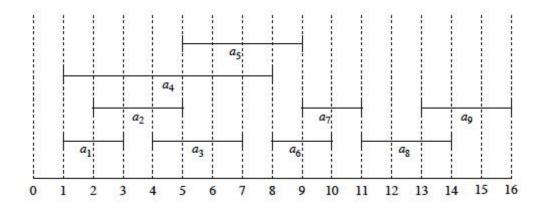
# PROBLEM A: Activity Selection



The x-axis indicates time.

Activity  $a_i$  starts at a time  $s_i$  and finishes at time  $t_i$ .

For a person, the current activity must finish BEFORE another activity can start.

Find the maximum number of activities that can be done by a person?

## **INPUT**

The first line is the number of activities, n.

Each of the next n lines gives the start time and finish time of an activity.

## OUTPUT

One number, the maximum number of activities that can be done by a person.

### From Wikipedia:

A greedy algorithm is any algorithm that follows the problem-solving heuristic of making the locally optimal choice at each stage with the intent of finding a global optimum.

For many problems, a greedy strategy does not usually produce an optimal solution, but nonetheless a greedy heuristic may yield locally optimal solutions that approximate a globally optimal solution in a reasonable amount of time.

A greedy algorithm walked through state space in forward-only manner. No state is reconsidered.

- The algorithm is generally very fast, provided that the decision making at each state is efficient.
- Thus, the algorithm depends heavily on the heuristic strategy that dictates the sequence of states to be visited.
- 1) For activity selection problem. Sort the activities under a heuristic strategy. Then pick activity, in the sorted order, that does not overlap with the time period of the one previously picked. (NOTE: same time = overlapped)

List out at least two strategies that you think are options that may lead to optimal solution.

- 2) Write the program to test each strategy.
- 3) As you should have at least two different programs by now, each sorts the activities based on a strategy different from the others. Conduct an experiment in order to fill in the blank below.

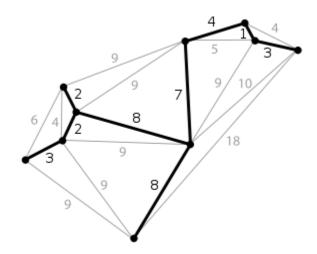
| The strategy that gives the al | ways gives the best answe | er is to sort the activities in | n the |
|--------------------------------|---------------------------|---------------------------------|-------|
| (increasing/decreasing)        | order of _                |                                 |       |

| If you get the right strategy, your algorithm will complete the prove below  |  |  |  |
|--|--|--|--|
|  |  |  |  |
| <b>PROOF of correctness for algorithm X</b> (that sorts the activities in the way answered in question 3)  |  |  |  |
| Assume that the optimal set of activities is $a_1^*$ , $a_2^*$ , $a_3^*$ ,, $a_m^*$ , and so the maximum number of activities possible is $m$ . And this list of activities is already sorted in the increasing order of finish time.    |  |  |  |
| Let the output of the algorithm X be $a_1^x$ , $a_2^x$ , $a_3^x$ , And also assume that this list of activities is sorted in the increasing order of finish time.  |  |  |  |
| Then, assume further that $a_i^x = a_i^*$ , for $i = 1, 2,, j$ . And then, $a_{j+1}^x <> a_{j+1}^*$  |  |  |  |
| If $a_{j+1}^x$ finishes later than $a_{j+1}^*$ , would algorithm X picks $a_{j+1}^x$ for its answer ?  |  |  |  |
| It would have picked instead!  |  |  |  |
| So, either $a_{j+1}^x$ finishes earlier or at the same time as $a_{j+1}^*$ .   |  |  |  |
| Thus, we can replace $a_{j+1}^*$ with $a_{j+1}^{\chi}$ and the number of possible activities will remain to be   |  |  |  |
| If we repeat the same consideration on the next activity of the two lists, $a_{j+2}^*$ and $a_{j+2}^{\chi}$ , we will find that we can replace $a_{j+2}^*$ with $a_{j+2}^{\chi}$ and the number of possible activities will remain to be |  |  |  |
| Is it possible that there is a $k < m$ such that $a_{k+1}^x$ does not exist ?  |  |  |  |
| Because $a_k^x$ will finish than $a_k^*$ , it will not conflict with $a_{k+1}^*$ .   |  |  |  |
| Therefore, at least algorithm X can at least pick for $a_{k+1}^x$ , and thus $a_{k+1}^x$ definitely exists.  |  |  |  |
| By repeating the same consideration for the next value of $k$ , it is clear that the number of activities produced by algorithm X must be at least   |  |  |  |
| But from assumption, the maximum number of activities possible is $k$ , therefore, the number of activities produced by algorithm X must be at most  |  |  |  |
| Therefore, we can conclude that the number of activities produced by algorithm X is exactly  |  |  |  |
| And thus, the algorithm X gives the maximum number of activities possible PROVED!  |  |  |  |
| A GREEDY ALGORITHM IS MOSTLY VERY EFFICIENT, BUT IT NEEDS TO BE  |  |  |  |

4)

PROVED FOR CORRECTNESS.

PROBLEM B: Minimum Spanning Tree



- A spanning tree T of an undirected graph G is a subgraph that is a tree which includes all of the vertices of G.
- A minimum spanning tree is a spanning tree whose sum of edge weights is as small as possible.

## **Example application**

The standard application is to a problem like phone network design. You have a business with several offices; you want to lease phone lines to connect them up with each other; and the phone company charges different amounts of money to connect different pairs of cities. You want a set of lines that connects all your offices with a minimum total cost.

#### \*\*\*\* MST WAS LEARNED IN DATA STRUCTURE AND ALGORITHM \*\*\*\*

Two famous solutions: Kruskal's (covered in this class) and Prim's

1) Review Kruskal's algorithm (from any offline or online source). For a small undirected graph, you should be able to compute by hand the total weight of an MST.

## **INPUT**

The first line contains the number of vertices (V) and the number of edges (E), respectively

Each of the following line represents an edge. It lists out three numbers; the first two are the vertices that are connected by the edge, and the last number is the weight of the edge. (vertex ID begins at 0)

#### **OUTPUT**

One number, the total weight of a minimum spanning tree.

- 2) Write the program that read the input and stores all edges in a list, each as a triple (v1, v2, weight).
- 3) Sort the edge list in the increasing order of edge weight.

- 4) Study the provided "Data Structure for Disjoint Sets". Write program that utilizes the data structure.
- 5) At the beginning of Kruskal's algorithm, each vertex is associated with a dedicated set.
  - Therefore, there are V sets at the start.
  - Sequentially consider the edge according to the sorted edge list.
    - o Take only the edge that connects two different sets, and then the edge causes the two
- 6)

| sets to unite into one.  |
|--|
| • The operation repeats until the number of sets is reduced to 1.  |
| A greedy algorithm is typically heuristic. It is accepted by being proved that it works correctly.   |
| PROOF:   |
| Let the minimum spanning tree of a graph G be T*.  |
| Suppose that Kruskal's algorithm produces T.   |
| Assume first, that the two trees are different, and the lightest edge in T* which is not in T is e.  |
| Adding e to T will create a (let's call it C)  |
| There must be an edge in C that is not in T*. Why? (let's call this edge f)  |
| Removing f from T will create a new spanning tree. Why ? (let's call this new spanning tree $T_1$ )  |
| $T_1$ will be more similar to $T^*$ than $T$ . But is the total weight of $T_1$ less than $T$ ?  |
| Suppose that it is, this means that e f. (a comparing operation)   |
| If e was really so, would it be picked by Kruskal's algorithm before f?  |
| Therefore, the fact must be that e f.  |
| Therefore, we can conclude that weight of $T_1$ $T$ .  |
| Continually transforming $T_1$ further in the same fashion until the resulted spanning tree becomes $T^*$ Will the transformed spanning tree has less total weight than $T$ ? Why? |
| But the total weight of T* is the minimum possible (by assumption). Therefore, the only possible conclusion is the total weight of T the total weight of T*. <b>PROVED!</b>        |