

Preliminaries

- Tyler \rightarrow HW1A short. (nb: correction, Bryant)
- PERIODIC TABLE: 1st gen matter
4 fundamental particles

EX: CHARGES

- RULES FOR QED
- QED + $\pi \rightarrow$ QWS (AWS?)

the game

- $|IN\rangle, |OUT\rangle$
- draw the box in between
- connected diagrams
- fewest vertices better

Last time:

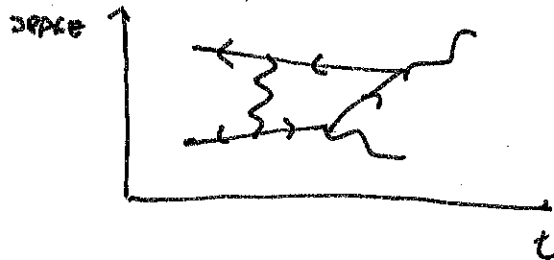
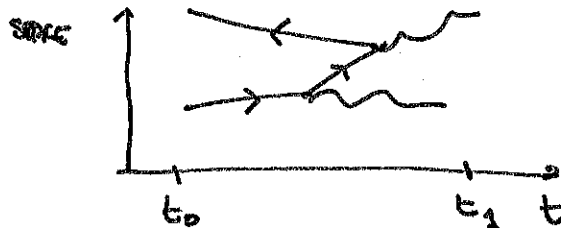
Dynamics \uparrow QM

want amplitude

$$\langle out | \underbrace{\text{time evolution}}_{e^{iHt}} | in \rangle$$

\nwarrow Taylor exp

"evidently" this can be expanded
as a sum over HISTORIES



More vertices
are higher order
terms in the
expansion

Kinematics

P^μ conservation
 $P^2 = m^2$

$$P^\mu = (E_p, p_x, p_y, p_z)$$



EACH IS SEPARATELY CONSERVED
in fact, if you know nothing about P^4 ,
then these are just 4 indep. quantities
that a particle has.

BUT E ACTUALLY
DEPENDS ON MOMENTUM!

→ nb: ROTATING YOUR FRAME
CAN MIX UP p_x, p_y, p_z !

$$\Rightarrow \boxed{E^2 - p^2 = m^2}$$

↑ encodes $E = mc^2$... but also kinetic E
(on your hw)

$$\text{EXPECT: } E = m + \frac{1}{2}mv^2 + \dots$$

POWERFUL NOTATION (just like diagrams are powerful notation)

use height of index as a code

$$P_\mu \equiv (E_p, -p_x, -p_y, -p_z)$$

just put minus sign
on spatial components

WEIRD THING TO DEFINE, BUT VERY USEFUL

A physical 4-momentum satisfies
OF A PARTICLE

$$\underline{E^2 - p^2 = m^2} \quad \leftarrow \text{name: } \underline{\text{on-shell}}$$

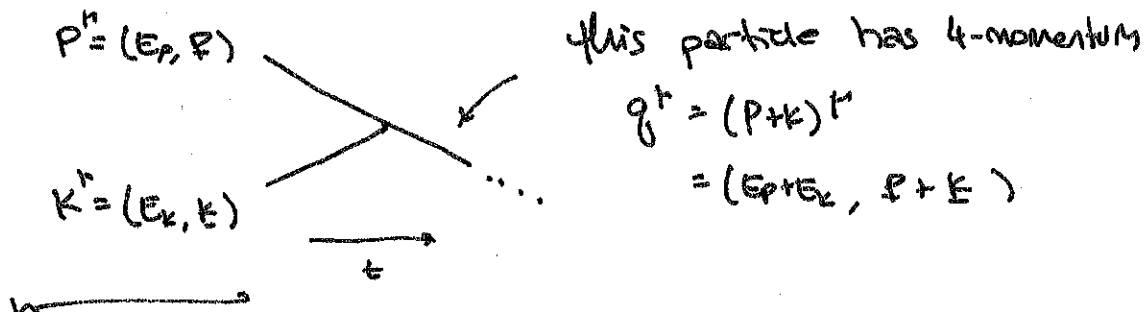
$$\sum_\mu P^\mu P_\mu \equiv P^\mu P_\mu \equiv P^2 \quad \leftarrow \text{notation}$$

"Unphysical" 4-momentum: $p^2 \neq m^2$

↳ then E & P are not related
... this is "nonsensical" momentum, classically.

KINEMATICS: 4-momenta add as you'd expect

consider this part of a graph



external particles
(on shell)

↳ in other words, EACH VERTEX
CONSERVES 4-MOMENTUM.

Q: if $P \rightarrow K$ are on-shell, is q on shell?

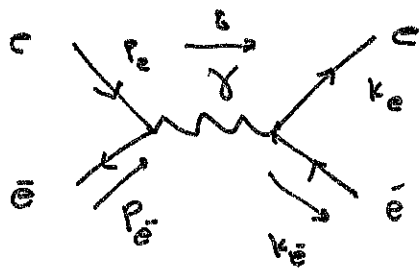
$$E_P^2 - P^2 = m^2$$

$$E_K^2 - K^2 = m^2$$

$$(E_P + E_K)^2 - (P + K)^2 \stackrel{?}{=} m^2$$

(simplify: assumed all have same mass)

NO! ... that's weird.



$$M_e = 0.5 \text{ MeV}$$

$$M_\gamma = 0$$

LET'S START W/ C of MASS FRAME :

$$P_e = (E, \underline{p})$$

$$P_{\bar{e}} = (E, -\underline{p})$$

on shell
(physical)

then: $Q = P_e + P_{\bar{e}} = (2E, 0)$

$$Q = K_e + K_{\bar{e}}$$

on shell

$$K = (E_e, \underline{k}_e) \quad \bar{K} = (E_{\bar{e}}, \underline{k}_{\bar{e}})$$

$$E_e + E_{\bar{e}} = 2E$$

$$\boxed{\underline{k}_e + \underline{k}_{\bar{e}} = 0}$$

$$\underline{k}_e = -\underline{k}_{\bar{e}} \quad (\text{opp momenta})$$

$$\Rightarrow E_e = E_{\bar{e}}$$

$$\Rightarrow E_e = E \Rightarrow |\underline{k}| = |\underline{p}|$$

so that: $K = (E, |\underline{p}| \hat{n})$

$$\bar{K} = (E, -|\underline{p}| \hat{n})$$

clearly total 4-momentum is conserved
in a graph.

↳ each vertex conserves momentum
lines don't change momentum.

BUT REQUIRING on-shell external states

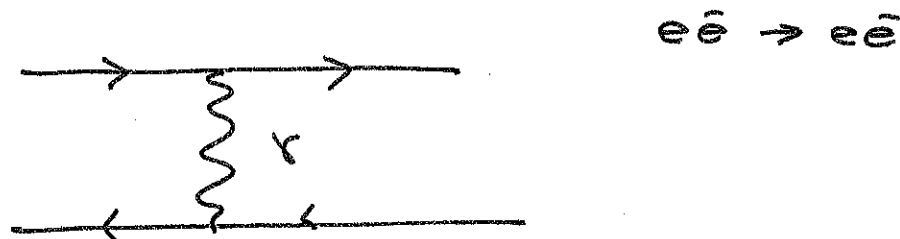
⇒ internal states have unphysical 4-momenta

⇒ VIRTUAL PARTICLES

INSIDE A DIAGRAM, 4-mom. conserved
but on-shellness is out the window

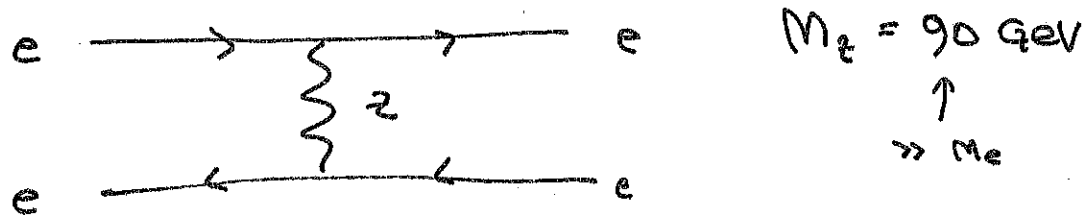
... that's fine! we never see those particles. they're "UNPHYSICAL PATHS" that we sum over.

Poetic analogy:



classically: Coulomb potential (eg, imagine static)

NEW THEORY: QED + Z



is the Z or the γ closer to being on-shell?

$\hookrightarrow \Delta E \Delta t \gtrsim \hbar$

1
IF WE HAVE TO BORROW ENERGY FROM THE VACUUM, THEN WE HAVE TO PAY IT BACK SOONER, A LOT

so "VIRTUAL Z" CANNOT PROPAGATE AS LONG AS SPACELY-VIRTUAL γ .

incidentally

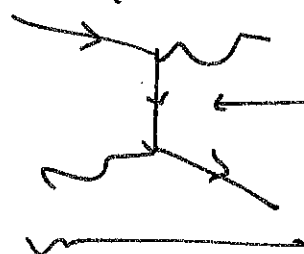
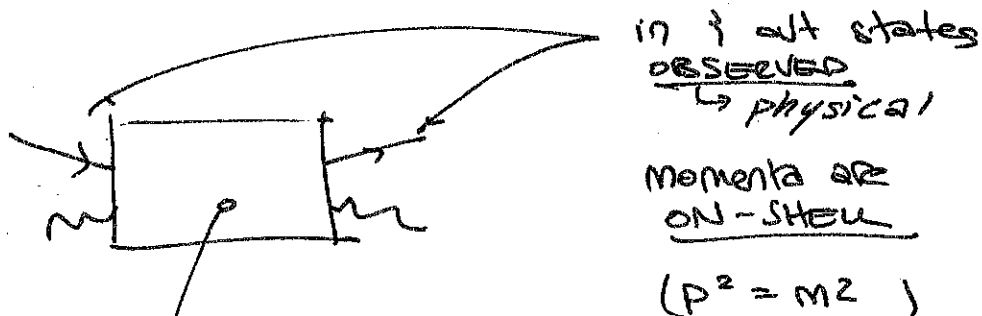
$$V_{\text{coulomb}} = \frac{e^2}{4\pi} \frac{-1}{r}$$

$$V_{\text{YUKAWA}} = \frac{g^2}{4\pi} \frac{-1}{r} e^{-Mr}$$

← mass of Ξ

↑ NP to O(1) factors
that I'm being sloppy about

SD:



momenta are (in gen)
OFF-SHELL

→ momentum is conserved

$$P^2 \neq M^2$$

(like pipes, or current)

NEW RULES FOR THE GAME:

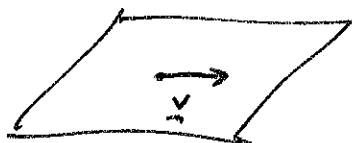
- in states & out states must ← KINEMATICS → conserve total 4-mom
- all intermediate vertices: 4-mom. conserved → be on-shell

INDICES

$P^M \leftarrow$ why is this useful?

INDEX IS A CUE ABOUT HOW IT TRANSFORMS.

simpler version: $v^i \leftarrow \begin{pmatrix} v_x \\ v_y \end{pmatrix}$ 2-vector



symmetry: 2D ROTATION $R = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$

under a rotation: $\underline{v} \rightarrow \underline{Rv} = \underline{v'}$

INDEXOLOGY : ^(column) vectors: upper index

$$R^i_j = \begin{pmatrix} R^1_1 & R^1_2 \\ R^2_1 & R^2_2 \end{pmatrix}$$

$\left\{ \begin{array}{l} \text{SECOND INDEX LOWER} \\ \text{FIRST INDEX UPPER} \end{array} \right.$

SAME CONVENTION:

any repeated upper & lower index are summed \leftarrow

"contracted"

so: $\underline{W} = \underline{Rv} \Leftrightarrow W^i = R^i_j v^j = R^i_j v_j$

Watch carefully:

$$W^1 = R^1_1 V^1 + R^1_2 V^2$$

$$W^2 = R^2_1 V^1 + R^2_2 V^2$$

compare to "matrix mult.":

$$\begin{pmatrix} W^1 \\ W^2 \end{pmatrix} = \begin{pmatrix} R^1_1 & R^1_2 \\ R^2_1 & R^2_2 \end{pmatrix} \begin{pmatrix} V^1 \\ V^2 \end{pmatrix}$$

$$= \begin{pmatrix} R^1_1 V^1 + R^1_2 V^2 \\ R^2_1 V^1 + R^2_2 V^2 \end{pmatrix}$$

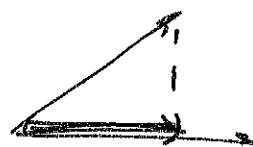
so what? we can also define row vectors.

$$\begin{pmatrix} \delta_1 & \delta_2 \end{pmatrix} \begin{pmatrix} W^1 \\ W^2 \end{pmatrix} = \delta_1 W^1 + \delta_2 W^2 = \underline{\underline{\delta \cdot W}}$$

↑ ↑
INVARIANT.

convention: lower index

evidently, row vectors transform "oppositely" to column vectors!



related to this projection
so rot. invt.

Rule: lower index object transforms w/ $R^t \leftarrow$ here $t = T$

$$\underline{R}^t = \underline{R}^{-1} \quad \text{for rotations}$$

$$R = \begin{pmatrix} c & -s \\ s & c \end{pmatrix}$$

$$\text{s.t. } R^t R = R R^t = 1$$

$$\underline{R}^t = (R^t)^j{}_i =$$

$$= \begin{pmatrix} \bar{R}^1{}_1 & \bar{R}^1{}_2 \\ \bar{R}^2{}_1 & \bar{R}^2{}_2 \end{pmatrix}$$

writing \bar{R} for simplicity
 $\bar{R}^i{}_j = R^i{}_j$

just #'s!

$$S_i \rightarrow S'_i = S_j \bar{R}^j{}_i = \bar{R}^j{}_i S_j$$

$$W^i \rightarrow W'^i = R^i{}_k W^k$$

$$S_i W^i \rightarrow S'_i W'^i = \bar{R}^j{}_i R^i{}_k S_j W^k$$

$$= (\bar{R} R)^j{}_k S_j W^k$$

$$1^k{}_k = \delta^j{}_k$$

$$= (1)^j{}_k S_j W^k$$

$$= S_k W^k$$

invariant. ✓

Rule: objects w/ many indices transform as product of R & R^{-1} matrices, each acting on a different index.

$$I^{ij} \rightarrow R^i_k R^j_l I^{kl}$$

↑
eg moment of inertia

$$T^{ij}_k \rightarrow R^i_l R^j_m \underbrace{\bar{R}^n_k}_{= R^k_n} T^{lm}_n$$

$$= R^k_n$$

BUT NOW SUMMATION CONVENTION IS WEIRD.

can you ever raise/lower indices?

yes \rightarrow use metric; in 3 space, metric is just the identity: δ_{ij}

why are we doing this?

LAWS of PHYSICS ARE WRITTEN WRT. ROTATIONAL INVARIANTS

$$V \sim \frac{1}{r} \quad \text{not } V(x,y,z)$$

NEXT WK: GENERALIZE TO SPACETIME: Lorentz symmetry
then GENERALIZE TO INTERNAL SYM. (DYNAMICS!)