# Set - 3: Modifications to the logistic equation

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CS302, Modelling and Simulation

#### I. EQUATIONS

#### A. Human Population Model

The logistic growth model is described by the differential equation:

$$\frac{dP}{dt} = rP\left(1 - \frac{P}{K}\right) \tag{1}$$

where: P(t) is the population at time t, r is the growth rate, K is the carrying capacity.

The solution to this equation is:

$$P(t) = \frac{K}{1 + \left(\frac{K - P_0}{P_0}\right)e^{-rt}} \tag{2}$$

where  $P_0$  is the initial population at t = 0.

#### B. Spread of Agricultural Innovation

The dynamical equation for the spread of agricultural innovations among farmers through personal communications is given by

$$\dot{x} = Cx(n-x) \tag{3}$$

similarly, dynamical equation for both through personal and impersonal communications is given by

$$\dot{x} = (Cx + C')(n - x) \tag{4}$$

The x(t) for the spread of agricultural innovations among farmers through personal and impersonal communications is given by

$$x = \frac{NC'[1 - e^{-(CN + C')t}]}{C' + CNe^{-(CN + C')t}}$$
 (5)

Defining 
$$X = \frac{x}{N}$$
,  $T = cNt$ ,  $A = \frac{C'}{CN}$ ,  $\dot{X} \equiv \frac{dX}{dT}$ 

The revised dynamical equation for the spread of agricultural innovations among farmers through personal communications is given by

$$\dot{X} = X(1 - X) \tag{6}$$

X(T) for the spread of agricultural innovations among farmers through personal communications is given by

$$X = \frac{1}{1 + A^{-1}e^{-T}} \tag{7}$$

Recasting dynamical equation,

$$\dot{X} = (X+A)(1-X) \tag{8}$$

X(T) for the spread of agricultural innovations among farmers through impersonal communications is given by

$$X = \frac{1 - e^{-(1+A)T}}{1 + A^{-1}e^{-(1+A)T}} \tag{9}$$

#### C. Harvesting Model

The logistic equation is modified as:

$$\dot{x} = f(x) = rx\left(1 - \frac{x}{k}\right) - h \tag{10}$$

where:  $\dot{x}$  is the rate of change,

r is the growth rate,

k is the carrying capacity,

h is the harvesting rate.

#### In General

• The x(t) of Euler's method is given by

$$x(n+1) = x(n) + f(x(n))\Delta t \tag{11}$$

• The relative error between the analytical solution and the numerical solution is given by

relative error = 
$$\frac{\text{numerical sol} - \text{analytical sol}}{\text{analytical sol}}$$
 (12)

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#### II. GRAPHS

#### A. Question 1

Fig. 1 shows Global Population Growth as per the global census data of 1961.

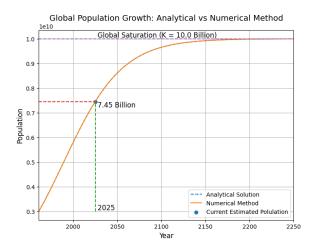


FIG. 1: Included Values:  $a=0.03,\,b=3\times10^{-12},\,x_0=3\times10^9,$  and  $\Delta t=0.001$  unit.

# Fig. 2 shows the relative error between numerical and analytical estimation of human population growth.

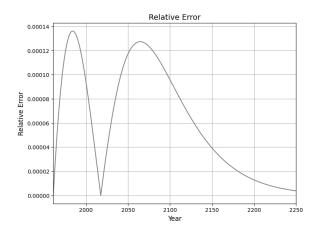


FIG. 2: plot of relative error  $\Delta t = 0.001$  unit

## B. Question 2

Fig. 3 shows  $\dot{X}$  versus X for A = 0, 0.2, 0.5.

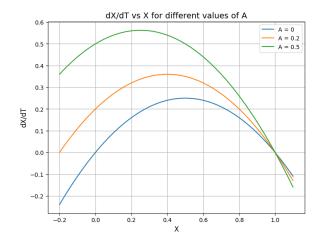


FIG. 3: plot  $\dot{X}$  versus X for A = 0, 0.2, 0.5.  $\Delta x$  =0.001 unit

Fig. 4 shows the integral solution X(T) for  $A=0,\,0.2,\,0.5.$ 

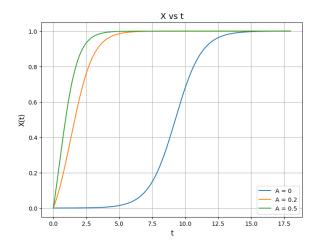


FIG. 4: Plot of the integral solution X(T) for A = 0, 0.2, 0.5 taking initial value X(0) = 0.1,  $\Delta t$ = 0.001 unit

## C. Question 3

Fig. 5 shows  $\dot{x}$  versus x with h = 0, 100, 500.

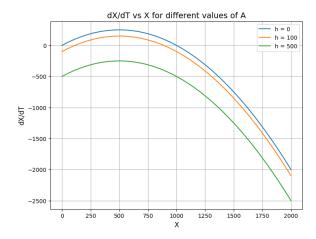


FIG. 5: Here  $r=1,\,k=1000$  and  $\Delta x{=}0.001$  unit

Fig. 6 shows x (by Euler's method) versus t with h=0, 100, 500.

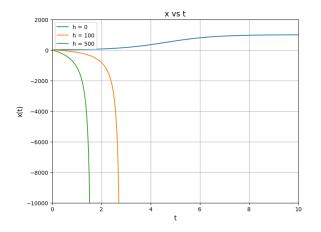


FIG. 6: The initial value are  $r=1,\ k=1000,\ x_0=10$  and  $\Delta t{=}0.001$  unit

Fig. 7 shows comparison between the analytical solution and the numerical solution for h=0.

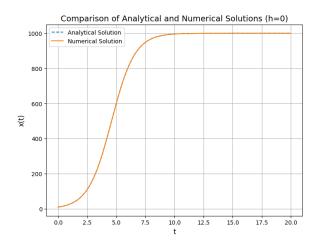


FIG. 7: Here shows comparison between the analytical solution and the numerical solution for  $h{=}0.$   $\Delta t=0.01$  unit

Fig. 8 The relative error between the analytical solution and the numerical solution for h=0.

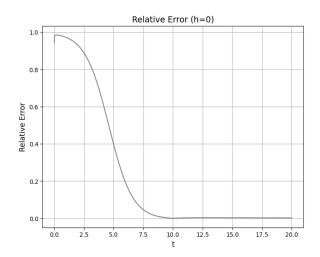


FIG. 8: Here The relative error between the analytical solution and the numerical solution for h=0.  $\Delta t=0.001$  unit