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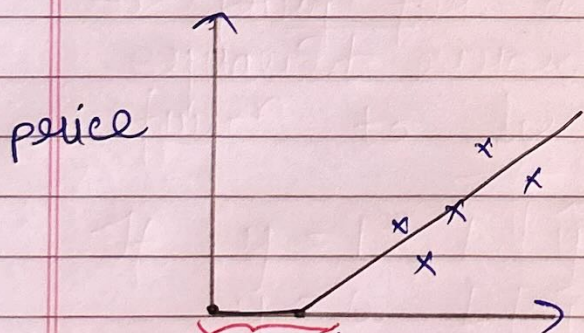
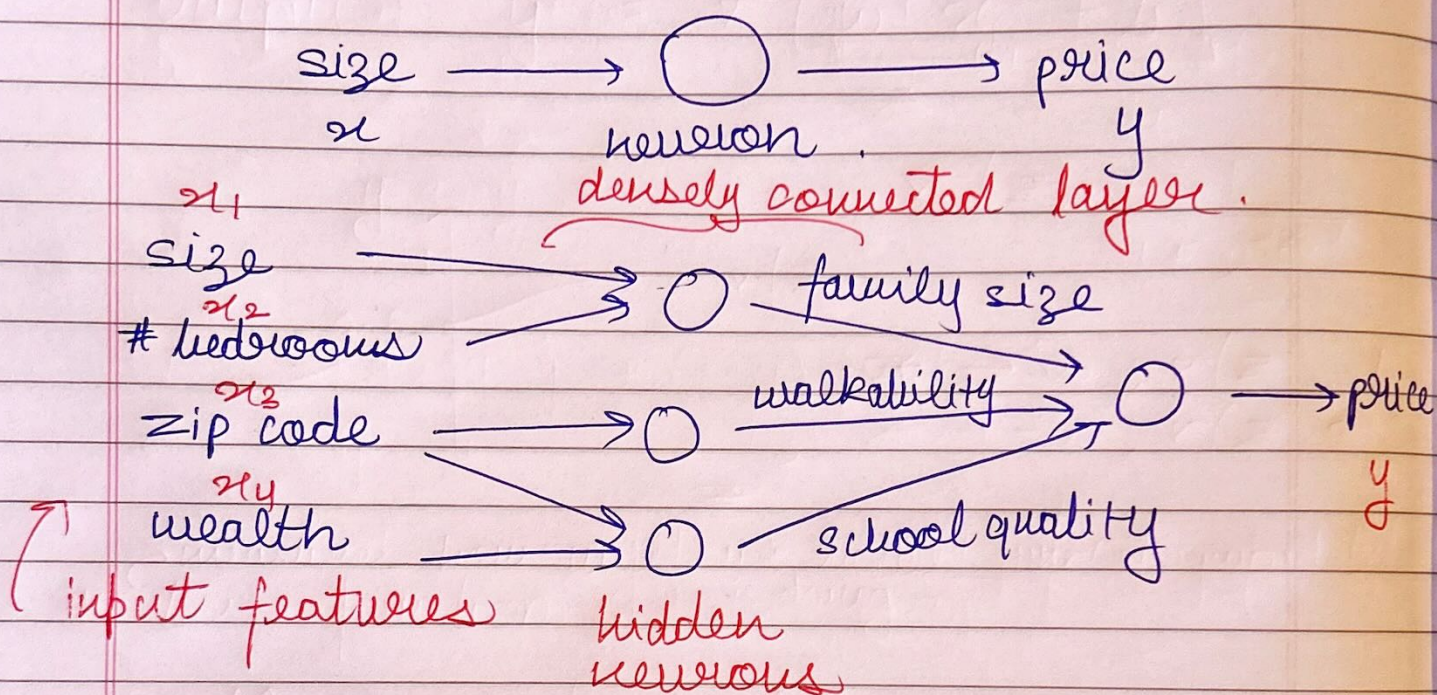
classmate

Date

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DEEP LEARNING

* What is a neural network?
Stacking together many neurons gives us a neural network.



Relu function
(Rectified Linear Unit)

∴ price cannot be negative

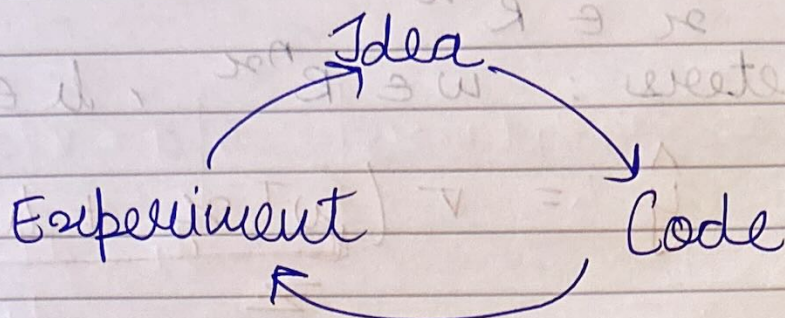
* Common Neural Networks

CNN	RNN
→ images	→ sequential data

Hybrid / custom
→ advanced models.

Structured Data
Proper data set, every
feature is defined

Unstructured Data
Images, audio,
random texts.



as building an effective NN is an **iterative process**.

* BINARY CLASSIFICATION:

input image : 64×64 .

feature vector: materialize $X = \begin{bmatrix} 255 \\ 231 \\ \vdots \\ 255 \\ 231 \\ \vdots \end{bmatrix} = 64 \times 64 \times 3$
 (RGB)

$$n_x = 12288 \text{ (here)}$$

$x \rightarrow \checkmark$
image of cat
no. of

$m = \text{training examples}$

Basic Notations

* $X \in \mathbb{R}^{n_x \times m}$ ($n_x \times m$ dimensional matrix)

$$X = \begin{bmatrix} | & | & & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & & | \end{bmatrix}$$

\uparrow
 n_x
 \downarrow

$$* Y \in \mathbb{R}^{1 \times m} = \begin{bmatrix} y^{(1)} & y^{(2)} & \dots & y^{(m)} \end{bmatrix}$$

$\leftarrow m \rightarrow$

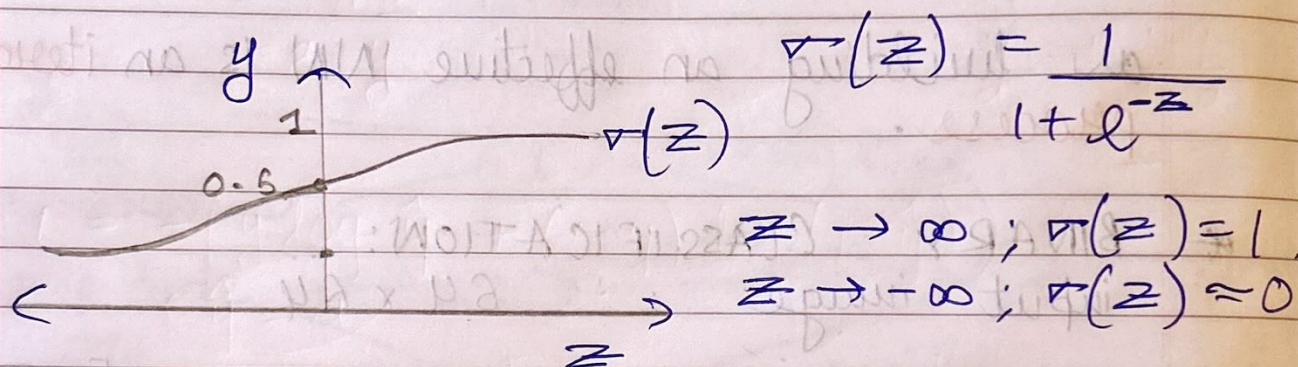
* LOGISTIC REGRESSION:

$$\hat{y} = P(y=1|x)$$

$$x \in \mathbb{R}^{n_x} \quad x \in \mathbb{R}^{n_x}$$

$$\text{Parameters: } w \in \mathbb{R}^{n_x}, b \in \mathbb{R}$$

$$\text{Output: } \hat{y} = \sigma(\underbrace{w^T x + b}_z)$$



* Loss function: measures how well our model funcⁿ (sigmoid here) is doing

$$L(\hat{y}, y) = -(y \log \hat{y} + (1-y) \log(1-\hat{y}))$$

→ opting for a sigmoid function over squared error here as we want the loss funcⁿ to be convex.

$$\begin{aligned} \text{If } y=1 \quad L(\hat{y}, y) &= -\log \hat{y} \\ y=0 \quad L(\hat{y}, y) &= -\log(1-\hat{y}) \end{aligned}$$

* Cost Function: measures how well parameters w, b are doing

$$J(w, b) = \frac{1}{n} \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)})$$

$$= -\frac{1}{n} \sum_{i=1}^m [y^{(i)} \log \hat{y}^{(i)} + (1-y^{(i)}) \log(1-\hat{y}^{(i)})]$$

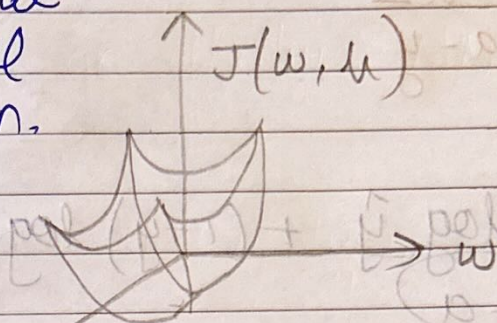
* GRADIENT DESCENT:

→ want to find w, b that minimizes $J(w, b)$

$$w = w - \alpha \frac{\partial J(w, b)}{\partial w}$$

$$b = b - \alpha \frac{\partial J(w, b)}{\partial b}$$

With any initial value, you will reach the min. (path maybe diff.)



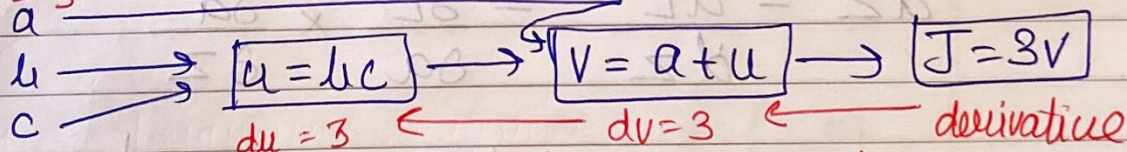
Why gradient descent?

→ it is a convex funcⁿ. Thus, has one minima only (global)

* COMPUTATION GRAPH:

$$J(a, b, c) = 3(a + bc)$$

$$\frac{dJ}{da} = 3$$

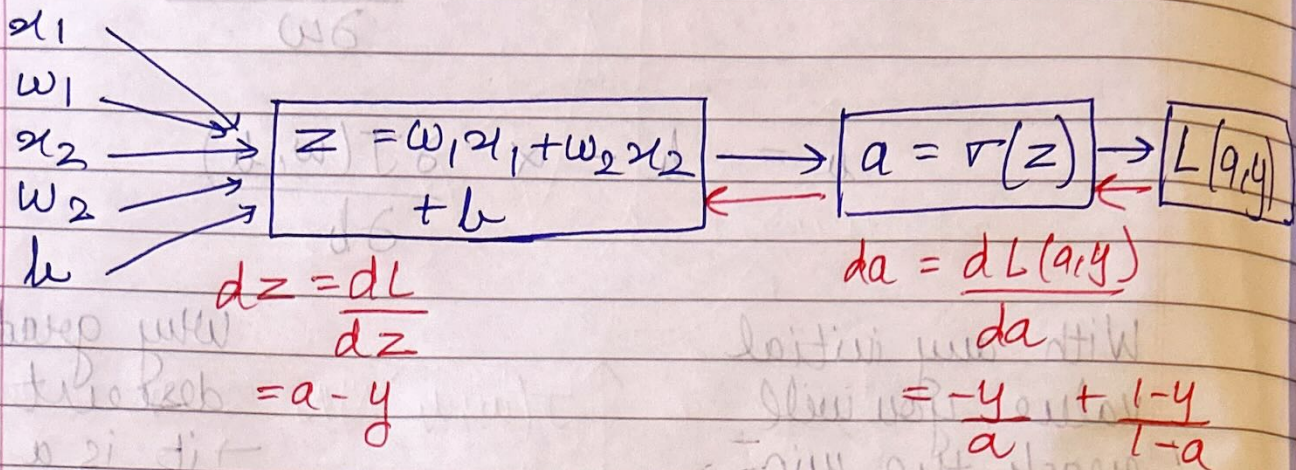


We observe, through a left to right pass we computed the value of J .

To compute derivatives, we move from right to left, i.e., in technical terms use backpropagation to calculate derivative.

* d_{vase} in code $\equiv J$ (here)
in code, $\frac{dJ}{da} = da = \underline{3}$ (here)

* Gradient Descent for Logistic Regression (using computation graph)



$$L = -(y \log \hat{y} + (1-y) \log (1-\hat{y}))$$

$\hat{y} = a$

$$\frac{da}{da} = \frac{\partial L}{\partial a} = -\left[\frac{y}{a} + \frac{-(1-y)}{(1-a)} \right] = -\frac{y}{a} + \frac{(1-y)}{(1-a)}$$

$$\frac{dz}{dz} = \frac{dL}{dz} = \frac{\partial L}{\partial a} \times \frac{\partial a}{\partial z}$$

$$= \left(-\frac{y}{a} + \frac{1-y}{1-a} \right) \frac{\partial r(z)}{\partial z}$$

$$= \left(-\frac{y}{a} + \frac{1-y}{1-a} \right) \times \frac{\partial}{\partial z} \frac{1}{1+e^{-z}}$$

$$\frac{\partial a}{\partial z} = \frac{+1}{(1+e^{-z})^2} (e^{-z})$$

$$a = \frac{1}{1+e^{-z}} \Rightarrow e^{-z} = \frac{1}{a} - 1$$

$$\frac{\partial a}{\partial z} = a^{\cancel{2}} \frac{(1-a)}{\cancel{a}} = a(1-a).$$

$$\therefore dz = \frac{dL}{dz} = \left(\frac{-y + ay + a - ay}{a(1-a)} \right) a(1-a)$$

$$dz = \underline{\underline{a - y}}$$

* Logistic Regression on m examples
- using for loop

for $i: 1 \rightarrow m$

$$z^{(i)} =$$

$$a^{(i)} =$$

$$J_t =$$

$$dz = a^{(i)} - y^{(i)}$$

$$dw_1 +=$$

$$dw_2 +=$$

$$db +=$$

} considering only w_1 & w_2

$$J = m$$

$$dw_1 / = m ; dw_2 / = m ; db / = m$$

Use

(greater datasets are involved)

As we advance in DL, for loops can be time-consuming, thus we use **vectorization**.

* VECTORIZATION

$$z = \text{np.dot}(\underbrace{w, x}_{w^T x}) + b$$