

```
In [4]: import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from sklearn.neighbors import KNeighborsClassifier
```

```
In [5]: # 1.1
miu_zero = [-1, 1]
miu_one = [-2.5, 2.5]
miu_two = [-4.5, 4.5]

sigma = [1, 1]
samples = np.zeros([700, 3])
for i in range(700):
    miu_index = 0
    rand_index = np.random.rand()
    if rand_index >= 2/3:
        miu_index = 2
        sample = np.random.normal(miu_two, sigma)
    elif 1/3 < rand_index < 2/3:
        miu_index = 1
        sample = np.random.normal(miu_one, sigma)
    else:
        sample = np.random.normal(miu_zero, sigma)

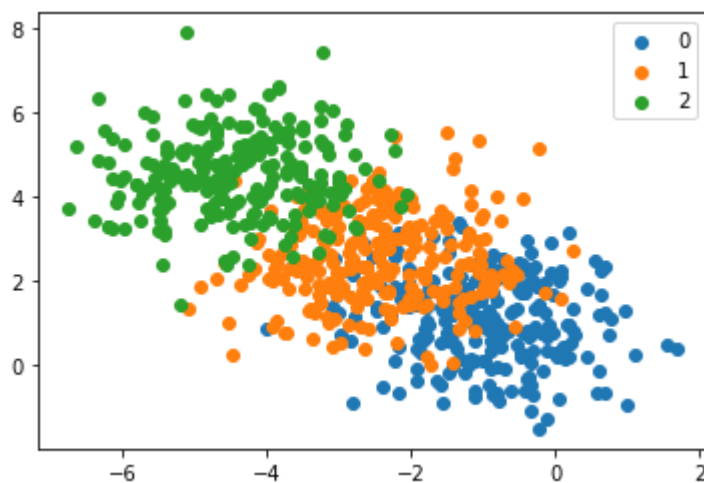
    samples[i] = [sample[0], sample[1], miu_index]
```

```
In [6]: # 1.2
data = pd.DataFrame(samples, columns = ['x', 'y', 'label'])

miu_zero_df = data[data['label'] == 0]
miu_one_df = data[data['label'] == 1]
miu_two_df = data[data['label'] == 2]
```

```
In [7]: plt.scatter(x=miu_zero_df['x'], y=miu_zero_df['y'], label='0')
plt.scatter(x=miu_one_df['x'], y=miu_one_df['y'], label='1')
plt.scatter(x=miu_two_df['x'], y=miu_two_df['y'], label='2')
plt.legend()
```

Out[7]: <matplotlib.legend.Legend at 0x7ffbcbce81250>



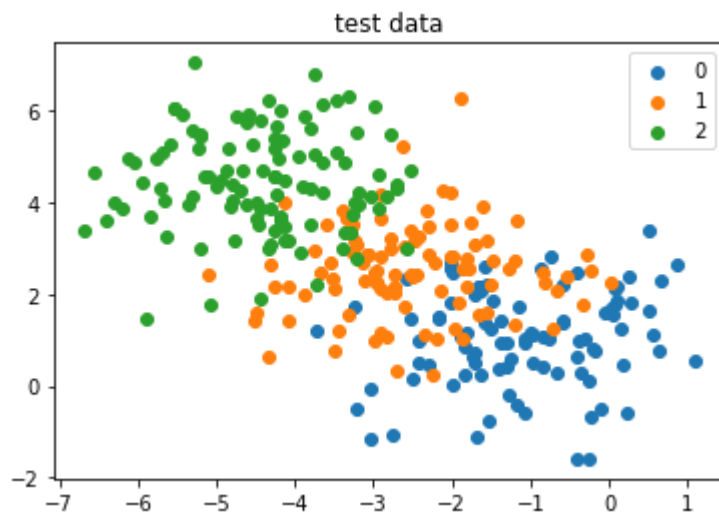
```
In [8]: # 1.3
test_samples = np.zeros([300, 3])
for i in range(300):
    miu_index = 0
    rand_index = np.random.rand()
    if rand_index >= 2/3:
        miu_index = 2
        sample = np.random.normal(miu_two, sigma)
    elif 1/3 < rand_index < 2/3:
        miu_index = 1
        sample = np.random.normal(miu_one, sigma)
    else:
        sample = np.random.normal(miu_zero, sigma)

    test_samples[i] = [sample[0], sample[1], miu_index]
test_data = pd.DataFrame(test_samples, columns=['x', 'y', 'label'])
```

```
In [9]: miu_zero_df = test_data[test_data['label'] == 0]
miu_one_df = test_data[test_data['label'] == 1]
miu_two_df = test_data[test_data['label'] == 2]

plt.scatter(x=miu_zero_df['x'], y=miu_zero_df['y'], label='0')
plt.scatter(x=miu_one_df['x'], y=miu_one_df['y'], label='1')
plt.scatter(x=miu_two_df['x'], y=miu_two_df['y'], label='2')
plt.legend()
plt.title('test data')

plt.show()
```



```
In [10]: # 1.4
k = 1
x_cols = ['x', 'y']
y_cols = 'label'
model = KNeighborsClassifier(n_neighbors=k)
model.fit(X=data[x_cols], y=data[y_cols])
y_train_pred = model.predict(X=data[x_cols])
y_test_pred = model.predict(X=test_data[x_cols])

y_train_true = data[y_cols].values
y_test_true = test_data[y_cols].values
train_error = np.sum(y_train_pred != y_train_true) / len(y_train_true)
test_error = np.sum(y_test_pred != y_test_true) / len(y_test_true)
print(train_error)
print(test_error)

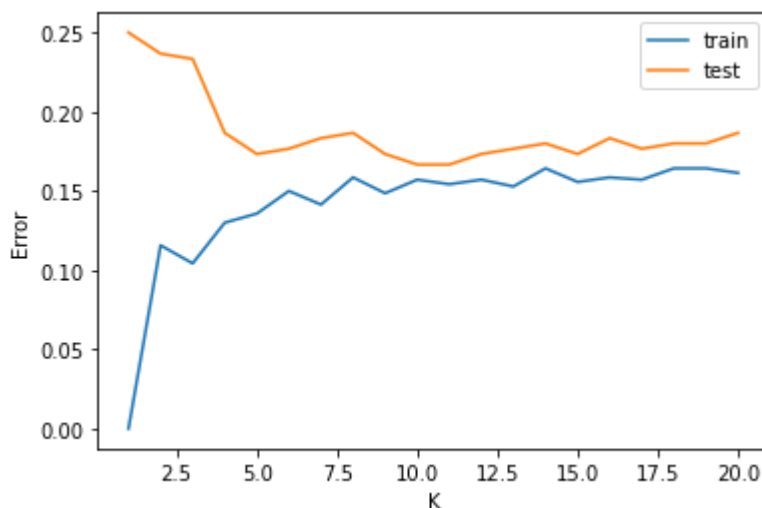
0.0
0.25
```

expected to increase accuracy with increase in K in the test set.

```
In [11]: # 1.5
errors = []
for i in range(1, 21):
    k = i
    model = KNeighborsClassifier(n_neighbors=k)
    model.fit(X=data[x_cols], y=data[y_cols])
    y_train_pred = model.predict(X=data[x_cols])
    y_test_pred = model.predict(X=test_data[x_cols])

    y_train_true = data[y_cols].values
    y_test_true = test_data[y_cols].values
    train_accuracy = np.sum(y_train_pred == y_train_true) / len(y_train_true)
    test_accuracy = np.sum(y_test_pred == y_test_true) / len(y_test_true)
    errors.append([1- train_accuracy, 1- test_accuracy])
```

```
In [12]: plt.plot( range(1,21), np.transpose(errors)[0], label='train')
plt.plot( range(1,21), np.transpose(errors)[1], label='test')
plt.xlabel("K")
plt.ylabel("Error")
plt.legend()
plt.show()
```



the test error decreased with k increase, matched expectations the test not always decrease with k , for example at the graph we got we have the error increase from k=10 to k~13

6. we expect the error to decrease with m\_train-i increase:

```
In [13]: # 1.6
def build_train(train_size):
    samples = np.zeros([train_size, 3])
    for i in range(train_size):
        miu_index = 0
        rand_index = np.random.rand()
        if rand_index >= 2 / 3:
            miu_index = 2
            sample = np.random.normal(miu_two, sigma)
        elif 1 / 3 < rand_index < 2 / 3:
            miu_index = 1
            sample = np.random.normal(miu_one, sigma)
        else:
            sample = np.random.normal(miu_zero, sigma)

        samples[i] = [sample[0], sample[1], miu_index]

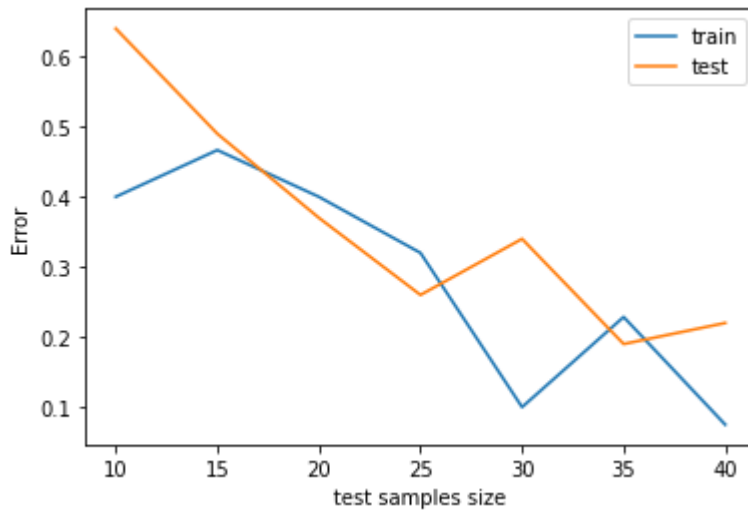
    data = pd.DataFrame(samples, columns=['x', 'y', 'label'])
    return data
```

```
In [14]: error = []

new_test = build_train(100)
for i in range(10, 41, 5):
    k = 10
    data = build_train(i)
    model = KNeighborsClassifier(n_neighbors=k)
    model.fit(X=data[x_cols], y=data[y_cols])
    y_train_pred = model.predict(X=data[x_cols])
    y_test_pred = model.predict(X=new_test[x_cols])

    y_train_true = data[y_cols].values
    y_test_true = new_test[y_cols].values
    train_error = np.sum(y_train_pred != y_train_true) / len(y_train_true)
    test_error = np.sum(y_test_pred != y_test_true) / len(y_test_true)
    error.append([train_error, test_error])
```

```
In [15]: plt.plot( range(10, 41, 5), np.transpose(error)[0], label='train')
plt.plot( range(10, 41, 5), np.transpose(error)[1], label='test')
plt.xlabel("test samples size")
plt.ylabel("Error")
plt.legend()
plt.show()
```



as we expected the error was overall decreasing, but the graph was erratic due to low train size.

1.7 and 1.8 are in the PDF

## שאלה 1 (7-8):

1.7

Yes, the plots change between the trials. Not always meet our expectations (from step 6) at every trial but the general trend is descending.

1.8

We will calculate  $y$  by the weighted score of the neighbors in the following way:

$p = (x_i, y_i)$ ,

$$y = \operatorname{argmax}_{label} \sum_{p \in N_k(x)} \frac{w(x, x_i)}{\sum_{j=1}^k w(x, x_j)} * 1[y_i = label],$$

$$w(x, x_i) = \frac{1}{d(x, x_i)}$$

We are doing  $\frac{1}{d}$  and not just  $d$  to give the closer points a heavier weight, and the far points less weight.

## שאלה 3 1.

$$P_w(Y_i = k | x_i) = \left( \frac{e^{w_k^T x_i}}{\sum_{j=1}^K e^{w_j^T x_i}} \right) = p_k \Rightarrow$$

for  $w_1, w_2$  lets find  $w$  such that  $p_1 = p, p_2 = 1 - p$

$$p_1 = \left( \frac{e^{w_1^T x_i}}{e^{w_1^T x_i} + e^{w_2^T x_i}} \right) p_2 = \left( \frac{e^{w_2^T x_i}}{e^{w_1^T x_i} + e^{w_2^T x_i}} \right)$$

נגדיר  $w = w_1 - w_2$

$$p = \left( \frac{e^{w^T x_i}}{1 + e^{w^T x_i}} \right) = \left( \frac{e^{(w_1 - w_2)^T x_i}}{1 + e^{(w_1 - w_2)^T x_i}} \right) = \left( \frac{\frac{e^{w_1^T x_i}}{e^{w_2^T x_i}}}{\frac{e^{w_2^T x_i}}{e^{w_2^T x_i}} + \frac{e^{w_1^T x_i}}{e^{w_2^T x_i}}} \right) = \frac{e^{w_1^T x_i}}{e^{w_2^T x_i}} * \frac{e^{w_2^T x_i}}{(e^{w_2^T x_i} + e^{w_1^T x_i})}$$

$$= \frac{e^{w_1^T x_i}}{(e^{w_2^T x_i} + e^{w_1^T x_i})} = p_1$$

$$1 - p_1 = 1 - \frac{e^{w_1^T x_i}}{(e^{w_2^T x_i} + e^{w_1^T x_i})} = \frac{(e^{w_2^T x_i} + e^{w_1^T x_i})}{(e^{w_2^T x_i} + e^{w_1^T x_i})} - \frac{e^{w_1^T x_i}}{(e^{w_2^T x_i} + e^{w_1^T x_i})} = \frac{e^{w_2^T x_i}}{(e^{w_2^T x_i} + e^{w_1^T x_i})} = p_2$$

נמשיך ונראה כי זה נכון עבור כל  $w$ , ועבור  $w_1, w_2$  מסוימים.  
נגדיר  $w = w_1, w_2 = 0$  ונקבל:

$$p_1 = \left( \frac{e^{w^T x_i}}{e^{w^T x_i} + 1} \right) \Rightarrow p_1 = p$$

$$p_2 = \left( \frac{1}{e^{w^T x_i} + 1} \right) = \frac{1 + e^{w^T x_i} - e^{w^T x_i}}{e^{w^T x_i} + 1} = \frac{e^{w^T x_i} + 1}{e^{w^T x_i} + 1} - \frac{e^{w^T x_i}}{e^{w^T x_i} + 1} = 1 - \frac{e^{w^T x_i}}{e^{w^T x_i} + 1}$$

$$= 1 - p_1$$

**2.**

כדי לפתור את  $\operatorname{argmax}_w$  נציב את הפיתוח מסעיף קודם ונגזור לפי  $w_k$  לכל  $k$  מתאים:  
ניזכר כי ראינו בהרצאה ש:

$$L_s(w) = \frac{1}{m} \sum_{i=1}^m -\log(P_w(Y_i = y_i | \mathbf{x}_i)) = \frac{1}{m} \sum_{i=1}^m \left( \log \left( \sum_k e^{w_k^T x_i} \right) - w_{y_i}^T x_i \right)$$

ולכן, נגדיר  $f_w(w) = \sum_{i=1}^m \log(P_w(Y_i = y_i | \mathbf{x}_i))$  ו-

$$f_s(w) = \sum_{i=1}^m \log(P_w(Y_i = y_i | \mathbf{x}_i)) = -m * L_s(w) = \sum_{i=1}^m \left( w_{y_i}^T x_i - \log \left( \sum_k e^{w_k^T x_i} \right) \right)$$

נגזור על ידי מה שראינו בתרגול, ונשווה ל-0:

$$\frac{\partial f_s(w)}{\partial w_k} = \sum_{i=1}^m 1[y_i = k]x_i - \sum_{i=1}^m \left( \frac{e^{w_k^T x_i}}{\sum_{j=1}^K e^{w_j^T x_i}} \right) x_i = 0 \Rightarrow$$

$$\boxed{\sum_{i=1}^m 1[y_i = k]x_i = \sum_{i=1}^m \left( \frac{e^{w_k^T x_i}}{\sum_{j=1}^K e^{w_j^T x_i}} \right) x_i}$$

**3.**

א. יש 3 וקטורי משקל  $w$  כיוון שיש 3 classes – וקטור מגדיר לכל מישור הפרדה לכל class.

ב. מכיוון שלוקטור  $x_i$  מוסיפים עוד רכיב של ה bias.

ג. אנו יודעים כי:

$$P_w(Y_i = k | x_i) = \frac{e^{w_k^T x_i}}{\sum_{j=1}^K e^{w_j^T x_i}}$$

ניזכר כי עלינו להוסיף עוד כניסה לכל ווקטור  $x_i$  שבה יהיה 1, בגלל הבias. אנו מניחים כי לכל ווקטור  $w$ , הרכיב הראשון הוא זה המתאים ל-bias. נחשב (שימו לב כי נסווג אח"כ):

$x_1$ :

$$p_{11} = \frac{e^{w_1^T x_1}}{\sum_{j=1}^K e^{w_j^T x_1}} = \frac{e^{21.5}}{e^{21.5} + e^{-9.5} + e^{-12}} = 1$$

$$p_{12} = \frac{e^{w_2^T x_1}}{\sum_{j=1}^K e^{w_j^T x_1}} = \frac{e^{-9.5}}{e^{21.5} + e^{-9.5} + e^{-12}} = 0.0344 * 10^{-12} \approx 0$$

$$p_{13} = \frac{e^{w_3^T x_1}}{\sum_{j=1}^K e^{w_j^T x_1}} = \frac{e^{-12}}{e^{21.5} + e^{-9.5} + e^{-12}} = 0.002525 * 10^{-12} \approx 0$$

$x_2$ :

$$p_{21} = \frac{e^{w_1^T x_2}}{\sum_{j=1}^K e^{w_j^T x_2}} = \frac{e^{-11}}{e^{-11} + e^8 + e^3} \approx 0$$

$$p_{22} = \frac{e^{w_2^T x_2}}{\sum_{j=1}^K e^{w_j^T x_2}} = \frac{e^8}{e^{-11} + e^8 + e^3} = 0.9933071435$$

$$p_{23} = \frac{e^{w_3^T x_2}}{\sum_{j=1}^K e^{w_j^T x_2}} = \frac{e^3}{e^{-11} + e^8 + e^3} \approx 0$$

$x_3$ :

$$p_{31} = \frac{e^{w_1^T x_3}}{\sum_{j=1}^K e^{w_j^T x_3}} = \frac{e^{-14}}{e^{-14} + e^2 + e^{12}} \approx 0$$

$$p_{32} = \frac{e^{w_2^T x_3}}{\sum_{j=1}^K e^{w_j^T x_3}} = \frac{e^2}{e^{-14} + e^2 + e^{12}} \approx 0$$

$$p_{33} = \frac{e^{w_3^T x_3}}{\sum_{j=1}^K e^{w_j^T x_3}} = \frac{e^{12}}{e^{-14} + e^2 + e^{12}} = 0.9999546021$$

כלומר, על פי מה שקיבלנו נראה כי:

$$\begin{aligned} y_1 &= 1 \\ y_2 &= 2 \\ y_3 &= 3 \end{aligned}$$