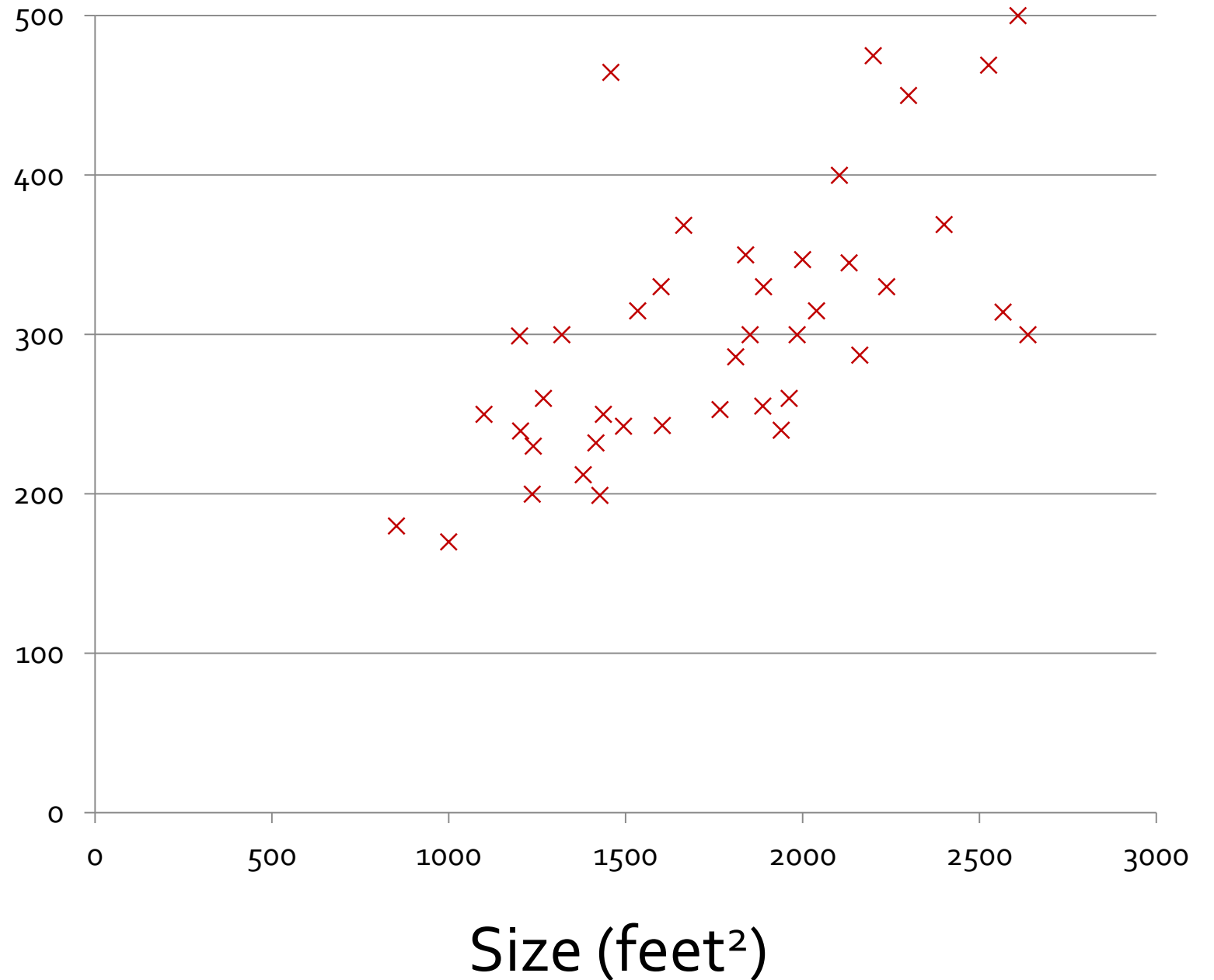


# Linear and Logistic Regression

# Housing Prices

Price  
(in 1000s of  
dollars)



## Training set of housing prices (Portland, OR)

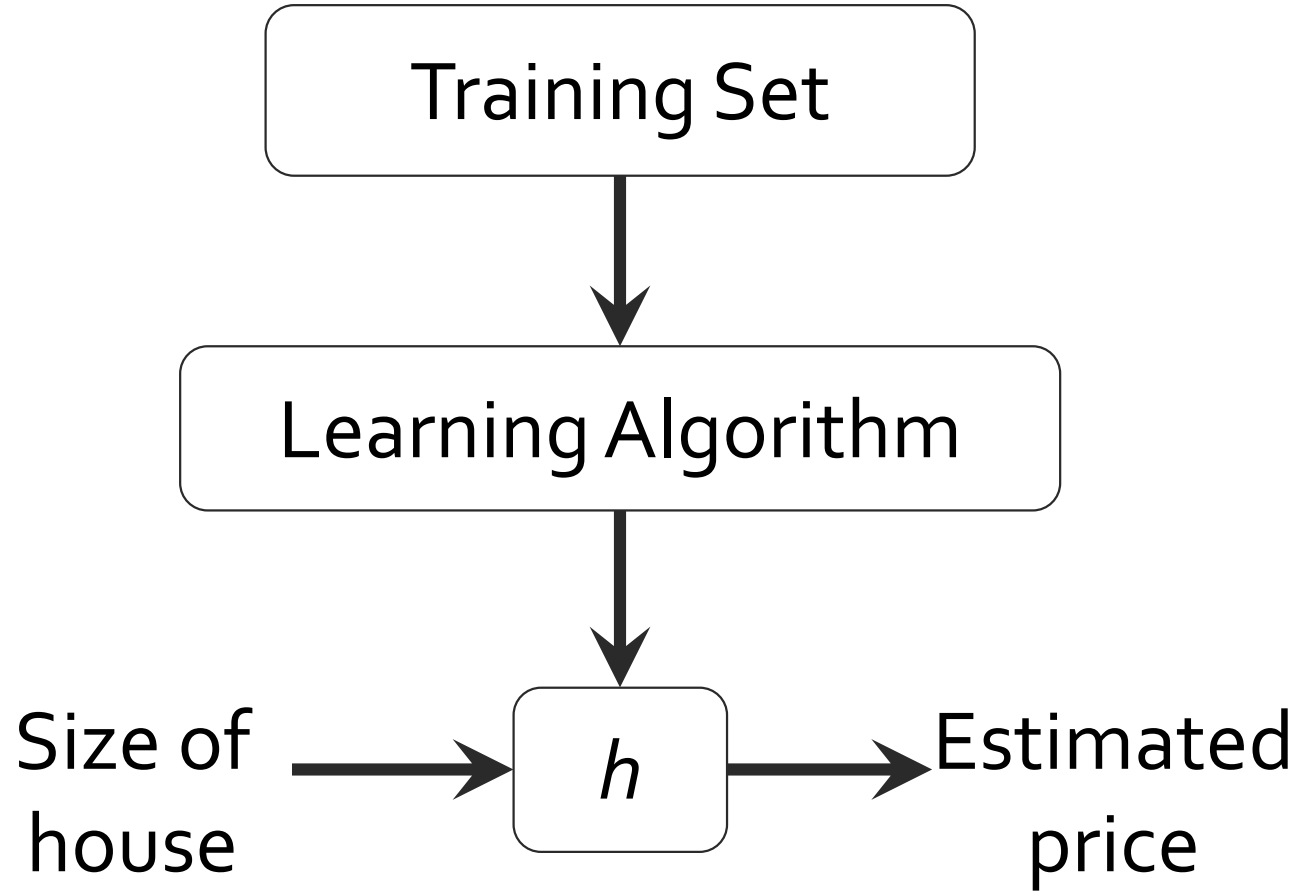
Size in feet <sup>2</sup> (x)	Price (\$) in 1000's (y)
2104	460
1416	232
1534	315
852	178
...	...

Notation:

**m** = Number of training examples

**x**'s = "input" variable / features

**y**'s = "output" variable / "target" variable



**How do we represent  $h$  ?**

Linear regression with one variable.  
Univariate linear regression.

Training Set	Size in feet <sup>2</sup> (x)	Price (\$) in 1000's (y)
	2104	460
	1416	232
	1534	315
	852	178
	...	...

Hypothesis:  $h_{\theta}(x) = \theta_0 + \theta_1 x$

$\theta_i$ 's: Parameters

How to choose  $\theta_i$ 's?

## Simplified

Hypothesis:

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

Parameters:

$$\theta_0, \theta_1$$

Cost Function:

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Goal: minimize  $J(\theta_0, \theta_1)$   
 $\theta_0, \theta_1$

$$h_{\theta}(x) = \theta_1 x$$

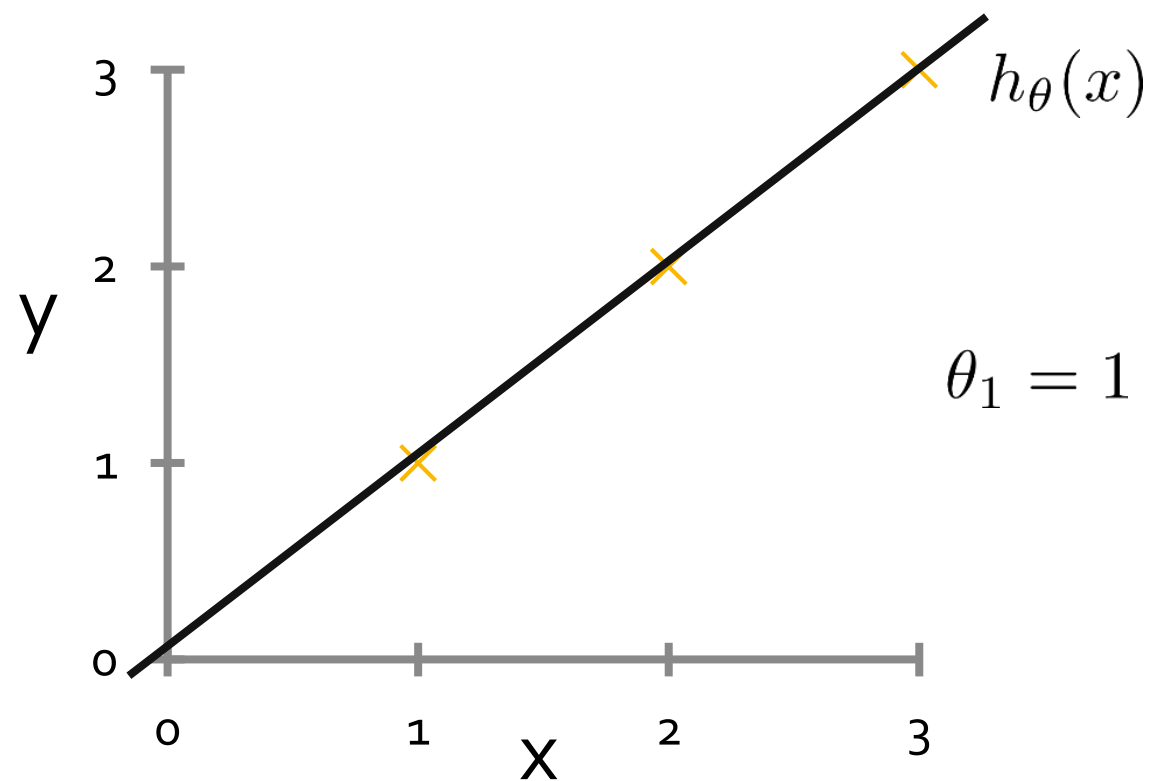
$$\theta_1$$

$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

minimize  $J(\theta_1)$   
 $\theta_1$

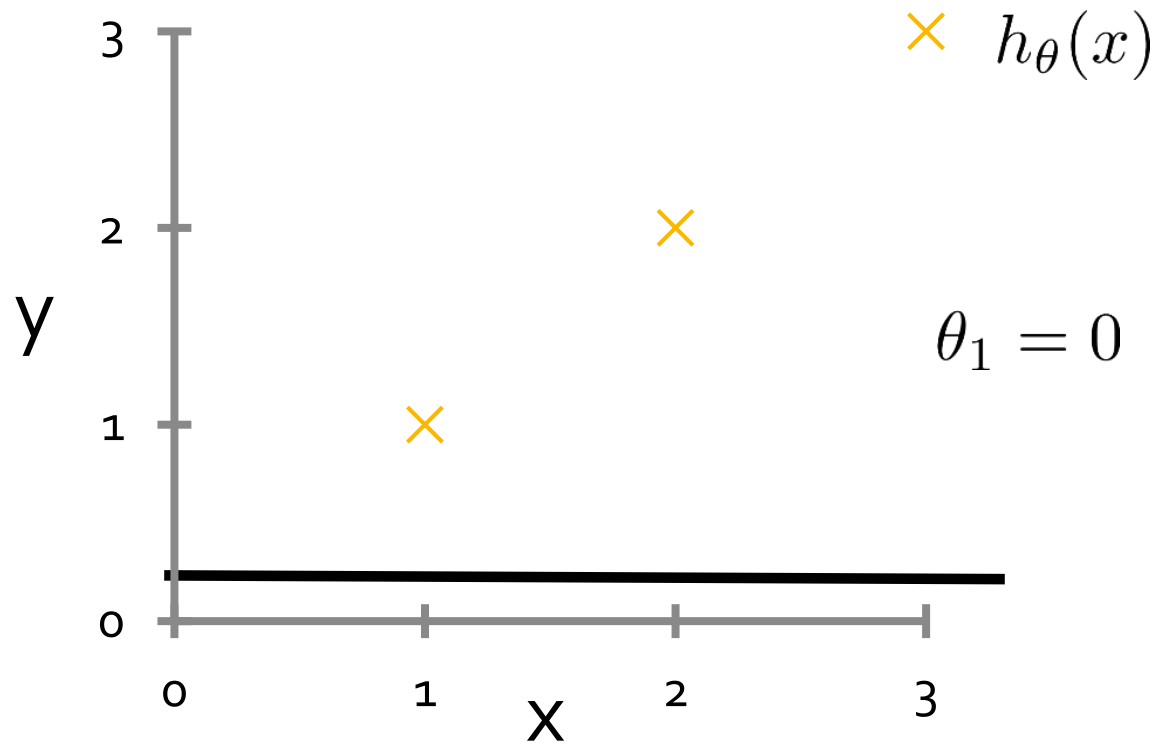
$$h_{\theta}(x)$$

(for fixed  $\theta_1$  this is a function of  $x$ )



$$h_{\theta}(x)$$

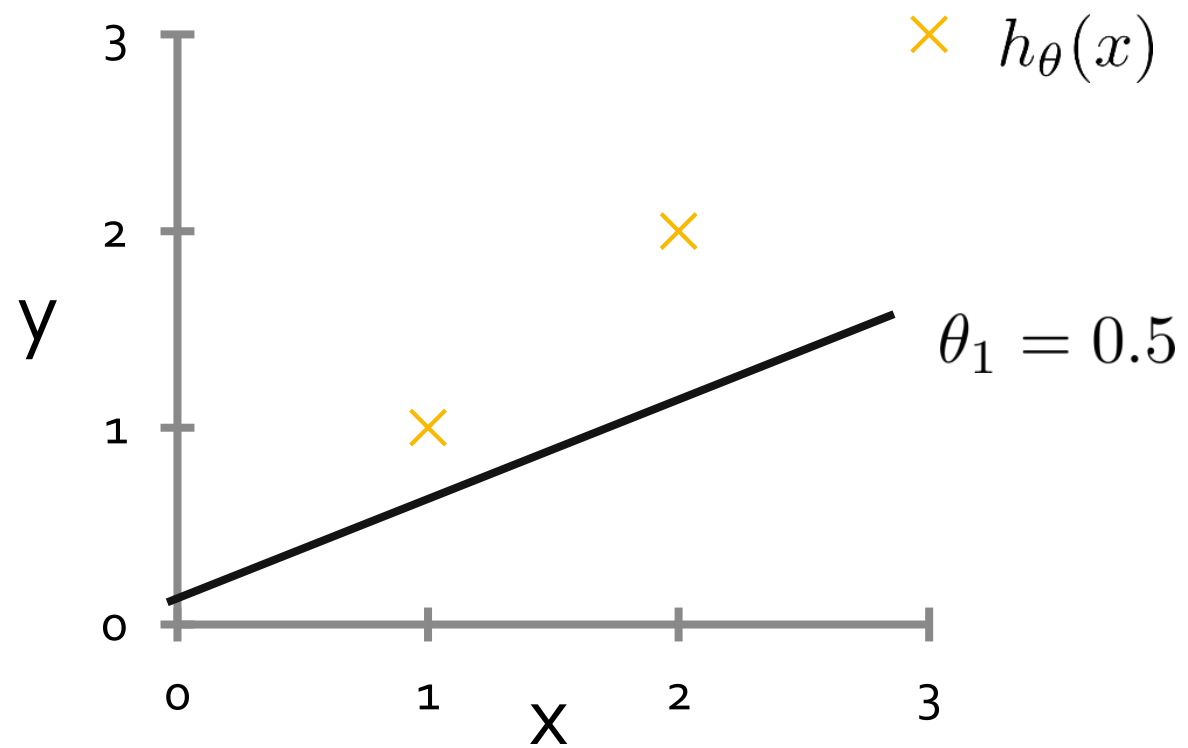
(for fixed  $\theta_1$ , this is a function of  $x$ )





$$h_{\theta}(x)$$

(for fixed  $\theta_1$  this is a function of  $x$ )



Hypothesis:  $h_{\theta}(x) = \theta_0 + \theta_1 x$

Parameters:  $\theta_0, \theta_1$

Cost Function:  $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$

Goal:  $\underset{\theta_0, \theta_1}{\text{minimize}} J(\theta_0, \theta_1)$

FOR A GIVEN  
THETA 0 AND THETA 1...

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^i) - y^i)^2$$

4. FIND THE  
AVERAGE

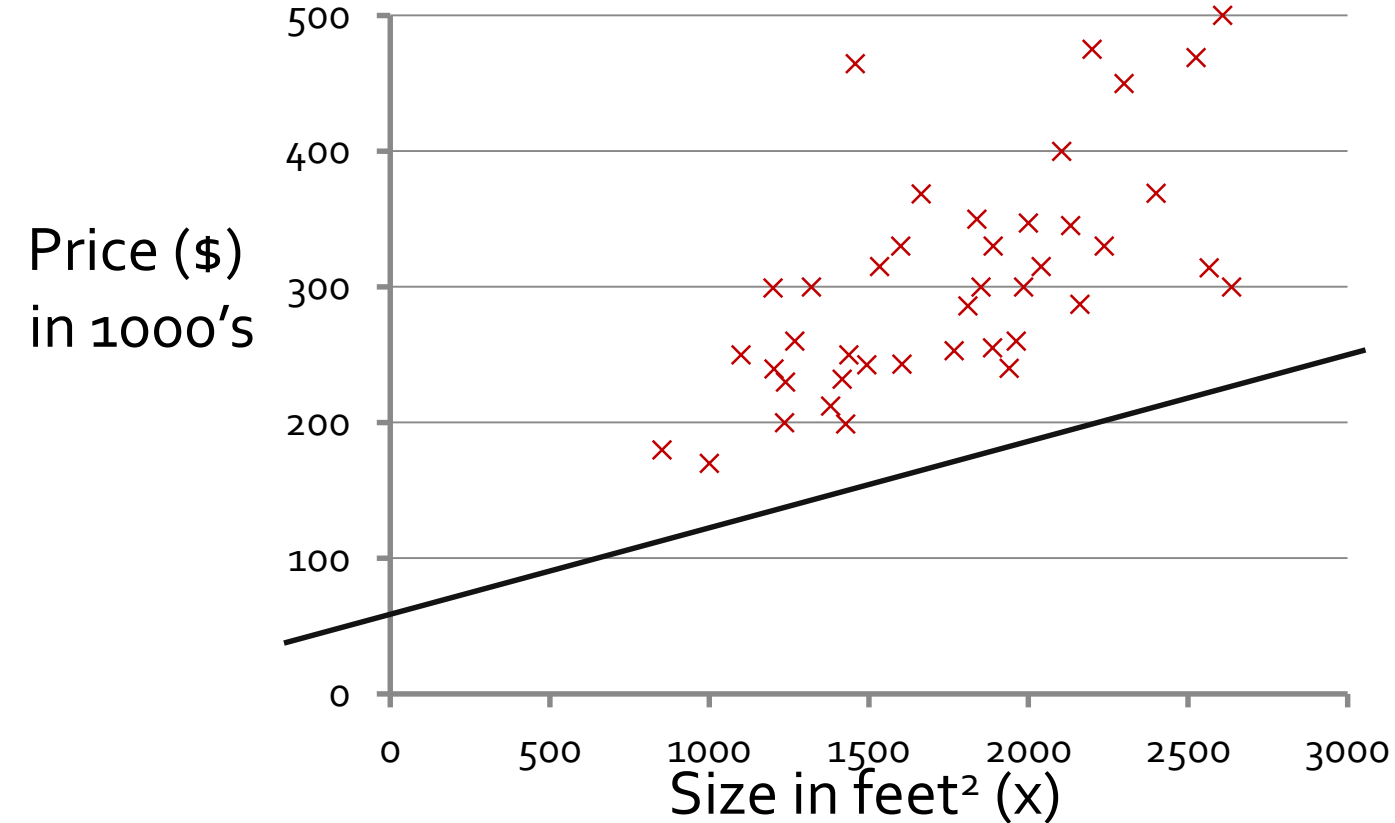
2. FIND THE DIFFERENCE  
BETWEEN THE PREDICTED  
AND ACTUAL VALUES

1. THE PREDICTED  
VALUE

3. FIND **ALL** THE DIFFERENCES  
BETWEEN PREDICTED AND ACTUAL

$$h_{\theta}(x)$$

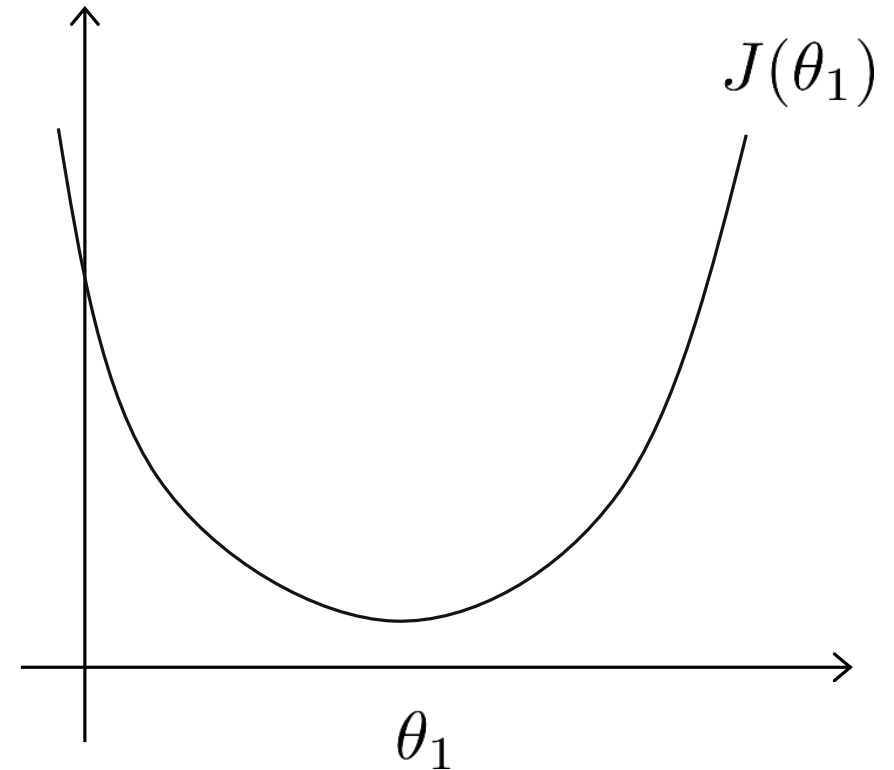
(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )

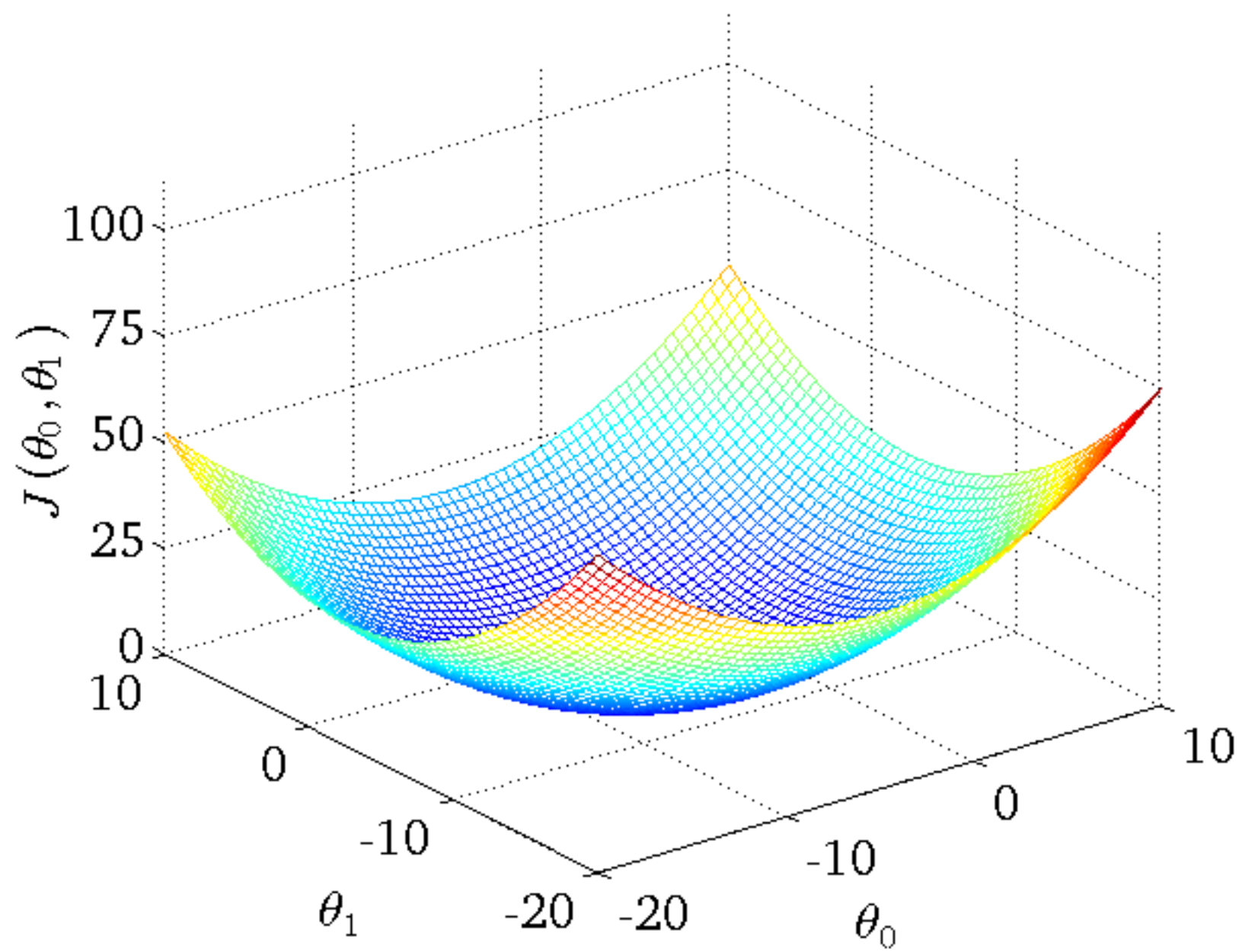


$$h_{\theta}(x) = 50 + 0.06x$$

$$J(\theta_0, \theta_1)$$

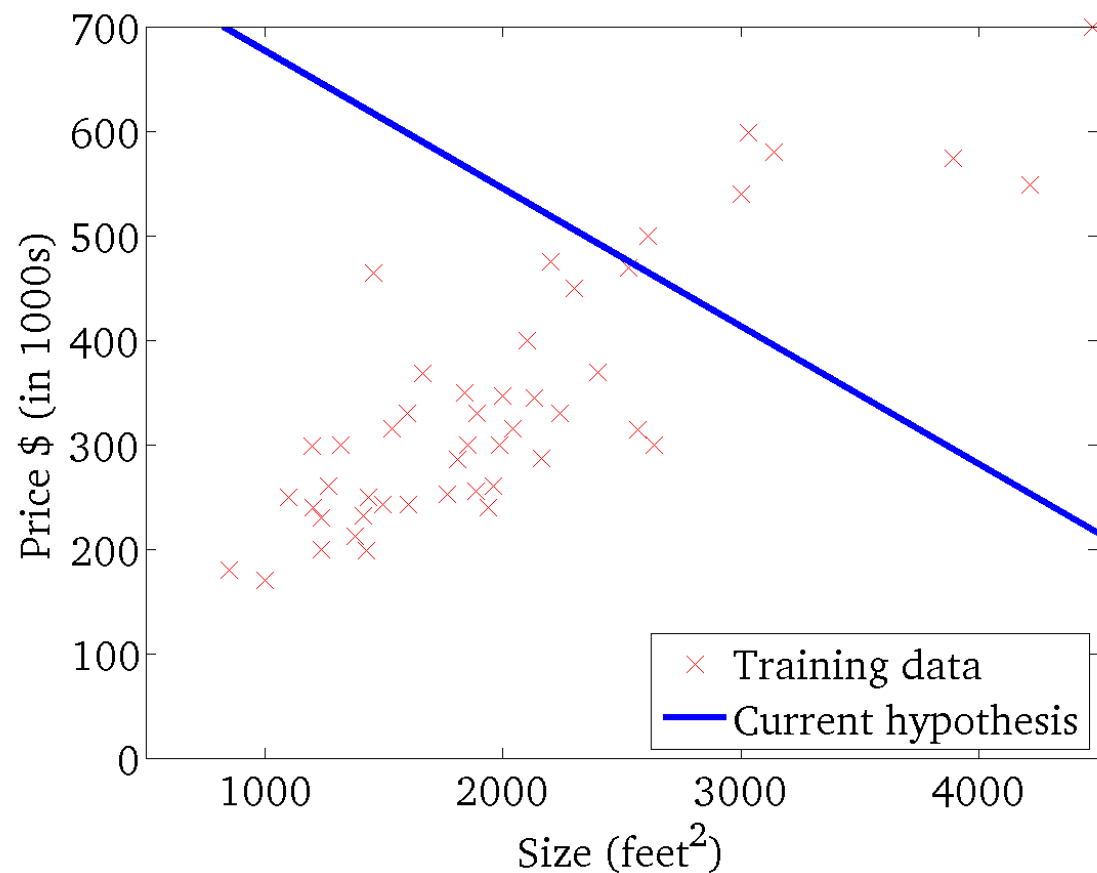
(function of the parameters  $\theta_0, \theta_1$ )





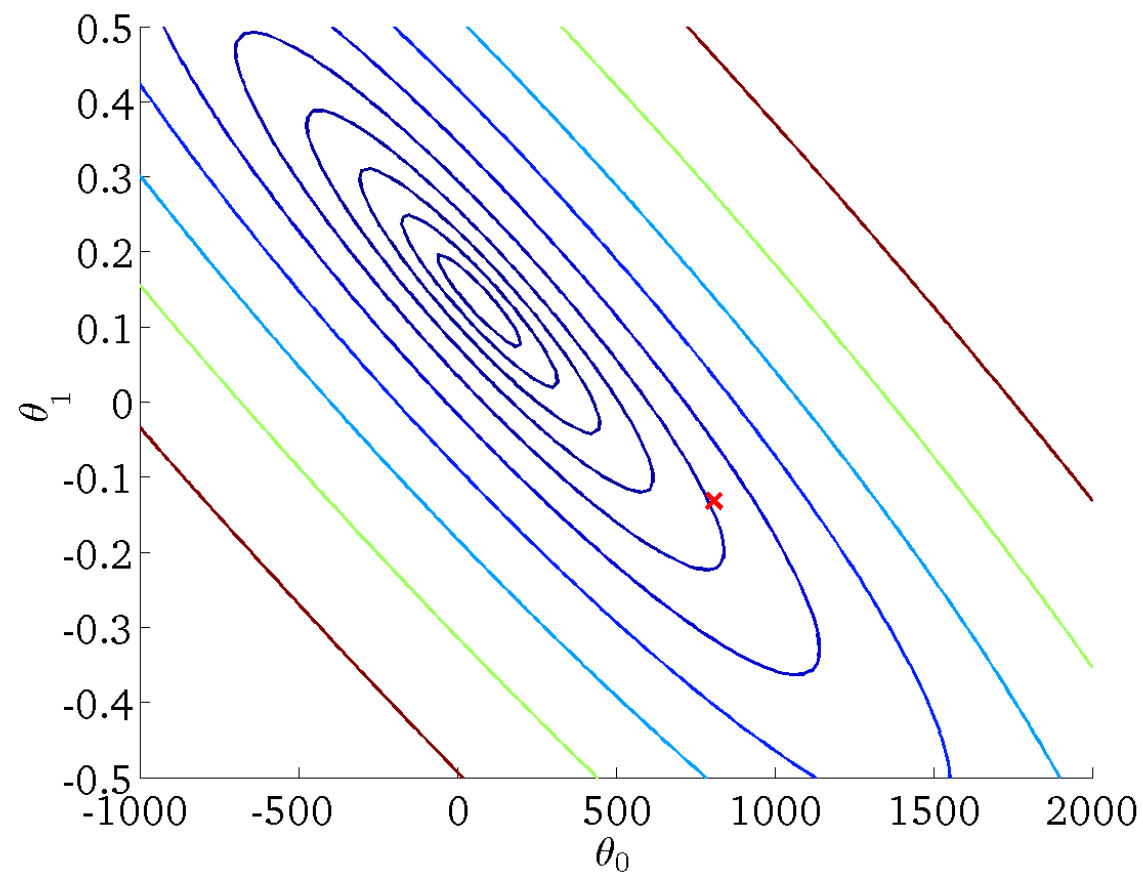
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



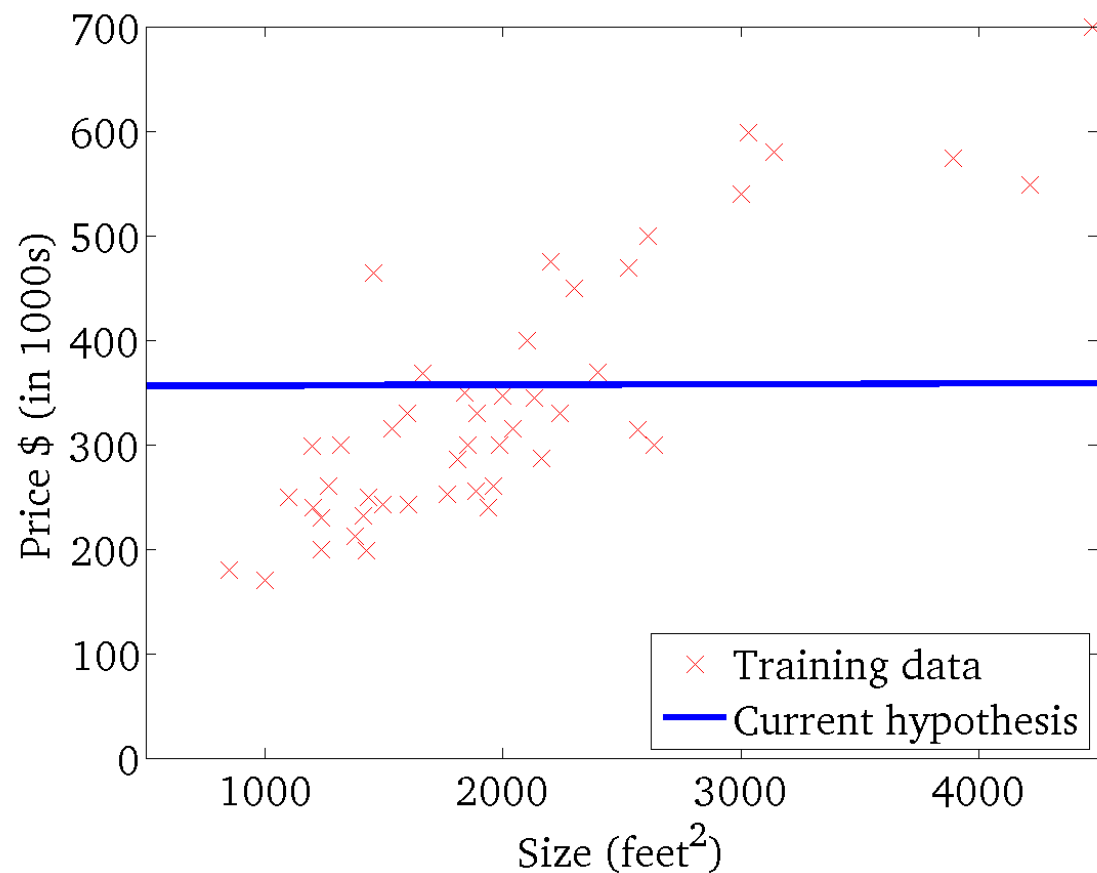
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



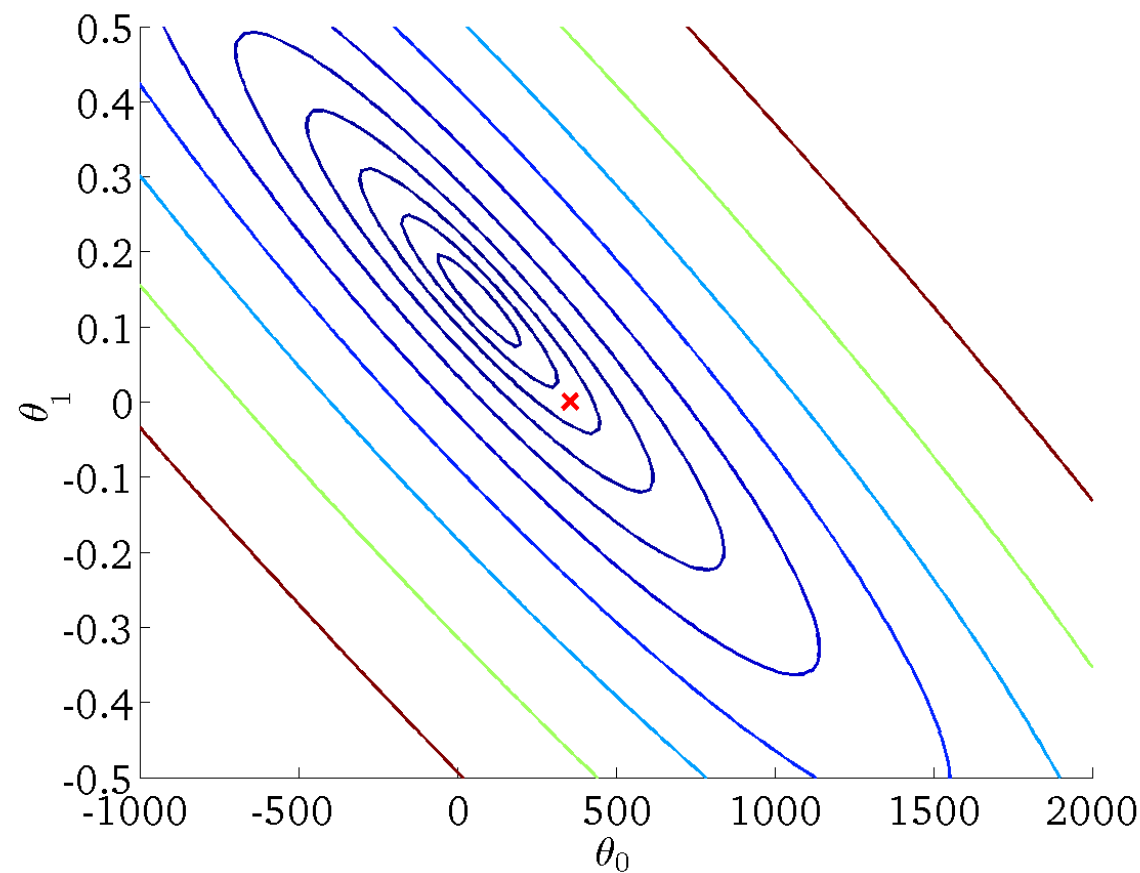
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



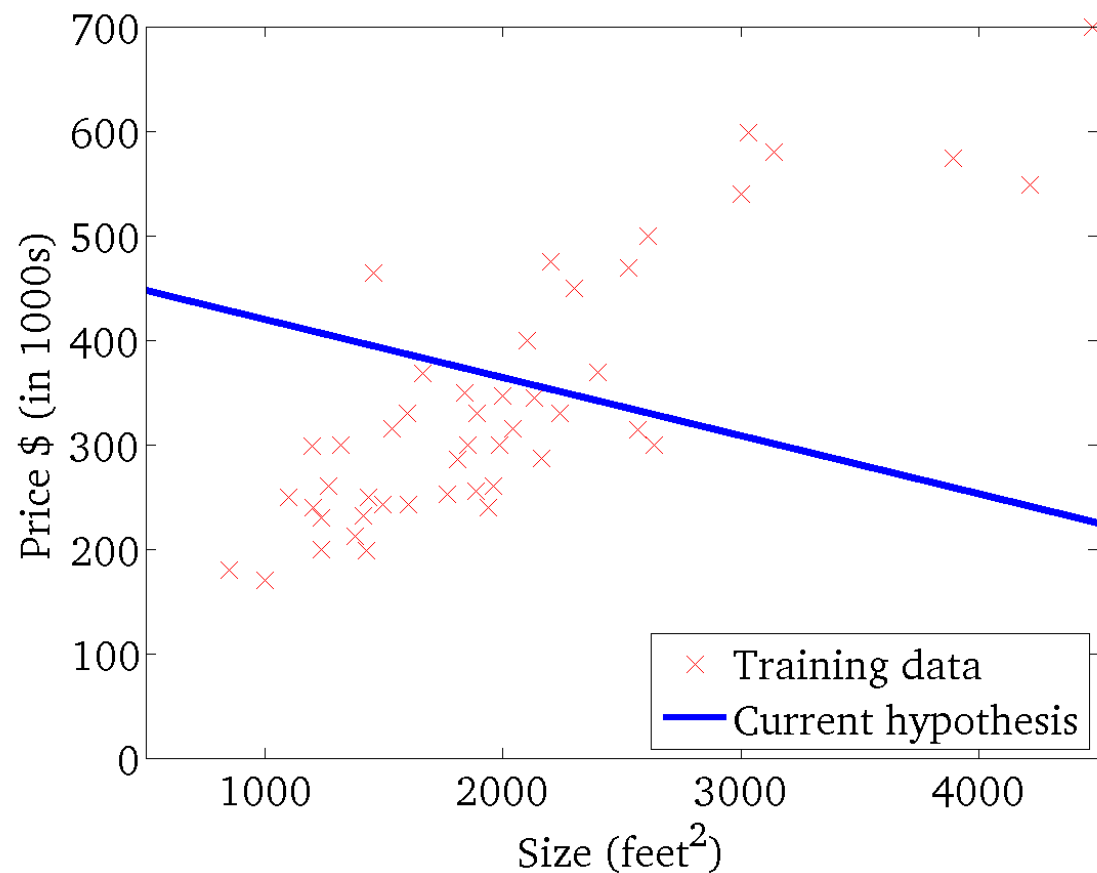
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



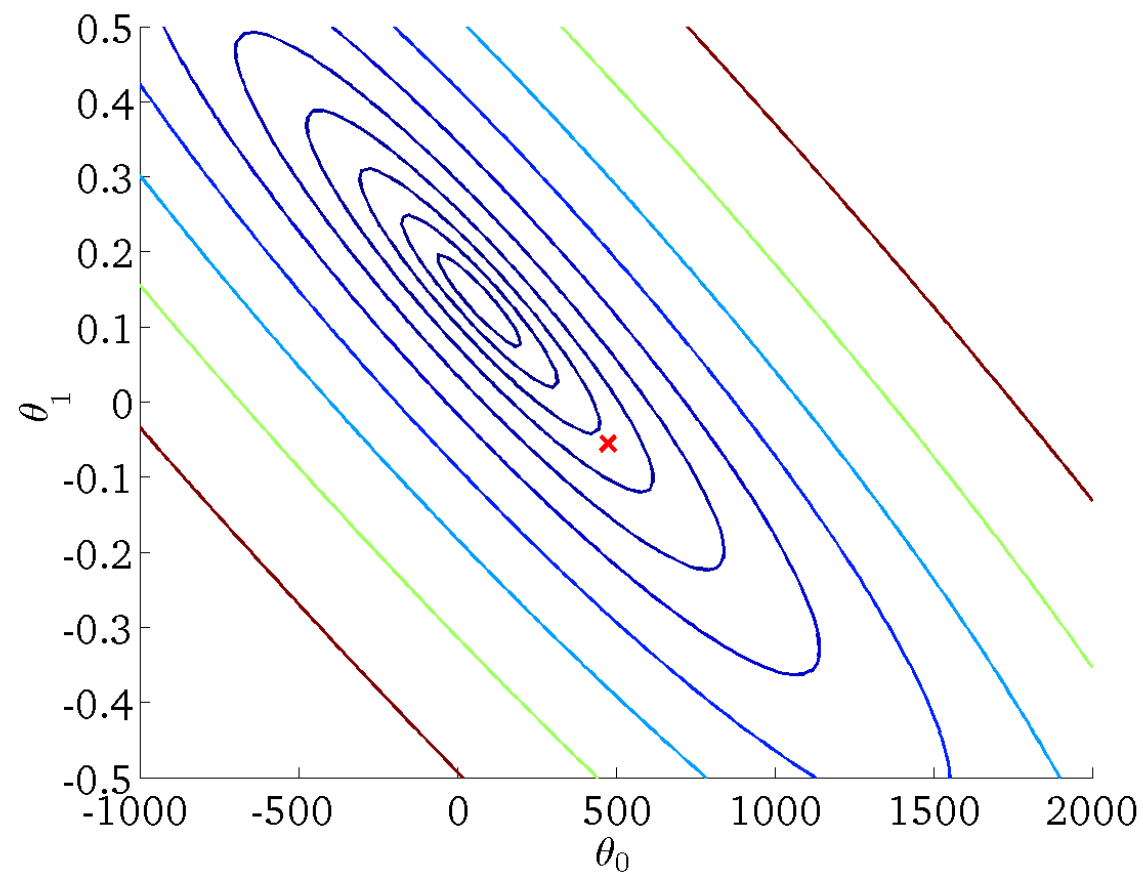
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

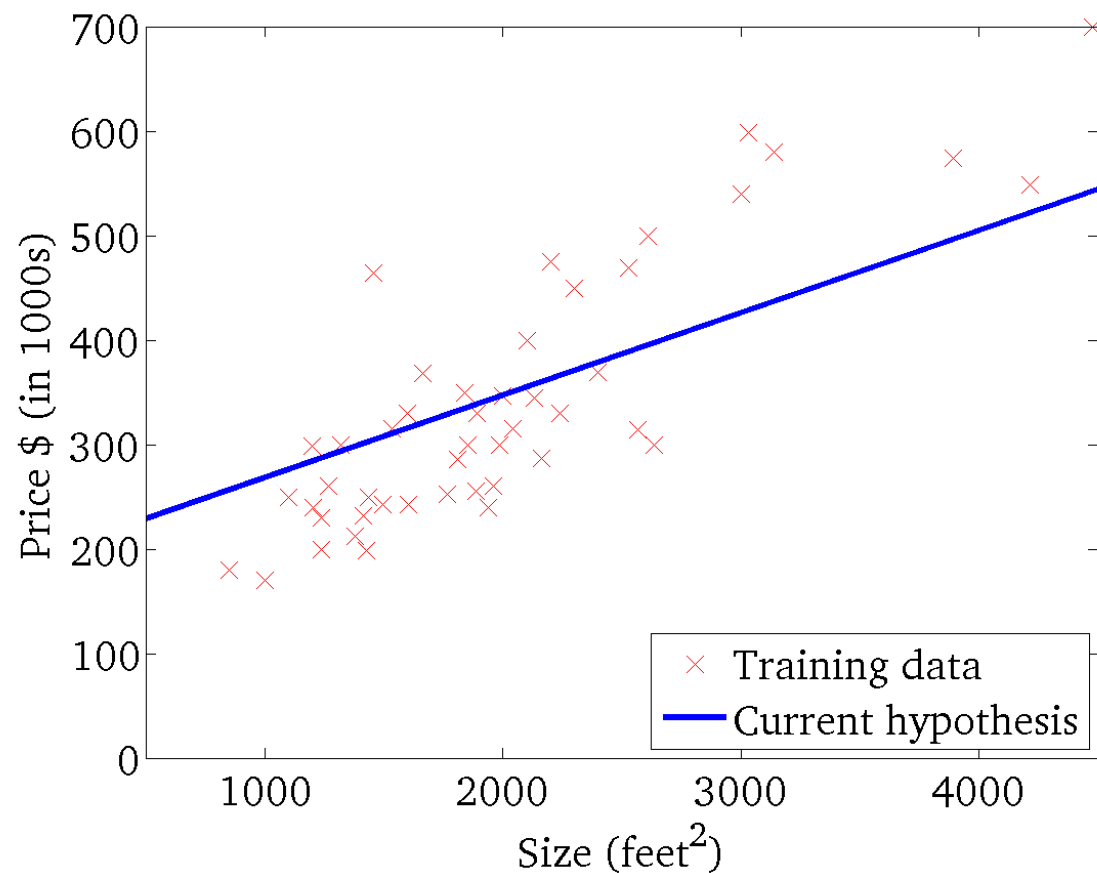
(function of the parameters  $\theta_0, \theta_1$ )





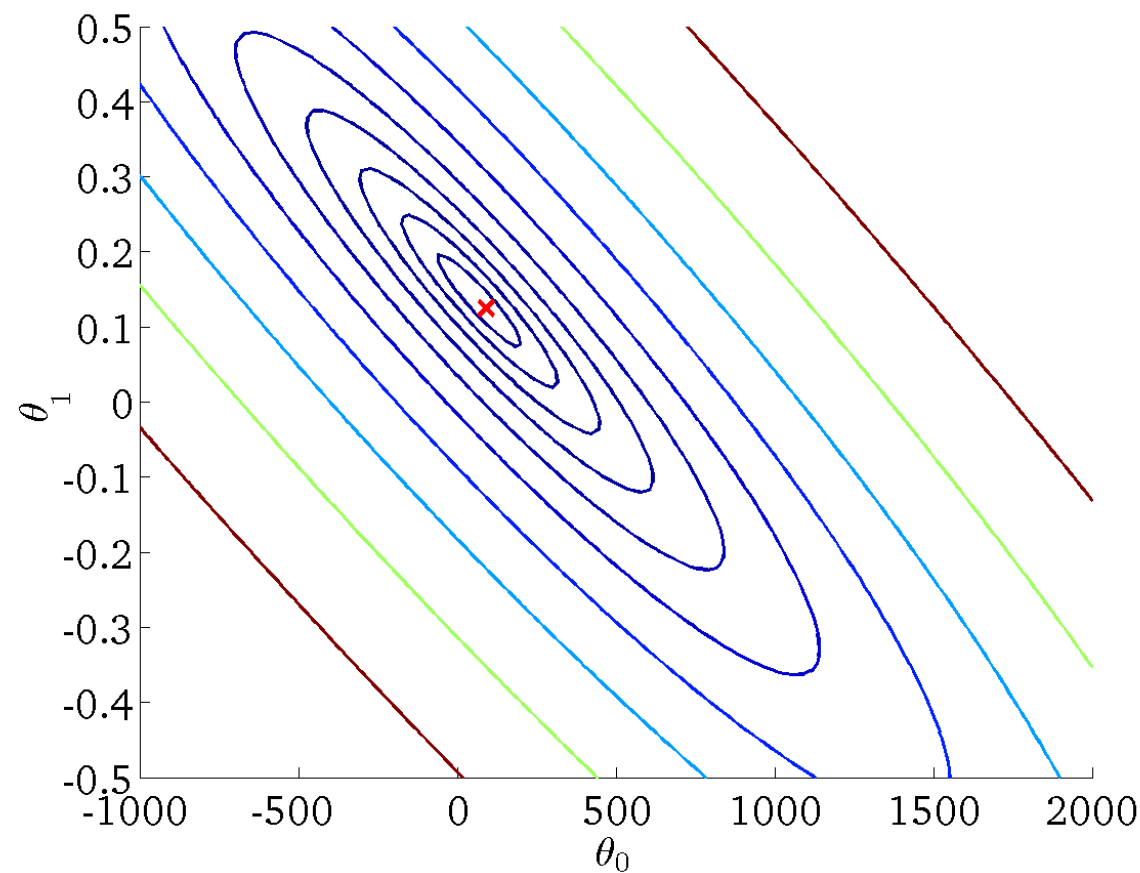
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



Linear regression  
with one variable

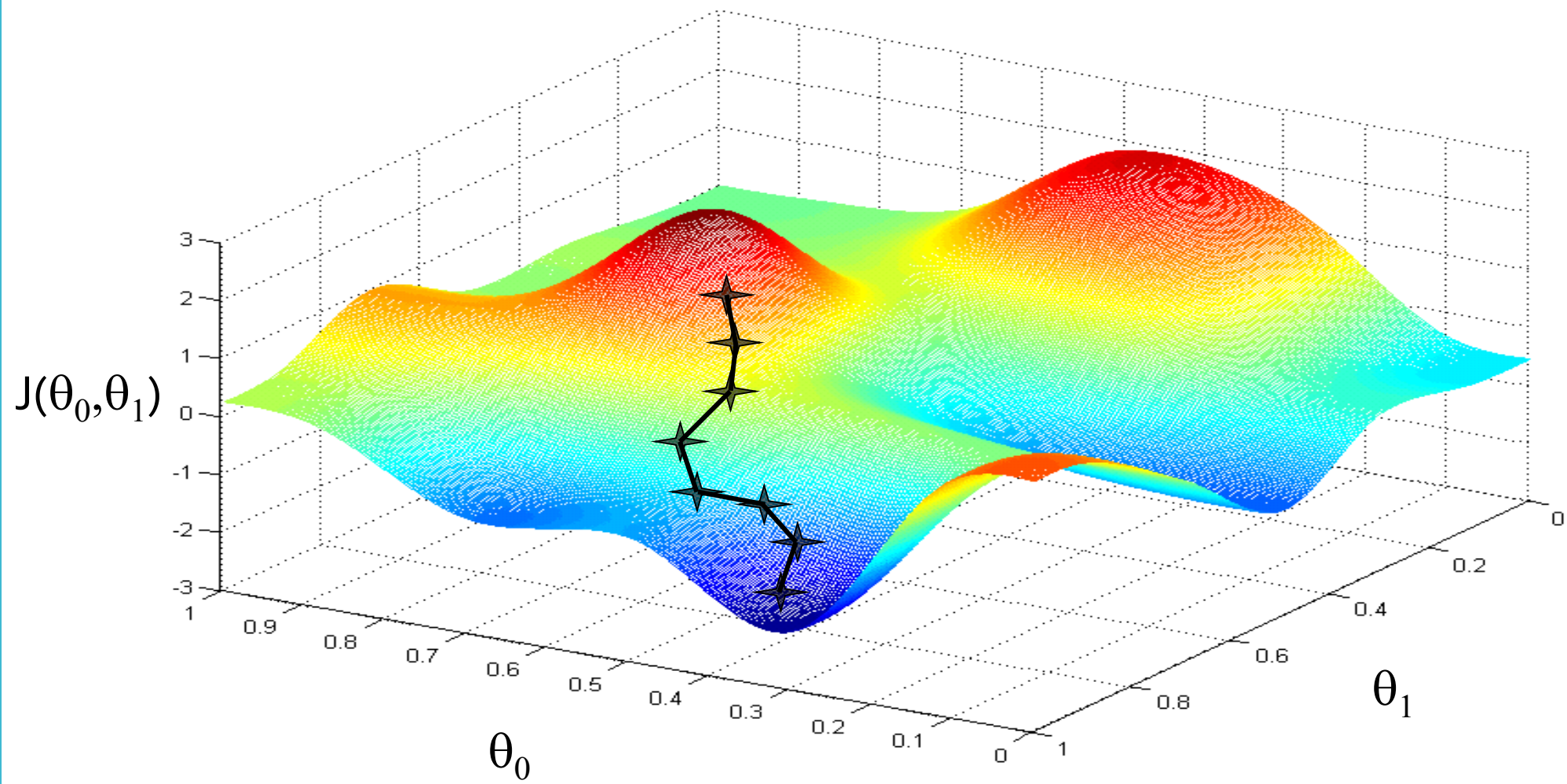
Gradient  
descent

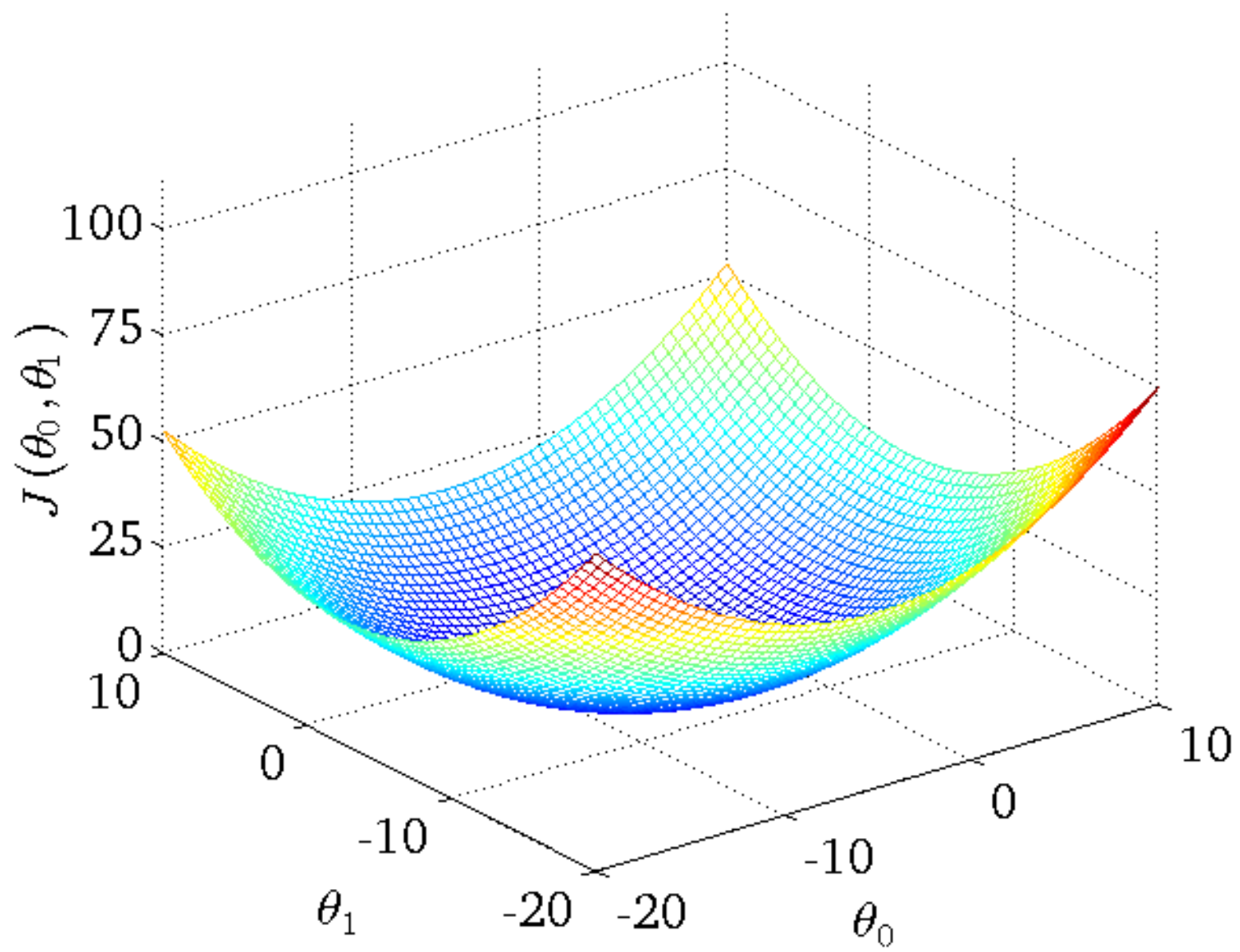
Have some function  $J(\theta_0, \theta_1)$

Want  $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$

## Outline:

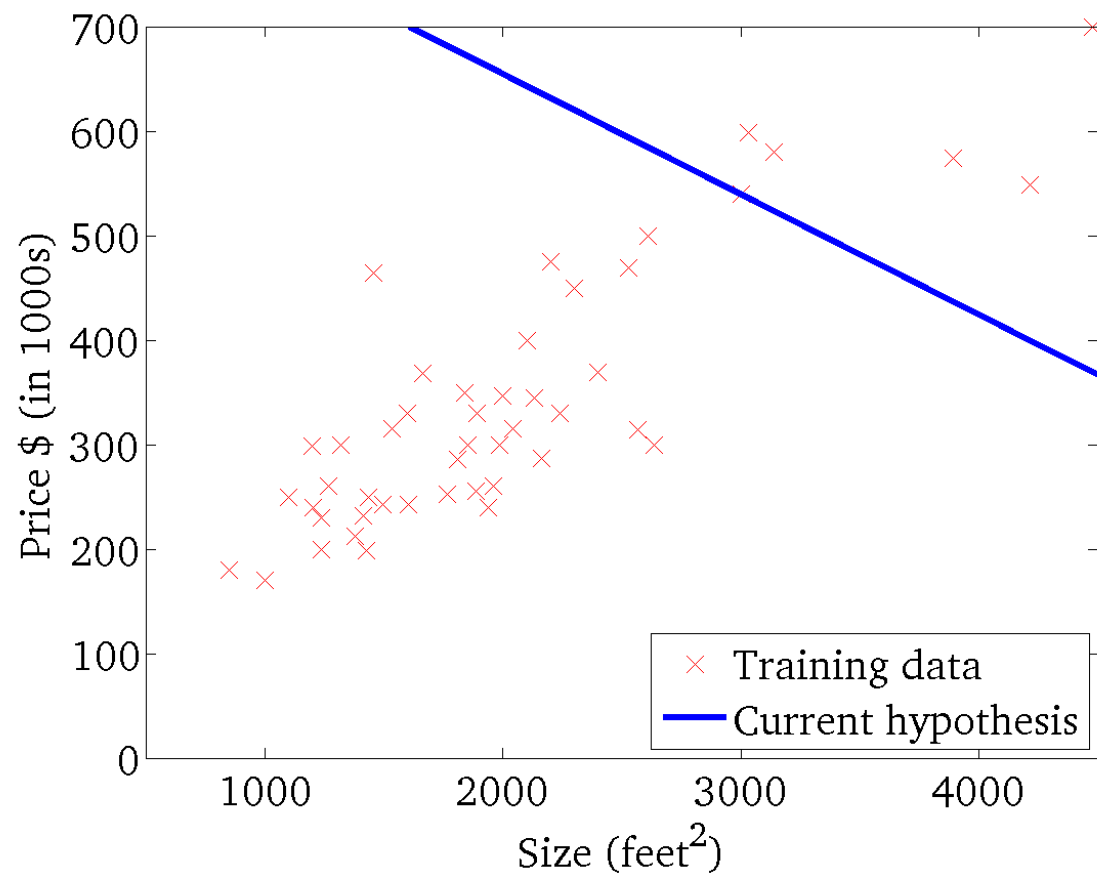
- Start with some  $\theta_0, \theta_1$
- Keep changing  $\theta_0, \theta_1$  to reduce  $J(\theta_0, \theta_1)$   
until we hopefully end up at a minimum





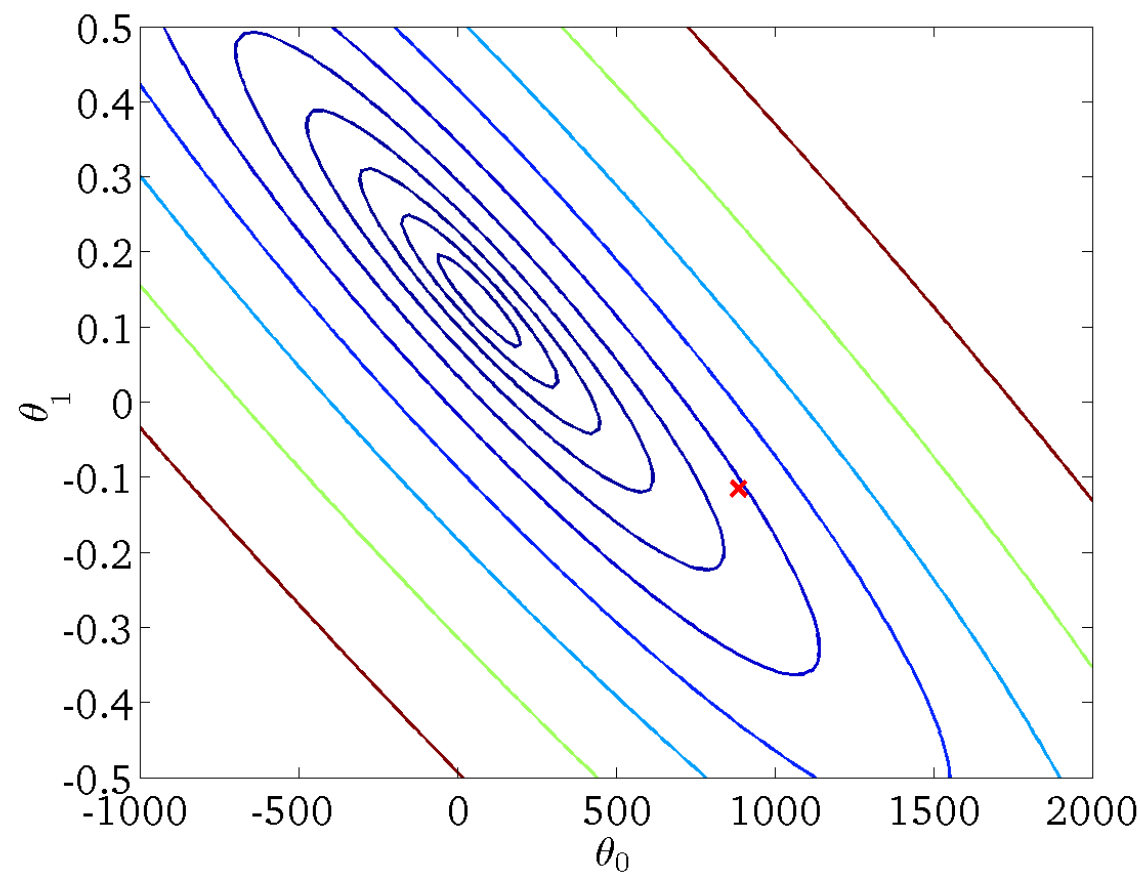
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



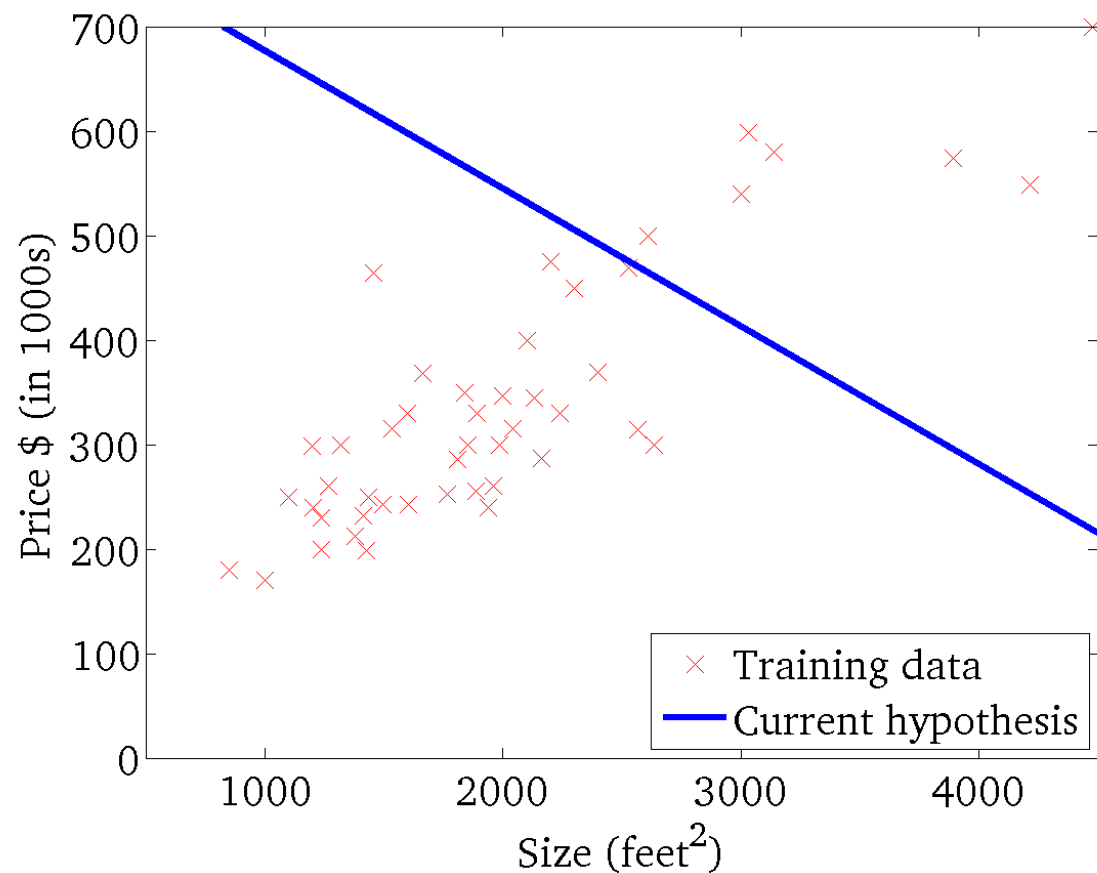
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



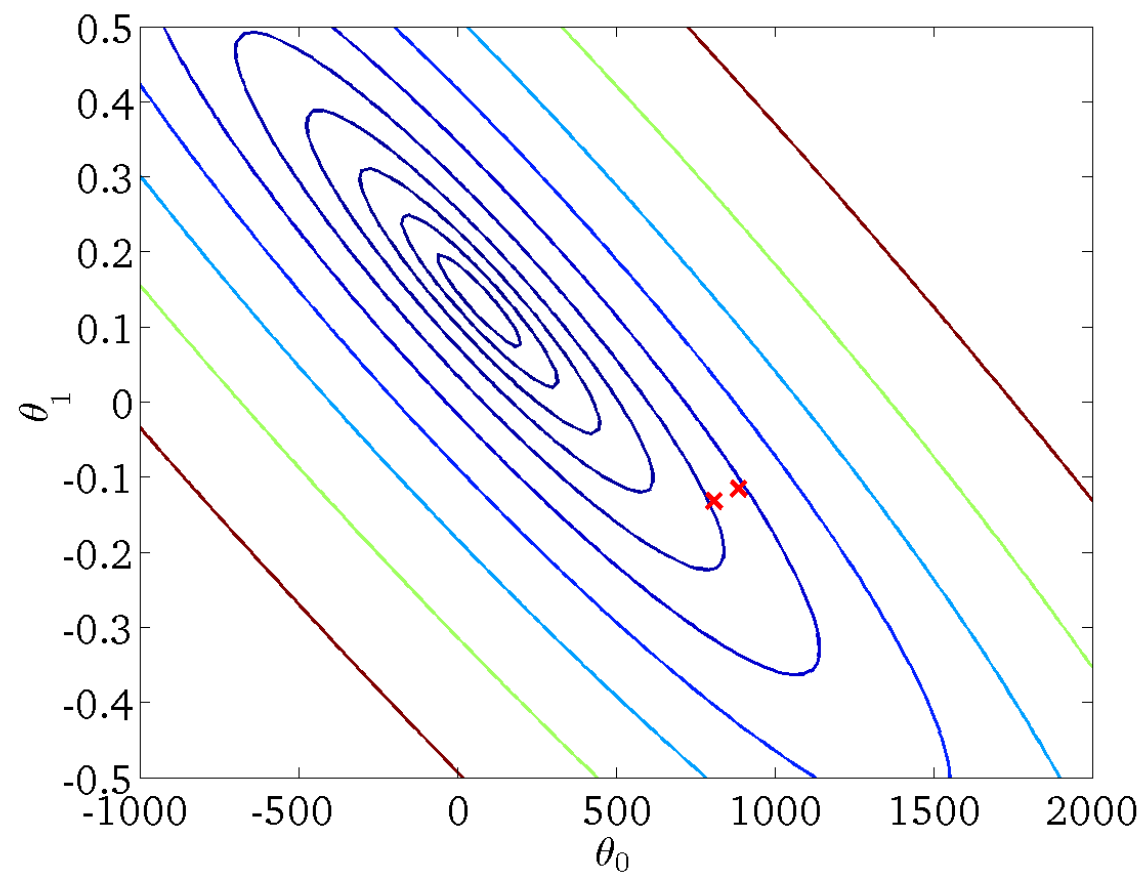
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



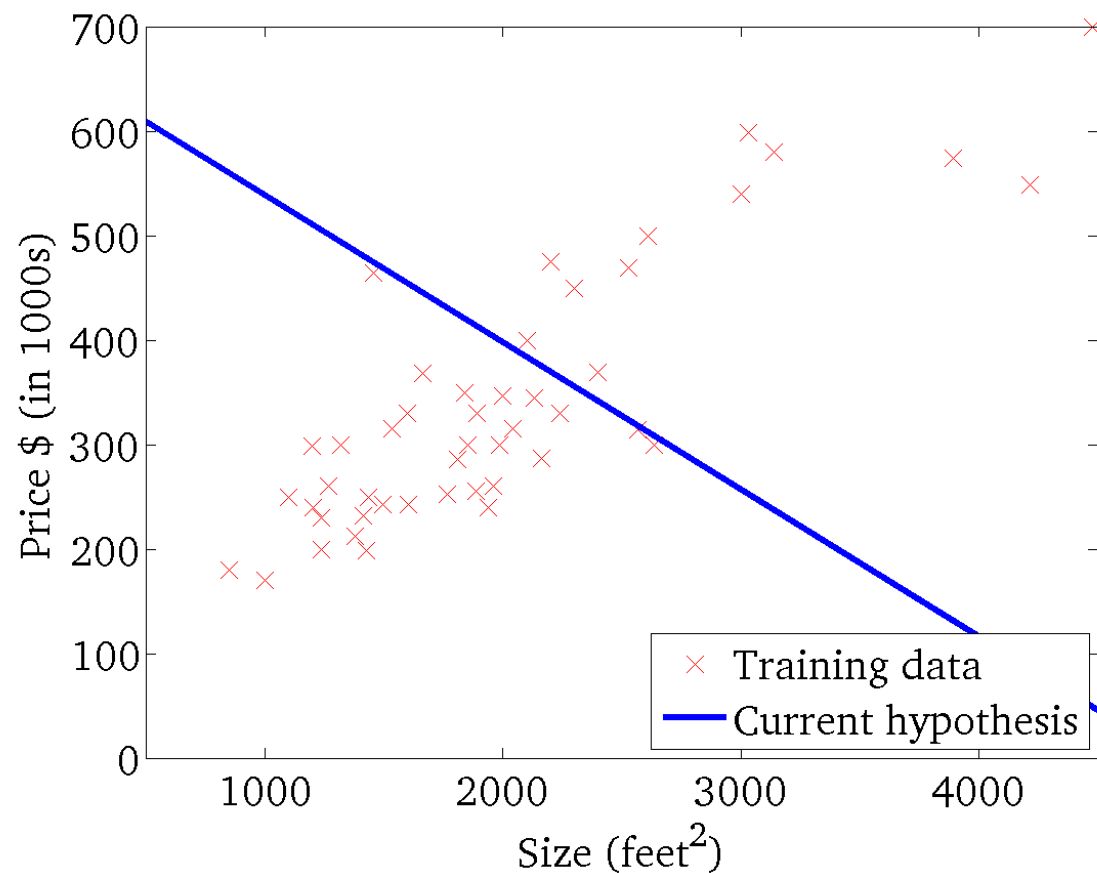
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



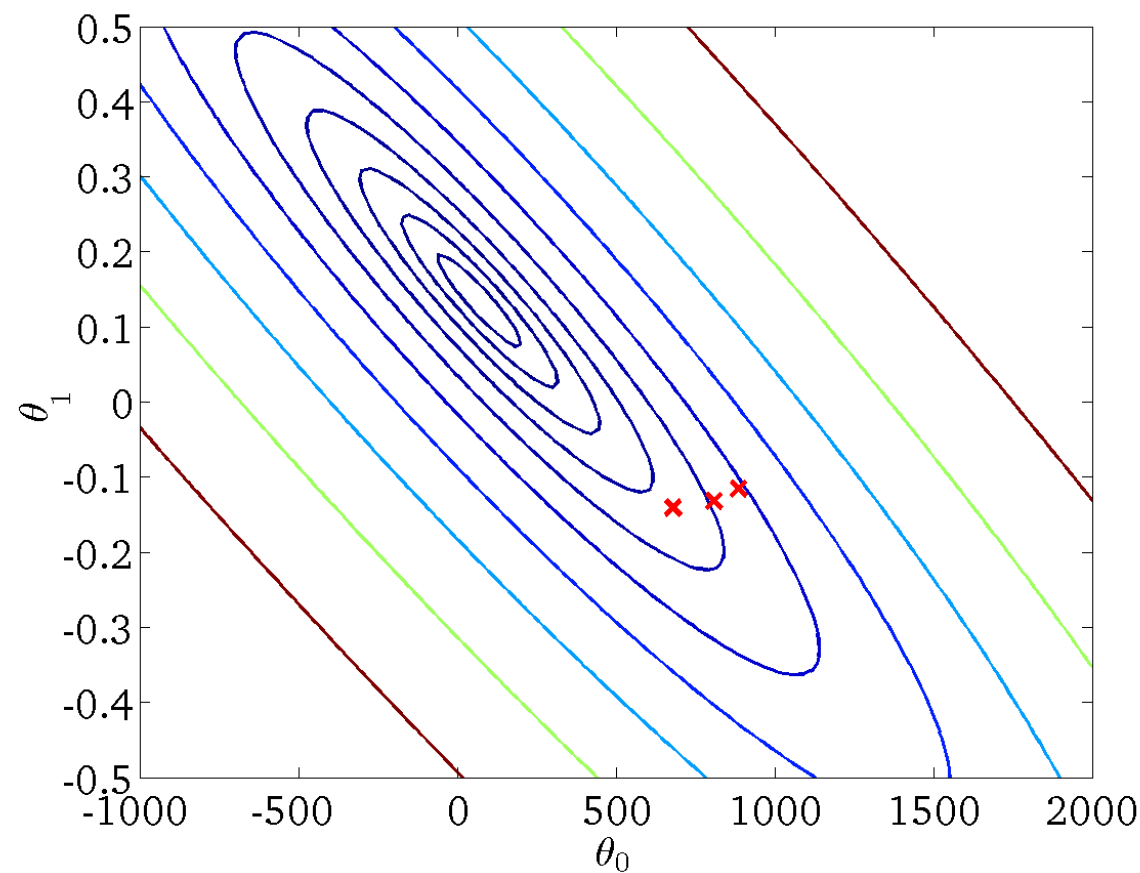
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

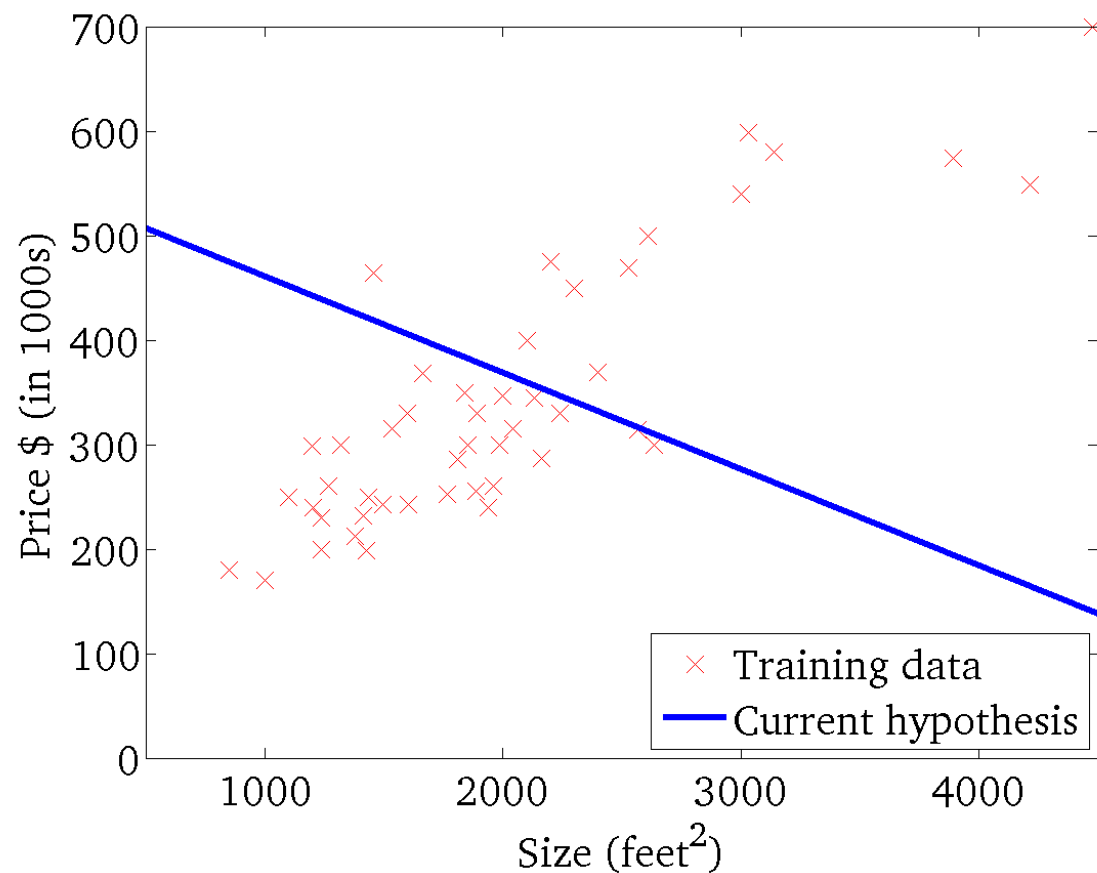
(function of the parameters  $\theta_0, \theta_1$ )





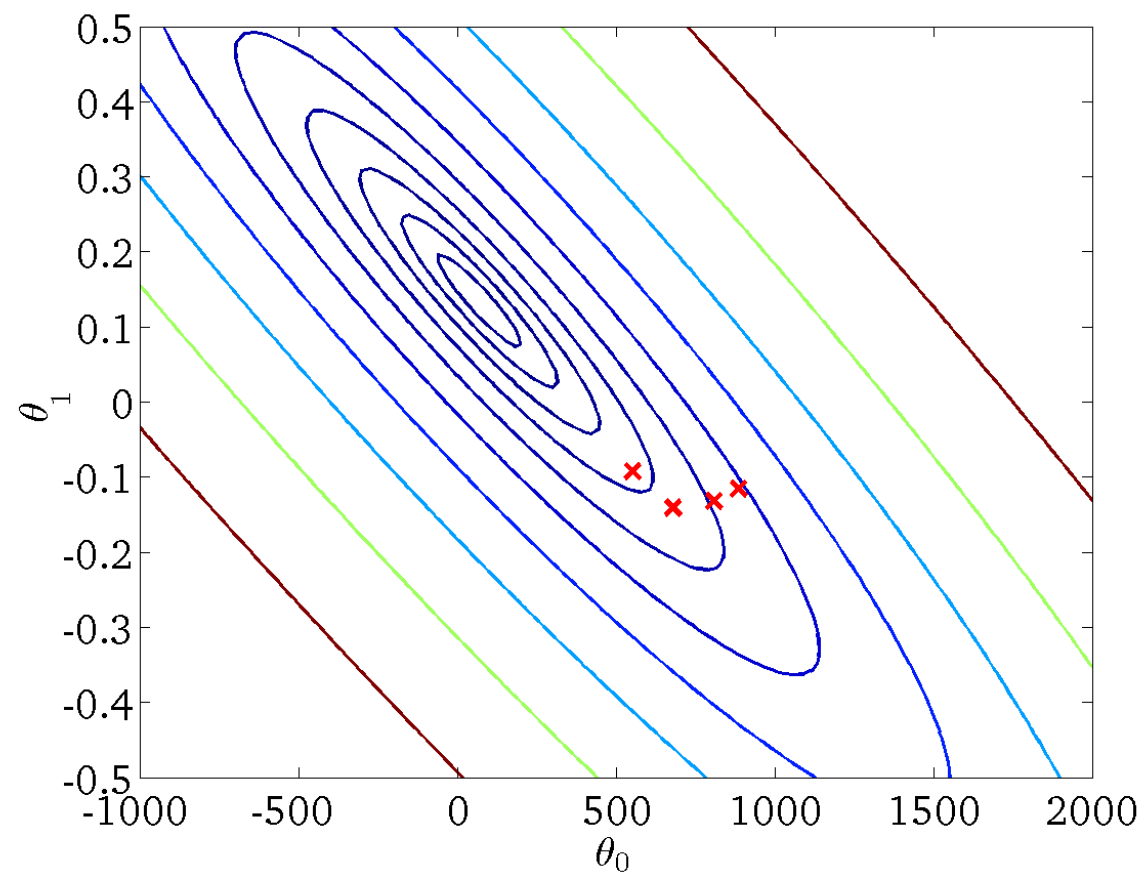
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



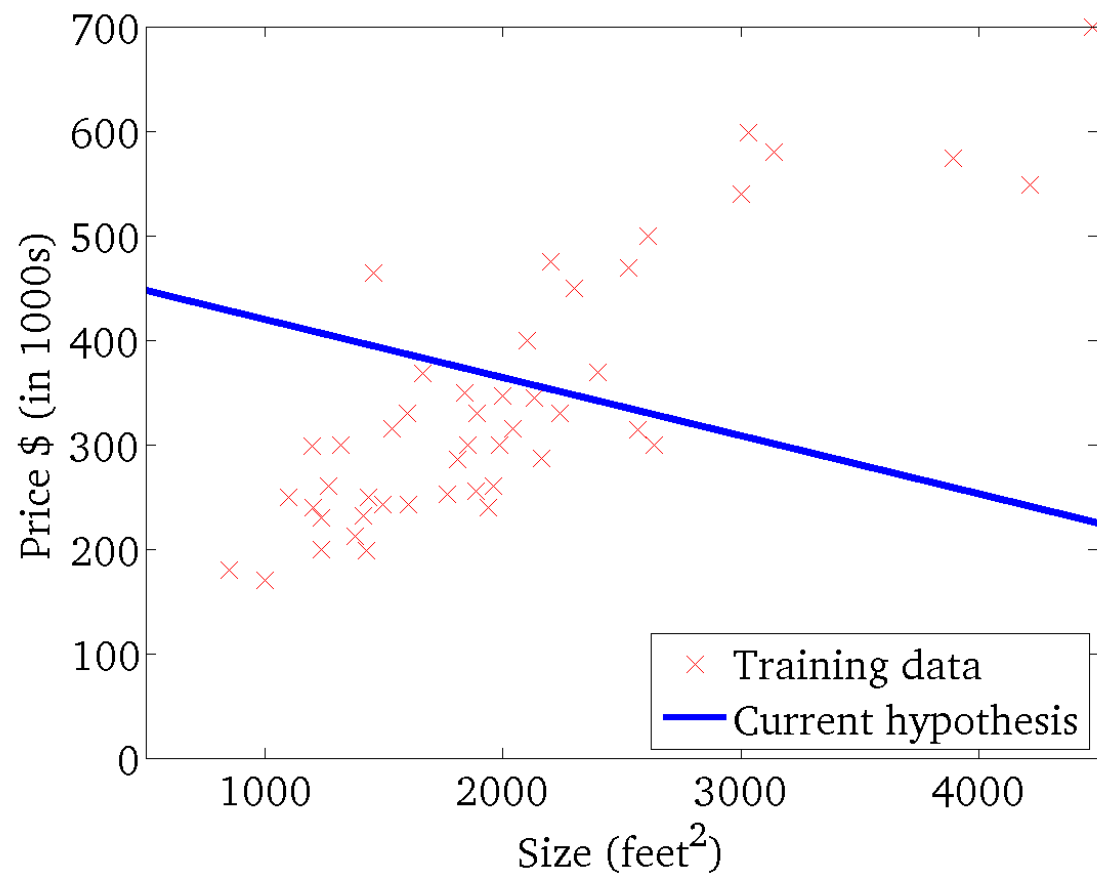
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



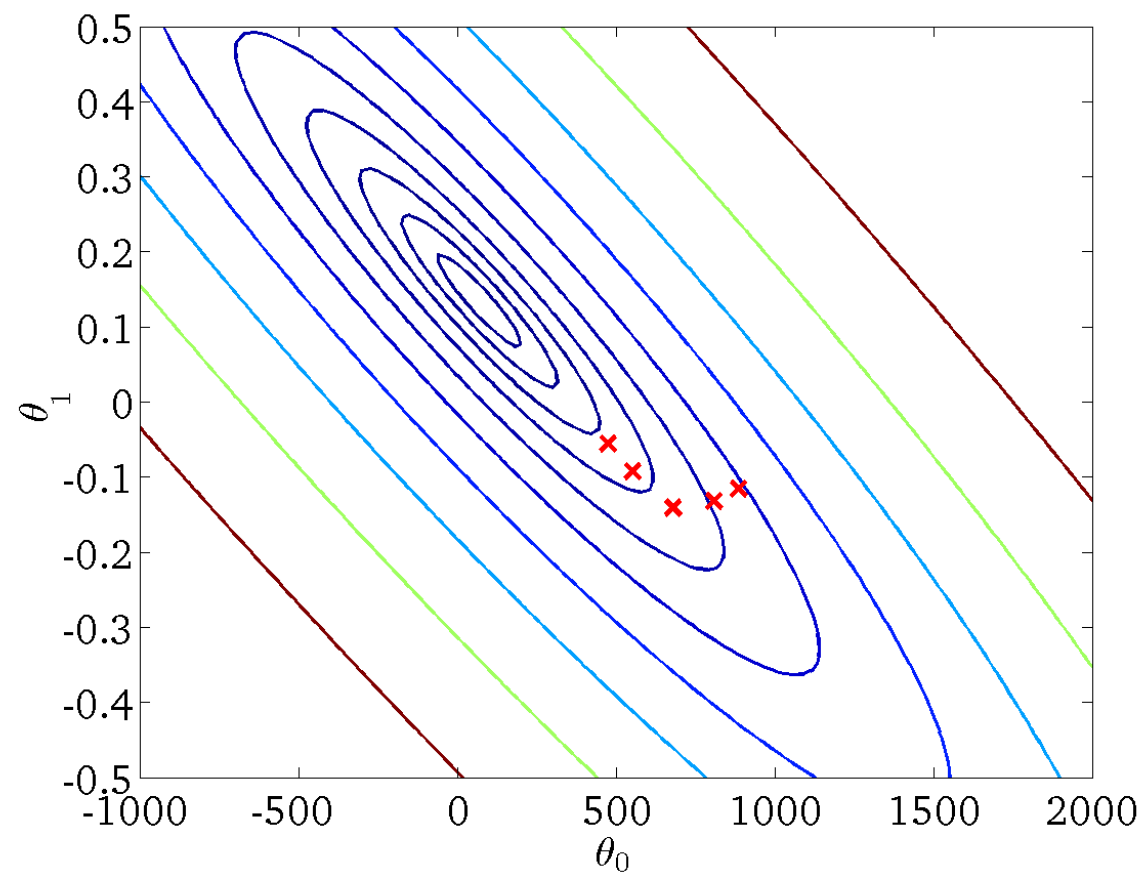
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



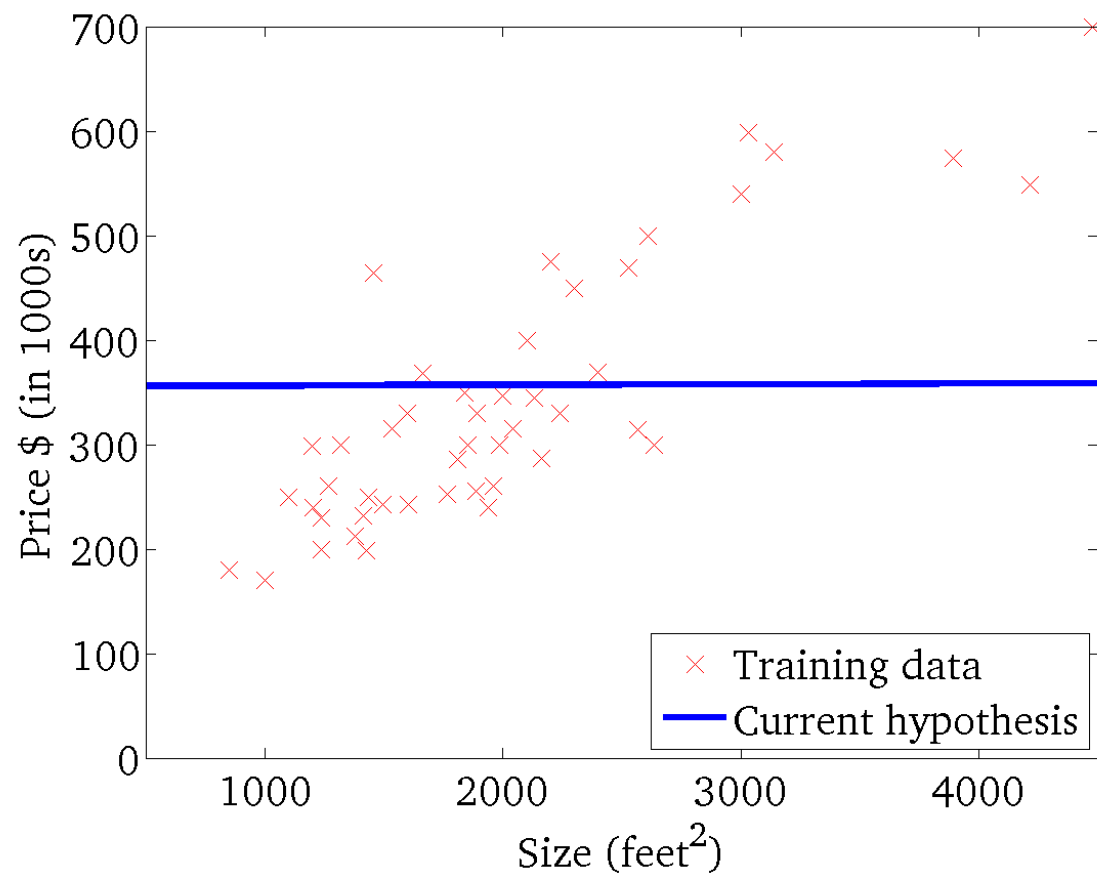
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



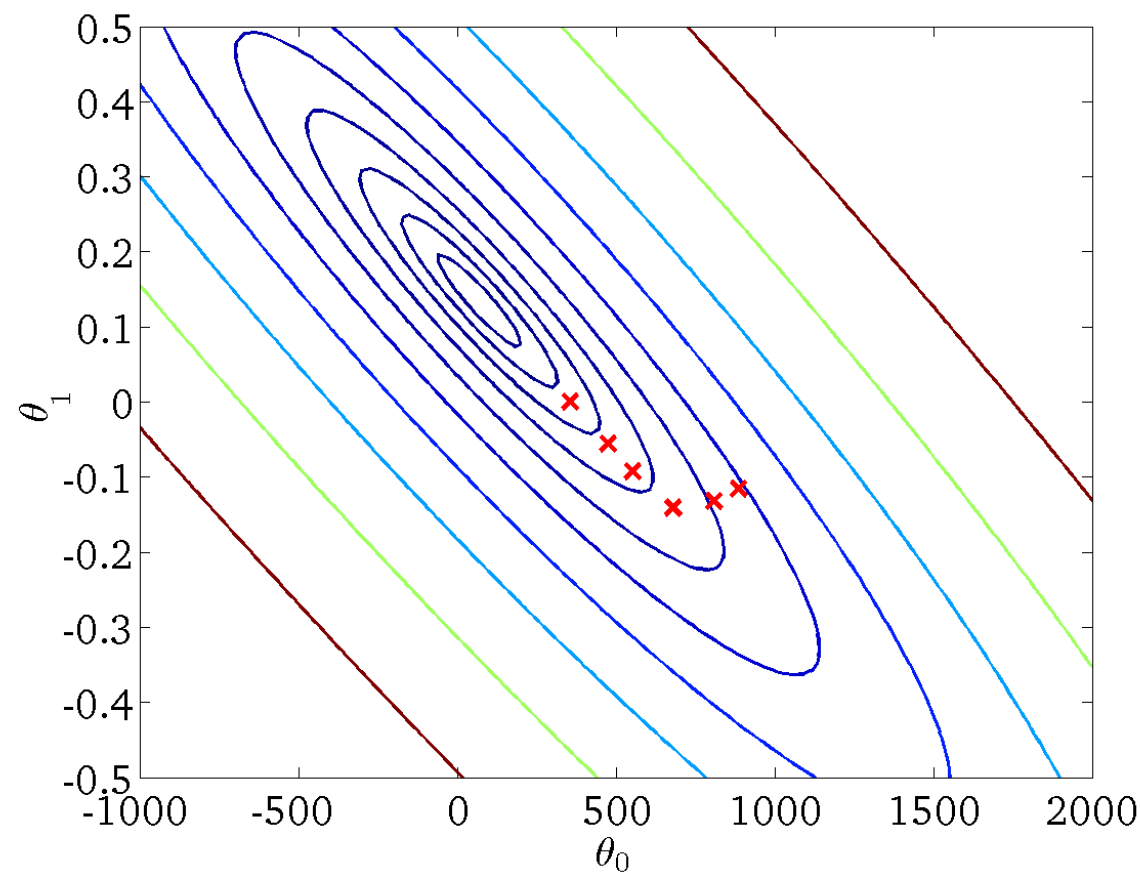
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



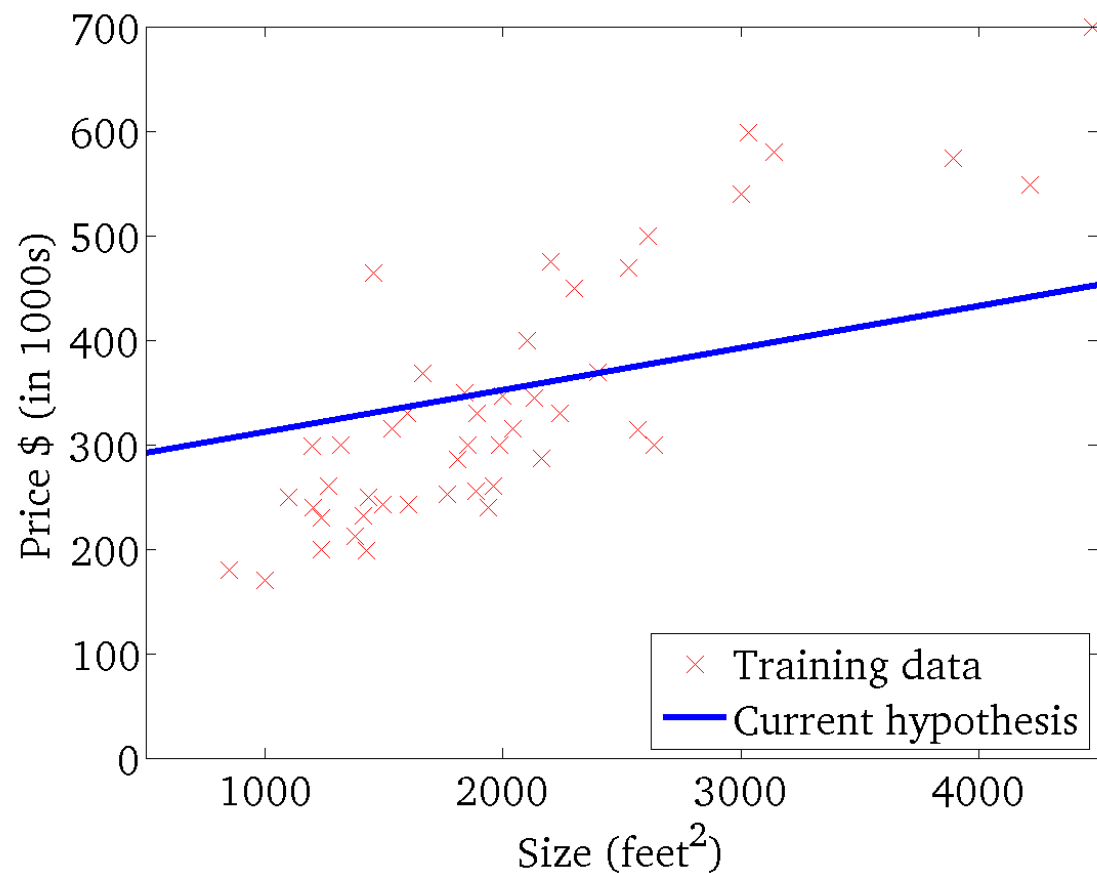
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



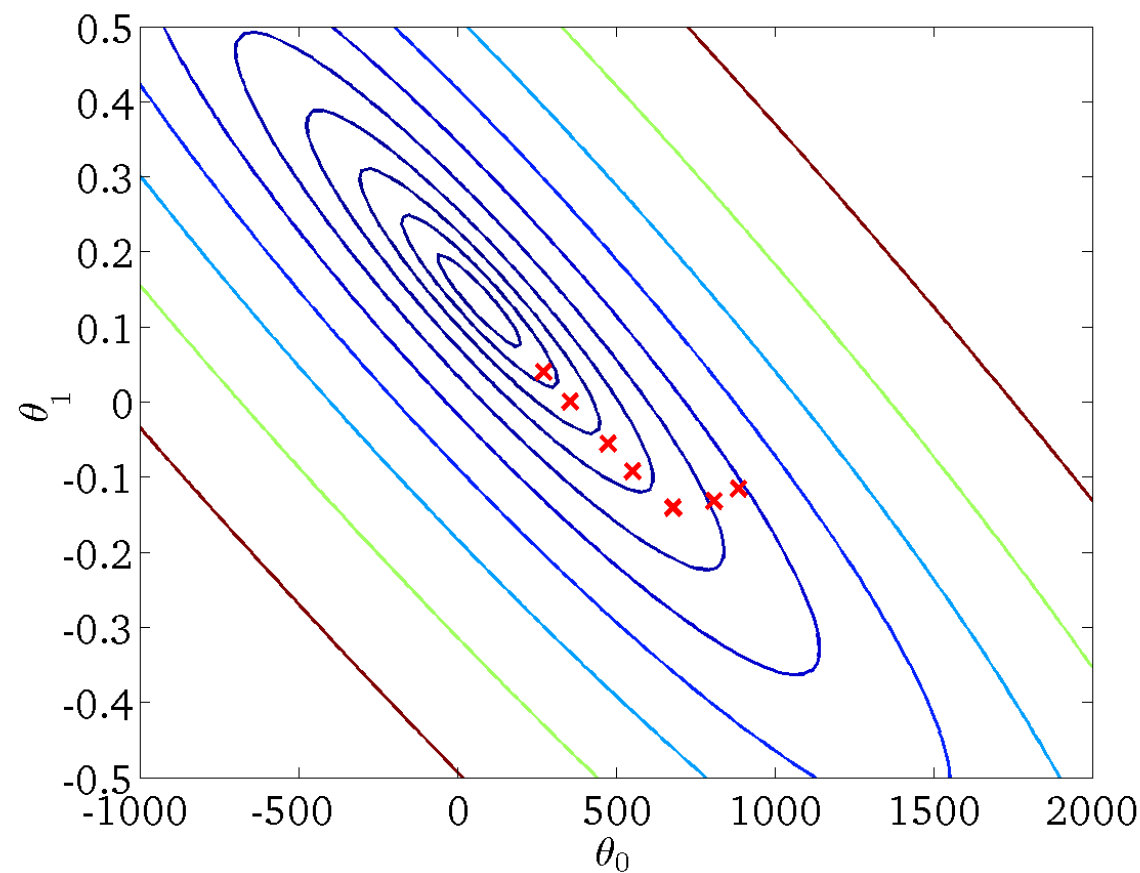
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



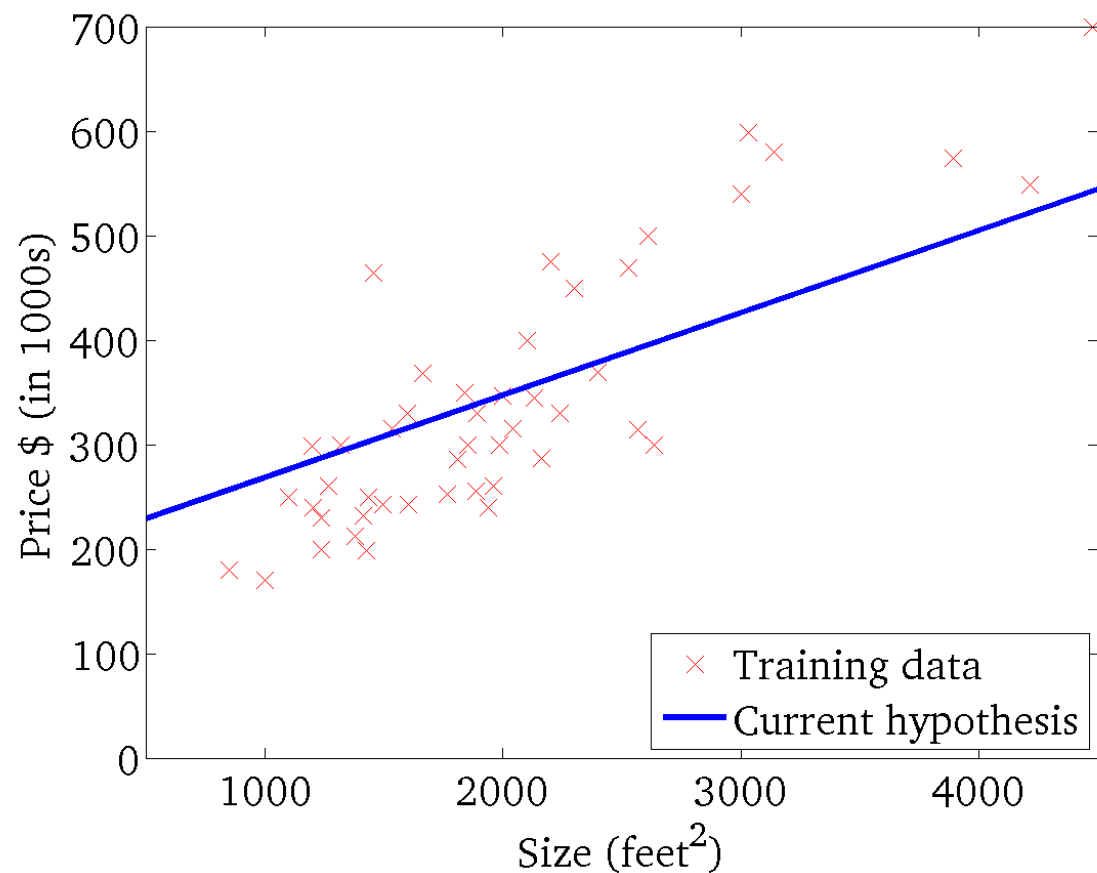
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



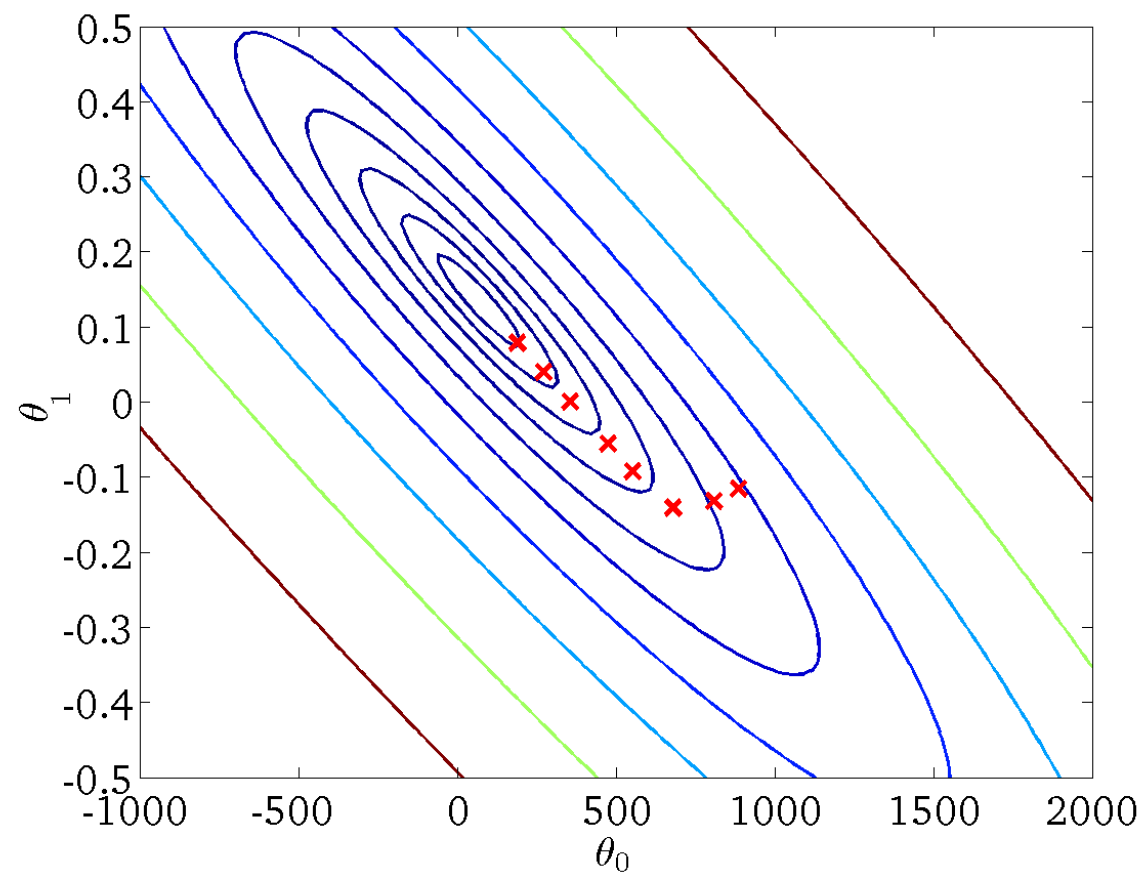
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



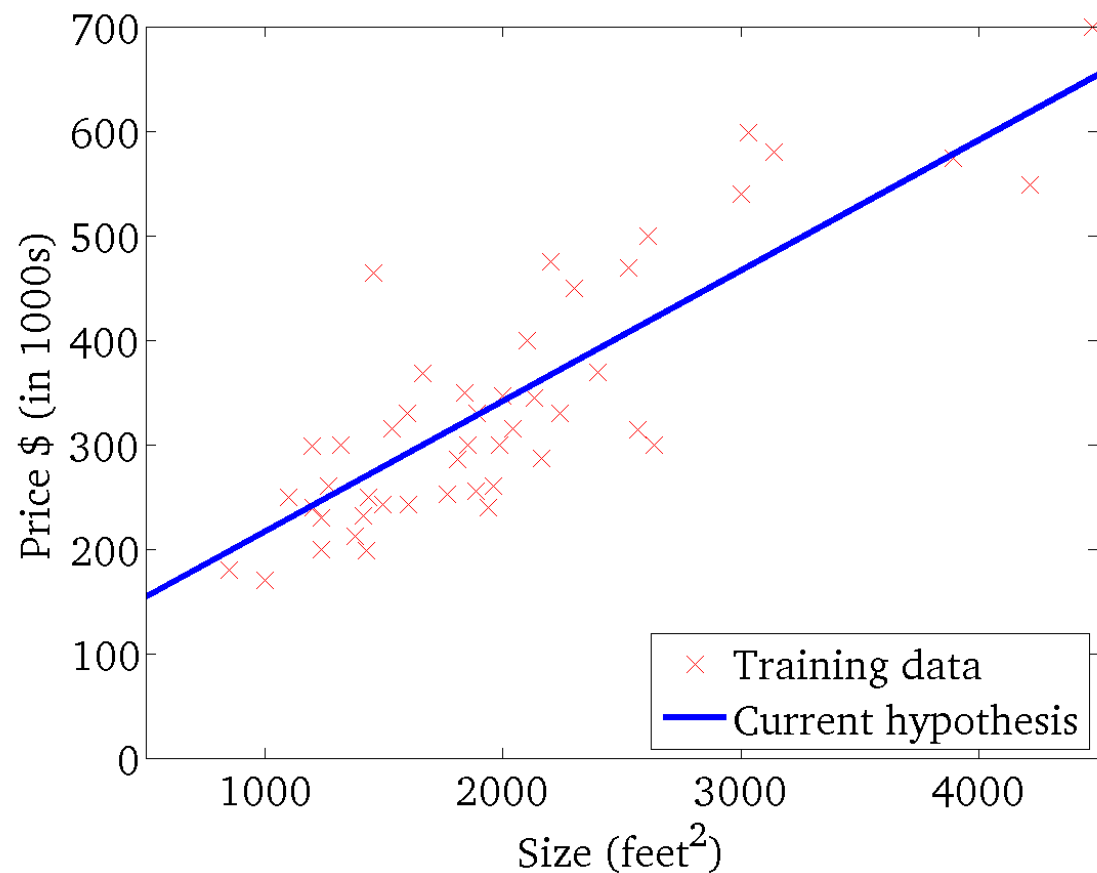
$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



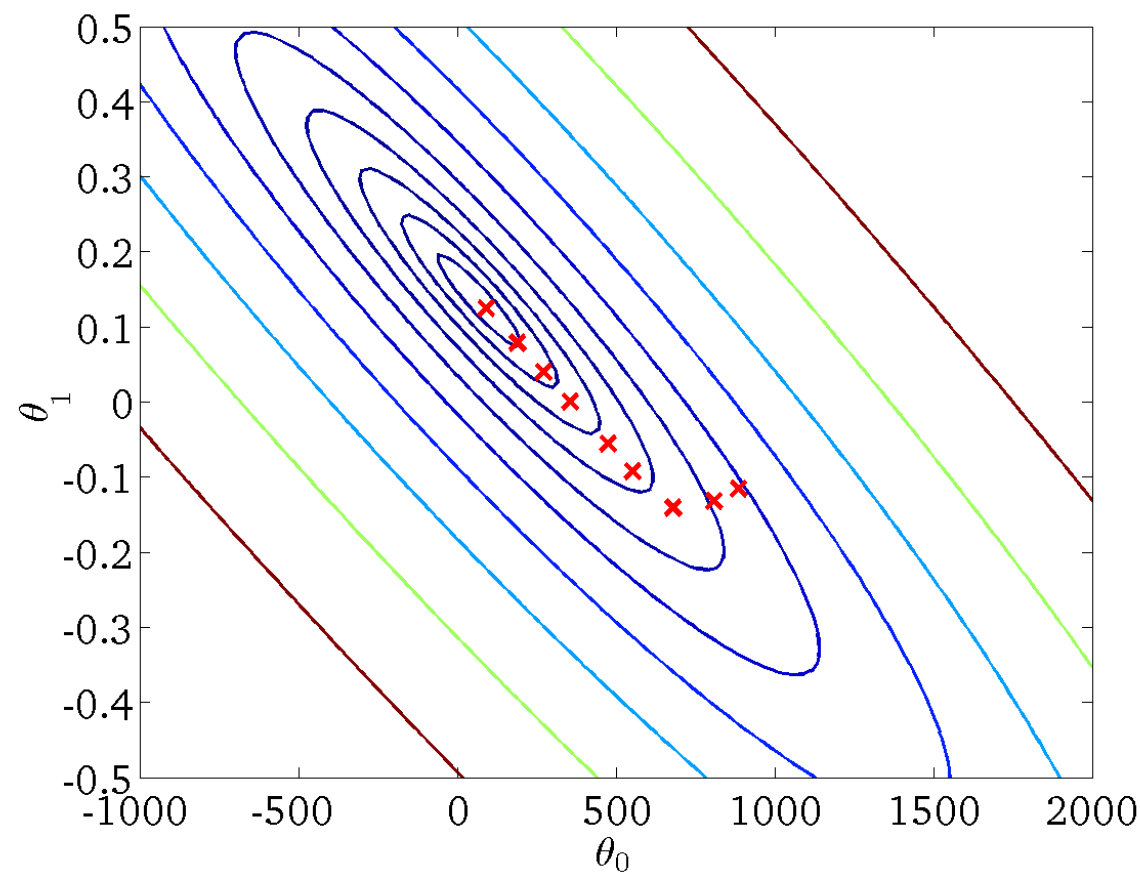
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$  this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



# Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad (\text{for } j = 0 \text{ and } j = 1)$$

}

Derivative

\*Alpha = learning rate

---

Correct: Simultaneous update

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\theta_0 := \text{temp0}$$

$$\theta_1 := \text{temp1}$$

Incorrect:

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

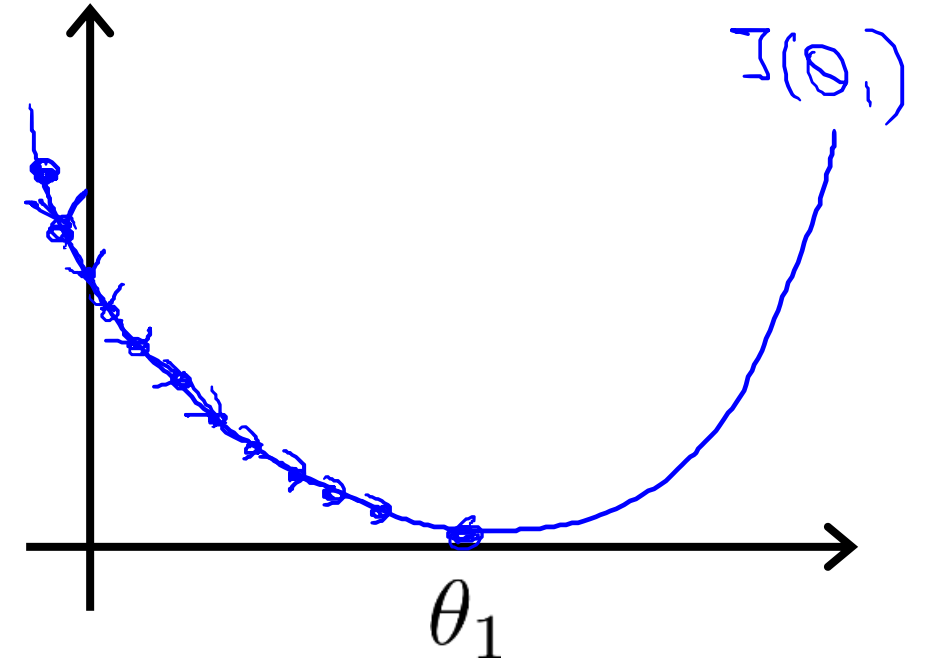
$$\theta_0 := \text{temp0}$$

$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

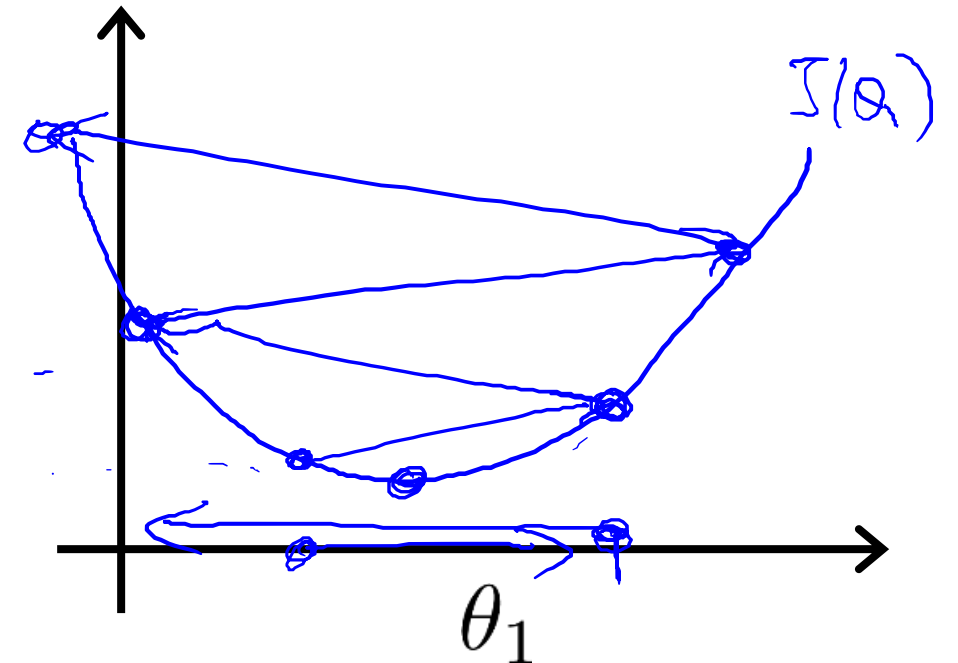
$$\theta_1 := \text{temp1}$$

$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If  $\alpha$  is too small, gradient descent can be slow.



If  $\alpha$  is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.

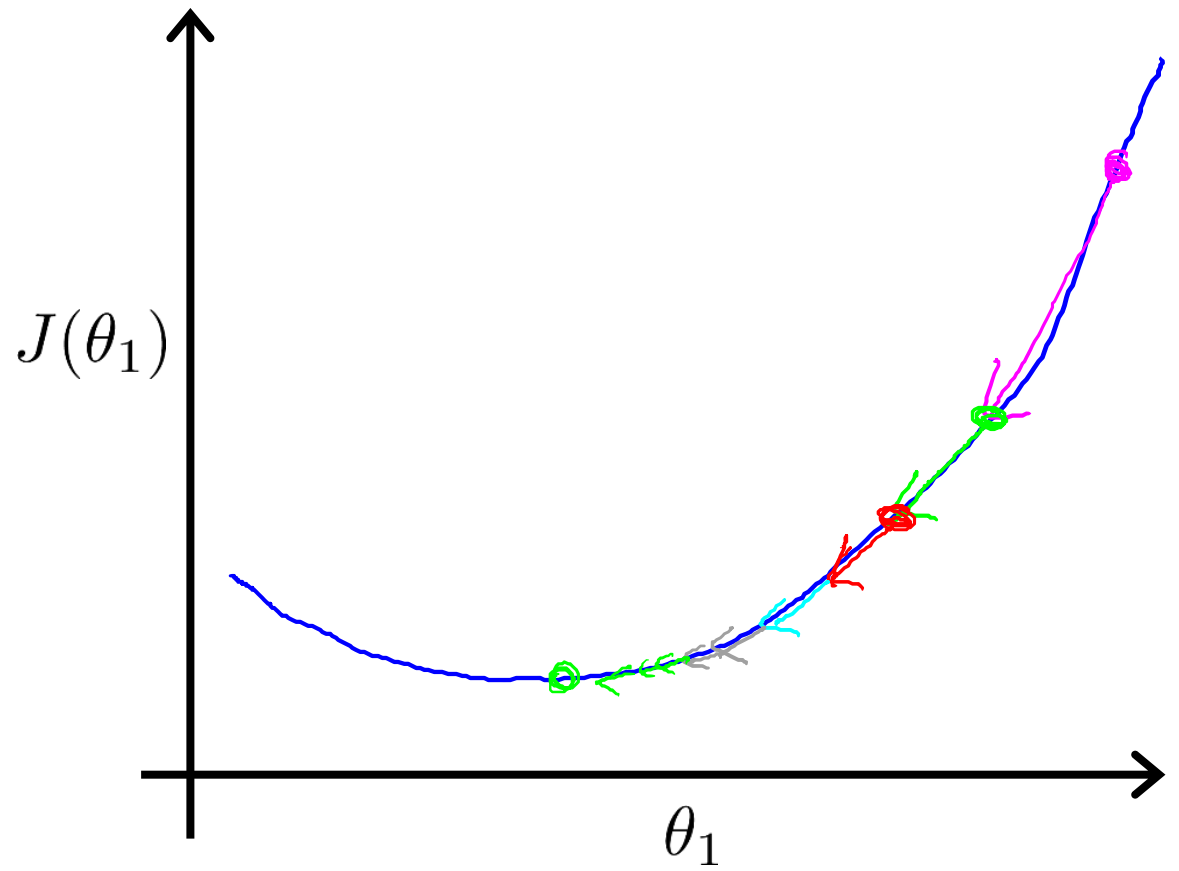




Gradient descent can converge to a local minimum, even with the learning rate  $\alpha$  fixed.

$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease  $\alpha$  over time.



## Gradient descent algorithm

repeat until convergence {  
     $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$   
    (for  $j = 1$  and  $j = 0$ )  
}

## Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

# Gradient descent algorithm

repeat until convergence {

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x^{(i)}$$

} update  
 $\theta_0$  and  $\theta_1$   
simultaneously

}

# Question

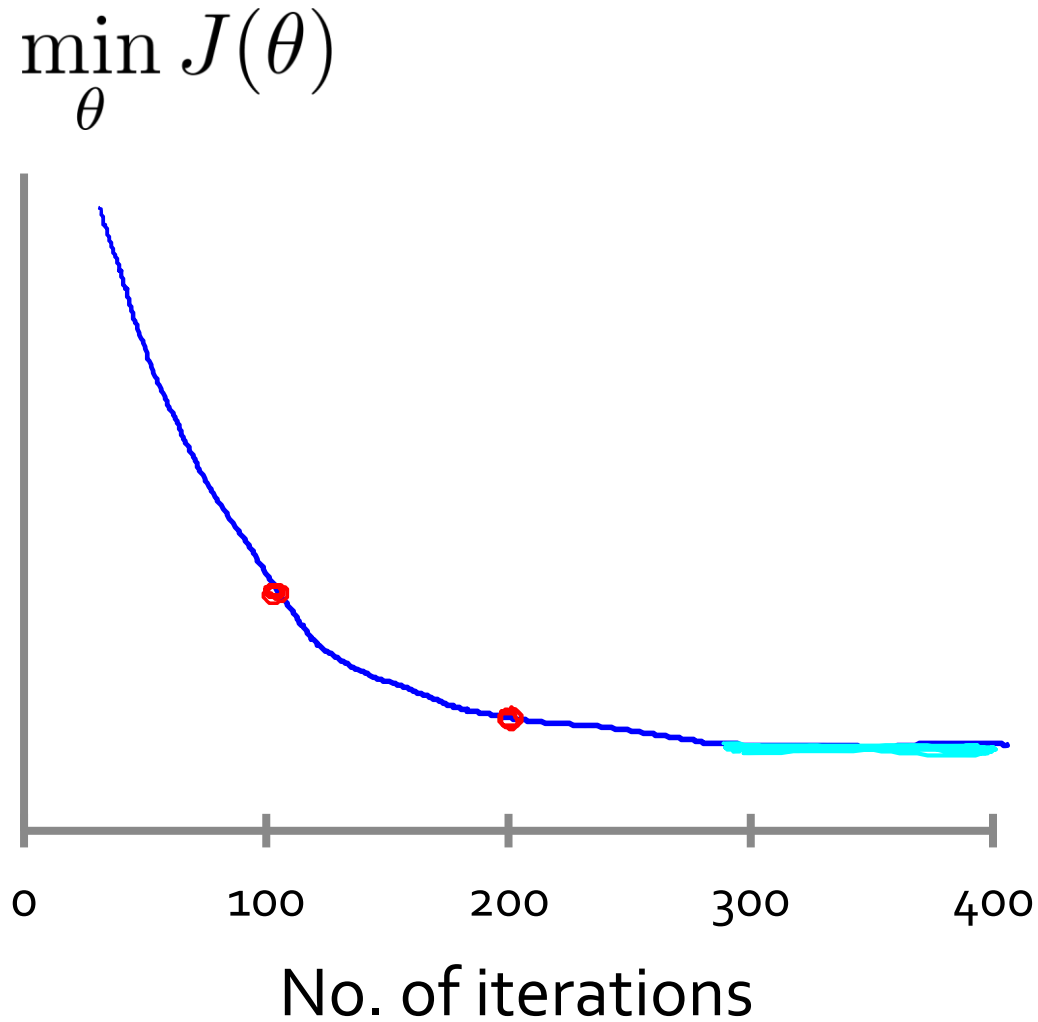
- Suppose you are the CEO of a restaurant franchise and are considering different cities for opening a new outlet.
- The chain already has trucks in various cities and you have data for profits and populations from the cities.
- You would like to use this data to help you select which city to expand to next.
- The first column is the **population of a city** and the second column is the **profit of a food truck in that city**.

# Gradient descent

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$$

- “Debugging”: How to make sure gradient descent is working correctly.
- How to choose learning rate  $\alpha$ .

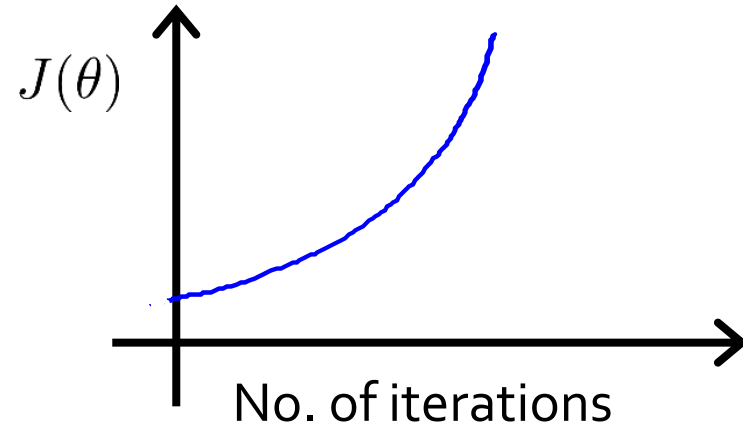
# Making sure gradient descent is working correctly.



Example automatic convergence test:

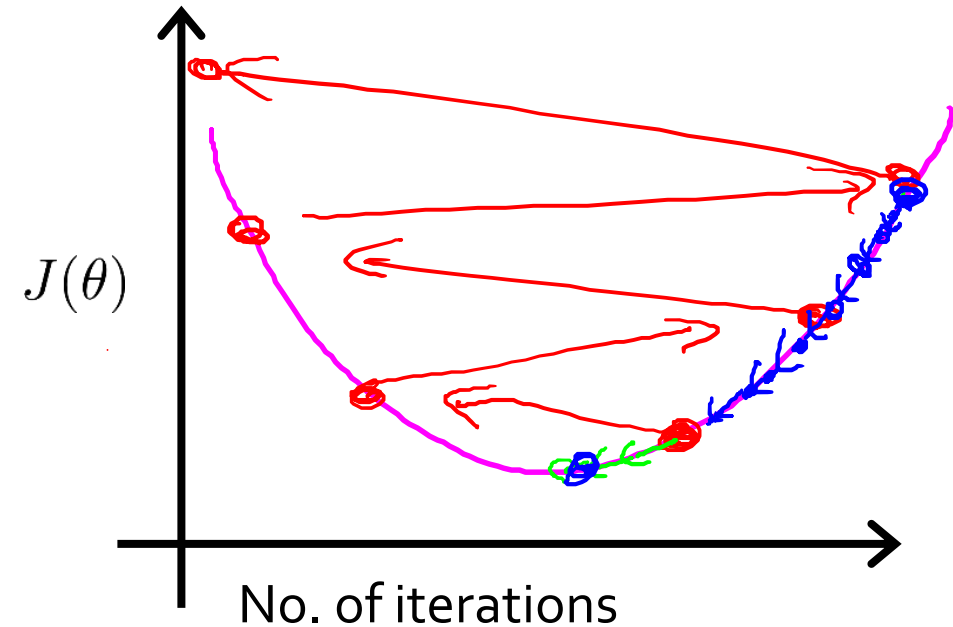
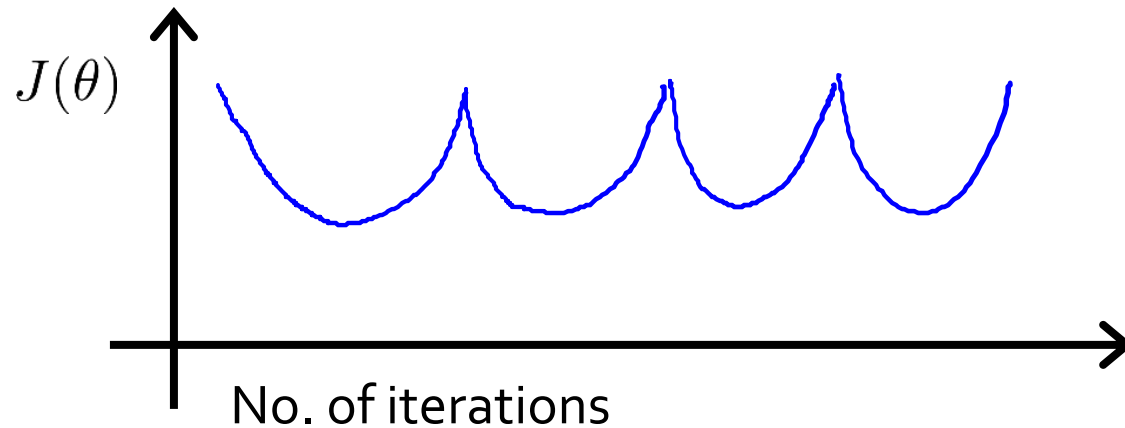
Declare convergence if  $J(\theta)$  decreases by less than  $10^{-3}$  in one iteration.

# Making sure gradient descent is working correctly.



Gradient descent not working.

Use smaller  $\alpha$



- For sufficiently small  $\alpha$ ,  $J(\theta)$  should decrease on every iteration.
- But if  $\alpha$  is too small, gradient descent can be slow to converge.

## Summary:

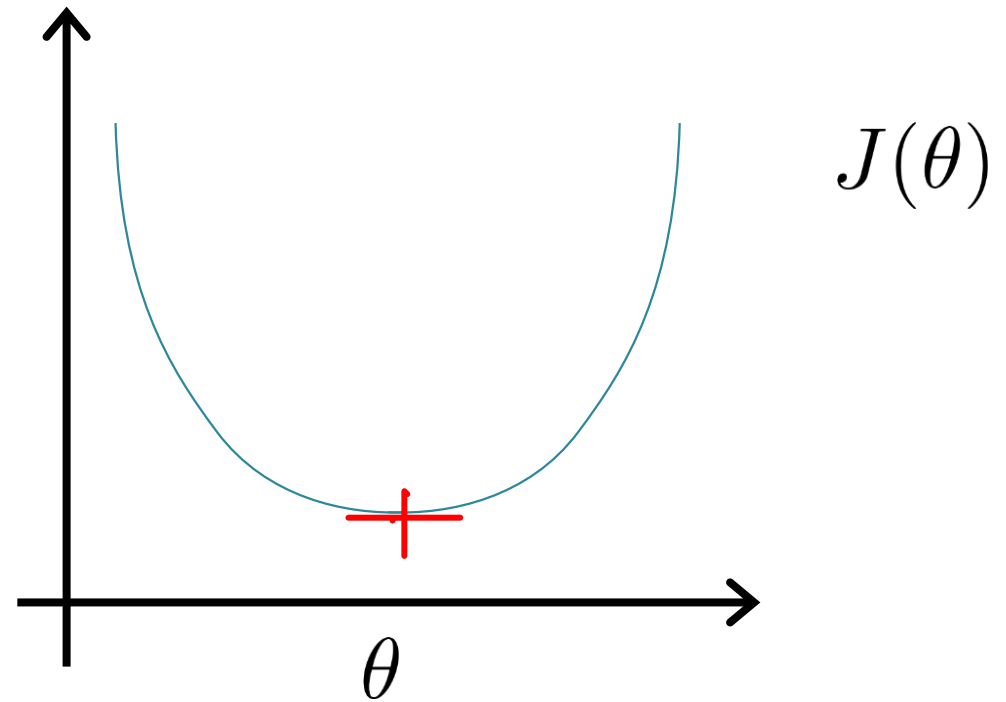
- If  $\alpha$  is too small: slow convergence.
- If  $\alpha$  is too large:  $J(\theta)$  may not decrease on every iteration; may not converge.

To choose  $\alpha$ , try

$\dots, 0.001, \quad , 0.01, \quad , 0.1, \quad , 1, \dots$



# Gradient Descent



Normal equation: Method to solve for  $\theta$  analytically.

Examples:  $m = 4$ .

	Size (feet <sup>2</sup> )	Number of bedrooms	Number of floors	Age of home (years)	Price (\$1000)
$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$y$
1	2104	5	1	45	460
1	1416	3	2	40	232
1	1534	3	2	30	315
1	852	2	1	36	178

$$X = \begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix}$$

$$y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$$

$$\theta = (X^T X)^{-1} X^T y$$

$$\theta = (X^T X)^{-1} X^T y$$

$(X^T X)^{-1}$  is inverse of matrix  $X^T X$

Octave: `pinv(x' * x) * x' * y`

$m$  training examples,  $n$  features.

### Gradient Descent

- Need to choose  $\alpha$ .
- Needs many iterations.
- Works well even when  $n$  is large.

### Normal Equation

- No need to choose  $\alpha$ .
- Don't need to iterate.
- Need to compute  $(X^T X)^{-1}$
- Slow if  $n$  is very large.

Logistic Regression

# **CLASSIFICATION PROBLEMS**

# Classification

Email: Spam / Not Spam?

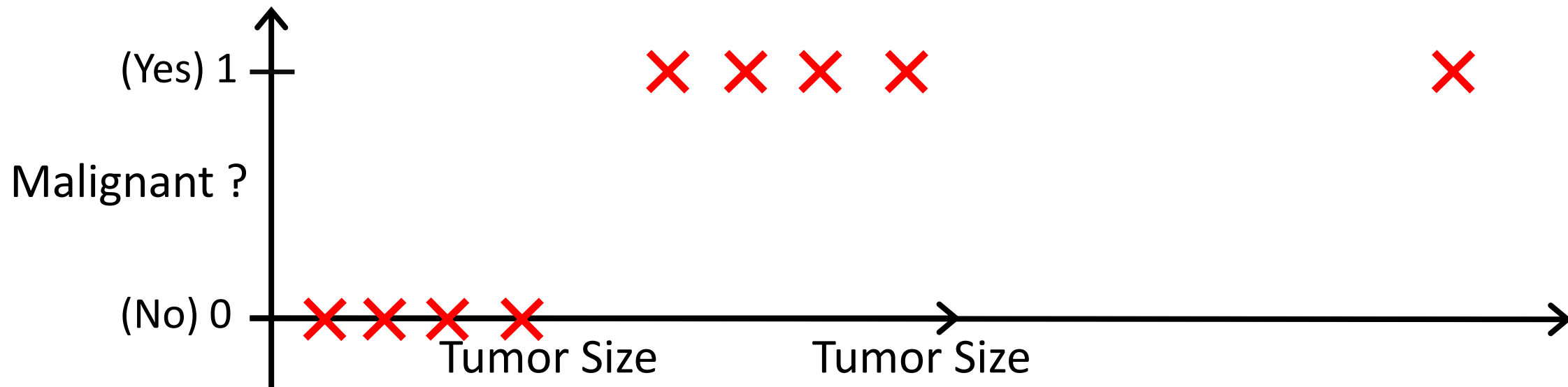
Online Transactions: Fraudulent (Yes / No)?

Tumor: Malignant / Benign ?

$$y \in \{0, 1\}$$

0: “Negative Class” (e.g., benign tumor)

1: “Positive Class” (e.g., malignant tumor)



Threshold classifier output  $h_{\theta}(x)$  at 0.5:

If  $h_{\theta}(x) \geq 0.5$ , predict "y = 1"

If  $h_{\theta}(x) < 0.5$ , predict "y = 0"

Classification:  $y = 0$  or  $1$

$h_{\theta}(x)$  can be  $> 1$  or  $< 0$

Logistic Regression:  $0 \leq h_{\theta}(x) \leq 1$



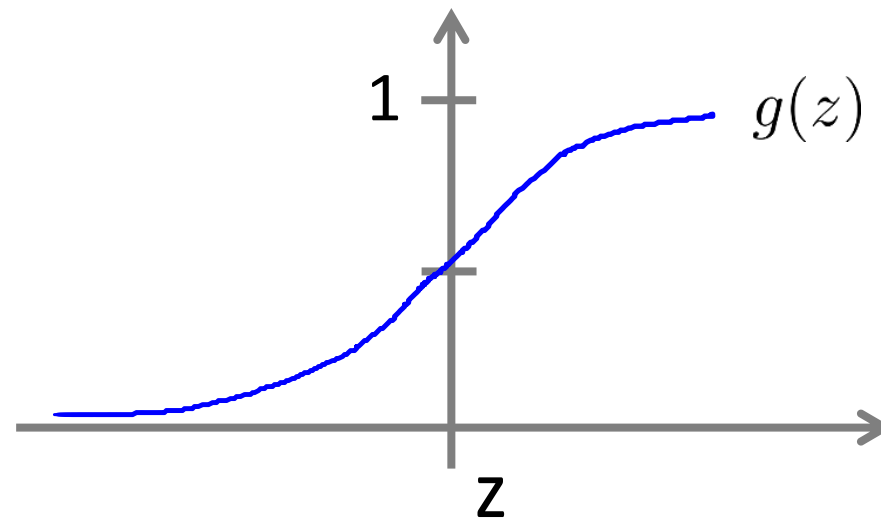
## Logistic regression

$$h_{\theta}(x) = g(\theta^T x)$$

$$g(z) = \frac{1}{1+e^{-z}}$$

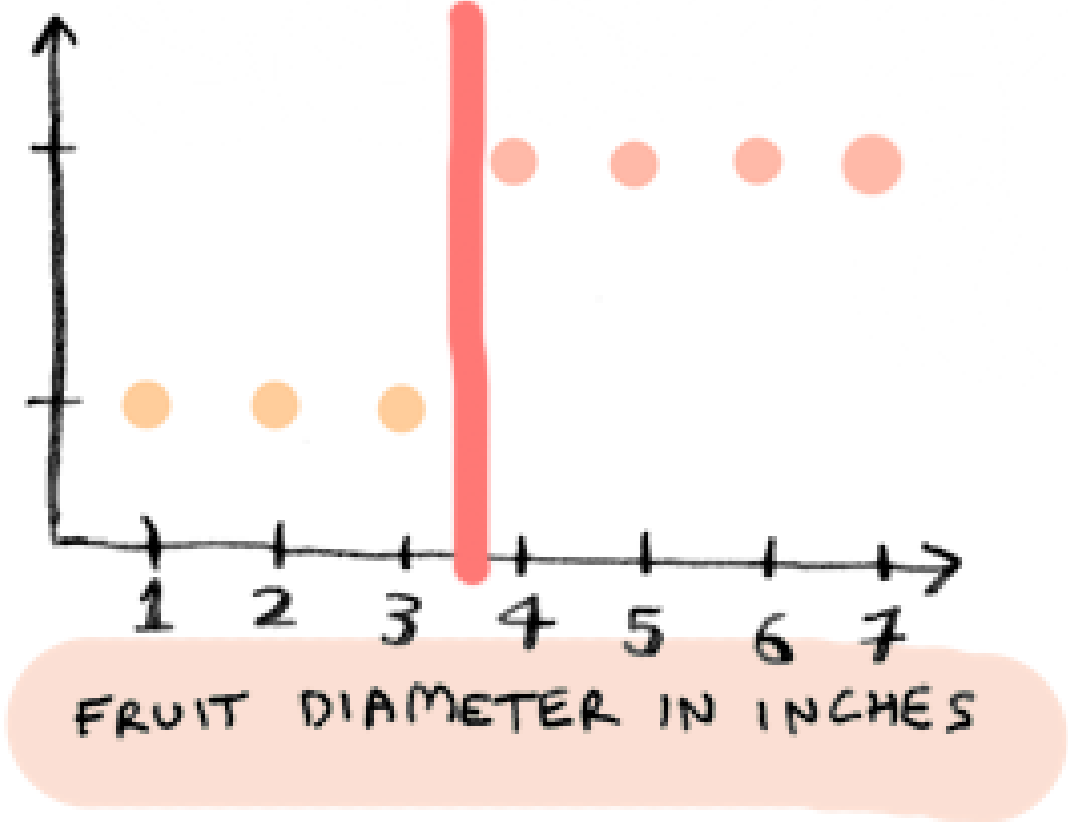
Suppose predict “ $y = 1$ ” if  $h_{\theta}(x) \geq 0.5$

predict “ $y = 0$ ” if  $h_{\theta}(x) < 0.5$



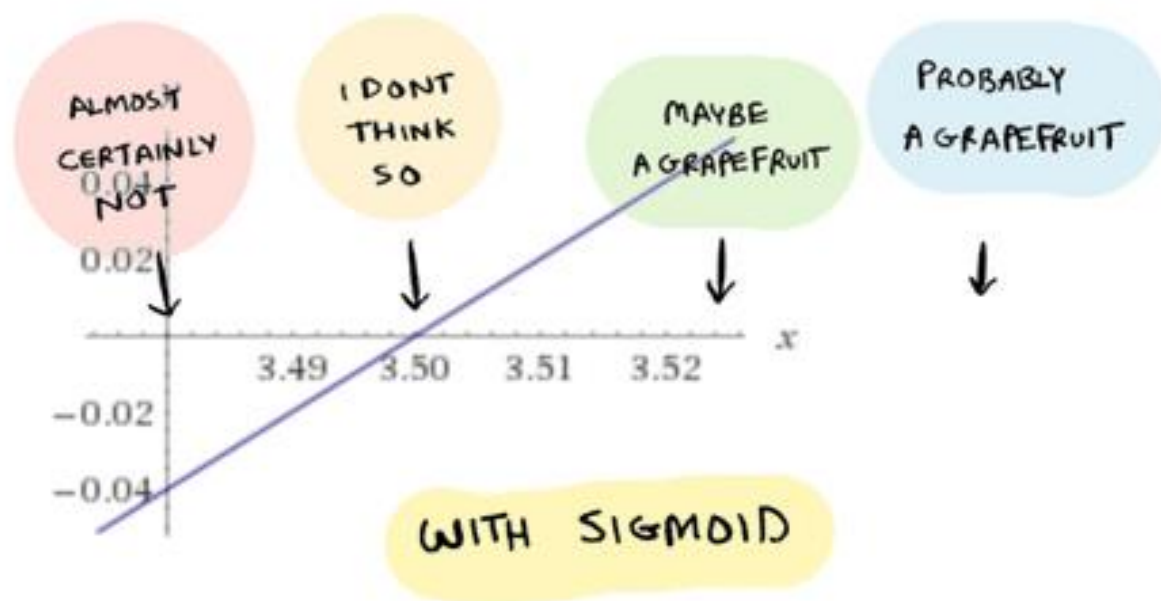
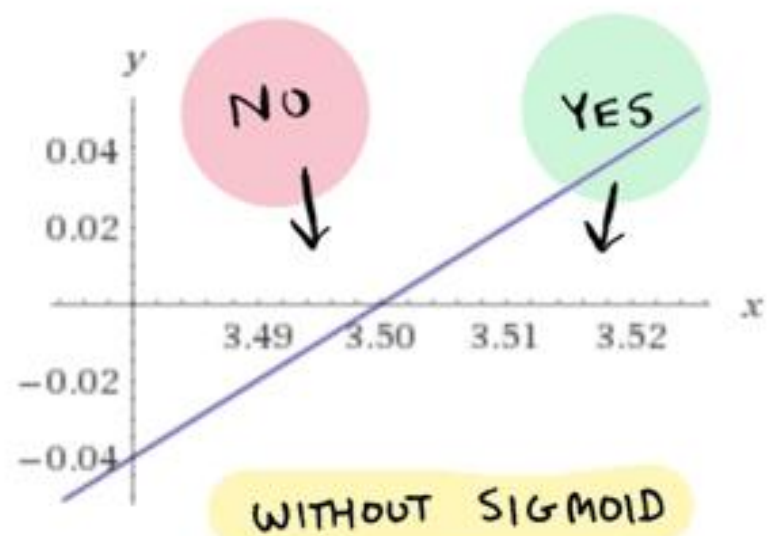
GRAPE  
FRUIT

ORANGE



A hand-drawn diagram illustrating a dataset. It features a central table with two columns and five rows. Above the columns are labels 'X' and 'Y' in green circles. To the left of the table is a pink circle containing the text 'FRUIT DIAMETER IN INCHES' with two arrows pointing to the first and second columns. To the right of the table is a pink rounded rectangle containing a legend: 'Ø = NOT A GRAPEFRUIT' and '1 = GRAPEFRUIT', with two arrows pointing to the first and second columns of the table.

X	Y
1	Ø
2	Ø
3	Ø
4	1
5	1

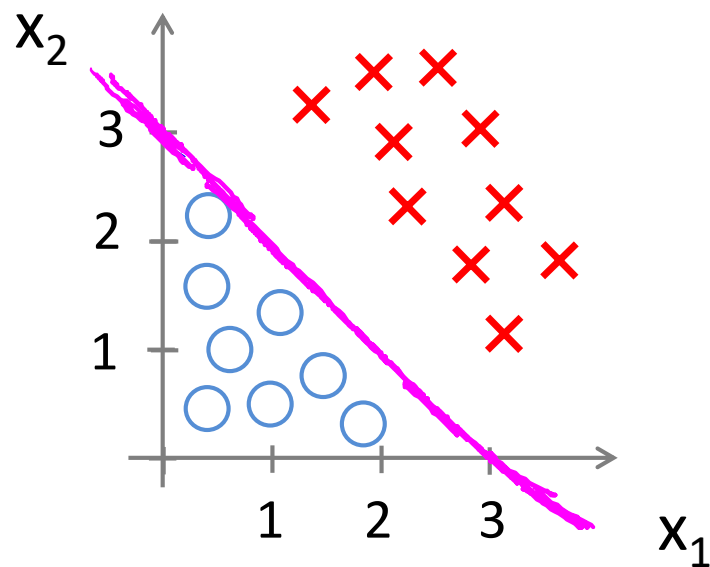


ACTUAL VALUE  
1 = IS A GRAPEFRUIT

X	Y	PREDICTED
1	Ø	Ø.6%
2	Ø	4.7%
3	Ø	26.9%
4	1	73.1%
5	1	95.2%

PERCENT  
CHANCE  
THAT THIS  
IS A GRAPEFRUIT

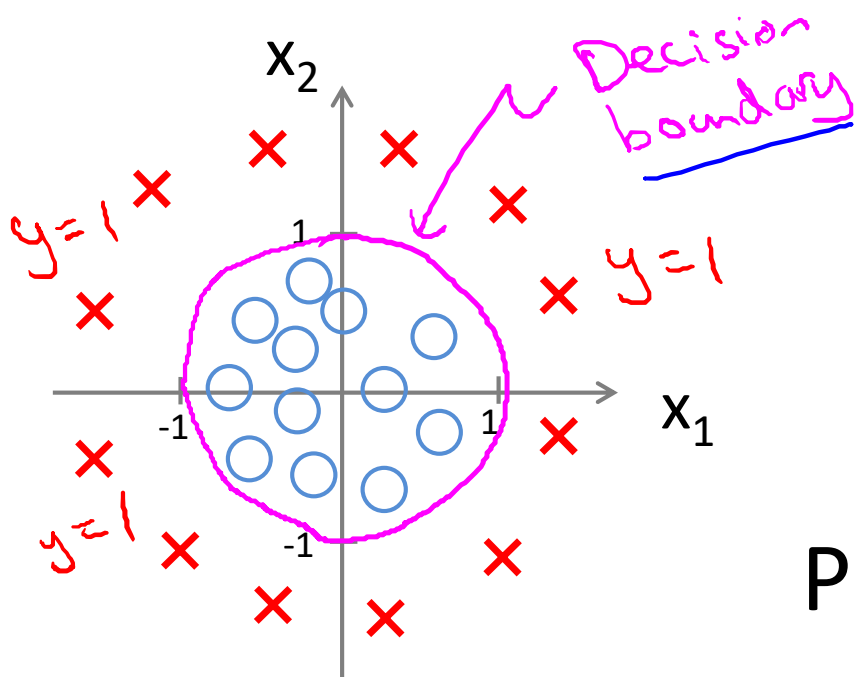
# Decision Boundary



$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

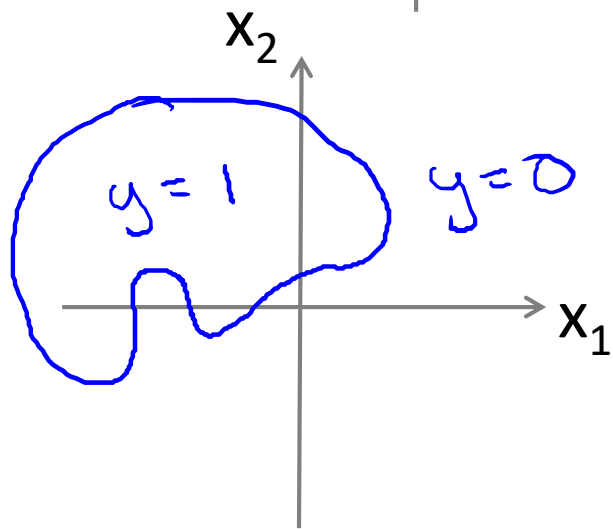
Predict “ $y = 1$ ” if  $-3 + x_1 + x_2 \geq 0$

# Non-linear decision boundaries



$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2)$$

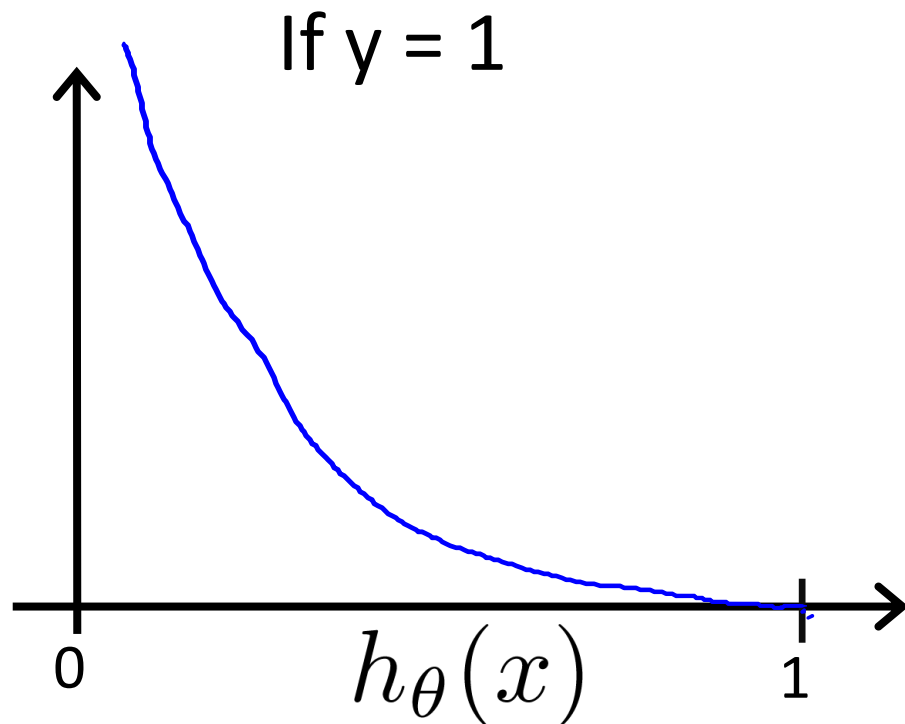
Predict “ $y = 1$ ” if  $-1 + x_1^2 + x_2^2 \geq 0$



$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_1^2 x_2 + \theta_5 x_1^2 x_2^2 + \theta_6 x_1^3 x_2 + \dots)$$

# Logistic regression cost function

$$\text{Cost}(h_{\theta}(x), y) = \begin{cases} -\log(h_{\theta}(x)) & \text{if } y = 1 \\ -\log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$



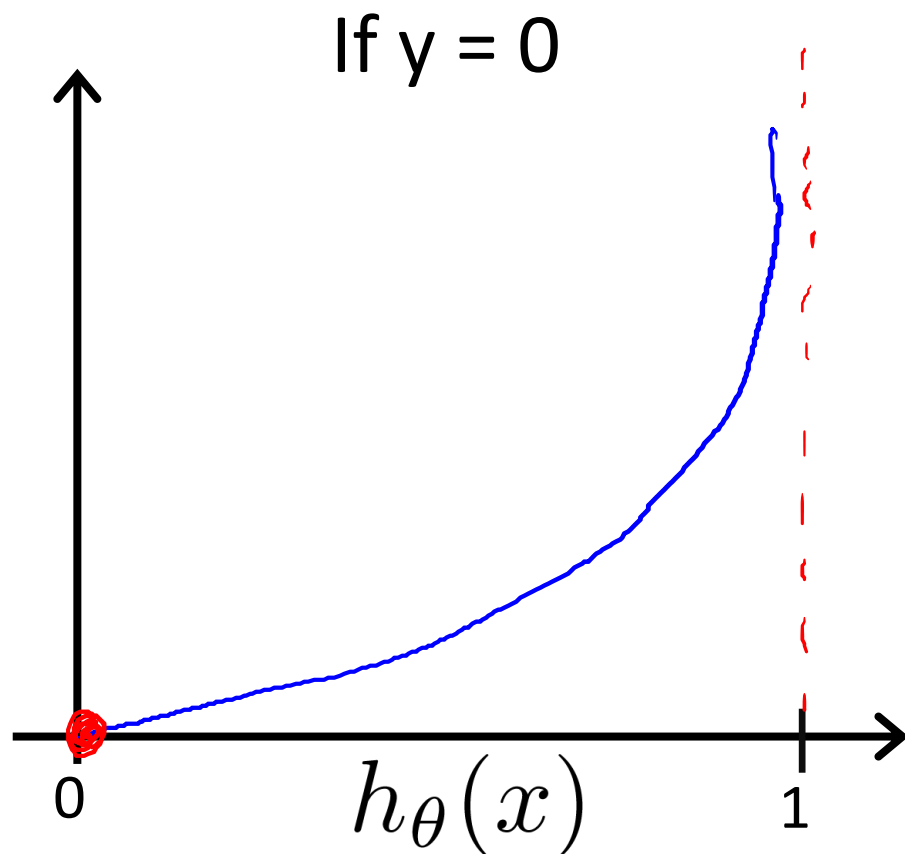
Cost = 0 if  $y = 1, h_{\theta}(x) = 1$   
But as  $h_{\theta}(x) \rightarrow 0$   
 $Cost \rightarrow \infty$

Captures intuition that if  $h_{\theta}(x) = 0$ ,  
(predict  $P(y = 1|x; \theta) = 0$ ), but  $y = 1$ ,  
we'll penalize learning algorithm by a very  
large cost.



# Logistic regression cost function

$$\text{Cost}(h_{\theta}(x), y) = \begin{cases} -\log(h_{\theta}(x)) & \text{if } y = 1 \\ -\log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$



THIS EVALUATES  
TO ZERO IF  
 $y_i = 0$

THIS EVALUATES  
TO ZERO IF  
 $y_i = 1$

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m y_i \cdot \log(h_{\theta}(x_i)) + (1 - y_i) \cdot \log(1 - h_{\theta}(x_i))$$

## Logistic regression cost function

$$\begin{aligned} J(\theta) &= \frac{1}{m} \sum_{i=1}^m \text{Cost}(h_{\theta}(x^{(i)}), y^{(i)}) \\ &= -\frac{1}{m} \left[ \sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log (1 - h_{\theta}(x^{(i)})) \right] \end{aligned}$$

To fit parameters  $\theta$ :

$$\min_{\theta} J(\theta)$$

To make a prediction given new  $x$ :

$$\text{Output } h_{\theta}(x) = \frac{1}{1 + e^{-\theta^T x}}$$

# Gradient Descent

$$J(\theta) = -\frac{1}{m} \left[ \sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log (1 - h_{\theta}(x^{(i)})) \right]$$

Want  $\min_{\theta} J(\theta)$ :

Repeat {

$$\theta_j := \theta_j - \alpha \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

} (simultaneously update all  $\theta_j$ )

Algorithm looks identical to linear regression!

# References

- Machine Learning, Stanford University Taught by: Andrew Ng , at Courcera
- <http://adit.io/posts/2016-02-20-Linear-Regression-in-Pictures.html>
- <http://adit.io/posts/2016-03-13-Logistic-Regression.html#non-linear-classification>