)}$$

Proof. If (T, d) is totally bounded, recall the ε -separated subset E of T : $d(x, y) > \varepsilon, x, y \in E$. And \mathcal{N} denotes the maximal number of $|E|$, then $\mathcal{N} \geq \mathcal{N}(T, d, \varepsilon)$ and $E(X_t - X_s)^2 = d_X^2(s, t) \geq \varepsilon^2$, if $s, t \in E$. Let $Y_t = \frac{\varepsilon}{\sqrt{2}}g_t, g_t \sim N(0, 1)$, then $d_Y(s, t) = \varepsilon^2$:

$$E \sup_{t \in T} X_t \geq E \sup_{t \in E} X_t \geq E \sup_{t \in E} Y_t = \frac{\varepsilon}{\sqrt{2}} E \sup_{t \in E} g_t \geq c\varepsilon \sqrt{\log \mathcal{N}} \geq c\varepsilon \sqrt{\log \mathcal{N}(T, d, \varepsilon)}$$

□

Example. If $(X_t)_{t \in T}$ is a canonical Gaussian process, then $\forall \varepsilon > 0, E \sup_{t \in T} \langle g, t \rangle_2 \geq c\varepsilon \sqrt{\log \mathcal{N}(E, d, \varepsilon)}$, d is Euclidean distance.

3 Gaussian Width

Definition. $E \sup_{t \in T} \langle g, t \rangle_2$ above is defined as the Gaussian width of T : $\omega(T)$, which is a basic geometric quantities associated with subset $T \subset \mathcal{R}^n$.

Property 1.

- (a) $\omega(T) < \infty \Leftrightarrow T$ is bounded.
- (b) $U \in M_{nn}(\mathcal{R})$ is orthonormal matrix and $y \in \mathcal{R}^n$, then $\omega(UT + y) = \omega(T)$.
- (c) $\omega(T) = \omega(\text{conv}(T))$.
- (d) $\omega(A + B) = \omega(A) + \omega(B)$ and $\omega(aT) = |a|\omega(T)$.
- (e) $\omega(T) = \frac{1}{2}\omega(T - T) = \frac{1}{2}E \sup_{x, y \in T} \langle g, x - y \rangle_2$.
- (f) $\frac{1}{\sqrt{2\pi}} \text{diam}(T) \leq \omega(T) \leq \frac{\sqrt{n}}{2} \text{diam}(T)$.

Proof.

(a) “ \Rightarrow ”: $\omega(T) < \infty \Rightarrow T$ is totally bounded $\Rightarrow T$ is bounded. “ \Leftarrow ”: $\langle g, t \rangle_2 \leq \|g\|_2 \|t\|_2 \Rightarrow \omega(T) \leq (\sup_{t \in T} \|t\|_2) E\|g\|_2$.

(b) $\langle Ut + y, g \rangle_2 = \langle t, U^T g \rangle_2 + \langle y, g \rangle_2 \Rightarrow \omega(UT + y) = E \sup_{t \in T} \langle Ut + y, g \rangle_2 = E \sup_{t \in T} \langle t, U^T g \rangle_2 = E \sup_{t \in T} \langle t, g \rangle_2$.

(c) $\langle \sum_n a_n t_n, g \rangle_2 = \sum_n a_n \langle t_n, g \rangle_2 \leq \sup_{t \in T} \langle t, g \rangle_2 \Rightarrow \sup_{h \in \text{conv}(T)} \langle h, g \rangle_2 \leq \sup_{t \in T} \langle t, g \rangle_2 \Rightarrow \omega(\text{conv}(T)) \leq \omega(T) \Rightarrow \omega(\text{conv}(T)) = \omega(T)$.

(d) $\omega(A + B) = E \sup_{t \in A+B} \langle t, g \rangle_2 = E \sup_{t_1 \in A, t_2 \in B} \langle t_1 + t_2, g \rangle_2 = \omega(A) + \omega(B)$. $\omega(aT) = E \sup_{t \in T} \langle at, g \rangle_2 = |a| E \sup_{t \in T} \langle t, \text{sign}(a)g \rangle_2 = |a|\omega(T)$.

(e) $\omega(T - T) = 2 \omega(T)$.

(f) $\omega(T) \geq \frac{1}{2} E |\langle g, x - y \rangle_2|, \forall x, y \in T$. Notice that $\langle g, x - y \rangle_2 \sim N(0, \|x - y\|_2^2)$. Let $X \sim N(0, \sigma^2)$,

$$E|X| = \int |x| p(x) dx = \frac{1}{\sqrt{2\pi\sigma^2}} \int_0^\infty \exp(-\frac{x^2}{2\sigma^2}) dx^2 = \sqrt{\frac{2\sigma^2}{\pi}}$$

Then $\omega(T) \geq \frac{1}{\sqrt{2\pi}} \|x - y\|_2 \Rightarrow \omega(T) \geq \frac{1}{\sqrt{2\pi}} \text{diam}(T)$

$\omega(T) \leq \frac{1}{2} \sup_{x, y \in T} \|x - y\|_2 E\|g\|_2 \leq \frac{\sqrt{n}}{2} \sup_{x, y \in T} \|x - y\|_2$. □

Lemma 5. If $g \sim N(0, I)$, then $r = \|g\|_2$ and $\theta := \frac{g}{r}$ are independent.

Note. If $g \sim N(0, I_n)$, $g = r\theta$. Moreover, $r \rightarrow \sqrt{n}$ and $\theta \sim Unif(S^{n-1})$. We can approximately think $N(0, I_n) \approx \sqrt{n} Unif(S^{n-1})$.

Definition. $\omega_s(T) := E \sup_{t \in T} \langle \theta, t \rangle_2 = \frac{1}{2} E \sup_{x, y \in T} \langle \theta, x - y \rangle_2$, $\theta \sim Unif(S^{n-1})$.

Note. $\omega(T) = E \sup_{t \in T} \langle t, r\theta \rangle_2 = Er \omega_s(T) \approx \sqrt{n} \omega_s(T)$. $\omega_s(T)$ indeed is the mean width of T .

Example. Let $B_p^n = \{x \in \mathcal{R}^n; \|x\|_p \leq 1\}$, $\omega_s(B_p^n) = \int_{S^{n-1}} \frac{1}{\|\theta\|_p} d\theta$:

$$\omega(B_p^n) = \int_0^\infty r P(dr) \int_{S^{n-1}} \frac{1}{\|\theta\|_p} d\theta = E \frac{\|g\|_2^2}{\|g\|_q}$$

If $p = 2$, $\omega(B_p^n) = Er$.

Definition. We define a squared version of Gaussian width $h(T) := \sqrt{E \sup_t \langle g, t \rangle_2^2}$, $g \sim N(0, I_n)$.

Property 2. $2\omega(T) \leq h(T - T) \leq 2C \omega(T)$.

Definition. For a bounded $T \in \mathcal{R}^n$, the statistical dimension of T : $d(T) = \frac{h(T-T)^2}{\frac{\omega(T)^2}{\text{diam}(T)^2}} \asymp$

Theorem 3. $d(T) \leq \dim(T)$.

Proof.

$$\begin{aligned} h(T - T)^2 &= E \sup_{t, s \in T} \langle g, t - s \rangle_2^2 \leq E \sup_{z \in \text{diam}(T) B_2^{\dim(T)}} \langle g, z \rangle_2^2 = \text{diam}(T)^2 E \sup_{z \in B_2^{\dim(T)}} \langle g, z \rangle_2^2 \\ &= \text{diam}(T)^2 E \sup_{z \in B_2^{\dim(T)}} \|g\|_2^2 \langle \theta, z \rangle_2^2 = \text{diam}(T)^2 \dim(T). \quad \square \end{aligned}$$

Note. If T is a Ball, $d(T) = \dim(T)$.

Example. $A \in M_{mn}(\mathcal{R})$, then

$$h(AB_2^n - AB_2^n) = E \sup_{t, s \in AB_2^n} \langle g, t - s \rangle_2^2 = n E \sup_{t, s \in AB_2^n} \langle \theta, t - s \rangle_2^2$$

Noticed that $\partial AB_2^n = \{x \in \mathcal{R}^n; \sum_{i \leq n} \frac{x_i^2}{\lambda_i^2} = 1\}$, λ_i is the singular value of $A \Rightarrow h(AB_2^n - AB_2^n) = 4n \int_{S^{n-1}} \frac{1}{\sum_{i \leq n} \frac{\theta_i^2}{\lambda_i^2}} d\theta = 4\|A\|_F^2 \Rightarrow d(AB_2^n) = \frac{\|A\|_F^2}{\|A\|_2^2}$.

Note. $r(A) = d(AB_2^n)$ is the stable rank of A .

4 Random Projection s of sets

$G_{n,m}$ is the collection of all the m dimensional subspace of \mathcal{R}^n and P is a random projection from \mathcal{R}^n onto $E \sim Unif(G_{n,m})$. And without loss of generality, we can assume that rows of P are orthonormal.

Theorem 4. $P(\text{diam}(PT) \leq C(\omega_s(T) + \sqrt{\frac{m}{n}} \text{diam}(T))) \geq 1 - 2e^{-m}$.

Proof.

$\text{diam}(PT) = \sup_{x \in T-T} \|Qx\|_2 = \sup_{x \in T-T} \max_{z \in S^{m-1}} \langle Qx, z \rangle_2$. Let $\mathcal{N} = \mathcal{N}(S^{m-1}, 1/2) \Rightarrow |\mathcal{N}| \leq 5^m$.

$$\sup_{x \in T-T} \max_{z \in S^{m-1}} \langle Qx, z \rangle_2 \leq 2 \sup_{x \in T-T} \max_{z \in \mathcal{N}} \langle Qx, z \rangle_2 = 2 \max_{z \in \mathcal{N}} \sup_{x \in T-T} \langle x, Q^T z \rangle_2.$$

Let $z \sim Unif(S^{m-1})$, $E \sup_{x \in T-T} \langle x, Q^T z \rangle_2 = 2\omega_s(T)$. Note that $f(z) = \sup_{x \in T-T} \langle x, Q^T z \rangle_2$ is Lipschitz function and its norm is $\text{diam}(T)$.

$$P(\sup_{x \in T-T} \langle x, Q^T z \rangle_2 \geq 2\omega_s(T) + t) \leq 2 \exp(-\frac{cnt^2}{\text{diam}(T)^2})$$

Then $P(\max_{z \in \mathcal{N}} \sup_{x \in T-T} \langle x, Q^T z \rangle_2 \geq 2\omega_s(T) + t) \leq 2|\mathcal{N}| \exp(-\frac{cnt^2}{\text{diam}(T)^2})$. Let $t = C\sqrt{\frac{m}{n}} \text{diam}(T)$, if C is large enough, $P(\frac{1}{2} \text{diam}(QT) \geq 2\omega_s(T) + C\sqrt{\frac{m}{n}} \text{diam}(T)) \leq 2e^{-m}$. \square

Note. Let m be the phase transition:

$$m = \frac{(\sqrt{n}w_s(T))^2}{\text{diam}(T)^2} \asymp \frac{w(T)^2}{\text{diam}(T)^2} \asymp d(T)$$

Then

$$\text{diam}(PT) \leq \begin{cases} C\sqrt{\frac{m}{n}} \text{diam}(T), & m \geq d(T) \\ Cw_s(T), & m \leq d(T) \end{cases}$$