

REM: Stone & Goldb. are pretty good for this + cu. u ish.  
(u. u prob DRAW FROM BOOK FOR HW)

1

## LEC 15: S. RELATIVITY, FORMS

OCT 26

LET'S GET SOME GROUNDING W/ TENSORS & METRICS  
W A SIMPLE, FAMILIAR EXAMPLE

### 2D SPECIAL RELATIVITY (1+1 dim)

easy to generalize to 1+3 dim

START W/ ASSERTION: imagine (1+1) dim Minkowski

this is a flat 2D space with the metric

$$ds^2 = dt^2 - dx^2 \quad \leftarrow \text{relative sign!}$$

(overall sign is convention)

INVARIANT  
DISTANCE

$$\eta_{\mu\nu} ds^\mu ds^\nu$$

BASIS DUAL VECTORS / 1-FORMS

$$\eta_{\mu\nu} = \text{diag}(1, -1)$$

$$\eta^{\mu\nu} = \text{diag}(1, -1)$$

### INVARIANTS ON THIS SPACE:

DOES NOT TRANSFORM UNDER "ROTATIONS"

what are the "rotations" of 2D Minkowski?

~~TRANSFORMS UNDER ROTATIONS~~

things w/ no indices

BECAUSE "INDICES TRANSFORM"

eg consider vectors

$$g^M = \begin{pmatrix} t \\ x \end{pmatrix} \quad \text{; } p^{\mu} = \begin{pmatrix} s \\ y \end{pmatrix}$$

then an invariant is:

$$\underbrace{g^M p^N \eta_{MN}}_{\substack{\rightarrow P_M \\ \text{LOWERS INDEX}}} = \underbrace{\eta_{MN} g^M p^N}_{\rightarrow g_N} = g^M p_M = g_M p^M = \text{etc.}$$

$$g^M p_M = g \cdot p = st - xy$$

even better, the length of  $g$ :

$$\|g\|^2 = g^2 = g^M g_M = g^M g^N \eta_{MN} = \boxed{t^2 - x^2}$$

(analog in  $\mathbb{R}^2$ :  ~~$t^2 + x^2$~~   $t^2 + x^2$ )

$\hookrightarrow$  this is invariant under:  $t \rightarrow t' = \cos \theta t + \sin \theta x$   
 $x \rightarrow x' = -\sin \theta t + \cos \theta x$

$$\text{from } \cos^2 \theta + \sin^2 \theta = 1$$

$$\cos x / \sin x = \frac{1}{2i}(e^{ix} \pm e^{-ix})$$

NOW RECALL HYPERBOLIC TRIG FUNCTIONS

$$\cosh x = \frac{1}{2}(e^x + e^{-x})$$

$$\sinh x = \frac{1}{2}(e^x - e^{-x})$$

satisfy:  $\boxed{\cosh^2 x - \sinh^2 x = 1}$

SO GUESS:  $\begin{pmatrix} t \\ x \end{pmatrix} \rightarrow \begin{pmatrix} \cosh r & \sinh r \\ \sinh r & \cosh r \end{pmatrix} \begin{pmatrix} t \\ x \end{pmatrix}$

IS AN INVARIANCE.

REMARK: NO MINUS SIGN ON LOWER-LEFT!  
in representation theory parlance:  
this "rotation" is non-compact.

NB: IN  $\mathbb{R}^2$ :  $\begin{pmatrix} c & s \\ -s & c \end{pmatrix}$  MINUS SIGN MEANT:  
AS ONE THING GETS BIGGER, SOMETHING  
ELSE IS GETTING SMALLER. IN  $\mathbb{R}^{1,1}$ ,  
CAN JUST KEEP MAKING THINGS 'BIGGER'

CHECK:  $q \rightarrow q' = \begin{pmatrix} ct + sx \\ st + cx \end{pmatrix} \leftarrow \text{where now } c = \cosh r \text{ etc.}$

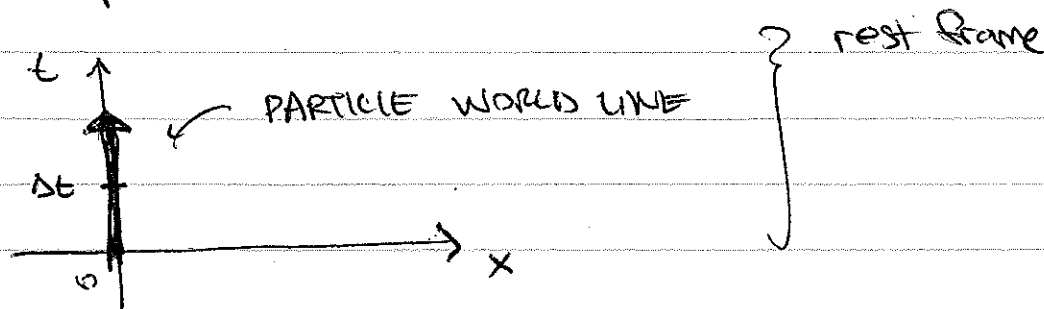
$$\begin{aligned} q'^2 &= (ct + sx)^2 - (st + cx)^2 = \cancel{c^2 t^2} + \cancel{2cs tx} + \cancel{s^2 x^2} \\ &\quad - \cancel{s^2 t^2} - \cancel{2cs tx} - \cancel{c^2 x^2} \\ &= t^2 - x^2 \quad \checkmark \end{aligned}$$

$x$  IS PARTICLE POSITION.

↓  
CONNECT THIS TO PHYSICS

START w/ A FRAME WHERE PARTICLE IS AT REST  
↑ COORDINATES!

$$\Rightarrow \text{velocity} = 0 \leftarrow \Delta x / \Delta t = 0$$



NOW TRANSFORM : ("ROTATE")

$$\begin{pmatrix} t \\ x \end{pmatrix} \rightarrow \begin{pmatrix} t \cosh \eta + x \sinh \eta \\ t \sinh \eta + x \cosh \eta \end{pmatrix} = \begin{pmatrix} t' \\ x' \end{pmatrix}$$

still  $(0,0)$  for  $t=x=0$ .

BUT NOW CONSIDER SOME  $t = \Delta t$

$$x = \Delta x = 0$$

$$\text{then: } \begin{pmatrix} \Delta t' \\ \Delta x' \end{pmatrix} = \begin{pmatrix} \Delta t \cosh \eta \\ \Delta t \sinh \eta \end{pmatrix}$$

∴ the velocity in this frame is

$$\boxed{\frac{\Delta x'}{\Delta t'} = \tanh \eta} \leftarrow \eta \text{ IS THE RAPIDITY}$$

↑ velocity  $\equiv \beta$  ( $= v/c$  for the dimensionful)

BUT NOW I WANT TO CONNECT THIS TO MORE FAMILIAR THINGS:

$$\Lambda = \begin{pmatrix} \cosh R & \sinh R \\ \sinh R & \cosh R \end{pmatrix}$$

$$\cosh^2 R - \sinh^2 R = 1$$

$$\Rightarrow 1 - \frac{\tanh^2 R}{\beta^2} = \frac{1}{\cosh^2 R}$$

↑  
to left element

$$\Rightarrow \Lambda = \begin{pmatrix} \gamma & \dots \\ \dots & \gamma \end{pmatrix} \quad \gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$$

BECAUSE  $\beta < 1 \Rightarrow$  gives time dilation

$$\Delta t' = \Delta t \gamma$$

$$\text{also: } \sinh R = \tanh R \cosh R \\ = \beta \gamma$$

$$\Rightarrow \Lambda = \begin{pmatrix} \gamma & \gamma\beta \\ \gamma\beta & \gamma \end{pmatrix}$$

2D LORENTZ TRANSFORM

FORMS

CONSIDER DUAL VECTORS. WE'VE SEEN  
2 EXAMPLES OF TENSORS w/ LOWER INDICES:

$$\text{METRIC } \eta_{\mu\nu} \hookrightarrow ds^2 = \underbrace{\eta_{\mu\nu}}_{\text{SYMMETRIC}} dx^\mu dx^\nu$$

$$\text{DIFFERENTIAL OF A FUNCTION: } dp = \frac{\partial f}{\partial x^i} dx^i$$

NOW WE WILL FOCUS ON A SPECIFIC CLASS OF  
DUAL VECTORS: THOSE w/ ANTISYMMETRIC INDICES.

FACT (pf is HW):

$$T_{ij} \dots = \underbrace{\frac{1}{2}(T_{ij} \dots + T_{ji} \dots)}_{\text{SYMMETRIC PART}} + \underbrace{\frac{1}{2}(T_{ij} \dots - T_{ji} \dots)}_{\text{ANTISYMMETRIC PART}}$$

$$= S_{ij} \dots = A_{ij} \dots$$

further: under a "rotation",

$S \rightarrow S'$  another symmetric matrix

$A \rightarrow A'$  another antisym. matrix

SO WE CAN TALK ABOUT ~~ANY~~ ANTISYM.  
MATRICES "BY THEMSELVES"

↳ "why?" will be clear soon.

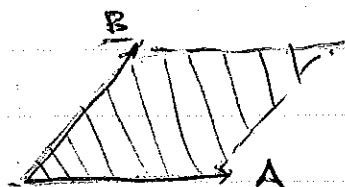
~~WHAT IS THE CROSS PRODUCT?~~

GIVEN 2 VEC IN

IMAGINE THE CROSS PRODUCT: (in  $\mathbb{R}^2$ )

$$\underline{A} \times \underline{B} = AB \sin \theta \leftarrow$$

$$= -\underline{B} \times \underline{A}$$



$$\underline{A} \times \underline{B} = (\pm) \underline{AREA}$$

$$\underline{A} \times \underline{B} = \begin{vmatrix} a^1 & b^1 \\ a^2 & b^2 \end{vmatrix} \leftarrow \text{det.}$$

$$= a^1 b^2 - a^2 b^1 \leftarrow \text{antisymmetric}$$

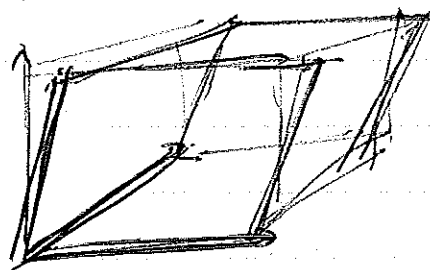
$$= \epsilon_{ij} a^i b^j$$

IN FACT: THIS GENERALIZES

given (3) 3-vectors  $\underline{A}, \underline{B}, \underline{C} \in \mathbb{R}^3$

VECTOR TRIPLE PRODUCT

$$\underline{A} \cdot (\underline{B} \times \underline{C}) =$$



Volume of  
parallelepiped

What a weird combination of  
3-vector operations. . .

TURNS OUT: (on  $\mathbb{R}^3$ )

$$A \cdot (B \times C) = \begin{vmatrix} a^1 & b^1 & c^1 \\ a^2 & b^2 & c^2 \\ a^3 & b^3 & c^3 \end{vmatrix} \quad \leftarrow \text{det}$$

$$= \underbrace{\sum_{ijk} \epsilon^{ijk} a^i b^j c^k}_{\substack{\text{3D LEVI-CIVITA TENSOR} \\ \text{ONE PERSON}}}$$

† so forth: the volume of an  $n$ -dim parallelepiped is ↖ w/ sides  $A_{ij}$

$$\left| \epsilon_{i_1 \dots i_n} a_{i_1}^{i_1} \dots a_{i_n}^{i_n} \right|$$

ANTISYMMETRIC FORMS  $\longleftrightarrow$  VOLUMES

$\rightsquigarrow$  integration?



# DIFFERENTIAL K-FORMS

## GENERALIZATION OF $df$

$$\boxed{\omega_{\mu_1 \dots \mu_n}(x)}$$

$\underbrace{\mu_1 \dots \mu_n}_{n \text{ lower indices}}$   
 in gen, func. of position

$$\underbrace{dx^{\mu_1} \wedge dx^{\mu_2} \wedge \dots \wedge dx^{\mu_n}}_{\text{basis of antisymmetric tensors}}$$

basis of antisymmetric tensors

sometimes  $1/n!$

$$dx^{\mu_1} \wedge dx^{\mu_2} = dx^{\mu_1} \otimes dx^{\mu_2} - dx^{\mu_2} \otimes dx^{\mu_1} \text{ etc.}$$

a special one: the VOLUME FORM  $d\Omega^{(n)}$  in  $n$ -DIM  
 (NOT ANGULAR DIFFERENTIAL, SORRY FOR NOTATION)

$$\int_V d\Omega^{(n)} = \int_V dx^{\mu_1} \wedge \dots \wedge dx^{\mu_n} = \text{Vol}(V)$$

WEDGE PRODUCT:

$$W = \omega_{\mu_1 \dots \mu_n} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_n}$$

$$P = p_{\nu_1 \dots \nu_p} dx^{\nu_1} \wedge \dots \wedge dx^{\nu_p}$$

$$W \wedge P = \omega p \underbrace{dx^{\mu_1} \wedge \dots \wedge dx^{\mu_n} \wedge dx^{\nu_1} \wedge \dots \wedge dx^{\nu_p}}$$

note:  $dx^{\mu_1} \wedge dx^{\mu_1} = 0$

$$\Rightarrow dx^{\mu_1} \wedge \dots \wedge dx^{\mu_n} \text{ for } n > \dim(M) = 0$$

EXTERIOR DERIVATIVE

↳ DIFFERENTIAL OPERATOR

$$\text{eg } df(x) \rightarrow \underbrace{\frac{\partial f}{\partial x^i}}_{\substack{\uparrow \\ \text{COMPONENT}}} \underbrace{dx^i}_{\substack{\uparrow \\ \text{BASIS 1-FORM}}}$$

$$\text{eg if } u = u(x, y), \quad du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy$$

$$\text{eg if } v = v(x, y) \quad \text{--- 4 ---}$$

$$\begin{aligned} du \wedge dv &= (u_x dx + u_y dy) \wedge (v_x dx + v_y dy) \\ &= u_x v_x \cancel{dx \wedge dx} + u_x v_y dx \wedge dy \\ &\quad + u_y v_x dy \wedge dx + u_y v_y \cancel{dy \wedge dy} \end{aligned}$$

$$= \underbrace{(u_x v_y - u_y v_x)}_{\text{Jacobian}} dx \wedge dy$$

$$\begin{vmatrix} u_x & v_x \\ u_y & v_y \end{vmatrix} = \text{Jacobian}(u, v; x, y)$$

IN GENERAL: for  $k$ -form  $W = \underbrace{w_{i_1 \dots i_k}}_{\substack{\uparrow \\ w_{i_1 \dots i_k}(x) \leftarrow \text{function of } M}} dx^{i_1} \wedge \dots \wedge dx^{i_k}$

$$\boxed{dW = \underbrace{(\partial_v w_{i_1 \dots i_k})}_{(k+1) \text{ tensor}} dx^v \wedge dx^{i_1} \wedge \dots \wedge dx^{i_k}}$$

(k+1) tensor

(or (0, k+1)-tensor to be precise)

$d$ :  $k$ -forms "over  $M$ "  $\rightarrow$   $(k+1)$ -forms over  $M$

this space is related to  
the "cotangent bundle"

OBSERVE:  $d^2 = 0$  ( $d$  is NILPOTENT)

$$d\omega = \partial_\nu \omega_{\mu \dots} dx^\nu \wedge dx^\mu \wedge \dots \frac{1}{(k-1)!}$$

$$d^2 \omega = \partial_\rho \partial_\nu \omega_{\mu \dots} dx^\rho \wedge dx^\nu \wedge dx^\mu \wedge \dots \frac{1}{(k-2)!}$$

$\downarrow$   
SYMMETRIC IN  
 $\rho \leftrightarrow \nu$

$\downarrow$   
ANTISYMMETRIC IN  $\rho \leftrightarrow \nu$

$$S_{\rho\nu} = \frac{1}{2}(S_{\rho\nu} + S_{\nu\rho})$$

$$A^{\rho\nu} = \frac{1}{2}(A^{\rho\nu} - A^{\nu\rho})$$

~~$$S_{\rho\nu} A^{\rho\nu} = \frac{1}{2}(S_{\rho\nu} + S_{\nu\rho}) A^{\rho\nu} = \frac{1}{2} S_{\rho\nu} A^{\rho\nu} + \frac{1}{2} S_{\nu\rho} A^{\rho\nu}$$~~

s.t. eg  ~~$S_{\rho\nu}$~~   $S_{\rho\nu} = \frac{1}{2}(A^{\rho\nu} - A^{\nu\rho})$

$$= \frac{1}{2} S_{\rho\nu} A^{\rho\nu} - \frac{1}{2} S_{\rho\nu} A^{\nu\rho}$$

$$= \frac{1}{2} S_{\nu\rho} A^{\nu\rho}$$

$$= 0$$

F IS EXACT (comes from potential)

A VERY NICE EXAMPLE: EM

$$A = (\phi, \vec{A})$$

$$F = dA \quad \text{on } \mathbb{R}^{1,3} \text{ (generalizes)}$$

$$\begin{aligned} \uparrow \\ \frac{1}{2} F_{\mu\nu} dx^\mu \wedge dx^\nu &= d(A_\nu dx^\nu) \\ &= \underbrace{\partial_\mu A_\nu}_{\text{effectively antisymmetrized}} \underbrace{dx^\mu \wedge dx^\nu}_{\text{ANTISYM.}} \end{aligned}$$

effectively antisymmetrized

$$\text{i.e. } (\partial_\mu A_\nu - \partial_\nu A_\mu) dx^\mu \otimes dx^\nu$$

$$F = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ + & 0 & -B_z & B_y \\ - & + & 0 & B_x \\ - & + & + & 0 \end{pmatrix}$$

antisymmetric

transformations of this give

$E$  &  $B$  in different frames

→ shows that  $E$  &  $B$  fields transform into each other under boosts

OBSERVE :  $dF = ddA = 0$

"F IS A CLOSED FORM"

for our purposes: CLOSED = EXACT.