

TO DISCUSS

- SHORT HW
- DETERMINANTS, TRACES ; DIAG & MATRICES
- SYM, HERM, UNITARY

finding
eigen.

inverse s

LAST TIME

MATRICES

ANNOYING

NOT SQUARE

PROJECTIONS
(DEGENERATE,
non invertible)

NICE

not symmetric, nondegen

ROTATIONSpreserve
inner product

SYMMETRIC

"DIAGONAL
IN SOME BASIS"SPECIAL
BASIS VECTORS: EIGENVECTORS \vec{e}_i DIAGONAL ELEMENTS: EIGENVALUES, λ_i

$$\text{s.t. } A \vec{e}_i = \lambda_i \vec{e}_i$$

this is IMPORTANT

eg. MATRIX INVERSES ARE HARD
SCALAR INVERSES ARE EASY

$$\text{if } A \vec{e}_i = \lambda_i \vec{e}_i \Rightarrow A^{-1} \vec{e}_i = \frac{1}{\lambda_i} \vec{e}_i$$

EASY!

HOW TO USE: if $\underline{v} = v^1 \vec{e}_1 + v^2 \vec{e}_2 + \dots$

$$\text{then } A^{-1} \underline{v} = v^1 (\lambda_1)^{-1} \vec{e}_1 + v^2 (\lambda_2)^{-1} \vec{e}_2 + \dots$$

EASY! once you know the EIGENVECTORS
& EIGENVALUES.

[do an example]

SYMMETRIC MATRICES

$$\bullet A^T = A \quad \Leftrightarrow \quad \underbrace{\langle \underline{v}, A \underline{w} \rangle}_{\underline{v}^T A \underline{w}} = \underbrace{\langle A \underline{v}, \underline{w} \rangle}_{\underline{v}^T A^T \underline{w}} = \underbrace{\langle \underline{v} | A | \underline{w} \rangle}_{\text{BRA KET}}$$

in abstract vec space (eg 2D dimensional),
THIS WILL BE OUR DEFINITION OF
SYMMETRIC

(there's a version of "SYMMETRIC"
for \mathbb{C} vec spaces: HERMITIAN)

• THERE IS AN ORTHONORMAL BASIS
WHERE A IS DIAGONAL:

$$\underline{e}_i \rightarrow R \underline{e}_i = \underline{\xi}_i \quad \text{for some rotation } R$$

$$A \rightarrow R A R^T = \hat{A} \quad \Leftrightarrow \text{hat is shorthand for "DIAGONAL"}$$

$$\text{s.t. } \boxed{\hat{A} \underline{\xi}_i = \lambda_i \underline{\xi}_i}$$

EIGENVALUE

EIGENVECTOR

notice!
essence of
transformation

REAL ; nb: IDENTICAL EIGVAL \rightarrow SUBSPACE w/ ROT. INVARIANCE

$$\hat{R} \hat{A} \underline{\xi} = \hat{R} \lambda \underline{\xi} = \lambda \hat{R} \underline{\xi}$$

• WHAT ABOUT LESS NICE MATRICES?

\rightarrow PROJECTIONS: SOME EIGENVALUES = 0,

\rightarrow NON-SYMMETRIC MATRICES

\rightarrow EIGENVALUES MAY BE \mathbb{C}

\rightarrow EIGENVECTORS NOT AN ORTHONORMAL BASIS

DETERMINANTS

→ see lec & notes

SUMMARY: if columns of A are vectors:

$$A = \begin{pmatrix} | & | & \dots & | \\ a_1 & a_2 & \dots & a_n \\ | & | & \dots & | \end{pmatrix}$$

then $\det A$ is the volume of the PARALLELEPIPED formed by $\{a_i\}$

↳ generalization of cross product

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

$$\begin{pmatrix} a \\ c \end{pmatrix} \times \begin{pmatrix} b \\ d \end{pmatrix} = ad - bc$$

convenient definition: LEVI-CIVITA TENSOR

↳ "totally antisymmetric tensor in d-DIM"

CONVENTION: $\epsilon^{123\dots d} = +1$
 $(\epsilon_{123\dots d} = +1 \text{ from metric})$

AND: $\epsilon^{\dots ij \dots} = -\epsilon^{\dots ji \dots}$

eg in 2D: $\epsilon = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

then: $\det A = \epsilon^{i_1 i_2 \dots i_n} a^{i_1}_{j_1} a^{i_2}_{j_2} \dots a^{i_n}_{j_n}$
 $= \frac{1}{n!} \epsilon^{i_1 \dots i_n} \epsilon_{j_1 \dots j_n} a^{j_1}_{i_1} \dots a^{j_n}_{i_n}$

eg in 2D: $\det A = \epsilon^{ij} a^i_1 a^j_2 = a^1_1 a^2_2 - a^1_2 a^2_1$ ✓
 $= \frac{1}{2!} (\epsilon^{12} \epsilon_{21} a^1_1 a^2_2) = \frac{1}{2} (a^1_1 a^2_2 - a^1_2 a^2_1)$ ✓
 $= a^2_1 a^1_2 + a^1_1 a^2_2$ ✓

2) LEVI-CIVITA TENSOR: in d-DIM, WE CAN USE LEVI-CIVITA TO FORM INVARIANTS BY CONTRACTING INDICES.

→ RELATED TO MEASURING VOLUMES
 & the d-DIM VOLUME ELEMENT dV
 eg the JACOBIAN IS A DETERMINANT

GOOD WAY
 TO
 FIND
 OR
 MEASURE
 VOLUME

eg the DETERMINANT IS INDEX-FREE → INVARIANT
 IT IS AN INTRINSIC PROPERTY OF THE TRANSFORMATION,
 NO MATTER WHAT BASIS

$$\det A = \det R A R^T$$

$$\det A^{-1} = (\det A)^{-1}$$

OBVIOUS FOR DIAGONAL MATRICES

FACT: $\det(AB) = (\det A)(\det B)$

PROOF (not for m-class)

$$(AB)^i_j = a^i_k b^k_j$$

$$\det AB = \varepsilon^{i_1 \dots i_n} (a^i_{k_1} b^{k_1}_{i_1}) (a^i_{k_2} b^{k_2}_{i_2}) \dots (a^i_{k_n} b^{k_n}_{i_n})$$

$$= (a^i_{k_1} \dots a^i_{k_n}) \underbrace{\varepsilon^{i_1 \dots i_n} (b^{k_1}_{i_1} \dots b^{k_n}_{i_n})}_{\text{ANTISYMMETRY IN } \{i\} \Rightarrow \text{IN } \{k\}}$$

$$(\dots b^{k_a}_{i_a} \dots b^{k_b}_{i_b} \dots) - (\dots b^{k_a}_{i_b} \dots b^{k_b}_{i_a} \dots) + \dots$$

if $k_a = k_b$, these
 cancel → no symm. piece in $\{k\}$

SO: WE SUM OVER PERMUTATIONS OF K w/ SIGN
 → this is just CONTRACTING w/ $\varepsilon_{k_1 \dots k_n}$

$$= \sum_{\{k\}} \text{sgn}(\{k\}) (a^i_{k_1} \dots a^i_{k_n}) \cdot \underbrace{\varepsilon^{i_1 \dots i_n} (b^{k_1}_{i_1} \dots b^{k_n}_{i_n})}_{= \det B \text{ for } \{k\}}$$

$$= \det A$$

$$= (\det A)(\det B) \quad \checkmark$$

for DIAGONAL matrix, $\hat{A} = \text{diag}(\lambda_1, \lambda_2, \dots)$

$$\hookrightarrow \det \hat{A} = \lambda_1 \lambda_2 \dots \lambda_n = \prod_n \lambda_n$$

invariant under rotations: $\det A = \det R \hat{A} R^T$

$$= (\det R)(\det \hat{A})(\det R^T)$$

$$= \det \hat{A}$$

$$\text{b/c } R^T = R^{-1} \rightarrow \det R^T = (\det R)^{-1}$$

\hookrightarrow so $\det A = \text{PRODUCT OF EIGENVALUES IN ANY BASIS.}$

TRACE IS SIMILAR:

$$\text{Tr } A = A^i_i = A^1_1 + A^2_2 + \dots$$

$$\text{Tr } \hat{A} = \lambda_1 + \lambda_2 + \dots$$

$$\text{claim: } \text{Tr } AB = \text{Tr } BA$$

$$A^i_j B^j_i = B^j_i A^i_j$$

$$\text{claim: } \text{Tr } (ABC) = \text{Tr } (CAB) \quad (\text{cyclic})$$

$$A^i_j B^j_k C^k_i = C^k_i A^i_j B^j_k \quad \checkmark$$

$$\Rightarrow \text{Tr } A = \text{Tr}(R \hat{A} R^T) = \text{Tr}(R^T R \hat{A}) = \text{Tr } \hat{A} = \sum \lambda_i$$

\uparrow trace is invariant

EIGENVALUE / CHARACTERISTIC EQ

$$\det A = \det \hat{A} = \prod \lambda_i$$

I want to find λ_i

TRICK: UNKNOWN λ

$$\text{then } \det(\hat{A} - \lambda \mathbb{1}) = \prod (\lambda_i - \lambda)$$

$$\begin{pmatrix} (\lambda_1 - \lambda) & & \\ & (\lambda_2 - \lambda) & \\ & & \ddots \end{pmatrix} = 0 \text{ when } \lambda = \lambda_i$$

this gives an n^{th} degree polynomial
whose roots are λ_i

→ FINDING EIGENVALUES
REDUCES TO SOLVING ALGEBRAIC EQN

SINCE \det is INVARIANT:

$$\begin{aligned} \det(\hat{A} - \lambda \mathbb{1}) &= \det(R(\hat{A} - \lambda \mathbb{1})R^T) \\ &= \det(A - \lambda \mathbb{1}) = \prod (\lambda_i - \lambda) \end{aligned}$$

eg $\begin{pmatrix} a & b \\ b & c \end{pmatrix}$ w/ eigenvals λ_1, λ_2

$$\text{then: } (a - \lambda)(c - \lambda) - b^2 = 0$$

has 2 solutions, $\lambda = \lambda_1, \lambda_2$

we also know: $a + c = \lambda_1 + \lambda_2$

$$\text{CHK: } \lambda^2 - (a+c)\lambda - b^2 \rightarrow \lambda = \frac{-(a+c) \pm \sqrt{(a+c)^2 + 4b^2}}{2}$$

$$\lambda_{\pm} = \frac{a+c \pm \sqrt{a^2 + 2ac + c^2 + 4b^2}}{2}$$

$$\Rightarrow \lambda_1 + \lambda_2 = a + c \quad \checkmark$$