

# LEC 9 SYMMETRIES, formally

9 FEB

- HW 4 - in progress still :-
- CORRECTIONS: Jon asked: effect of DM on PERTEURION OF  $\Phi$ ?  
 → CONTRIBUTES TO  $1/r$  POTENTIAL BUT not const (GAUSS' LAW)

REMINDER: ALL MU SIGNS ARE SUBJECT TO ERROR!

$$p^2 = E^2 - p^2 \quad \text{vs.} \quad -E^2 + p^2$$

$$= m^2 \quad \quad \quad = -m^2$$

LAST TIME: circuitous discussion of different topics

SCHW. METRIC:  $(1 - r_s/r) dt^2 - (1 - r_s/r)^{-1} dr^2 \dots$

↳ think about black holes ...

$r_s$  significance

HOW TO STUDY: geodesic into black hole!

... BUT WE WANTED MORE METHODOLOGY:

CONS. QUANTITIES  $\leftrightarrow$  SYM.

APPLICATION: PERTURBATION OF  $\Phi$

TODAY: DIS IN  $\Phi$  DEVELOP TOOLS TO GET BACK TO BH BUSINESS (1 other GR)

## SYMMETRY — why?

1. allows us to carry tools to solve ordinary mechanics problems to relativistic mechanics

↳ eg. PERHELION OF MERCURY

2. SYMMETRIES ARE POWERFUL

↳ best eg: AdS/CFT correspondence

↑  
isometries  
of this  
manifold ...

↑  
spacetime sym.  
of this theory

LAST TIME: hint of Noether's theorem  
in curved space

$$L(x, \dot{x}) = \left( ds/d\tau \right)^2 = g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu$$

"  
1

↑  
• = d/dτ

$$\frac{d}{d\tau} \frac{\partial L}{\partial \dot{x}^\mu}$$

$$= \frac{\partial L}{\partial x^\mu}$$

SO IF METRIC IS INDEP  
OF A COORDINATE,  
THEN  $\partial L / \partial x^\mu$   
IS  $\tau$ -INDEP.

BUT:  $\frac{\partial L}{\partial \dot{x}^{\bar{\mu}}} = 2g_{\bar{\mu}\nu} \dot{x}^{\nu}$  is not invariant

$\bar{\mu}$  means NOT a tensor index, rather: some fixed value, eg  $\bar{\mu} = 0$  for ENERGY cons.

CONSERVED  $\nabla$   
INVARIANT ARE  
DIFFERENT!

SO WE DEFINED A "HELPER VECTOR"  
TO LET US PICK OUT A DIRECTION:

$$K_{(\bar{\mu})}^{\nu} = \delta_{\bar{\mu}}^{\nu} \quad \text{eg } (1, 0, 0, 0) \\ \text{for } K_{(t)}^{\nu}$$

then  $\frac{\partial L}{\partial \dot{x}^{\bar{\mu}}} = \frac{\partial L}{\partial \dot{x}^{\nu}} K_{(\bar{\mu})}^{\nu} \sim \dot{x} \cdot K_{(\bar{\mu})}$   
is conserved  $\nabla$  invariant.

KILLING VECTOR.

WE INTRODUCED KILLING VECTOR AS A HACK,  
BUT THEY'RE TELLING US SOMETHING:

$$\partial L / \partial \dot{x}^\mu = 0$$

$$\uparrow$$

$$\Rightarrow \frac{\partial}{\partial \dot{x}^\mu} g_{\dots} = 0$$

"the metric is constant along this direction"

$\uparrow$   
iso metric

CONSERVED QUANTITIES:

for massive particles:  $p = \dot{x} m$

for massless particles: CAN CHOOSE  
AFFINE PARAMETER s.t.  $p = \dot{x}$

$\uparrow$   
geodesic eq is 2<sup>nd</sup> Q  
 $\rightarrow$  so invt. if  $\tau \rightarrow a\tau + b$

SO A NICE PHYSICAL QUANTITY  
THAT IS CONSERVED IS  $\boxed{p \cdot K(\dot{x})}$

"along geodesic"



↑ up to m

cancel  
out. 3

$$0 = \frac{d}{d\tau} (P \cdot K) \propto P \cdot D(K \cdot P)$$

↑  
 $\dot{x} \cdot D$ 

$$= P^\mu (D_\mu K_\nu) P^\nu + P^\mu K_\nu (D_\mu P^\nu)$$

$(P \cdot D) P^\nu = 0$   
by geodesic eq  
(geodesic: we parallel  
transport  $\dot{x} \propto P$ )

$$= P^\mu P^\nu D_\mu K_\nu$$

~~~~~

BUT THIS IS TOTALLY

SYMMETRIC  $\rightarrow$  PROJECTSOUT ANTISYMMETRIC PART OF  $D_\mu K_\nu$ 

$$= \frac{1}{2} P^\mu P^\nu \underbrace{D_\mu K_\nu + D_\nu K_\mu}$$

$$\equiv D_{(\mu} K_{\nu)}$$

momentum cons in  $K$   
dir  $\rightarrow$  no grav. force.

KILLING'S EQ:  $D_{(\mu} K_{\nu)} = 0 \Rightarrow (K \cdot P)$  conserved

↑ actually a Killing field (@ ea point)

$$HW: \underbrace{D_\mu D_\sigma K^\rho}_{2^{nd} \text{ deriv of } K} = R^\rho_{\sigma\mu\nu} \underbrace{K^\nu}_{1^{st} \text{ deriv}}$$

2<sup>nd</sup> deriv of  $K$ 1<sup>st</sup> deriv.

Wenbo  
6.5, 11.1

THIS RESULT IS OF MATHEMATICAL INTEREST:

GIVEN  $K$  &  $DK$ , WE CAN NOW  
BOOTSTRAP  $D^2K$  & ALL HIGHER DERIVATIVES

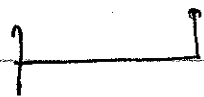
SO THE DATA IN A KIUNG FIELD IS GIVEN BY

$$K^\mu = A(x)^\nu \underbrace{K(0)^\nu}_{\text{FUNCTIONS OF POS.}} + B(x)^{\mu\nu} \underbrace{D_\nu K(0)^\rho}_{\text{DETERM. FROM A \& B}} + \dots$$

@ x

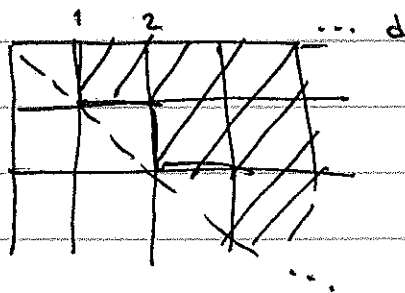
$K(0)^\nu$  HAS  $d$  DOF IN  $d$  DIMENSIONS

$D_\nu K(0)^\rho$  ?



two indices  $\rightarrow d^2$  dof

BUT  $D_\nu K^\rho = 0$ , s.t. symmetric part vanishes  
only antisymmetric piece left



$$\frac{1}{2} d^2 - \frac{1}{2} d = \boxed{\frac{1}{2} (d-1)d}$$

so: total DOF:  $d + \frac{1}{2}d(d-1) = \boxed{\frac{1}{2}d(d+1)}$

A SPACE w/ A FULL SET OF KILLING VECTORS (fields) IS MAXIMALLY SYMMETRIC (implications below).

CHECK:  $d=4$ , max # KILLING VEC = 10 ... ?!

$$L = g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu$$

↑

then said: look for ISOMETRIES

$$\frac{\partial g_{\mu\nu}}{\partial x^\alpha} = 0$$

↑ only four of these!

so: what are the isometries of Minkowski?

4 translations

$(\partial/\partial x^\mu)$

HOMOGENEITY

6 rotations

$(x^\mu/\partial x^\mu - x^\nu/\partial x^\nu)$

ISOTROPY

↑

not linearly independent??

BUT CLEARLY A SYMMETRY

@ any point  $K$ 's may be lin. dependent

↳ a lin comb  $a K_{(1)} + b K_{(2)}$  is also a Killing vector... lin. dep.

BUT WE'RE TALKING ABOUT VECTOR FIELDS

$$\underline{a(x)} K_{(1)}(x) + \underline{b(x)} K_{(2)}(x)$$

this resulting ~~vector~~ vector field  
is not nec. a dependent...  
... ~~or~~ is it nec. a Killing field!

IN FACT, FINDING KILLING VECTORS FROM  
A METRIC IS TRICKY... not clear  
when to stop looking

↖ part of why MAXIMALLY SYMMETRIC  
SPACES ARE NICE.

is SCHWARZSCHILD MAX SYM? no.

↳ BUT COUSINS OF MINKOWSKI ARE:  
DE SITTER → ANTI-de SITTER



PUNCHLINE: if space is maximally symmetric then geometry looks the same everywhere.

→ CURVATURE is the same everywhere  
calculate  $R = g^{\mu\nu} R_{\mu\nu} = R^{\mu}{}_{\mu}$  @ one place  
if you're done.

↑  
R encodes everything there is  
to know about the geometry (local)  
of the space!  
(given dimensionality, # time dir, ...) (eg not topo.)

ARGUMENT: LOC. INT. FRAME:  $g_{\mu\nu} = \eta_{\mu\nu}$  @ a point.

no preferred  
direction

↑  
unchanged by Lorentz  
transforms @ that point

so want  $R_{\mu\nu}$  to also be unchanged  
by Lorentz transf in this frame.

→  $R_{\mu\nu}$  must be constructed from  
the tensors that are Lorentz invariant

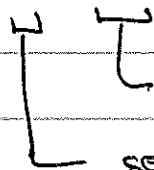
↳  $g_{\mu\nu}, \delta^{\mu}_{\nu}, \epsilon_{\mu\nu\rho\sigma}$

So @ this point  $i$  in these coords.

$R_{\dots}$  must be made out of  $g_{\dots}$ ,  $\delta_{\dots}$ ,  $\epsilon_{\dots}$ .

BUT (HW)  $R$  HAS VERY SPECIFIC SYMMETRIES w/rt its indices!

$R_{\dots}$



ANTISYM w/rt interchange

SEPARATELY ANTISYM w/rt interchange

$$R_{\mu\nu\rho\sigma} = R_{\rho\sigma\mu\nu}$$

$$R_{\rho\sigma\mu\nu} + R_{\mu\nu\rho\sigma} + R_{\nu\sigma\mu\rho} = 0$$

UNIQUE SOLUTION:

$$R_{\rho\sigma\mu\nu} \propto g_{\rho\mu} g_{\sigma\nu} - g_{\rho\nu} g_{\sigma\mu}$$

BUT THIS IS A TENSORIAL EQ (even though written in specific coords)

↳ both sides transform well (& consistently) w/rt change of coords.

PROPORTIONALITY CONST:

$$R_{\rho\sigma\mu\nu} = A (g_{\rho\mu} g_{\sigma\nu} - g_{\rho\nu} g_{\sigma\mu})$$

$g_{\rho\mu} g_{\sigma\nu}$   $\nearrow$

LHS:  $R$

RHS:  $(d^2 - d)$

$$\Rightarrow \boxed{A = \frac{R}{d(d-1)}}$$

So: In a maximally symmetric space  $\Leftrightarrow$

$$R_{\rho\sigma\mu\nu} = \frac{R}{d(d-1)} (g_{\rho\mu} g_{\sigma\nu} - g_{\rho\nu} g_{\sigma\mu})$$

$\uparrow$   
w/  $R$  some constant over spacetime

Locally: WHAT MATTERS IN CLASSIFICATION IS

$$R \longrightarrow \neq, 0 ?$$

# LIE DERIVATIVE

NOTIONS OF DERIVATIVE:

$\partial_\mu$  PARTIAL  $\rightarrow$  not covariant

$D_\mu$  COVARIANT  $\rightarrow$  introduces connection,  $\Gamma$ ,  
to "fix" non-covariance  
of  $\partial_\mu$

$\uparrow$   
 $X \cdot D$

$\uparrow$

COULD ~~USE THIS~~ DEFINE  $\Gamma$ ,

BUT ON A MEASURE SPACE

(Riemannian Manifold)

THERE IS A NATURAL CHOICE.

important for GEODESICS

$\uparrow$

~~BOTH~~  $D_\mu$  takes  $T \rightarrow \underline{DT}$

$\uparrow$  higher-rank Tensor.

important for INTEGRAL CURVES  
SHOWS UP IN GEOM MECHANICS

LIE DERIVATIVE:  $\mathcal{L}_X$  takes tensor to  
same rank tensor

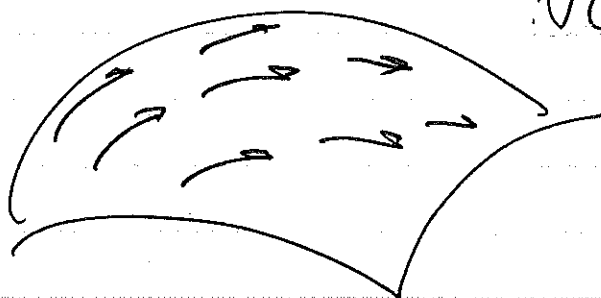
When we touched on this, we noted  
that the Lie derivative of a vector  
(field) is

$$\mathcal{L}_X Y = [X, Y] = (X \cdot \partial) Y - (Y \cdot \partial) X$$

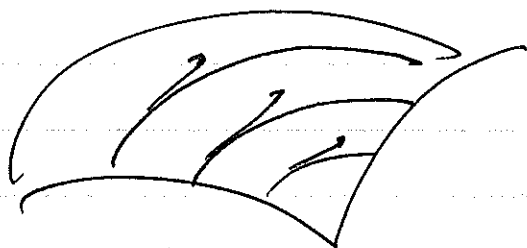
D'INVERNO

p. 70

MORE INTUITIVE PICTURE: COMPARING ACTIVE VS PASSIVE



$V(x)$  vector field



DEFINES TRAJECTORIES


$$\frac{dx^\mu}{d\tau} = V^\mu(x(\tau))$$

(reaffirms our identification of vectors  
w/ partial derivatives)

WHAT IS THE DERIVATIVE OF A TENSOR  $T$   
@  $x$  IN THE DIRECTION OF  $V^\mu(x)$ ?

~~PROBLEM~~ COMPARE 2 VERSIONS OF  $T(x)$ :

- ① PASSIVE TRANSFORM OF COORDINATES  
 $T$  stays "the same", it's just coord.  
 system that's changing



eg  $T^{\mu\nu}(x) \rightarrow T'^{\mu\nu}(x')$

(same point, in different coordinates)

$$x' = x + \delta\tau V(x) + \dots$$

$$\frac{\partial x'^{\mu}}{\partial x^{\alpha}} = \delta_{\alpha}^{\mu} + \delta\tau \frac{\partial}{\partial x^{\alpha}} V^{\mu}(x) + \dots$$

$$T'^{\mu\nu}(x') = \left(\frac{\partial x'^{\mu}}{\partial x^{\alpha}}\right)_{\alpha} \left(\frac{\partial x'^{\nu}}{\partial x^{\beta}}\right)_{\beta} T^{\alpha\beta}(x)$$

$$= T^{\mu\nu}(x) + \delta\tau (\partial_{\alpha} V^{\mu}) T^{\alpha\nu}(x) + \delta\tau (\partial_{\beta} V^{\nu}) T^{\mu\beta}(x) + \dots$$

② ACTIVE TRANSFORMATION (maybe I got these labels mixed up...)

EVALUATE  $T^{\mu\nu}(x)$  @ A DIFFERENT POINT ON THE MANIFOLD,  $x' = x + \delta\tau V(x)$

$$T^{\mu\nu}(x') = T^{\mu\nu}(x) + \delta\tau V^{\gamma} \frac{\partial}{\partial x^{\gamma}} T^{\mu\nu}(x) + \dots$$

$$L_v T = \lim_{\delta x \rightarrow 0} \frac{T^\mu(x') - T'^\mu(x')}{\delta x}$$

nearby point  
↓
same points  
diff coord  
↓

$$= V^\alpha \partial_\alpha T^\mu - T^{\mu\beta} \partial_\beta V^\mu - T^{\alpha\mu} \partial_\alpha V^\mu$$

obs: GIVES PREV. RESULT WHEN  $T = \text{vector}$ ;  $X_v W = [V, W]$   
 now easy to generalize

→ BCW:  
 CAN REPLACE  
 $\partial \rightarrow D$   
 SINCE THE  
 CONNECTION  
 PIECES  
 VANISH  
 (by antisym)

→ lower index:  $\partial x / \partial x'$ , so FUP SIGN

$$L_v T_\mu = V^\alpha \partial_\alpha T_\mu + T_\alpha \partial_\mu V^\alpha$$

from  $T'_\mu(x') = \left( \frac{\partial x}{\partial x'} \right)^\alpha_\mu T_\alpha(x)$

$$= (\delta^\alpha_\mu - \delta x \partial_\mu V^\alpha) T_\alpha$$

PROPERTIES:  $L_v(aT + bS) = aL_v T + bL_v S$   
 LINEAR

$$L_v(TS) = T L_v S + (L_v T) S$$

LEIBNIZ

~~really~~  $L_v(\phi) = V^\alpha \partial_\alpha \phi$

→ really a DERIVATIVE

## BACK TO ISOMETRIES:

ANOTHER WAY OF IDENTIFYING ISOMETRY:  
DERIVATIVE VANISHES

↳ why didn't we just say  
 $D_\mu g_{\nu\rho} = 0$ ?

THIS IS ALWAYS TRUE FOR OUR  
 COVARIANT DERIVATIVE!  
 (metric compatibility)

LIE DERIVATIVE GIVES ALTERNATIVE:

$$\mathcal{L}_V g_{\mu\nu} = V^\rho \partial_\rho g_{\mu\nu} + g_{\mu\lambda} \partial_\nu V^\lambda + g_{\lambda\nu} \partial_\mu V^\lambda$$

CAN PROMOTE  $\partial \rightarrow D$

(connection terms cancel)

metric commutes  
 w/ cov. der.

$$\mathcal{L}_V g_{\mu\nu} = \cancel{V^\rho \partial_\rho g_{\mu\nu}} + D_\mu V_\nu$$

$\underbrace{V^\rho \partial_\rho g_{\mu\nu}}_{=0 \text{ BY COMPATIBILITY}}$

$$= D_\mu V_\nu = 0 \quad \text{for isom.}$$

(KILLING EQUATION)