

LEC 16: DIFFERENTIAL FORMS

28 OCT

→ "Vector calculus" is really "form calculus"

• SEE STONE & GOLDBART

• also: math.GT/0306194

ADV: A. NEWERNEY

1st steps in DIFF GEO.

or: ANY GE TEXT.

REVIEWBASIS OF DUAL VECTORS: dx^i

s.t. $dx^i(\partial_j) = \delta^i_j$

↑ BASIS OF VECTORS

$V = V^i \partial_i$

can act on a function $f: M \rightarrow \mathbb{R}$
to give directional derivativeHOW DO WE GET THESE dx^i 's?

DIFFERENTIAL OPERATOR / EXTERIOR DERIVATIVE

 $d: k\text{-form} \rightarrow (k+1)\text{form}$ so: a 0-form is just a function, f .
(has no form-ness.)

$df = \frac{\partial f}{\partial x^i} \boxed{dx^i}$

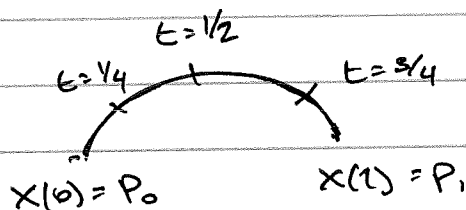
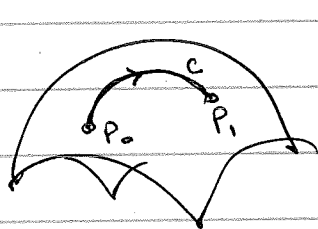
↑ basis 1-form

↑ takes a vector V to give directional deriv.

df is a 1-form

BORN TO BE INTEGRATED: $\int_C df = ?$

from ordinary calculus, you instinctively want to write: $\int_C df = f(P_1) - f(P_0)$



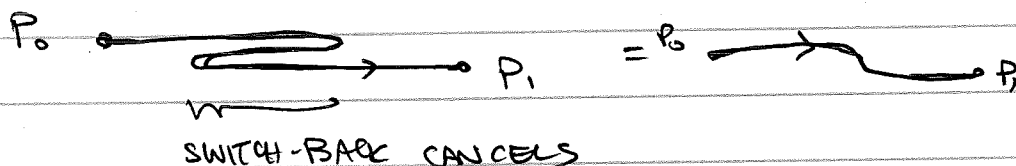
ONE WAY TO SEE THIS: PARAMETERIZE THE

PATH: let $x: \mathbb{R} \rightarrow M$ s.t. $\begin{cases} x(1) = P_1 \\ x(0) = P_0 \end{cases}$
 \uparrow LIKE A TIME PARAM

$$\text{then: } \int_C df = \int_0^1 \left(\frac{df(x(t))}{dt} \right) dt$$

"signed integral"

$$\frac{\partial f(x(t))}{\partial x^i} \underbrace{\frac{\partial x^i}{\partial t}}$$

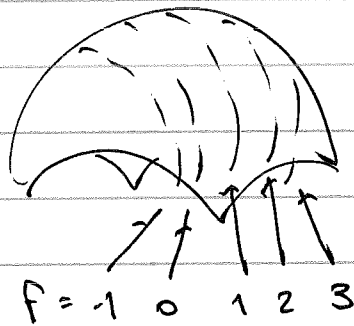


HW

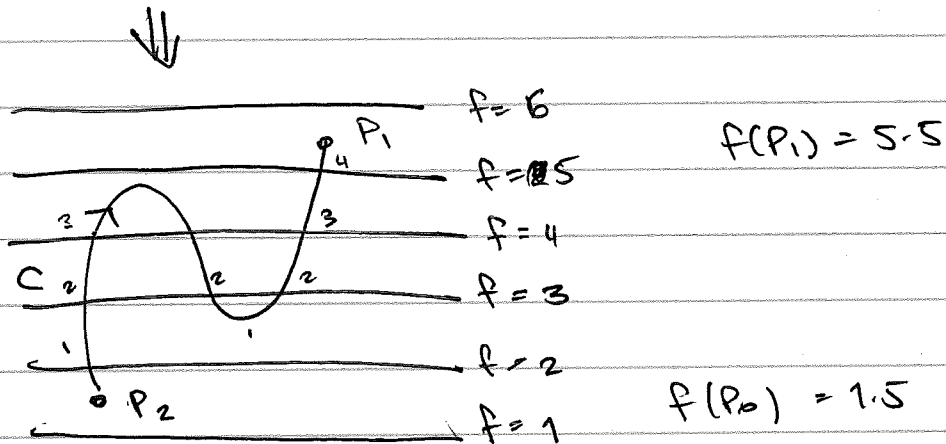
COMPARE THIS TO UNSIGNED INTEGRAL
 FOR, eg, ARCLength.

$$\int \left| \frac{df}{ds} \right| ds$$

A MORE GEOMETRIC PICTURE: IMAGINE CONTOURS OF CONSTANT f ON M .



DASHED LINES: POINTS $x \in M$
s.t. $f(x) = -1, 0, 1, \dots$



GEOM. DEF

then:

$$\int_C df = \# \text{ times we move up a contour} - \# \text{ times we move down}$$

$$\Rightarrow \int_C df = f(P_1) - f(P_2) \quad \text{short cut.}$$

ORIENTED BOUNDARY

$$= f|_{\text{BOUNDARY}}$$

nb McInerney
is good

2-forms

$$\begin{aligned} x^1 &= x \\ x^2 &= y \end{aligned}$$

$$\omega = \frac{1}{2!} \omega_{\mu\nu} dx^\mu \wedge dx^\nu$$

$$= \frac{1}{2} [\omega_{xy} dx \wedge dy + \omega_{yx} dy \wedge dx]$$

$$= \frac{1}{2} [\underbrace{\omega_{xy} - \omega_{yx}}_{2\omega_{xy} \text{ BY INDUCED ANTISYM.}}] dx \wedge dy \quad \leftarrow dx \wedge dy = -dy \wedge dx$$

$$= \omega_{xy} dx \wedge dy$$

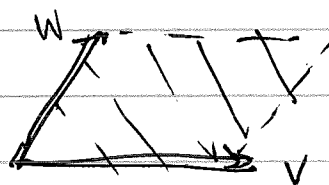


MACHINE THAT TAKES 2 VECTORS
→ SPTS OUT ANTISYMMETRIC
PRODUCT OF COMPONENTS

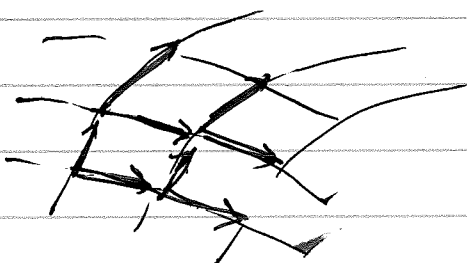
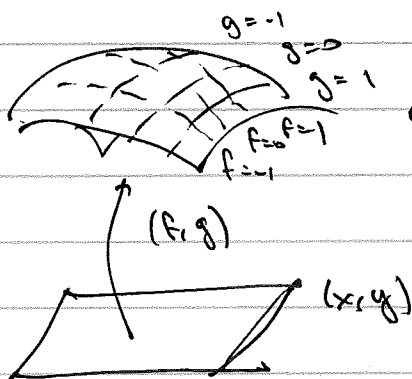
$$dx \wedge dy = dx \otimes dy - dy \otimes dx$$

$$dx \wedge dy(V, W) = V^1 W^2 - V^2 W^1$$

gives vol of
parallelogram
(ORIENTED)



$$\text{if } \omega = d(f(x,y)) \wedge d(g(x,y))$$



14w. stG
§ 12.2.2.

THIS STORY GENERALIZES

- 2-form is infinitesimal area of a manifold. (ORIENTED) 5
- 3-form is infinitesimal volume, also oriented

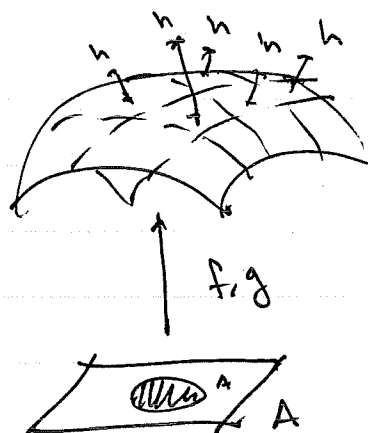
$$\int_A h(x,y) df \sim dg$$

"HEAT MAP"

↑ WEIGHS EACH AREA ELEMENT

$$f, g: \mathbb{R}^2 \rightarrow M$$

$$h: \mathbb{R}^2 \rightarrow \mathbb{R}$$

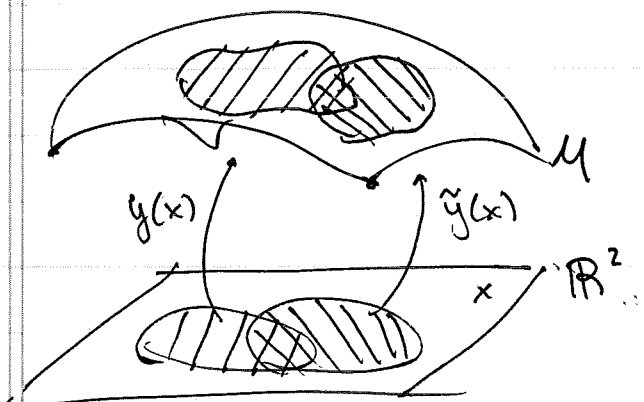


then: $\int_A h df \sim dg$
is a 2D RIEMANN
INTEGRAL OF h

↑ this is a nice way to PARAMETERIZE

induced
metric
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ALSO GIVES A PICTURE FOR US TO EXPLORE A
BETTER WORKING DEFINITION OF A MANIFOLD.



n-DIM

SPACE WHICH IS EVERYWHERE

LOCALLY (in patches)

DIFFEOMORPHIC w/ \mathbb{R}^n

s.t. THESE MAPS

AGREE WHERE

THEY OVERLAP

eg. S^2 , 2-SPHERE. ONE PATCH WON'T DO.

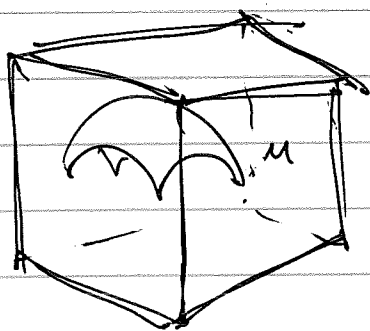
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STO G
VOLUME

SPECIAL CASE: n -DIM MANIFOLD IS EMBEDDED
IN A HIGHER-DIM EUCLIDEAN SPACE

"normal" w/ usual sense
of VOLUMES ... ie w/ EUCL. METRIC

nb: (1) MANIFOLDS DON'T HAVE TO BE EMBEDDINGS
(2) YOU DON'T NEED METRIC TO INTEGRATE
↳ we didn't use it; not when we
have differential forms

in this case:



not antisymm.

$$ds^2 = \sum_{i=1}^{m \geq n} (dx^i \otimes dx^i)$$

SURFACE M IS A RESTRICTION
so $x^i = x^i(y^1, \dots, y^n)$

STO G
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INDUCED METRIC : $ds^2 = \sum_{i=1}^{m \geq n} \left(\frac{\partial x^i}{\partial y^r} dy^r \right) \otimes \left(\frac{\partial x^i}{\partial y^v} dy^v \right)$

$$= \left(\sum_{i=1}^{m \geq n} \frac{\partial x^i}{\partial y^r} \frac{\partial x^i}{\partial y^v} \right) dy^r \otimes dy^v$$

$\underbrace{\hspace{10em}}_{g_{rv} \text{ on } M}$

HW:

IN THIS CASE, THE DIFFERENTIAL "VOLUME"
is

$$d(\text{Vol}) = \underbrace{\sqrt{\det g_{\mu\nu}}}_{\text{jacobian}} dy^1 \wedge \dots \wedge dy^n$$

invariant under change
of coordinates

Stokes' theorem

INTEGRALS TAKE $d\omega$ over a "volume"
to ω over a "surface area"

$$\int_V \underbrace{d\omega}_{\substack{\uparrow \\ (k+1)\text{-form}}} = \int_{\partial V} \underbrace{\omega}_{\substack{\uparrow \\ k\text{-form} \\ \text{ENCL. AREA}}} \quad \int \text{ORIENTED}$$

$(k+1)\text{-DIM MANIF.}$



$$\int_C dF = \int_{\partial C} F = F(P_1) - F(P_0)$$

2D CASE: CONSIDER $\omega = A_i dx^i = A_x dx + A_y dy + A_z dz$

$$d\omega = d(A_x dx) + \dots$$

$$= \left(\underbrace{\frac{\partial A_x}{\partial x} dx \wedge dx}_{=0 \text{ by antisym}} + \frac{\partial A_x}{\partial y} dy \wedge dx + \frac{\partial A_x}{\partial z} dz \wedge dx + \underbrace{A_x dx \wedge dx}_{=0 \text{ by } dz=0} \right) + \dots$$

$$= \left(-\frac{\partial A_x}{\partial y} dx \wedge dy + \frac{\partial A_x}{\partial z} dz \wedge dx \right) + \dots$$

chk:

$$= \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) dx \wedge dy + \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) dy \wedge dz + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) dz \wedge dx$$

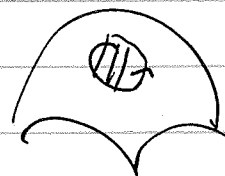
RECOGNIZE: the components are $(\nabla \times \vec{A})_i$;
the 2-form basis in the
last line are the (+ oriented)
areas of parallelograms
 \Leftrightarrow normal vectors
 $(dx \wedge dy \sim \vec{dx} \times \vec{dy} = \vec{dz})$

$$\int d\omega$$



$$\int_V d(A_i dx^i) = \int (\vec{\nabla} \times \vec{A}) \cdot d\vec{A}$$

$$\int_{\partial V} \omega = \oint \vec{A} \cdot d\vec{\ell}$$



Green's thm

SUGGESTIVE
NAMING:
 \vec{F}

3D CASE: $\omega = f_x dy \wedge dz + f_y dz \wedge dx + f_z dx \wedge dy$

$$d\omega = \underbrace{\left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial z} + \frac{\partial f_z}{\partial x} \right)}_{\vec{\nabla} \cdot \vec{F}} dx \wedge dy \wedge dz$$

$$\int_V d\omega = \int_V \vec{\nabla} \cdot \vec{F} \, d(\text{vol})$$

$$\int_{\partial V} \omega = \int_{\partial V} \underbrace{\vec{F} \cdot d\vec{A}}$$

IDENTIFYING, eg $dy \wedge dz = \hat{n}_x dA$

FURTHER REMINDING US OF "VECTOR CALCULUS":

FOR ω A 0-FORM (Function) $d\omega$ IS A 1-FORM $(\partial_x f dx + \dots)$ $d^2\omega$ IS A 2-FORM $[(\vec{\nabla} \times (\vec{\nabla} f))_x dy \wedge dz + \dots]$

"0 (eg b/c BNDY OF BNDY = 0)

$$\Rightarrow \vec{\nabla} \times \vec{\nabla} = 0 \quad [\text{curl} \circ \text{grad} = 0]$$

FOR ω A 1-FORM

$$\omega = f_x \cancel{dx \wedge dy} + \dots$$

 $d\omega$ IS A 2-FORM

$$(\vec{\nabla} \times \vec{F})_z dx \wedge dy + \dots$$

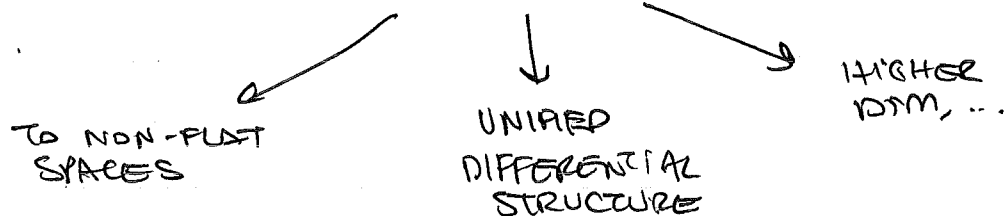
 $d^2\omega$ IS A 3-FORM

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{F}) dx \wedge dy \wedge dz$$

"0

$$\Rightarrow \vec{\nabla} \cdot \vec{\nabla} = 0 \quad (\text{div} \circ \text{curl} = 0)$$

~~SOME~~ CONTEXT: We "generalized" vector calculus.



Killer app for vector calculus? $E \rightarrow M!$

first, a quick result:

\swarrow ω comes from potential

EXACT FORM: $\omega = dA$

CLOSED FORM: $d\omega = 0$

OBVIOUS: EXACT \Rightarrow CLOSED

not obvious: \Leftarrow

\uparrow Poincaré lemma

~~if~~ \rightarrow holds for "nice" spaces } most of our cases.
(CONTRACTIBLE)

POTENTIALS

Poincaré: SUPPOSE "VEC" $E_i dx^i$ s.t. $\nabla \times E = 0$
FIELD

$$\rightarrow dE = 0 \Leftrightarrow E = d\psi$$

$$\uparrow \vec{E} = \vec{\nabla} \psi$$

i.e. \vec{E} HAS NO CURL $\Rightarrow \vec{E}$ IS GRAD OF SCALAR.

SIMILARLY: SUPPOSE "VEC" ~~FIELD~~ $B_x + y^1 dz + \dots$

HW:
Maxwell's
eq.

nb: very diff. object!

$$dB = 0 \Leftrightarrow B = dA$$

$$\uparrow \quad \quad \quad \uparrow$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \quad \quad \vec{\nabla} \times \vec{A}$$



on this note: an interesting operator

HODGE STAR: \star on n dim manifold

$$\star dx^{i_1} \wedge \dots \wedge dx^{i_k} = \frac{1}{(n-k)!} \epsilon_{i_1 \dots i_n} \dots$$

$$dx^{i_{k+1}} \wedge \dots \wedge dx^n$$

turns 2-form \rightarrow 1-form in 3-SPACE.

SO: IN MINKOWSKI SPACE,
EM FIELDS LIVE IN $F_{\mu\nu}$

1 one key point is $F = dA$

4- POTENTIAL

$$A_\mu = (\phi, \underline{A})$$

next time: pushing vectors