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**EXP NO : 1**

**Aim : Implementation of Coordinate system conversion 1: Cartesian to Cylindrical, Cartesian to Spherical 2: Cylindrical to Cartesian, Cylindrical to Spherical. 3: Spherical to Cartesian, Spherical to Cylindrical**

**Software used : MATLAB**

**Theory :** Cartesian Coordinates : Cartesian coordinates are a system used to uniquely determine the position of a point in space. In a 2-dimensional space, it is defined by two axes: the x-axis (horizontal) and the y-axis (vertical). The position of any point in this plane is determined by a pair of numerical coordinates  $(x,y)$ . Each coordinate represents the distance of the point from the respective axis.

In a 3-dimensional space, an additional z-axis (perpendicular to both the x and y axes) is introduced, and a point is represented by a triplet  $(x,y,z)$ , where:

- x is the distance from the yz-plane.
- y is the distance from the xz-plane.
- z is the distance from the xy-plane.

**Spherical Coordinates :** Spherical coordinates provide a different method to locate a point in space using three parameters: radius  $r$ , polar angle  $\theta$  (often called colatitude), and azimuthal angle  $\phi$  :

- $r$ : The distance from the origin to the point.
- $\theta$ : The angle between the positive z-axis and the line formed between the origin and the point  $(0 \leq \theta \leq \pi)$ .
- $\phi$ : The angle between the positive x-axis and the projection of the point onto the xy-plane  $(0 \leq \phi < 2\pi)$ .

**Cylindrical Coordinates :** Cylindrical Coordinates are a hybrid between Cartesian and spherical systems. They use three parameters: radius  $r$ , azimuthal angle  $\phi$ , and height  $z$ :

- $r$ : The radial distance from the origin to the projection of the point onto the xy-plane.
- $\phi$ : The same as in spherical coordinates, representing the angle between the positive x-axis and the projection of the point onto the xy-plane.
- $z$ : The height of the point above the xy-plane, similar to the z-coordinate in Cartesian coordinates.

- A point in cylindrical coordinates is represented as  $(r, \theta, z)$

### Pointwise Comparison

- In Cartesian Coordinates: A point is expressed as  $(x, y, z)$  with each value representing a linear distance along a principal axis.
- In Spherical Coordinates: A point is expressed as  $(r, \theta, \phi)$  with  $r$  indicating the radial distance,  $\theta$  the angle from the  $z$ -axis, and  $\phi$  the angle in the  $xy$ -plane.
- In Cylindrical Coordinates: A point is expressed as  $(r, \theta, z)$  combining the radial distance and angular position from spherical coordinates with the height from Cartesian coordinates.

## 1.1 Cartesian to Cylindrical Co-ordinate

```
%Declaration of the variables :
x=35;
y=50;
z=10;
fprintf("The cartesian coordinates are: ");
```

The cartesian coordinates are:

```
fprintf("x");disp(x);
```

```
x      35
```

```
fprintf("y");disp(y);
```

```
y      50
```

```
fprintf("z");disp(z);
```

```
z      10
```

```
%Conversion of Cartesian to Cylindrical
m= x^2 + y^2 ;
rho= sqrt(m);
phi = atan(y/x);
z=z;

fprintf("the cylindrical coordinates are ");
```

the cylindrical coordinates are

```
fprintf("the radial distance :");disp( rho);
```

```
the radial distance :    61.0328
```

```
fprintf("the angle with the x axis is :");disp(phi);
```

the angle with the x axis is :      0.9601

```
fprintf("the height of the cylinder :");disp(z);
```

the height of the cylinder :      10

## 1.2 Cartesian to Spherical Co-ordinate

```
%Conversion of Cartesian to Spherical
n= x^2 + y^2 + z^2;
r= sqrt(n);
theta = acos(z/r);
phi = atan(y/x);
fprintf("The spherical coordinates are: ");
```

The spherical coordinates are:

```
fprintf("The radial distance is: ");disp(r);
```

The radial distance is:      61.8466

```
fprintf("The angle with z axis is: ");disp(theta);
```

The angle with z axis is:      1.4084

```
fprintf("The angle with x axis is: ");disp(phi);
```

The angle with x axis is:      0.9601

## 2.1 Cylindrical to Cartesian Co-ordinate

```
%%Declaration of the variables :
rho=25;
phi=0.4;
z=35;
fprintf("The cylindrical coordinates are: ");
```

The cylindrical coordinates are:

```
fprintf("rho=");disp(rho);
```

rho=      25

```
fprintf("phi=");disp(phi);
```

phi=      0.4000

```
fprintf("z=");disp(z);
```

z=      35

```
%Conversion 2.1: Cylindrical to cartesian
```

```
x= rho*cos(phi);
y=rho*sin(phi);
z=z;
fprintf("The cartesian coordinates are: ");
```

The cartesian coordinates are:

```
fprintf("x");disp(x);
```

```
x    23.0265
```

```
fprintf("y");disp(y);
```

```
y    9.7355
```

```
fprintf("z");disp(z);
```

```
z    35
```

## 2.2 Cylindrical to spherical Co-ordinate

```
%2.2.Conversion of Cylindrical to Spherical
r= sqrt(rho^2+z^2);
theta=atan(rho/z);
phi=phi;
fprintf("The Spherical coordinates are: ");
```

The Spherical coordinates are:

```
fprintf("The radial distance ");disp(r);
```

```
The radial distance    43.0116
```

```
fprintf("The angle with z axis ");disp(theta);
```

```
The angle with z axis    0.6202
```

```
fprintf("The angle with x axis");disp(phi);
```

```
The angle with x axis    0.4000
```

## 3.1 Spherical to Cartesian Co-ordinate

```
%%Declaration of the variables :
r=30;
phi=0.4;
theta=0.8;
fprintf("The spherical coordinates are: ");
```

The spherical coordinates are:

```
fprintf("r=");disp(r);
```

```
r=    30
```

```
fprintf("phi=");disp(phi);
```

```
phi=    0.4000
```

```
fprintf("theta=");disp(theta);
```

```
theta=    0.8000
```

```
%Conversion 3.1: Spherical to cartesian
```

```
x=r*cos(phi)*sin(theta);
```

```
y=r*sin(phi)*sin(theta);
```

```
z=r*cos(theta);
```

```
fprintf("The cartesian coordinates are: ");
```

```
The cartesian coordinates are:
```

```
fprintf("x");disp(x);
```

```
x    19.8219
```

```
fprintf("y");disp(y);
```

```
y     8.3805
```

```
fprintf("z");disp(z);
```

```
z    20.9012
```

### 3.2 Spherical to Cylindrical Co-ordinate

```
%Conversion 3.2: Spherical to cylindrical
```

```
rho=r*sin(theta);
```

```
phi=phi;
```

```
z=r*cos(theta);
```

```
fprintf("The cylindrical coordinates are: ");
```

```
The cylindrical coordinates are:
```

```
fprintf("rho");disp(rho);
```

```
rho    21.5207
```

```
fprintf("phi");disp(phi);
```

```
phi     0.4000
```

```
fprintf("z");disp(z);
```

```
z    20.9012
```

### Manual Solutions :

## Manual Solutions

1] 1.1] Cartesian to Polar coordinates

$$x = 35 \text{ m} \quad y = 50 \text{ m} \quad z = 10 \text{ m} \quad (\text{given})$$

Formulae for conversion:

$$\rho = \sqrt{x^2 + y^2} \quad \phi = \tan^{-1}(y/x) \quad z = z$$

Applying,

$$\rho = \sqrt{35^2 + 50^2} = 61.0328 \text{ m}$$

$$\phi = \tan^{-1}\left(\frac{50}{35}\right) = 0.9601 \text{ rad}$$

$$z = 10 \text{ m} = 10 \text{ m}$$

1.2] Cartesian to spherical coordinates.

Formulae

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \cos^{-1}\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right)$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

Applying,

$$r = \sqrt{35^2 + 50^2 + 10^2} = 61.8466 \text{ m}$$

$$\theta = \cos^{-1}\left(\frac{10}{61.8466}\right) = 1.4084 \text{ rad}$$

$$\phi = \tan^{-1}\left(\frac{50}{35}\right) = 0.9601 \text{ rad.}$$



2] 2.1] Cylindrical to Cartesian  
 $p = 25$ ,  $\phi = 0.4$ ,  $z = 35$  (given)

Formulae:

$$x = p \cos \phi, y = p \sin \phi, z = z$$

Applying,

$$x = 25 \cos(0.4) = 23.0265 \text{ m}$$

$$y = 25 \sin(0.4) = 9.7355 \text{ m}$$

$$z = 35 = 35 \text{ m}$$

2.2] Cylindrical to spherical

Formulae:

$$r = \sqrt{p^2 + z^2}$$

$$\theta = \tan^{-1}\left(\frac{p}{z}\right)$$

$$\phi = \phi$$

Applying,

$$r = \sqrt{25^2 + 35^2} = 43.0116 \text{ m}$$

$$\theta = \tan^{-1}\left(\frac{25}{35}\right) = 0.6202 \text{ rad}$$

$$\phi = 0.4 = 0.4 \text{ rad.}$$





## 3] 3.1] Spherical to cylindrical

$$\left. \begin{aligned} r &= 30 \\ \theta &= 0.8 \text{ rad} \\ \phi &= 0.4 \text{ rad} \end{aligned} \right\} \text{ (given)}$$

Formulae:

$$x = r \cos \phi \sin \theta, \quad y = r \sin \phi \sin \theta, \quad z = r \cos \theta$$

Applying,

$$x = 30 \cos(0.4) \sin(0.8) = 19.8219 \text{ m}$$

$$y = 30 \sin(0.4) \sin(0.8) = 8.3805 \text{ m}$$

$$z = 30 \cos(0.4) = 20.9012 \text{ m}$$

## 3.2] spherical to cylindrical

Formulae:

$$\rho = r \sin \theta, \quad \phi = \phi, \quad z = r \cos \theta$$

Applying,

$$\rho = 30 \sin(0.4) = 21.5207 \text{ m}$$

$$\phi = 0.4 = 0.4 \text{ rad}$$

$$z = 30 \cos(0.4) = 20.9012 \text{ m}$$



### Conclusion:

From the given experiment, I was able to gain a comprehensive understanding of the interconversion between cylindrical, Cartesian and spherical coordinates.

Additionally, I had an opportunity to learn a new software MATLAB, and was also able to get a hands-on experience with it. The experience not only enhanced my theoretical knowledge but also developed my practical skills.

