

LAB REPORT

Full Adder Simulations Report

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Introduction

In this lab, I built full adder simulations in `Vivado` software, involving behavioral simulation, post-synthesis functional simulation, post-synthesis timing simulation, post-implement functional simulation, and post-implement timing simulation. After these elaborate simulations, I had a better understanding of the basics of digital system design. In short, digital system design is quite different from developing software, which not only requires us to write feasible and logical code but also requires us to have physical hardware in mind. The most significant difference is that concurrent statements are the main components in a `VHDL` file, which means the statements do not execute line by line. Due to the physical constraints on board, I also understand that not all designs are synthesizable or implementable, and even if one design is capable of being synthesized, it may appear different behaviors in different simulation stages.

Key words: FPGA simulation, full adder, VHDL

Prerequisite

This lab focuses on full adder, so let's first analyze a full adder using Boolean algebra.

Basically, a full adder can be described in the following Boolean expression:

$$\begin{aligned}s_1 &= A \oplus B \\ s_2 &= \text{Cin} \times s_1 \\ s_3 &= A \times B \\ \text{sum} &= s_1 \oplus \text{Cin} \\ \text{cout} &= s_2 + s_3\end{aligned}$$

This expression can be transferred to an equivalent logic diagram (Figure 1):

where A and B are two one-bit inputs, Cin is the carry bit of the previous bit full adder (i.e. Cout of the previous full adder). s_1 , s_2 and s_3 are intermediate signals.

When applying the stimulus signals like Figure 2, using the Boolean algebra, we can then manually derive the timing diagram (Figure 3) of the above logic diagram. The timing diagram uses `Wavedrom editor` to generate.

Note that, we added a 10ns of gate delay to all the gates above. Every grid represents 10ns. The dotted line in the signal means at this time, the signal is not yet initialized. In this timing diagram, the intermediate signals as well as the output signals are represented in a slow-variation fashion (i.e. there is a ramp when the signal jumps from 0 to 1 or vice versa).

Source Code Analysis

Design Source

Describing the logic diagram in `VHDL` language is easy, the core part of the full adder's code is almost a direct translation of the Boolean

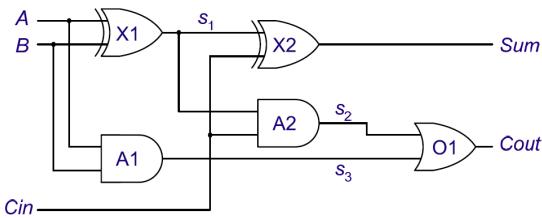


Figure 1. Logic diagram of the Boolean expression

expression.

```
architecture dataflow of full_addr is
    signal s1, s2, s3 : std_logic;
    constant gate_delay : time := 10 ns;
begin
    L1: s1 <= (A xor B) after gate_delay;
    L2: s2 <= (Cin and s1) after gate_delay;
    L3: s3 <= (A and B) after gate_delay;
    L4: sum <= (s1 xor Cin) after gate_delay;
    L5: cout <= (s2 or s3) after gate_delay;
end architecture dataflow;
```

We set the `gate_delay` explicitly here as 10ns.

Testbench

Testbench is a kind of special .vhd file, which is used to verify the design source. Typically, a testbench doesn't have any input/output port, and it treats the design source as a kind of *blackbox* component. It applies self-defined stimulus signals and measures the output of the *blackbox*.

To treat the design source as a component, we need to first declare the input/output port of the full adder like the code below:

```
component full_addr is
    port(A, B, Cin : in std_logic;
         Sum, Cout : out std_logic);
end component full_addr;
```

Then in the body of the architecture, we instantiated the full adder component.

```
UUT : full_addr port map (A=>A_tb, B=>B_tb, Cin
                           =>Cin_tb, Sum=>Sum_tb, Cout=>Cout_tb);
```

After the *blackbox* is ready, we design the stimulus signals as Figure 2, using a naive implementation shown in the below code:

```
-- Define stimulus signal
A_tb <= '1', '0' after 10ns, '1' after 20ns, '0'
      after 30ns, '1' after 40ns, '0' after 50ns,
      '1' after 60ns, '0' after 70ns;
B_tb <= '0', '1' after 20ns, '0' after 40ns, '1'
      after 60ns;
Cin_tb <= '0', '1' after 10ns, '0' after 20ns,
      '1' after 50ns, '0' after 60ns;
```

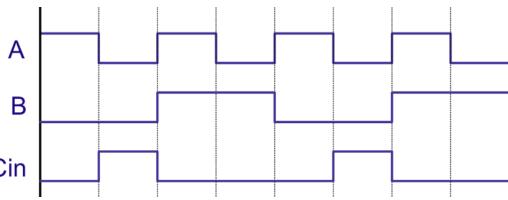


Figure 2. Input waveforms

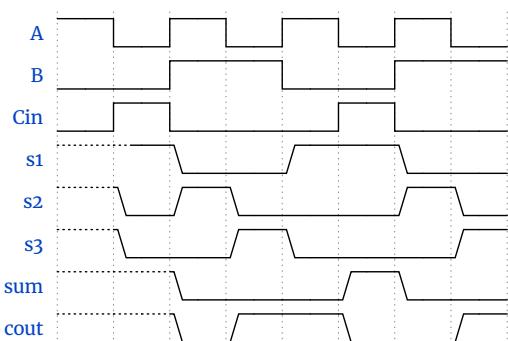


Figure 3. Manually derived timing diagram

Simulation Results

The simulated object in this part is the testbench code. During the different stage of the simulation (i.e behavioral, post-synthesis, post-implement simulations), the simulation results are different.

Behavioral Simulation

Behavioral simulation is completely based on the source design code, which is really alike the process of compiling source code. All the gate delays are preserved in this stage of simulation. The result is as follows (Figure 4):

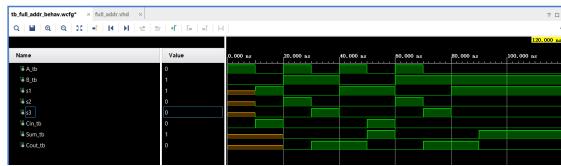


Figure 4. Behavioral simulation

The behavioral simulation result is the same as the previous manually developed results (Figure 3). If we look at the RTL schematic (Figure 5), we notice that the logic diagram is totally the same as Figure 1.

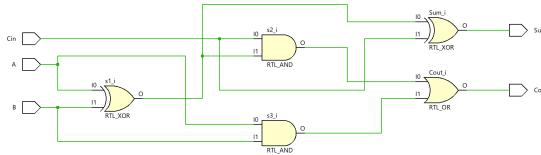


Figure 5. RTL schematic

However, due to the huge gate delay we set for the behavioral simulation, the addition result is not consistent with our common sense, since the input signals vary as quickly as the gate delay.

To make it closer to our common sense, we can simply modify the gate delay to ons, and rerun the simulation. The result (Figure 6) is more like an intuitive full adder now.



Figure 6. Behavioral simulation with zero gate delay

Post-Synthesis Simulation

The synthesis process transfers the design source to a physically compatible design, regardless of the specific hardware board. Since onboard devices mainly involve Look-up tables (LUTS) and use them to fulfill combinational logic, it may have some performance differences with that design directly using logic gates to accomplish. Moreover, the synthesis process eliminates those unnecessary self-defined gate delays. The schematic of the synthesis result (Figure 7) doesn't resemble the one in the previous RTL schematic (Figure 5), showing the root cause of the difference between the post-synthesis simulation and the behavioral simulation.

Functional

Post-synthesis functional simulation eliminates all self-defined gate delays as well as the actual gate delays. The result is as Figure 8, which is the same as the zero gate delay behavioral simulation, and it is consistent with our common sense of a full adder.

Note: Although the synthesis eliminates those self-defined gate

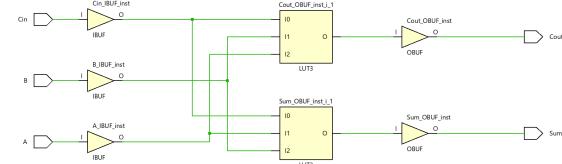


Figure 7. Post-synthesis schematic



Figure 8. Post-synthesis functional simulation

delays in the source design file (i.e. statement like `after x ns`), the stimulus signals defined in the testbench preserved the timing characteristic.

Timing

Post-synthesis timing simulation only differs from the functional simulation in that it involves generally estimated gate delays (i.e. gate delays in different devices are estimated the same). As shown in Figure 9, the output signals `Sum_tb` and `Cout_tb` are simply a constant time-delayed version of the functional simulation as shown in Figure 8.



Figure 9. Post-synthesis timing simulation

Post-Implementation Simulation

Post-implementation is also regarded as post-place-and-route simulation. This type of simulation considered the actual hardware devices on board as well as the wiring. However, in this lab, post-implementation simulation is generally alike post-synthesis simulation. The schematic of the implementation result (Figure 10) is the same as the synthesis result (Figure 7).

Functional

The post-implementation functional simulation also ignores the self-defined gate delays in the source design while preserving the timing characteristic defined in the testbench. The simulation result (Figure 11) is consistent with our common sense as well as the post-synthesis functional simulation.

Timing

The most important part of the post-implementation timing simulation is that it considers the actual gate delays of different devices and the transport delay (i.e. delay due to the signal propagation in wires), so it can uncover some potential problems in our previous design. In this lab, post-implementation timing simulation does do this job. As shown in Figure 12, there are a lot of spikes in the waveforms, which indicates that the design exhibits **race hazard**. Race hazard is usually due to the simultaneous variations of several input signals which can result in opposite output.

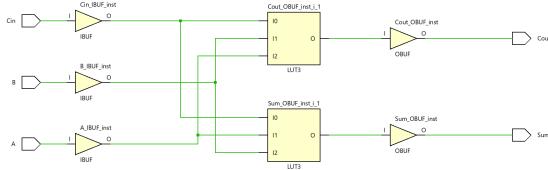


Figure 10. Post-implementation schematic



Figure 11. Post-implementation functional simulation

Extension: Eliminating Spikes In Post-Implementation Simulation

In the post-implementation timing simulation, we notice that there exist spikes in the waveform. The implementation is done by placing devices and routing wires on board, which can lead to different delays if the signal takes on different paths. And this tiny delay difference can result in spikes.

My core idea for eliminating the spikes is that we can add a clock signal to drive the output, instead of making the full adder output anytime. This can greatly reduce the potential of the full adder to capture some transient states that exhibit singularity.

This idea needs the involvement of **D flip-flop**, which only outputs the result when there is a rising edge of the clock signal.

In the design source, we need to add an input port of clock, and also add a `when` statement at the output.

```
entity full_addr_clk is
Port(
    ...
    clk: in STD_LOGIC;
    ...
);
end full_addr_clk;

architecture dataflow of full_addr_clk is
...
begin
    ...
    L4: sum <= (s1 xor Cin) after gate_delay when
        rising_edge(clk);
    L5: cout <= (s2 or s3) after gate_delay when
        rising_edge(clk);
    ...
end architecture dataflow;
```

The above code causes the RTL design changes shown in Figure 13, with D flip-flops appended to the output of the previous design.

In the testbench, I added a clock source, which is a `process`:



Figure 12. Post-implementation timing simulation

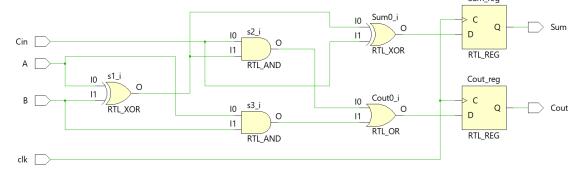


Figure 13. RTL schematic with D flip-flops

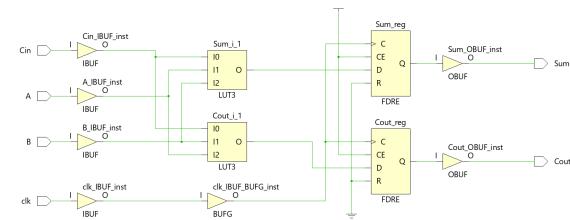


Figure 14. Post-implementation schematic with D flip-flops

```
process is
begin
    wait for 3ns;
    clk_tb <= not clk_tb;
end process;
```

The period of 3ns is arbitrarily taken. However, if the period is set too short, D flip-flops may not react correctly. And if the period is set too long, the delay of the full adder then will be too large.

However, in my first experiment, I only found zero outputs of `Sum_tb` and `Count_tb` in post-implementation timing simulation (Figure 15), while all other functional simulations and behavioral simulation accord with intuition. The post-implementation schematic is shown in Figure 14.



Figure 15. Post-implementation timing simulation with D flip-flops

So, I first establish my hypothesis that D flip-flops on this board are not capable of handling this kind of rapid change of input signal. Thereafter, I extend all signals' duration tenfold in the test-bench and make the period of the clock to be 33ns.

Then I rerun the post-implementation simulation, and I found that while the general shape of the waveform is satisfying (Figure 16), the `Sum_tb` output is not consistent with the one in the previous version (Figure 12).

After tons of this kind of simulation with changing parameters, I found a phenomenon in common, that is: the output signals don't vary at all until around 100ns after the stimulus signals were fed into the system.

Then I hypothesize that D flip-flops need more time to initialize than LUTs, due to there may exist larger parasitic capacitance



Figure 16. Post-implementation timing simulation with tenfold duration input

in this kind of device, and the “power-on initialization” time is around 100ns.

So then, I make the input signals (clock included) back to the original state and repeat them twice. The post-implementation timing simulation waveform is shown in Figure 17.



Figure 17. Post-implementation timing simulation with input repeated twice

From Figure 17, we can see that in the first cycle, the outputs are all zeros. However, during the second cycle, all outputs are in accord with our manual derivation with no spikes at all. And the period of the clock can be as short as 3ns!

Conclusion

In this lab, we investigate the differences among the five types of simulations. These simulations stand for each stage in which we carry our design from a draft to a hardware-compatible one. As the simulation proceeds, we can discover if our design can be carried out on physical hardware. Post-synthesis simulation tells us how the logic gate will be replaced by stuff like LUTs on hardware, and whether this design is synthesizable. Then post-implementation simulation helps us uncover potential problems that will happen on hardware. On top of that, we delve deeper into the formation of spikes in post-implementation simulation, and we develop a strategy of using clock-driven output to eliminate unexpected spikes.

Appendix: Full code

```
full_addr.vhd

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity full_addr is
    Port ( A : in STD_LOGIC;
           B : in STD_LOGIC;
           Cin : in STD_LOGIC;
           Sum : out STD_LOGIC;
           Cout : out STD_LOGIC);
end full_addr;

architecture dataflow of full_addr is
    signal s1, s2, s3 : std_logic;
    constant gate_delay : time := 10 ns;
begin
```

```
L1: s1 <= (A xor B) after gate_delay;
L2: s2 <= (Cin and s1) after gate_delay;
L3: s3 <= (A and B) after gate_delay;
L4: sum <= (s1 xor Cin) after gate_delay when
      rising_edge(clk);
L5: cout <= (s2 or s3) after gate_delay when
      rising_edge(clk);
end architecture dataflow;
```

tb_full_addr.vhd

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity tb_full_addr is
    Port ( );
end tb_full_addr;

architecture test of tb_full_addr is
    component full_addr is
        port(A, B, Cin : in std_logic;
              Sum, Cout : out std_logic);
    end component full_addr;
    signal A_tb, B_tb, Cin_tb : std_logic;
    signal Sum_tb, Cout_tb : std_logic;
begin
    — Create an instance of the full_addr circuit
    UUT : full_addr port map (A=>A_tb, B=>B_tb, Cin
        =>Cin_tb, Sum=>Sum_tb, Cout=>Cout_tb);
    — Define stimulus signal
    A_tb <= '1', '0' after 10ns, '1' after 20ns, '0'
        after 30ns, '1' after 40ns, '0' after 50ns,
        '1' after 60ns, '0' after 70ns;
    B_tb <= '0', '1' after 20ns, '0' after 40ns, '1'
        after 60ns;
    Cin_tb <= '0', '1' after 10ns, '0' after 20ns,
        '1' after 50ns, '0' after 60ns;
end test;
```

full_addr_clk.vhd

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity full_addr_clk is
    Port ( A : in STD_LOGIC;
           B : in STD_LOGIC;
           Cin : in STD_LOGIC;
           clk : in STD_LOGIC;
           Sum : out STD_LOGIC;
           Cout : out STD_LOGIC);
end full_addr_clk;

architecture dataflow of full_addr_clk is
    signal s1, s2, s3 : std_logic;
    constant gate_delay : time := 10 ns;
begin
    L1: s1 <= (A xor B) after gate_delay;
    L2: s2 <= (Cin and s1) after gate_delay;
    L3: s3 <= (A and B) after gate_delay;
    L4: sum <= (s1 xor Cin) after gate_delay when
          rising_edge(clk);
    L5: cout <= (s2 or s3) after gate_delay when
          rising_edge(clk);
end architecture dataflow;
```

```
tb_full_addr_clk.vhd

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity tb_full_addr is
-- Port ( );
end tb_full_addr;

architecture test of tb_full_addr is
component full_addr is
    port(A, B, Cin : in std_logic;
          Sum, Cout : out std_logic);
end component full_addr;
signal A_tb, B_tb, Cin_tb : std_logic;
signal Sum_tb, Cout_tb : std_logic;
begin
    — Create an instance of the full_addr circuit
    UUT : full_addr port map (A=>A_tb, B=>B_tb, Cin
                               =>Cin_tb, Sum=>Sum_tb, Cout=>Cout_tb);
    — Define stimulus signal
    A_tb <= '1', '0' after 10ns, '1' after 20ns,'0'
           after 30ns, '1' after 40ns,'0' after 50ns,
           '1' after 60ns,'0' after 70ns;
    B_tb <= '0', '1' after 20ns, '0' after 40ns, '1'
           after 60ns;
    Cin_tb <= '0', '1' after 10ns, '0' after 20ns,
           '1' after 50ns, '0' after 60ns;
end test;
```