

# Questions?

SO FAR: VECTORS (KET)  $\in V$  vector space  
 ROW VECTORS (BRA)  $\in V^*: V \rightarrow \mathbb{H}$   
 $\underbrace{\hspace{1cm}}$   
 linear func.  
 of  $V$ .

NOW: what is transpose/adjoint/Hermitian conjugate?

$\hookrightarrow$  way of turning vectors into row vec.  
 $\uparrow$  vice versa.

(gives a sense of there being only one type of object)

TO UNDERSTAND THIS, WE NEED TO INTRODUCE AN ADDITIONAL MATHEMATICAL OBJECT:

dot product / inner product / metric

$$\underline{V} \cdot \underline{W} \quad \underbrace{\langle \underline{V}, \underline{W} \rangle} \quad g(\underline{V}, \underline{W})$$

$$\langle \underline{V} | \underline{W} \rangle \leftarrow \text{suggestive!}$$

PROPERTIES:  $V \times V \rightarrow \mathbb{H}$

bilinear

takes 2 vecs, spits out  $\mathbb{H}$

$$\left. \begin{aligned} g(\underline{V} + \underline{V}', \underline{W}) &= g(\underline{V}, \underline{W}) + g(\underline{V}', \underline{W}) \\ g(\underline{V}, \underline{W} + \underline{W}') &= g(\underline{V}, \underline{W}) + g(\underline{V}, \underline{W}') \end{aligned} \right\}$$

[conjugate] symmetric

$$g(\underline{V}, \underline{W}) = g(\underline{W}, \underline{V})^*$$

simplest eg: EUCLIDEAN SPACE in CARTESIAN COORDS

$$\underline{V} \cdot \underline{W} = \langle \underline{V}, \underline{W} \rangle = V^1 W^1 + V^2 W^2 + V^3 W^3 + \dots$$

SPURF to this example

more generally (I will swap btwn  $\cdot$ ,  $\langle$ ,  $\rangle$ ,  $g$  to make as clear as poss.)

$$\begin{aligned} g(\underline{v}, \underline{w}) &= g(v^1 \underline{e}_1 + v^2 \underline{e}_2 + \dots, w^1 \underline{e}_1 + w^2 \underline{e}_2 + \dots) \\ &= v^1 w^1 g(\underline{e}_1, \underline{e}_1) + v^1 w^2 g(\underline{e}_1, \underline{e}_2) + \dots \\ &\quad + v^2 w^1 g(\underline{e}_2, \underline{e}_1) + v^2 w^2 g(\underline{e}_2, \underline{e}_2) + \dots \\ &\quad \vdots \end{aligned}$$

FOR ORTHONORMAL BASES (nice bases)

$$g(\underline{e}_i, \underline{e}_j) = \pm \delta_{ij}$$

signature

(has to do w/ 'space' vs. 'time')

but not true in general

eg: POLAR COORDINATES  
CURVED SPACES

} not our concern (see P208)

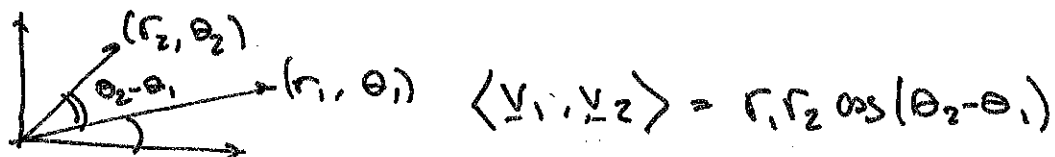
there are a lot of subtleties here

→ eg how does this make sense for polar coordinates?

END UP GOING INTO SOME DIFF. GEOMETRY

↑ hint: related to the idea that

"POSITION VECTORS DO NOT EXIST"



think about this. ☺

IN INDICES:

$$g(\underline{v}, \underline{w}) = v^i g_{ij} w^j$$

$\hookrightarrow g(e_i, e_j)$

LOOKS ALMOST LIKE MATRIX MULTIPLICATION.

OBSERVE:

$$(v^i g_{ij})$$

is an object w/  
one lower index

$$(\text{||||})_j$$

ROW VECTOR!  
takes vec, gives #

"metric w/ a vector pre-loaded"

$g(\underline{v}, \underline{\quad})$  is a machine that takes  
a vector & spits out #

PUT IT HERE

$$g(\underline{v}, \underline{w})$$

So the metric takes vectors & turns them  
into row vectors.

CAN ALSO DERIVE INVERSE METRIC.

$\hookrightarrow$  shortcut:  $g_{ij} g^{jk} = \delta_i^k$

$\hookrightarrow$  DEP on your  
vector space

(SPACE VS SPACETIME)

in general, we work w/ complex functions.

↳ so we often write "row vector" as  
Hermitian conjugate  $\leftarrow$  transpose + complex conjugate

$$\langle x | \equiv | x \rangle^\dagger$$

$$= \langle x, \_ \rangle$$

so that  $\langle x | y \rangle = \langle x, y \rangle$

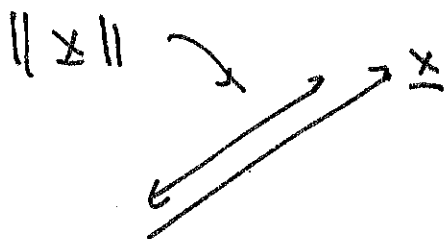
$\uparrow$        $\uparrow$                        $\uparrow$   
 BRA      KET                      2 KETS

~~eg. SPECIAL RELATIVITY~~

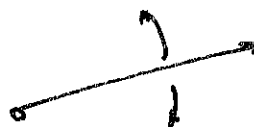
remark:  $\langle x | x \rangle = \|x\|^2$ , norm  
"length of a vector"

↳ usually relevant b/c it is preserved

→ IDEA OF SYMMETRY, CONSERVED QUAN



invariant under  
rotations



$$|\underline{v}|^2 = (v^1)^2 + (v^2)^2 + \dots$$

EUCLID

eg RELATIVITY  $P_\mu = (E, \mathbf{p})$

$$\|P\|^2 = E^2 - \mathbf{p}^2 = m^2$$

$$\uparrow$$

$$g_{\mu\nu} = \begin{pmatrix} 1 & & \\ & -1 & \\ & & -1 \end{pmatrix}$$

(note units)

WHAT ABOUT FUNCTION SPACE?

DIFF OPERATOR  $\mathcal{Q} = P_0(x) + P_1(x) \frac{d}{dx} + P_2(x) \left(\frac{d}{dx}\right)^2 + \dots$

$\uparrow$  call this a "formal" operator  
almost like our <sup>lin.</sup> transformations.

except we should specify SPACE & BOUNDARY COND  
 $\hookrightarrow$  then call it a "concrete" operator.

LET'S NOT MAKE A BIG DEAL ABOUT BC TODAY.  
(eg assume periodic or DIRICHLET)

INNER PRODUCT ? (you may GUESS from QM)

given functions  $f(x)$  &  $g(x)$

$$\langle f, g \rangle = \int f^*(x) g(x) dx$$

more general:  $\langle f, g \rangle_w = \int dx \underset{\substack{\uparrow \\ \text{weight}}}{w(x)} f^*(x) g(x)$

(SHOWS UP IF YOU USE WEIRD COORDS, FOR EXAMPLE)

SO WHAT?

now that we have "matrices"  $\mathcal{O}$   
that act on "vectors"  $|f\rangle$   
† an inner product  $\langle f, g \rangle$

CAN TALK ABOUT  $\boxed{\mathcal{O}^\dagger}$

$\mathcal{O}|f\rangle$  is a vector  $|\mathcal{O}f\rangle$   
w/ row vector

$$\langle \mathcal{O}f | = \langle f | \mathcal{O}^\dagger$$

or. this is like  $\begin{cases} \underline{v}' = \underline{A} \underline{v} \\ \underline{v}' \cdot \underline{w} = \underline{v}'^T \underline{w} = \underline{v}'^T \underline{A}^T \underline{w} \end{cases}$

in QM:  $T \rightarrow t$

SPECIAL OPERATORS: HERMITIAN/SELF-ADJOINT

$$\hookrightarrow \mathcal{O}^\dagger = \mathcal{O}$$

why?  $\rightarrow$  Real EIGENVALUES ( $\mathbb{C}$   $\mathcal{O}$ )

HERMITIAN :  $\mathbb{R}$  eigval

COMPLETE BASIS of ORTHOG EIGENVECTORS

even gives a natural basis!

eg.  $\mathcal{Q} = -\partial_x^2$

DOMAIN :  $[0, 1]$  w/  $f(0) = f(1) = 0$   
 $(L^2, \text{square integrable functions})$

INNER PROD :  $\langle f, g \rangle = \int_0^1 dx f^* g$

is  $\mathcal{Q}^\dagger = \mathcal{Q}$ ?

$\langle f, \mathcal{Q}g \rangle \stackrel{!}{=} \langle \mathcal{Q}f, g \rangle$

$-\int dx f^* (\partial_x^2 g)$

$-\int dx (\partial_x^2 f)^* g$

$= - \underbrace{(\partial_x f)^* g} = 0 \Big|_0^1 + \int (\partial_x f)^* \partial_x g dx$

$= + \underbrace{f^* \partial_x^2 g} = 0 \Big|_0^1 - \int f^* (\partial_x^2 g) dx$

$= - \int dx f^* (\partial_x^2 g)$

i think this is from Stone & Goldbart

EIGENVECTORS (you already know)

$$f_n(x) = \sin(n\pi x)$$

$$\lambda_n = n^2\pi^2$$

$$\int_0^1 \sin(n\pi x) \sin(m\pi x) dx = \frac{\delta_{nm}}{2}$$

have to  
normalize

we know from Fourier theory  
that this spans "nice"  $L^2$   
functions over  $[0,1]$  w/ Dirichlet BC.