

Fundamentals Machine Learning

Vector Calculus: Lagrange Multiplier

Constrained optimization

- ❖ **Constrained optimization is the process of optimizing an objective function with respect to some variables in the presence of constraints on those variables.**
- ❖ **The objective function** is either
 - a cost function or energy function which is to be minimized, or
 - a reward function or utility function, which is to be maximized.
- ❖ **Constraints** can be either
 - hard constraints which set conditions for the variables that are **required** to be satisfied, or
 - soft constraints which have some variable values that are penalized in the objective function if the conditions on the variables are not satisfied

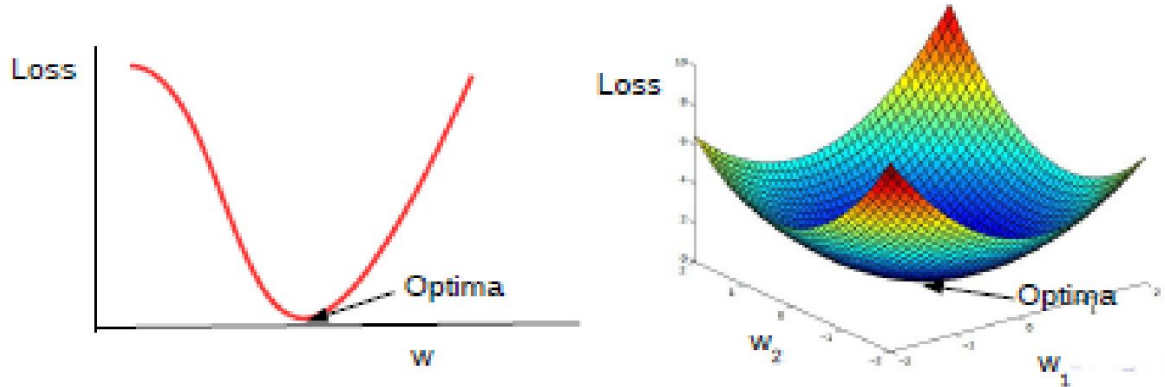
- A general constrained minimization problem:

$$\begin{array}{ll}\min & f(\mathbf{x}) \\ \text{subject to} & g_i(\mathbf{x}) = c_i \text{ for } i = 1, \dots, n \text{ (Equality constraints)} \\ & h_j(\mathbf{x}) \geq d_j \text{ for } j = 1, \dots, m \text{ (Inequality constraints)}\end{array} \quad (1)$$

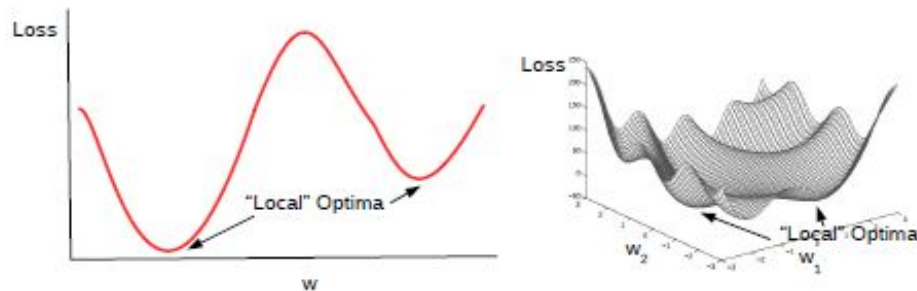
where $g_i(\mathbf{x}) = c_i$ and $h_j(\mathbf{x}) \geq d_j$ are called *hard constraints*.

Optimization Problems in ML

Wish to find the optima (minima) of an objective function, that can be seen as a **curve/surface**



In many cases, the functions may even look like this



Functions with unique minima: **Convex**;
Functions with many local minima:
Non-convex

The Lagrange Multipliers

- Lagrange Multipliers are a mathematical method used to solve constrained optimization problems of differentiable functions

$$\text{Minimize } f(x_1, x_2)$$

subject to

$$g(x_1, x_2) = 0$$

i.e., optimize f , while constraining f with g .

Lagrange Multipliers is the following equation:

$$\nabla f(x) = \lambda \nabla g(x)$$

The **gradient of f** is equal to some multiplier (**lagrange multiplier**) times the **gradient of g** , where $g(x)=0$

The gradient of a scalar-valued multivariable function $f(x, y, \dots)$ denoted ∇f packages all its partial derivative information into a vector:

Scalar-valued multivariable function

$$\nabla f(x_0, y_0, \dots) = \begin{bmatrix} \frac{\partial f}{\partial x}(x_0, y_0, \dots) \\ \frac{\partial f}{\partial y}(x_0, y_0, \dots) \\ \vdots \end{bmatrix}$$

Notation for gradient, called "nabla".

∇f takes the same type of inputs as f

∇f outputs a vector with all possible partial derivatives of f .

The diagram illustrates the definition of the gradient. It shows the expression $\nabla f(x_0, y_0, \dots)$ equated to a column vector of partial derivatives. A green arrow points from the text 'Scalar-valued multivariable function' to the function f . A blue bracket under the inputs (x_0, y_0, \dots) is labeled ' ∇f takes the same type of inputs as f '. A red bracket under the vector of partial derivatives is labeled ' ∇f outputs a vector with all possible partial derivatives of f '. A black arrow points from the text 'Notation for gradient, called "nabla".' to the ∇ symbol.

Combining Lagrange multiplier and constraint function $g(x)=0$, the Lagrange Function is defined as

$$L(x, \lambda) = f(x) - \lambda g(x)$$

Using the above equation, look for the points where:

$$\nabla L(x, \lambda) = 0$$

Example 1: One Equality Constraint

Problem: Given,

$$\begin{aligned}f(x, y) &= 2 - x^2 - 2y^2 \\g(x, y) &= x + y - 1 = 0\end{aligned}$$

Find the extreme values

Solution: Step 1: we put the equations into the form of a Lagrangian:

$$\begin{aligned}L(x, y, \lambda) &= f(x, y) - \lambda g(x, y) \\&= 2 - x^2 - 2y^2 - \lambda(x + y - 1)\end{aligned}$$

Step 2: solve for the gradient of the Lagrangian

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda \nabla g(x, y) = 0$$

$$L(x, y, \lambda) = 2 - x^2 - 2y^2 - \lambda(x + y - 1)$$

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda \nabla g(x, y) = 0$$

$$\frac{\partial}{\partial x} L(x, y, \lambda) = -2x - \lambda = 0 \quad (1)$$

$$\frac{\partial}{\partial y} L(x, y, \lambda) = -4y - \lambda = 0 \quad (2)$$

$$\frac{\partial}{\partial \lambda} L(x, y, \lambda) = x + y - 1 = 0 \quad (3)$$

From Equation (1) and (2) we have $x = 2y$. Substituting this into Equation (3) gives $x = \frac{2}{3}$ and $y = \frac{1}{3}$

These values give $\lambda = \frac{-4}{3}$ and $f = \frac{4}{3}$

Example 2: One Equality Constraint

Problem: Given,

$$\begin{aligned}f(x, y) &= x + 2y \\g(x, y) &= y^2 + xy - 1 = 0\end{aligned}$$

Find the extreme values.

Solution: First, we put the equations into the form of a Lagrangian:

$$\begin{aligned}L(x, y, \lambda) &= f(x, y) - \lambda g(x, y) \\&= x + 2y - \lambda(y^2 + xy - 1)\end{aligned}$$

and we solve for the gradient of the Lagrangian (Equation 4):

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda \nabla g(x, y) = 0$$

which gives us:

$$\frac{\partial}{\partial x}L(x, y, \lambda) = 1 - \lambda y = 0$$

$$\frac{\partial}{\partial y}L(x, y, \lambda) = 2 - 2\lambda y - \lambda x = 0$$

$$\frac{\partial}{\partial \lambda}L(x, y, \lambda) = y^2 + xy - 1 = 0$$

This gives $x = 0$, $y = \pm 1$, $\lambda = \pm 1$ and $f = \pm 2$.

Multiple Constraints

Lagrangian function for multiple constraints:

$$L(x, \lambda) = f(x) - \sum_i \lambda_i g_i(x)$$

Here $g_i(x)$ and λ_i are the multiple constraints (denoted by i), and associated Lagrange Multipliers.

Note : that each constraint has its own multiplier.

Again, look for points where:

$$\nabla L(x, \lambda) = 0$$

Example 3: Two Equality

Problem: Given,

$$f(x, y) = x^2 + y^2$$

$$g_1(x, y) = x + 1 = 0$$

$$g_2(x, y) = y + 1 = 0$$

Find the extreme values.

Solution: Step 1: Put the equations into the form of a Lagrangian:

$$\begin{aligned} L(x, y, \lambda) &= f(x, y) - \lambda_1 g_1(x, y) - \lambda_2 g_2(x, y) \\ &= x^2 + y^2 - \lambda_1(x + 1) - \lambda_2(y + 1) \end{aligned}$$

Step 2: solve for the gradient of the Lagrangian

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda_1 \nabla g_1(x, y) - \lambda_2 \nabla g_2(x, y) = 0$$

$$\frac{\partial}{\partial x} L(x, y, \lambda) = 2x - \lambda_1 = 0 \quad (1)$$

$$\frac{\partial}{\partial y} L(x, y, \lambda) = 2y - \lambda_2 = 0 \quad (2)$$

$$\frac{\partial}{\partial \lambda_1} L(x, y, \lambda) = x + 1 = 0 \quad (3)$$

$$\frac{\partial}{\partial \lambda_2} L(x, y, \lambda) = y + 1 = 0 \quad (4)$$

Equation (3) gives $x = -1$. Equation (4) gives $y = -1$.

Substituting this into Equation (1) and (2) gives $\lambda_1 = -2$, $\lambda_2 = -2$ and **$f = 2$** .

Inequality Constraints

Lagrange Multipliers with Inequality Constraints (ie $g(x) \leq 0, g(x) \geq 0$).

The formulation of the Lagrangian

$$L(x, \lambda) = f(x) - \lambda g(x)$$

The rules on how the Lagrange Multipliers encode the inequality constraints:

$$g(x) \geq 0 \Rightarrow \lambda \geq 0 \quad (\text{R1})$$

$$g(x) \leq 0 \Rightarrow \lambda \leq 0 \quad (\text{R2})$$

$$g(x) = 0 \Rightarrow \lambda \text{ is unconstrained} \quad (\text{R3})$$

Example 4: One Inequality Constraint

Problem: Given,

$$f(x, y) = x^3 + y^2$$

$$g(x, y) = x^2 - 1 \geq 0$$

Find the extreme values.

Solution: Step 1: Put the equations into the form of a Lagrangian:

$$\begin{aligned} L(x, y, \lambda) &= f(x, y) - \lambda g(x, y) \\ &= x^3 + y^2 - \lambda(x^2 - 1) \end{aligned}$$

Step 2: solve for the gradient of the Lagrangian

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda \nabla g(x, y) = 0$$

$$\frac{\partial}{\partial x} L(x, y, \lambda) = 3x^2 - 2\lambda x = 0 \quad (1)$$

$$\frac{\partial}{\partial y} L(x, y, \lambda) = 2y = 0 \quad (2)$$

$$\frac{\partial}{\partial \lambda} L(x, y, \lambda) = x^2 - 1 = 0 \quad (3)$$

Furthermore,

$$\lambda \geq 0 \quad (4)$$

From Equation (2), we have $y = 0$.

From Equation (3), we have $x = \pm 1$.

Substituting this into Equation (1) gives $\lambda = \pm \frac{3}{2}$

Since we require that $\lambda \geq 0$, $\lambda = \frac{3}{2}$

This gives $x = 1$, $y = 0$ and $f = 1$.

Equations (1) through (4) are called **the KKT conditions**.

Example 5: Two Inequality Constraints

Problem: Given,

$$\begin{aligned}f(x, y) &= x^3 + y^3 \\g_1(x, y) &= x^2 - 1 \geq 0 \\g_2(x, y) &= y^2 - 1 \geq 0\end{aligned}$$

Find the extreme values.

Solution: Step 1: put the equations into the form of a Lagrangian:

$$\begin{aligned}L(x, y, \lambda) &= f(x, y) - \lambda_1 g_1(x, y) - \lambda_2 g_2(x, y) \\&= x^3 + y^3 - \lambda_1(x^2 - 1) - \lambda_2(y^2 - 1)\end{aligned}$$

Step 2: solve for the gradient of the Lagrangian

$$\nabla L(x, y, \lambda) = \nabla f(x, y) - \lambda_1 \nabla g_1(x, y) - \lambda_2 \nabla g_2(x, y) = 0$$

$$\frac{\partial}{\partial x} L(x, y, \lambda) = 3x^2 - 2\lambda_1 x = 0 \quad (1)$$

$$\frac{\partial}{\partial y} L(x, y, \lambda) = 3y^2 - 2\lambda_2 y = 0 \quad (2)$$

$$\frac{\partial}{\partial \lambda_1} L(x, y, \lambda) = x^2 - 1 = 0 \quad (3)$$

$$\frac{\partial}{\partial \lambda_2} L(x, y, \lambda) = y^2 - 1 = 0 \quad (4)$$

Furthermore,

$$\lambda_1 \geq 0 \quad (5)$$

$$\lambda_2 \geq 0 \quad (6)$$

- From Equations (3) and (4), we have $x = \pm 1$ and $y = \pm 1$. Substituting $x = \pm 1$ into Equation (1) gives $\lambda_1 = \pm \frac{3}{2}$.

Furthermore $\lambda_1 \geq 0$, hence $\lambda_1 = +\frac{3}{2}$

- substituting $y = \pm 1$ into Equation (2) gives $\lambda_2 = \pm \frac{3}{2}$

Since we require that $\lambda_2 \geq 0$, then $\lambda_2 = +\frac{3}{2}$.

This gives $x = 1$, $y = 1$ and $f = 2$.

Application in Support Vector Machine

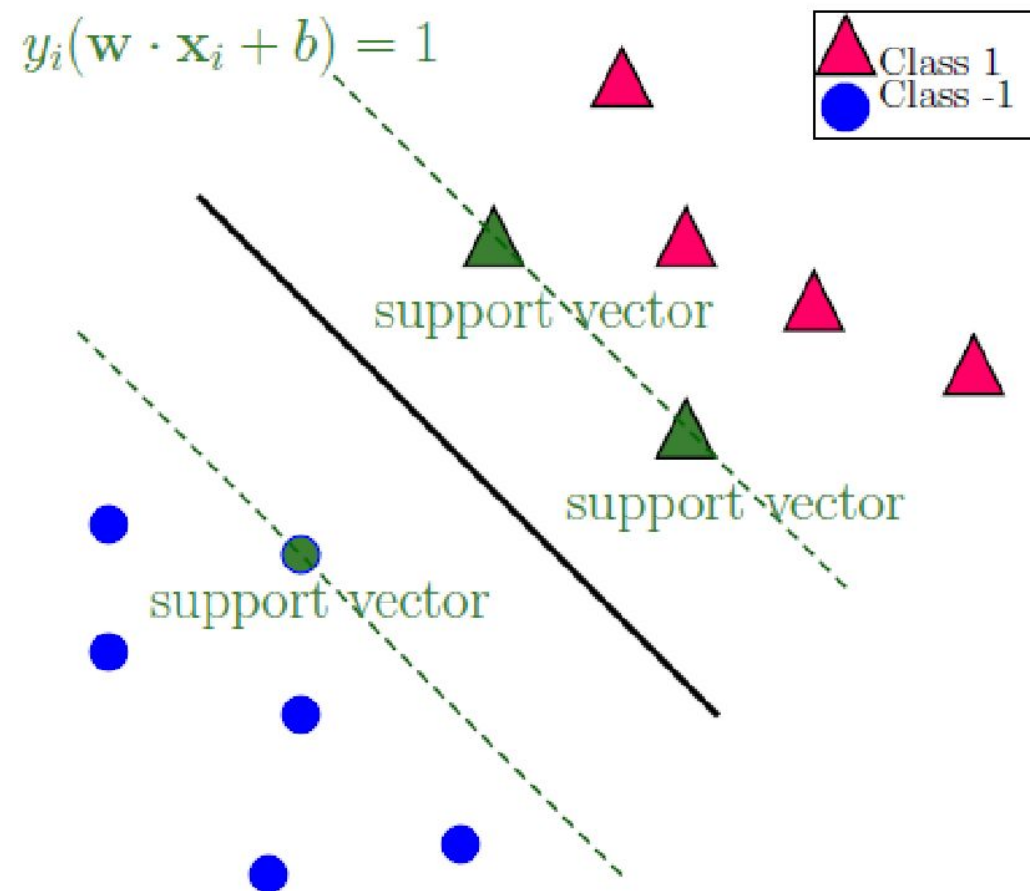


Which line creates the maximum margin or “widest road”?

SVM

- The samples on the edge of the boundary lines (dotted) lines, are known as **'Support Vectors'**.
- On the left side there are two such samples (blue stars), compared to the one on the right.
 - *Support Vectors are the samples that are most difficult to classify.*
 - *They directly affect the process to find the optimum location of the decision boundaries (dotted lines).*
- This is a **constrained optimization** problem.
- *Optimization* — because, we are to find the line from which the support vectors are maximally separated
- *Constrained* — because, the support vectors should be away from the road and not on the road.
- **Lagrange Multipliers** are used to solve this problem in SVM

SVM



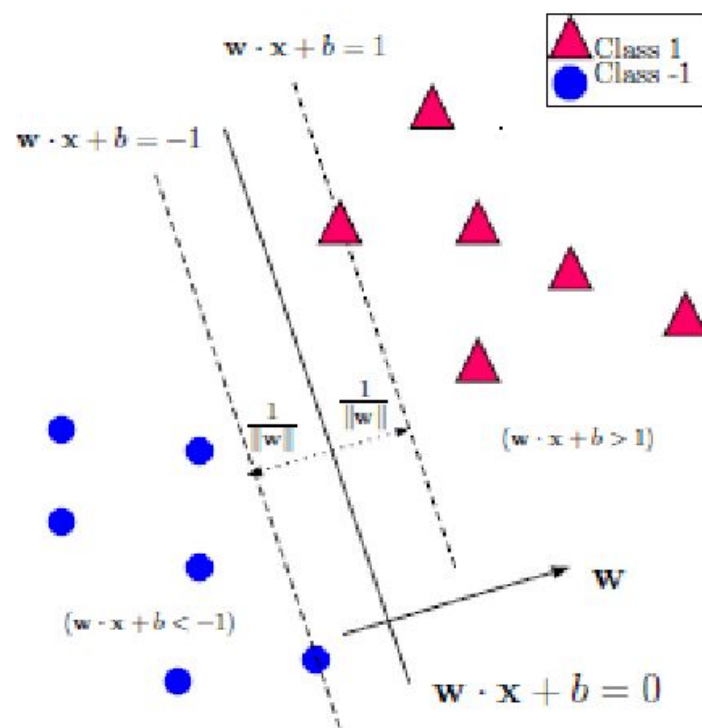
The binary SVM problem

Problem. Given training data $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$ with labels $y_i = \pm 1$, SVM finds the optimal separating hyperplane by maximizing the class margin.

Specifically, it tries to solve

$$\begin{aligned} \max_{\mathbf{w}, b} \quad & \frac{2}{\|\mathbf{w}\|_2} \quad \text{subject to} \\ & \mathbf{w} \cdot \mathbf{x}_i + b \geq 1, \quad \text{if } y_i = +1; \\ & \mathbf{w} \cdot \mathbf{x}_i + b \leq -1, \quad \text{if } y_i = -1 \end{aligned}$$

Remark. The classification rule for new data \mathbf{x} is $y = \text{sgn}(\mathbf{w} \cdot \mathbf{x} + b)$.



The previous problem is equivalent to

$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|_2^2 \quad \text{subject to} \quad y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1 \text{ for all } 1 \leq i \leq n.$$

This is an optimization problem with linear, inequality constraints.

Lagrange method applied to binary SVM

- The Lagrange function is

$$L(\mathbf{w}, b, \lambda_1, \dots, \lambda_n) = \frac{1}{2} \|\mathbf{w}\|_2^2 - \sum_{i=1}^n \lambda_i (y_i (\mathbf{w} \cdot \mathbf{x}_i + b) - 1)$$

- The KKT conditions are

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum \lambda_i y_i \mathbf{x}_i = 0, \quad \frac{\partial L}{\partial b} = \sum \lambda_i y_i = 0$$

$$\lambda_i (y_i (\mathbf{w} \cdot \mathbf{x}_i + b) - 1) = 0, \quad \forall i$$

$$\lambda_i \geq 0, \quad \forall i$$

$$y_i (\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1, \quad \forall i$$

References

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