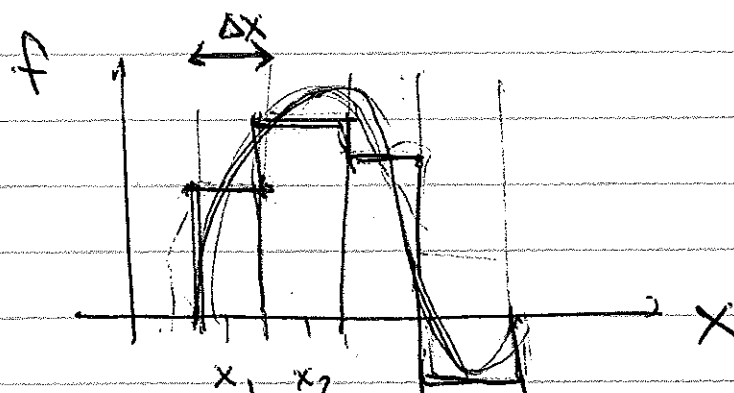


LECTURE 3

23 SEPT

LAST TIME: "DISCRETIZED FUNCTION" AS A
 CRUTCH TO UNDERSTAND FUNCTION SPACE AS
 VECTOR SPACE.



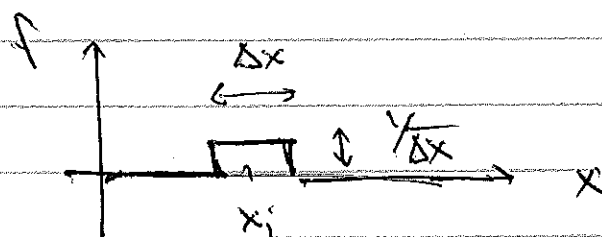
BASIS VECTORS:

← CORRECTION FROM LAST TIME

$$|e_i\rangle = \begin{cases} \frac{1}{\Delta x} & \text{if } x \in [x_i - \frac{\Delta x}{2}, x_i + \frac{\Delta x}{2}) \\ 0 & \text{otherwise} \end{cases}$$

↑

$e_i(x)$



WHY? A GOOD BASIS IS ORTHONORMAL

↑

DEPENDS ON INNER
 PRODUCT.

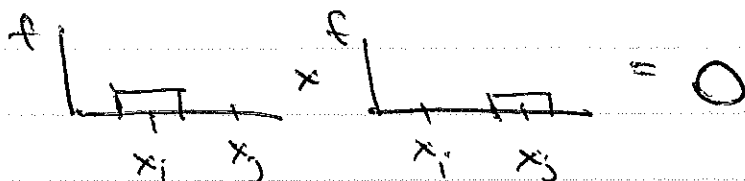
ON OUR FAVORITE FUNCTION SPACE (HILBERT SPACE)
WE HAVE THE FOLLOWING INNER PRODUCT

$$\langle f | g \rangle = \int_{-\infty}^{\infty} f^*(x) g(x) dx \approx \sum_i f^*(x_i) g(x_i) \Delta x$$

~~$$\langle e_i | e_j \rangle = \int_{x_i - \Delta x/2}^{x_i + \Delta x/2} \frac{1}{\Delta x} \frac{1}{\Delta x} dx = \frac{1}{\Delta x} \quad ?!$$~~

$$\langle e_j | e_i \rangle = 0 \quad \text{because}$$

$j \neq i$



"has no support"

$$\langle e_i | e_i \rangle = \sum_i \left(\frac{1}{\Delta x} \right) \left(\frac{1}{\Delta x} \right) \Delta x = \frac{1}{\Delta x}$$

$$\text{or: } \langle e_i | e_j \rangle = \frac{1}{\Delta x} \delta_{ij} \rightarrow \delta(x_i - x_j) \neq \delta_{ij}$$

↳ SO I LIED LAST TIME. THIS IS A
WEIRD BASIS. δ IS PART OF THE WEIRDNESS
OF ∞ -DIM VECTOR SPACES!
IN PART THIS IS BECAUSE δ FUNCTIONS
ARE NOT REAL FUNCTIONS AND AREN'T
PART OF OUR FUNCTION SPACE. WE ~~WANT~~ ^{WANT}
TO USE THEM AS BASIS VECTORS, THE
COST IS WEIRD BEHAVIOR LIKE $\langle e_i | e_j \rangle$

nb I DON'T THINK YOU CAN FIX THIS

eg. IF YOU USED

$$|e_i\rangle = \begin{array}{c} \xleftarrow{\Delta x} \xrightarrow{\hspace{1cm}} \\ \text{---} \boxed{\hspace{1cm}} \text{---} \\ \text{---} x_i \text{---} \end{array} \updownarrow \sqrt{\Delta x}$$

$$\text{then } \langle e_i | e_j \rangle = \sum_k e_i(x_k) e_j(x_k) \Delta x \\ = \delta_{ij} \quad \checkmark$$

BUT THEN: $e_i(x)$ is NOT NORMALIZED
TO INTEGRATE TO 1
→ doesn't become δ -fun.

$$|f\rangle = \sum_i \underbrace{f(x_i)}_{C_i} \underbrace{\sqrt{\Delta x}}_{\text{weight}} |e_i\rangle$$

WHAT'S REALLY HAPPENING IS

$$\lim_{x_i \rightarrow x_j} \int dx \, \delta(x-x_i) \delta(x-x_j) = \delta(x_i-x_j)$$

LHS IS DISASTER
WHEN $x_i = x_j$

INTERPRET
AS DISTRIBUTION.



ANYWAY: ALL THAT IS TO SHOW THAT SOMETIMES
OUR INTUITION BREAKS DOWN.
↳ OUR SIMPLE MODELS.

ESP WHEN GOING FROM FINITE $\rightarrow \infty$ DOF.
(e.g. tunneling)

AS PHYSICISTS: PUSH ON ANYWAY!

(UNLESS IT BREAKS WHERE
WE NEED IT.)
↗
e.g. INFORMATION LOSS PROBLEM

DERIVATIVES

$$\begin{array}{ccc} & \checkmark f_i = f(x_i) & \frac{d}{dx} f(x_i) \\ & & \Downarrow \\ \begin{pmatrix} \vdots & \frac{-1}{\Delta x} & \frac{+1}{\Delta x} & \vdots \end{pmatrix} \begin{pmatrix} f_i \\ f_{i+1} \\ \vdots \end{pmatrix} & = & \begin{pmatrix} \vdots & \frac{1}{\Delta x} (f(x_{i+1}) - f(x_i)) & \vdots \end{pmatrix} \\ & & \uparrow \\ & & f(x_i + \Delta x) \end{array}$$

SO: DIFFERENTIAL OPERATORS ARE
SIMPLY MATRICES IN THIS CASE

~~SE~~

WHAT ABOUT SECOND DERIVATIVES?

$$\begin{pmatrix} & i-1 & i & i+1 \\ & \frac{1}{\Delta x^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} \end{pmatrix} \begin{pmatrix} f_{i-1} \\ f_i \\ f_{i+1} \end{pmatrix} = \left(\frac{f(x_i + \Delta x) - f(x_i)) - (f(x_i) - f(x_i - \Delta x))}{\Delta x^2} \right)$$

Q: HAS ANYONE USED 3RD & DIFF EQ?

$$\boxed{d^2 f / dx^2}$$

OBSERVE: as you expect intuitively from Taylor expansion,

~~however~~

HIGHER ORDER DERIVATIVES
ARE INCREASINGLY NONLOCAL,
PROBE SPACETIME/SPACETIME
POINTS THAT ARE FAR APART.

You also probably have a good sense now that physics is LOCAL.

↳ SO IT IS DESCRIBED BY LOW ORDERS OF DERIVATIVES. «

NEED SOME DERIV. B/C
WE'RE DESCRIBING DYNAMICS
(how things change in time)

SO PHYSICS LOOKS SOMETHING LIKE THIS:

$$\begin{pmatrix} 0 & & \\ & 0 & \\ & & \ddots \end{pmatrix} \begin{pmatrix} 1 \\ \vdots \\ f(x_i) \\ \vdots \end{pmatrix} = \dots$$

typically up to 2ND ORDER.

WHY SECOND ORDER ? NOT THIRD? FOURTH?

↳ DIMENSIONAL ANALYSIS.

$\frac{d}{dt}$ HAS DIMENSIONS.

ACTION DOES TOO (not in natural units)

↑
in nat units $e^{iS/\hbar}$ I GUESS.

$$S = \int dt L = \int \underbrace{d^4x}_{\text{DIM}} \underbrace{\mathcal{L}}_{\text{DIM}}$$

IF YOU WANT A TERM IN \mathcal{L} WITH MORE DERIVATIVES, YOU PICK UP OTHER DIMENSIONFUL PARAMETERS TO COMPENSATE.

↳ typically get k/Λ suppression.

$$A|f\rangle = |g\rangle \Rightarrow \int dy \underline{A(x,y)} f(y) = g(x)$$

$$\uparrow$$

$$\sum_j A_{ij} f_j = g_i$$

[upto some factors of Δx]

WHAT DOES THIS MEAN

Green's functions: $f = A^{-1}g$

LINEAR DIFF. OPERATORS

$A(x,y)$ is written to look nonlocal

we can also write it in an "expansion in locality", ie as a differential operator

$$A = \sum_n a_n(x) \left(\frac{d}{dx} \right)^n$$

\uparrow LOCAL FUNCTION

\nwarrow DIFFERENTIAL OPERATOR

* REMARK: see SG § 3.2 FOR NORMAL FORM

\hookrightarrow GIVES SCHRÖDINGER-TYPE EQ,

IN PHYSICS, typically $\left[a_2(x) \frac{d^2}{dx^2} + a_1(x) \frac{d}{dx} + a_0(x) \right] f$

DEF: $\tilde{f} = h(x) f(x) \rightarrow$ ~~$\tilde{f} = h(x) f(x)$~~

$$(a_2 h) f'' + (a_1 h + 2a_2 h') f' + (a_0 h + a_1 h')$$

$$\text{SET } = 0; \quad h = \exp \left[-\frac{1}{2} \int_0^x \frac{a_1(y)}{a_2(y)} dy \right]$$

then: a BET EQ of form

$$\left[b_2(x) \left(\frac{d}{dx} \right)^2 + b_0(x) \right] f \rightarrow \text{series of } \dots$$

USEFUL TO DEF A GENERALIZED INNER PRODUCT:

$$\langle f | g \rangle_w = \int_0 \underbrace{w(x)}_{\substack{\uparrow \\ \text{WEIGHT FUNCTION}}} f^*(x) g(x) dx$$

\uparrow
FUNCTIONS OBEYING
BOUNDARY CONDITIONS

WEIGHT FUNCTION

eg. in spherical coords
METRIC COMES w/ r^2

SO HAVING A WEIGHT HERE
IS ACTUALLY RATHER NATURAL.

\uparrow eg also in curved space
WHERE $d^4x \rightarrow \sqrt{|g|} d^4x$

THEN WE ALSO WANT SENSE OF HERMITICITY

$$\langle f | A g \rangle_w = \langle A^+ f | g \rangle_w$$

\uparrow
UN. DIFF. OPERATOR

WANT: $\int_0 w(x) f^*(x) \left(\sum_n a_n(x) \left(\frac{d}{dx} \right)^n \right) g(x) dx$

MOVE OVER TO ACT
ON $f(x)$

ST. EXPR. STAYS SAME.

HOW TO DO IT? INTEGRATION BY PARTS.

USEFUL EXAMPLE: 1D MOMENTUM

$$\boxed{P = -i \frac{d}{dx}}$$

$$\langle f | g \rangle_{W=1} = \int f^*(x) g(x) dx \quad \text{USUAL } L^2 \text{ NORM}$$

↑

WAVEFUNCTIONS IN QM (Φ functions)

SQUARE INTEGRABLE → $\text{BC} \in \infty$

$$\frac{d}{dx}(fg) = f'g + fg'$$

$$\langle f | P g \rangle = \int f^*(x) \left(-i \frac{d}{dx}\right) g(x) dx$$

$$= (-i) \int \left(\frac{d}{dx} f^*(x)\right) g(x) dx - i \int \frac{d}{dx} (f^* g) dx$$

$$= \int \left(-i \frac{d}{dx} f(x)\right)^* g(x) dx + \int \frac{d}{dx} Q dx$$

USUAL DERIV.
 $= \frac{d}{dx} Q$

$$= \langle P f | g \rangle + \int \frac{d}{dx} Q dx$$

↑
 $P^\dagger = P$
 SELF ADJOINT
 (HERMITIAN)

$$= Q = 0$$

as long as
 f, g SATISFY
 BC

BC IMPORTANT! PART OF
 DEFINITION OF HERMITIAN ONS.

OBS: ROLE OF THE i ! REQ. FOR HERMITICITY
 → R eigenvalues, ORTHOG EIGENFUN.

STURM-LIOUVILLE PROBLEMS

IT IS COMMON IN PHYSICS TO HAVE FUNCTIONALS (like HAMILTONIANS) of the FORM :

(see 1.178) ~~1~~

$$S[f] = \int_{x_1}^{x_2} \left[\frac{1}{2} P(x) (f'(x))^2 + \frac{1}{2} q(x) f(x)^2 \right] dx$$

↑
 $f(x) = 0$ @ x_1, x_2

↑ SOME NORMALIZE, eg. $\int_{x_1}^{x_2} f^2 dx = 1$

IN SOME GOLDBART § 1.5 THIS IS TREATED AS
A LAGRANGE MULTIPLIER PROBLEM.

I'D LIKE TO WRITE AS

$$S(f) = \int_{x_1}^{x_2} \frac{1}{2} P(x) \odot f'(x) \odot f(x) dx$$

BECAUSE THEN EOM IS ~~$\odot f(x) = 0$~~

$$\odot f(x) = 0.$$

PROBLEM IS $\frac{1}{2} P(x) \left(\frac{d}{dx} f(x) \right) \left(\frac{d}{dx} f(x) \right)$
INT. BY PARTS:

$$= -\frac{1}{2} f(x) \frac{d}{dx} \left[P(x) \frac{d}{dx} f(x) \right]$$

END UP W/

$$\boxed{-[P(x) f'(x)]' + q f = 0}$$

↑
STURM-LIOUVILLE PROBLEM
COMES UP OVER & OVER AGAIN.

PROBLEM: REDUCING GENERAL 2nd ORDER LIN DIFF OF
TO SCHRÖDINGER FORM.

WE CAN DO SOMETHING SIMILAR TO
REDUCE TO STURM-LIOUVILLE FORM

SG. P. 166

$$A = a_2 \left(\frac{d}{dx} \right)^2 + a_1 \frac{d}{dx} + a_0$$

↑ ↑ ↑ functions of x

TO AVOID
SINGULAR
POINT

→ SUPPOSE $a_2 > 0$ over domain I $a_i \in \mathbb{R}$

DEF. $W = \frac{1}{a_2(x)} \int_{x_1}^x \frac{p a_1(y)}{a_2(y)} dy$ weight!

POSITIVE ON (x_1, x_2)

$$A f = \frac{1}{w} (w a_2 y')' + a_0 y$$

$$\frac{1}{w} [\underbrace{w' a_2 y'}_{w a_1 - a_2' w y'} + w a_2 y'']$$

NOW CHECK: $\langle f | A g \rangle \stackrel{?}{=} \langle A f | g \rangle$

$$\begin{aligned} \langle f | A g \rangle &= \int dx w \frac{1}{w} (w a_2 g')' f^* + a_0 f^* g \\ \langle A f | g \rangle &= \int dx (w a_2 f')' g + a_0 f^* g \end{aligned}$$

$$\begin{aligned} &= \int \frac{d}{dx} (w a_2 g' f^*) - w a_2 g' f^{*'} \\ &\quad - \int \frac{d}{dx} (w a_2 g^* f') + w a_2 g^* f' \end{aligned}$$

= 0 for
DIRICHLET or
NEUMANN.

$$= \int_{x_1}^{x_2} [w a_2 g' f^* - w a_2 g^* f'] dx$$

= Q

EIGENVALUE PROBLEM B

$$\underbrace{Af}_{\substack{\uparrow \\ a_2}} = \lambda f$$

$$\frac{1}{w} (w \frac{a_2}{w} f')' + a_0 f = \lambda f$$

$$\boxed{(w a_2 f')' + w a_0 f = \lambda w f}$$

So Stone & Goldbart offer
the following hint:

IF YOU SEE AN EIGENVAL EQ.

W/ WEIGHT ON RHS; SUSPECT

IT IS SELF-ADJOINT WRT W.

↑

RR eigenvals

ORTHOG EIGENF.

(PARTIAL) DIFFERENTIAL EQUATIONS

MANY VARS. eg
SPACE + TIME

↑
not integrable
in general!!

BAG OF TRICKS
APPROACH

↑
1 INDEP. VAR.
USUALLY TIME

↓
SOLUTION EXISTS
& IS UNIQUE
(Picard thm)

$$y' = F(x, y)$$

$$\left\{ \begin{array}{l} f_1' = f_2 \\ f_2' = f_3 \\ f_3' = f_4 \\ \vdots \\ f_n' = f_{n+1} \dots \end{array} \right.$$

TRICK TO WRITE n^{th}
① ODE AS 1st ②
ODE IN HIGHER DIM

GRAPHICALLY:
VECTOR FIELDS
THAT HAVE TO
BE INTEGRATED
TO DETERMINE
FLOWS.

↓
These flows ~~form~~ ^{calculate}
manifolds —
becomes a
geometric question

conversely, easy to solve numerically

(P) DIFF EQNONLINEARcontains powers of $f(x)$
or $\left[\left(\frac{d}{dx} \right)^k f(x) \right]$ cannot be written as Af
what to do if you're faced
w/a nonlinear DIFF EQ?GO HOME & RECONSIDER YOUR
LIFE CHOICESLINEAR : $Af(x)$ $= 0$

HOMOGENEOUS

just solve it

 $= g(x)$

INHOMOGENEOUS

green's functions

piece together
solutionSOME OTHER
FUNCTION