

LAST WEEK: EIGENVECTORS for \mathbb{R} VECTOR SPACES

TODAY: commutation relations
degenerate eigenvalues

in QM, the commutator of 2 matrices (operators)
is SIGNIFICANT. $\Rightarrow [A, B] = AB - BA$

Where does this come from?

eg. Rotations do not commute

(the way in which they
do not commute tells us
about their mathematical
relation to each other)

do example w/ an asymmetric book

BUT: \exists an ∞ # of rotations

\rightarrow BUT A FINITE # of rotation axes

the mathematical structure of "rotations"
is encoded in the comm. relation
w/ infinitesimal rotations.

$$R(\theta) = e^{i\theta T} \quad \text{eg } T = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \text{ for 2D ROT.}$$

$$R_{xy2}(\theta) = e^{i\theta T_{xy2}} \quad \uparrow \text{"GENERATOR"} \rightarrow \text{HERMITIAN: } T^\dagger = T$$

$$[R_x(\phi), R_z(\theta)] \approx_{\phi, \theta \ll 1} (1 + i\phi T_x)(1 + i\theta T_z) - (1 + i\theta T_z)(1 + i\phi T_x)$$

$$= -\theta\phi [T_x, T_z]$$

shows up in
GRUP theory

if $[T_x, T_z] = 0$,
then the
rotations commute

FACT: if 2 SYMMETRIC MATRICES ARE DIAGONALIZED BY THE SAME ROTATIONS, THEN THEY COMMUTE.

$$\begin{aligned} A &= R \hat{A} R^T \\ B &= R \hat{B} R^T \end{aligned} \Rightarrow [A, B] = 0$$

w/ \hat{A}, \hat{B} DIAGONAL

why: $[A, B] = R [\hat{A}, \hat{B}] R^T$
 $= 0$ b/c DIAGONAL MATRICES

turns out: converse is true as well
 (HOW WE USUALLY USE THIS)

$$[A, B] = 0 \Rightarrow \text{can diagonalize BOTH } A \text{ \& } B \text{ by doing one rotation.}$$

EIGENVECTORS SATISFY

$$A \vec{f}_{(i,j)} = \lambda_i \vec{f}_{(i,j)}$$

$$B \vec{f}_{(i,j)} = \beta_j \vec{f}_{(i,j)}$$

MORE CONVENIENT: LABEL A KET BY ITS EIGENVALUES WRT A \& B

$$\vec{f}_{(i,j)} = |\lambda_i, \beta_j\rangle$$

$$\text{s.t. } A |\lambda_i, \beta_j\rangle = \lambda_i |\lambda_i, \beta_j\rangle$$

$$B |\lambda_i, \beta_j\rangle = \beta_j |\lambda_i, \beta_j\rangle$$

if this vector is a QUANTUM STATE, it is characterized by its eigenvalues wrt commuting OPERATORS.

DEGENERATE EIGENVALUES

$$A = R \begin{pmatrix} \lambda & \\ & \lambda \end{pmatrix} R^T = \lambda R R^T = \lambda \mathbb{1}$$

⌈ ANY ORTHONORMAL BASIS IS A BASIS OF EIGENVECTORS ; EACH w/ EIGENVALUE λ

$$\text{eg } e_{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad e_{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$e'_{(1)} = \begin{pmatrix} c \\ -s \end{pmatrix} \quad e'_{(2)} = \begin{pmatrix} s \\ c \end{pmatrix}$$

⌈ RECALL: COLUMNS of ROT matrix
to DIAGONALIZE A
ARE THE EIGENVECTORS.

ANY ROTATION DIAGONALIZES A.

SAME IS TRUE FOR SUBSPACES.

$$A = R \begin{pmatrix} \lambda_1 & \\ & \lambda_2 \end{pmatrix} R^T$$

$$= R \tilde{R} \begin{pmatrix} \lambda_1 & \\ & \lambda_2 \end{pmatrix} \tilde{R}^T R^T$$

$$\uparrow \tilde{R} = \begin{pmatrix} 1 & \\ & c \ s \\ & -s \ 0 \end{pmatrix}$$

So if R diagonalizes A, so does $(R\tilde{R})$.

The columns of R & $(R\tilde{R})$ ARE EQUALLY
VALID EIGENVECTORS.

→ DEGENERATE EIGENVALUES → REDUNDANT OPTIONS
FOR EIGENVECTORS

BREAKING the DEGENERACY IF YOU HAVE A COMMUTING MATRIX to SIMULTANEOUSLY DIAGONALIZE.

EASY CASE: $A = R \left(\begin{array}{c|c} \lambda_1 & \\ \hline & \lambda_2 \lambda_2 \end{array} \right) R^T$

$$C = R \left(\begin{array}{c|c} p_1 & \\ \hline & p_2 p_3 \end{array} \right) R^T$$

then: once you diagonalize C, no more ambiguity.

$$R = \left(\begin{array}{c|c|c} \hat{f}_1 & \hat{f}_2 & \hat{f}_3 \end{array} \right)$$

eigenvectors of C AND A

$$\hat{f}_i = |\lambda_i g p_i\rangle$$

What happened to REDUNDANCY in A? R vs. ($R\tilde{R}$)?

↳ I CAN ROTATE $\underbrace{R \left(\begin{array}{c|c} \lambda_1 & \\ \hline & \lambda_2 \lambda_2 \end{array} \right) R^T}_{A \rightarrow A}$

BUT: this does not work on C

$$\tilde{R} \left(\begin{array}{c|c} p_1 & \\ \hline & p_2 p_3 \end{array} \right) \tilde{R} \neq \left(\begin{array}{c|c} p_1 & \\ \hline & p_2 p_3 \end{array} \right)$$

will be some off diagonal mess.

In fact, two degenerate ^{sim.} matrices that commute w/ different degeneracies can totally lift (remove) the degeneracy

eg $A = R \left(\begin{array}{c|c} \lambda_1 & \\ \hline & \lambda_2 \end{array} \right) R^T$

$$B = R \left(\begin{array}{c|c} p_1 & \\ \hline & p_2 \end{array} \right) R^T$$

$$A \text{ HAS } \underbrace{R \hat{A} R^T}_= \hat{A}$$

$$B \text{ HAS } \underbrace{R R' \hat{B} R'^T}_= \hat{B}$$

$$\text{when } R' = \begin{pmatrix} c & s \\ -s & c \end{pmatrix}$$

BUT: A is not degen w/rt \tilde{R}' } must pick $\tilde{R} = R' = \mathbb{1}$
 B \longrightarrow w/rt \tilde{R} } to diagonalize both

\Rightarrow no ambiguity left in the "correct" eigenbasis.

IN QM: HYDROGEN ATOM: 3 commuting matrices whose eigenvalues carry physical significance

$$[H, L^2, L_z] \rightarrow \text{EIGENBASIS: } |E_n, l, m\rangle$$

↑
 ENERGY (Hamiltonian)
 ↑
 TOTAL ANGULAR momentum, squared
 ↑
 ANGULAR momentum in z-DIR

in QM these take discrete values

eg $L^2 |E_n, l, m\rangle = l(l+1)\hbar^2 | \dots \rangle$
 $L_z | \dots \rangle = m\hbar | \dots \rangle$
 $H | \dots \rangle = E_n | \dots \rangle$

eg. in GROUND STATE, $n=1$

CAN HAVE $l=1$ state

total angular momentum = 1

DEGENERACY: 2 particles w/ spin $\frac{1}{2}$

can be configured

in many ways to give $l=1$

The L_z EIGENVALUES BREAK the DEGENERACY

↑

↑↑

$l=1$

$m=1$

$\frac{1}{\sqrt{2}}(\uparrow\downarrow - \downarrow\uparrow)$

$l=1$

$m=0$

↓↓

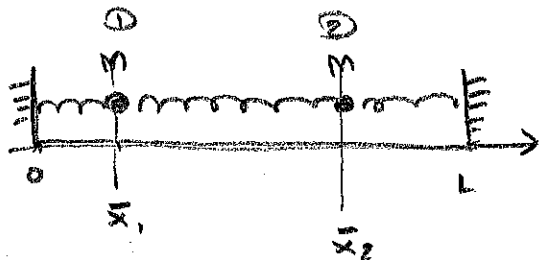
$l=1$

$m=-1$

eg proton, e spin
UP or DOWN

GIVES a fixed basis to describe the
HYDROGEN states w/ DEGENERATE l

"SPRING THEORY" SHANKAR ex 1.6

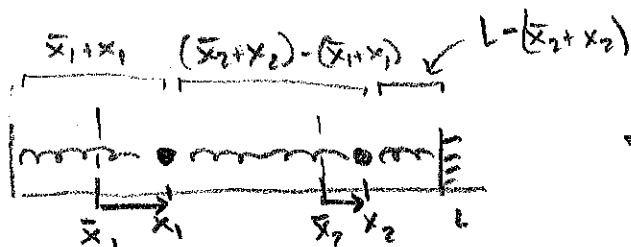


EQUILIBRIUM

Hooke's law: $m\ddot{x} = -kx$

on ① $0 = -k\bar{x}_1 + k(\bar{x}_2 - \bar{x}_1)$

② $0 = -k(\bar{x}_2 - \bar{x}_1) + k(L - \bar{x}_2)$



out of EQUILIBRIUM

x_1, x_2 MEAS. RELATIVE TO EQUILIBRIUM \rightarrow DISPLACEMENTS

$$\begin{aligned} m\ddot{x}_1 &= -k(\bar{x}_1 + x_1) + k((\bar{x}_2 + x_2) - (\bar{x}_1 + x_1)) \\ &= -k\bar{x}_1 + k(\bar{x}_2 - \bar{x}_1) \quad \leftarrow = 0 \\ &\quad -kx_1 + k(x_2 - x_1) \end{aligned}$$

$$\begin{aligned} m\ddot{x}_2 &= -k((\bar{x}_2 + x_2) - (\bar{x}_1 + x_1)) + k(L - (\bar{x}_2 + x_2)) \\ &= -k(\bar{x}_2 - \bar{x}_1) + k(L - \bar{x}_2) \quad \leftarrow = 0 \\ &\quad -k(x_2 - x_1) - kx_2 \end{aligned}$$

coupled 2nd order diff eq.

$$\ddot{x}_1 = -2\frac{k}{m}x_1 + \frac{k}{m}x_2$$

$$\ddot{x}_2 = \frac{k}{m}x_1 - 2\frac{k}{m}x_2$$

$$\ddot{\underline{x}} = \frac{k}{m} \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix} \underline{x} \quad \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

SYMMETRIC MATRIX

BASIS: $|1\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

"displace 1st MASS BY 1 UNIT"

$|2\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

"displace 2nd MASS BY 1 UNIT"

EIGENSTUFE

$$\ddot{x} = \underbrace{\frac{k}{m} \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}}_A x$$

Werte: $\lambda = \frac{k}{m} \bar{\lambda}$

$$\det(A - \lambda \mathbb{1}) = 0 \rightarrow \text{eigene Be } \lambda_1, \lambda_2$$

$$(A - \lambda \mathbb{1}) \vec{f} = 0 \rightarrow \text{eigene Be } \vec{f}_1, \vec{f}_2$$

$$\begin{aligned} \det\left[\frac{k}{m}(A - \bar{\lambda} \mathbb{1})\right] &= \left(\frac{k}{m}\right)^2 \det\begin{pmatrix} -2-\bar{\lambda} & 1 \\ 1 & -2-\bar{\lambda} \end{pmatrix} \\ &= \left(\frac{k}{m}\right)^2 (\bar{\lambda}^2 + 4\bar{\lambda} + 3) \\ &= (\bar{\lambda} + 3)(\bar{\lambda} + 1) \end{aligned}$$

$$\Rightarrow \boxed{\lambda_1 = -\frac{k}{m}} \quad \boxed{\lambda_2 = -3\frac{k}{m}}$$

EIGENWAL ER: $\ddot{f}_1 = -\frac{k}{m} f_1 \equiv -\omega_1^2 f_1$

$\ddot{f}_2 = -3\frac{k}{m} f_2 \equiv -\omega_2^2 f_2$

DEF. NORMALE FREQ.

EIGENVEKTORS :

$$A - \lambda_1 \mathbb{1} = \frac{k}{m} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \rightarrow \underbrace{\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}}_{-a+b=0} = 0$$

$$\vec{f}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \langle \vec{f}_1, \vec{f}_1 \rangle = 1$$

$$A - \lambda_2 \mathbb{1} = \frac{k}{m} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \rightarrow \underbrace{\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}}_{a+b=0} = 0$$

$$\vec{f}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\langle \vec{f}_2, \vec{f}_2 \rangle = 1$$

Now write $\underline{x}(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = x_1(t) \underline{f}_1 + x_2(t) \underline{f}_2$

$$x_1(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + x_2(t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = x_1 \underline{e}_1 + x_2 \underline{e}_2$$

then: $\ddot{\underline{x}}(t) = \ddot{x}_1(t) \underline{f}_1 + \ddot{x}_2(t) \underline{f}_2$

$$= \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix}_E$$

EIGENBASIS

$$= \begin{pmatrix} -\omega_1^2 & 0 \\ 0 & -\omega_2^2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}_E$$

$$\ddot{x}_i = -\omega_i^2 x_i$$

Now assume (init cond) $\dot{x}_i(0) = 0$

$$x_i(t) = \underline{x_i(0)} \cos \omega_i t$$

mit displ. in eig basis

$$\underline{x}(t) = x_1(t) \underline{f}_1 + x_2(t) \underline{f}_2$$

$$= x_1(0) \cos \omega_1 t |\underline{f}_1\rangle + x_2(0) \cos \omega_2 t |\underline{f}_2\rangle$$

convert back to standard basis

Multiply by $\underline{1} = |\underline{e}_1\rangle\langle\underline{e}_1| + |\underline{e}_2\rangle\langle\underline{e}_2|$

$$= x_1(0) \cos \omega_1 t \left(\underbrace{|\underline{e}_1\rangle\langle\underline{e}_1|}_{1/\sqrt{2}} |\underline{f}_1\rangle + \underbrace{|\underline{e}_2\rangle\langle\underline{e}_2|}_{1/\sqrt{2}} |\underline{f}_1\rangle \right) \\ + x_2(0) \cos \omega_2 t \left(\underbrace{|\underline{e}_1\rangle\langle\underline{e}_1|}_{1/\sqrt{2}} |\underline{f}_2\rangle + \underbrace{|\underline{e}_2\rangle\langle\underline{e}_2|}_{-1/\sqrt{2}} |\underline{f}_2\rangle \right)$$

$$\underline{x_1(\omega) \text{ \& } x_2(\omega)} : |x(\omega)\rangle = x_1(\omega)|\zeta_1\rangle + x_2(\omega)|\zeta_2\rangle$$

$$= x_1(\omega) \underbrace{(\langle e_1|\zeta_1\rangle)}_{1/\sqrt{2}} |e_1\rangle + \underbrace{(\langle e_2|\zeta_1\rangle)}_{1/\sqrt{2}} |e_2\rangle$$

$$+ x_2(\omega) \left(\underbrace{(\langle e_1|\zeta_2\rangle)}_{1/\sqrt{2}} |e_1\rangle + \underbrace{(\langle e_2|\zeta_2\rangle)}_{-1/\sqrt{2}} |e_2\rangle \right)$$

$$= \underbrace{\frac{1}{\sqrt{2}} (x_1(\omega) + x_2(\omega))}_{= x_1(\omega)} |e_1\rangle$$

$$+ \underbrace{\frac{1}{\sqrt{2}} (x_1(\omega) - x_2(\omega))}_{= x_2(\omega)} |e_2\rangle$$

can invert to give $x_1(\omega)$ & $x_2(\omega)$
in terms of $x_1(\omega)$, $x_2(\omega)$