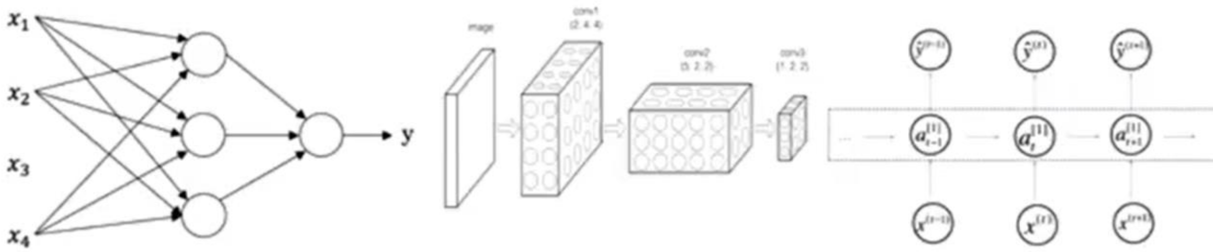
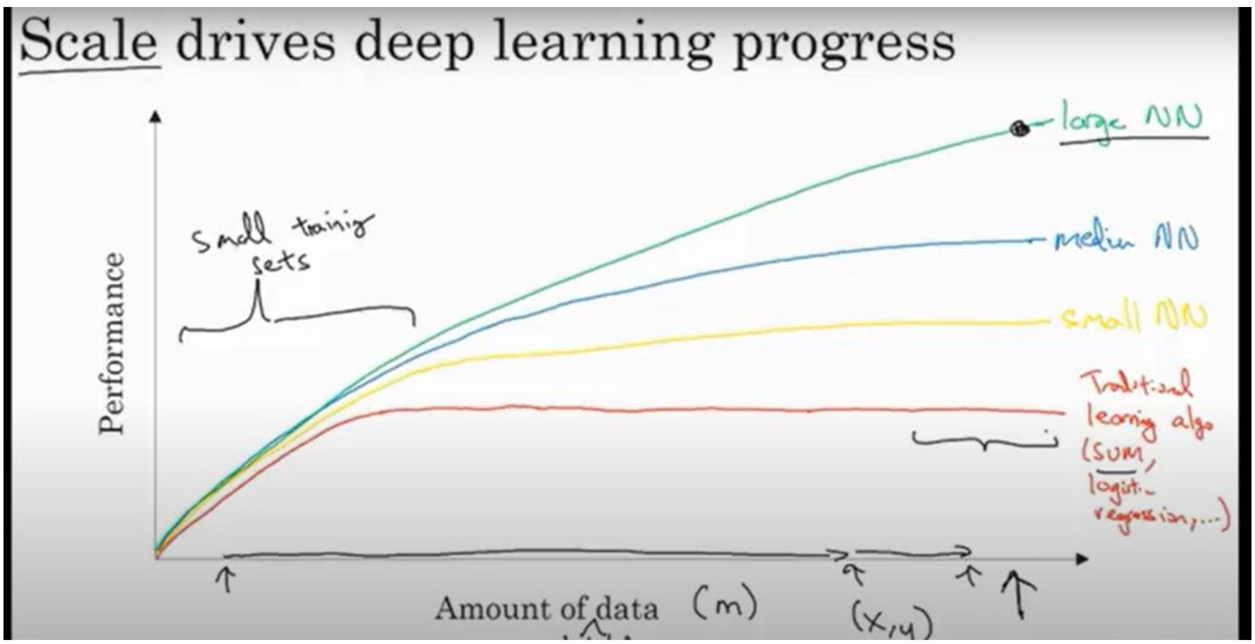
Neural Network examples



Standard NN Convolutional NN Recurrent NN



Outline of this Course

Week 1: Introduction

Week 2: Basics of Neural Network programming

Week 3: One hidden layer Neural Networks

Week 4: Deep Neural Networks

Logistic regression on m examples

$J=0$; $dw_1=0$; $dw_2=0$; $db=0$

For $i=1$ to m

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J \mathrel{+}= -[y^{(i)} \log a^{(i)} + (1-y^{(i)}) \log(1-a^{(i)})]$$

$$dz^{(i)} = a^{(i)} - y^{(i)}$$

$$dw_1 \mathrel{+}= x_1^{(i)} dz^{(i)}$$

$$dw_2 \mathrel{+}= x_2^{(i)} dz^{(i)}$$

$n=2$

$$db \mathrel{+}= dz^{(i)}$$

$J /= m$

$dw_1 /= m$; $dw_2 /= m$; $db /= m$.

$$dw_1 = \frac{\partial J}{\partial w_1}$$

$$w_1 := w_1 - \alpha\, dw_1$$

$$w_2 := w_2 - \alpha\, dw_2$$

$$b := b - \alpha\, db$$

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Logistic regression derivatives

$J = 0,\ dw1 = 0,\ dw2 = 0,\ db = 0$

$\rightarrow$ for i = 1 to m:

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J \mathrel{+}= -[y^{(i)} \log \hat{y}^{(i)} + (1-y^{(i)}) \log(1-\hat{y}^{(i)})]$$

$$dz^{(i)} = a^{(i)}(1-a^{(i)})$$

for $j = 1 \ldots n_x$

$dw_j \mathrel{+}= \ldots$

$$dw_1 \mathrel{+}= x_1^{(i)} dz^{(i)}$$

$$dw_2 \mathrel{+}= x_2^{(i)} dz^{(i)}$$

$n_x = 2$

$$db \mathrel{+}= dz^{(i)}$$

$J = J/m,\ dw_1 = dw_1/m,\ dw_2 = dw_2/m,\ db = db/m$

Vectorizing Logistic Regression

$dz^{(1)} = a^{(1)} - y^{(1)} \qquad dz^{(2)} = a^{(2)} - y^{(2)} \qquad \ldots$

$\boxed{dZ = [dz^{(1)}\ dz^{(2)} \ldots dz^{(m)}]}_{1 \times m} \leftarrow$

$A = [a^{(1)} \ldots a^{(m)}] \qquad Y = [y^{(1)} \ldots y^{(m)}]$

$\rightarrow dZ = A - Y = [a^{(1)} - y^{(1)} \quad a^{(2)} - y^{(2)} \quad \ldots]$

$\cancel{dw_1}$

$\cancel{dw_2}$

$\rightarrow dw = 0$

$dw \mathrel{+}= x^{(1)} dz^{(1)}$

$dw \mathrel{+}= x^{(2)} dz^{(2)}$

$\vdots$

$dw /= m$

$db = 0$

$db \mathrel{+}= dz^{(1)}$

$db \mathrel{+}= dz^{(2)}$

$\vdots$

$db \mathrel{+}= dz^{(m)}$

$db /= m.$

$$\boxed{db = \frac{1}{m} \sum_{i=1}^{m} dz^{(i)} = \frac{1}{m} np.sum(dZ)}$$

$$\boxed{dw = \frac{1}{m} X dZ^T}$$

$$= \frac{1}{m} \begin{bmatrix} | & & | \\ x^{(1)} & \ldots & x^{(m)} \\ | & & | \end{bmatrix} \begin{bmatrix} dz^{(1)} \\ \vdots \\ dz^{(m)} \end{bmatrix}$$

$$= \frac{1}{m} \underbrace{[x^{(1)} dz^{(1)} + \ldots + x^{(m)} dz^{(m)}]}_{n \times 1}$$

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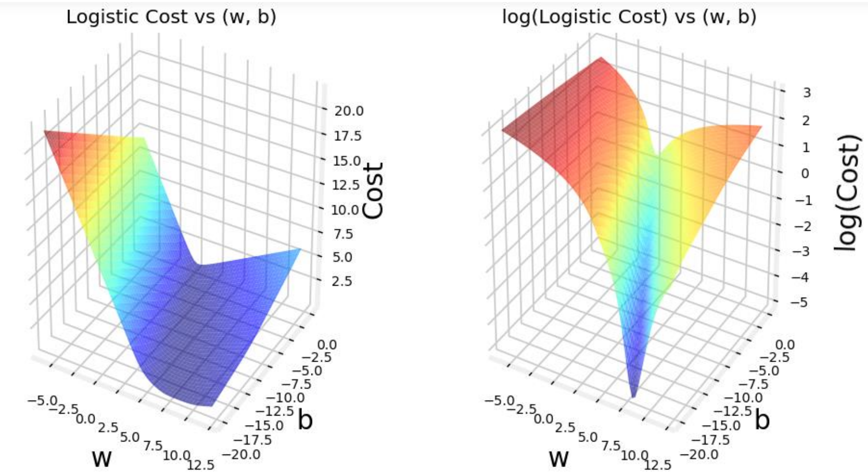
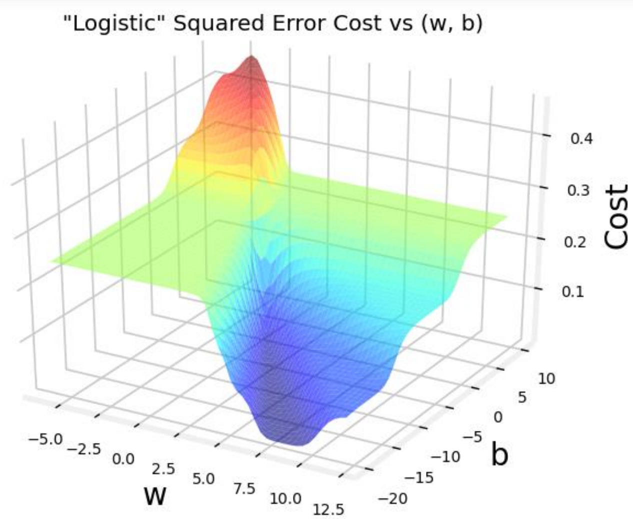


This curve is well suited to gradient descent! It does not have plateaus, local minima, or discontinuities. Note, it is not a bowl as in the case of squared error. Both the cost and the log of the cost are plotted to illuminate the fact that the curve, when the cost is small, has a slope and continues to decline. Reminder: you can rotate the above plots using your mouse.



While this produces a pretty interesting plot, the surface above not nearly as smooth as the 'soup bowl' from linear regression!

Logistic regression requires a cost function more suitable to its non-linear nature. This starts with a Loss function. This is described below.

Thus, we do not use squared error for logistic regression.

Broadcasting example

Calories from Carbs, Proteins, Fats in 100g of different foods:

	Apples	Beef	Eggs	Potatoes
Carb	56.0	0.0	4.4	68.0
Protein	1.2	104.0	52.0	8.0
Fat	1.8	135.0	99.0	0.9

$= A$ $(3,4)$

axis 0 ↓, axis 1 →

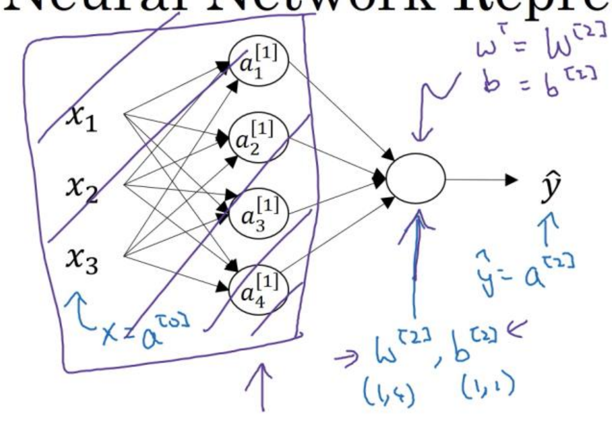
59cal

$\frac{56}{59} \approx 94.9\%$

Calculate % of calories from Carb, Protein, Fat. Can you do this without explicit for-loop?

```
cal = A.sum(axis = 0)
percentage = 100*A/(cal.reshape(1,4))
```

Neural Network Representation learning



$z = w^T x + b$

$\hat{y} = a = \sigma(z)$

Given input x:

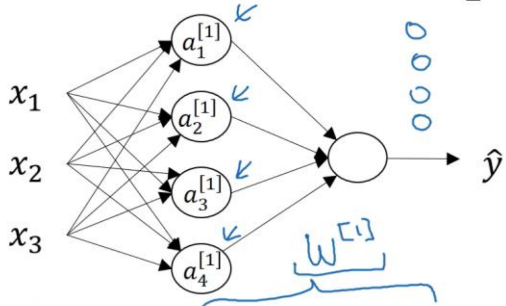
$$\underset{(4,1)}{z^{[1]}} = \underset{(4,3)}{W^{[1]}} \underset{(3,1)}{\overset{a^{[0]}}{\cancel{x}}} + \underset{(4,1)}{b^{[1]}}$$

$$\underset{(4,1)}{a^{[1]}} = \sigma(\underset{(4,1)}{z^{[1]}})$$

$$\underset{(1,1)}{z^{[2]}} = \underset{(1,4)}{W^{[2]}} \underset{(4,1)}{a^{[1]}} + \underset{(1,1)}{b^{[2]}}$$

$$\underset{(1,1)}{a^{[2]}} = \sigma(\underset{(1,1)}{z^{[2]}})$$

Neural Network Representation



$(w_1^{[1]})^T x$ $\quad a^{[1]}$

$$z_1^{[1]} = w_1^{[1]T} x + b_1^{[1]}, \quad a_1^{[1]} = \sigma(z_1^{[1]})$$
$$z_2^{[1]} = w_2^{[1]T} x + b_2^{[1]}, \quad a_2^{[1]} = \sigma(z_2^{[1]})$$
$$z_3^{[1]} = w_3^{[1]T} x + b_3^{[1]}, \quad a_3^{[1]} = \sigma(z_3^{[1]})$$
$$z_4^{[1]} = w_4^{[1]T} x + b_4^{[1]}, \quad a_4^{[1]} = \sigma(z_4^{[1]})$$

$$z^{[1]} = \underbrace{\begin{bmatrix} — w_1^{[1]T} — \\ — w_2^{[1]T} — \\ — w_3^{[1]T} — \\ — w_4^{[1]T} — \end{bmatrix}}_{W^{[1]}\ (4,3)} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \underbrace{\begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix}}_{b^{[1]}\ (4,1)} = \begin{bmatrix} w_1^{[1]T} x + b_1^{[1]} \\ w_2^{[1]T} x + b_2^{[1]} \\ w_3^{[1]T} x + b_3^{[1]} \\ w_4^{[1]T} x + b_4^{[1]} \end{bmatrix} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix}$$

$$a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ \vdots \\ a_4^{[1]} \end{bmatrix} = \sigma(z^{[1]})$$

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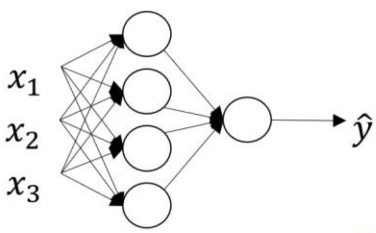
Vectorizing across multiple examples



$$z^{[1]} = W^{[1]}x + b^{[1]}$$
$$a^{[1]} = \sigma(z^{[1]})$$
$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$
$$a^{[2]} = \sigma(z^{[2]})$$

$x \longrightarrow a^{[2]} = \hat{y}$

$x^{(1)} \longrightarrow a^{[2](1)} = \hat{y}^{(1)}$

$x^{(2)} \longrightarrow a^{[2](2)} \quad \hat{y}^{(2)}$

$\vdots$

$x^{(m)} \longrightarrow a^{[2](m)} \quad \hat{y}^{(m)}$

$a^{[2](i)}$ ← example i, ← layer 2

for $i = 1$ to m,

$$z^{[1](i)} = W^{[1]} x^{(i)} + b^{[1]}$$
$$a^{[1](i)} = \sigma(z^{[1](i)})$$
$$z^{[2](i)} = W^{[2]} a^{[1](i)} + b^{[2]}$$
$$a^{[2](i)} = \sigma(z^{[2](i)})$$

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Vectorizing across multiple examples

```
for i = 1 to m:
```

$$\boxed{z^{[1](i)}} = W^{[1]}x^{(i)} + b^{[1]}$$

$$\boxed{a^{[1](i)}} = \sigma(z^{[1](i)})$$

$$\boxed{z^{[2](i)}} = W^{[2]}a^{[1](i)} + b^{[2]}$$

$$\boxed{a^{[2](i)}} = \sigma(z^{[2](i)})$$

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = \sigma(Z^{[1]})$$

$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = \sigma(Z^{[2]})$$

$$X = \begin{bmatrix} | & | & & | \\ x^{(1)} & x^{(2)} & \cdots & x^{(m)} \\ | & | & & | \end{bmatrix} \quad (n_x, m)$$

training examples

hidden units

$$Z^{[1]} = \begin{bmatrix} | & | & & | \\ z^{[1](1)} & z^{[1](2)} & \cdots & z^{[1](m)} \\ | & | & & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} | & | & & | \\ a^{[1](1)} & a^{[1](2)} & \cdots & a^{[1](m)} \\ | & | & & | \end{bmatrix}$$

hidden units

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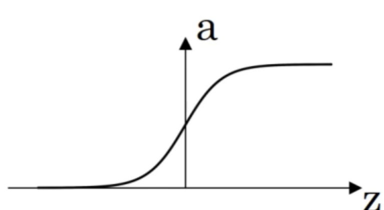
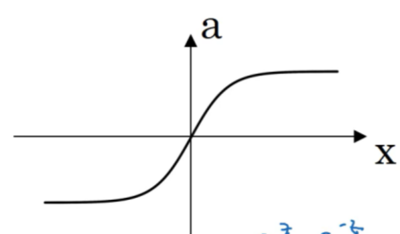
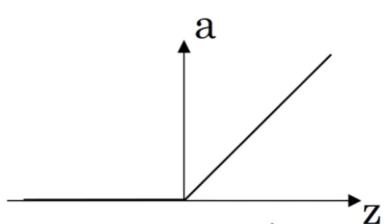
Pros and cons of activation functions



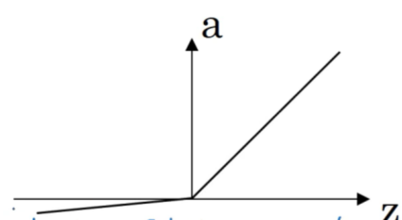
sigmoid: $a = \dfrac{1}{1 + e^{-z}}$



tanh: $a = \dfrac{e^{z} - e^{-z}}{e^{z} + e^{-z}}$



ReLU $a = \max(0, z)$



Leaky ReLU $a = \max(0.01z, z)$

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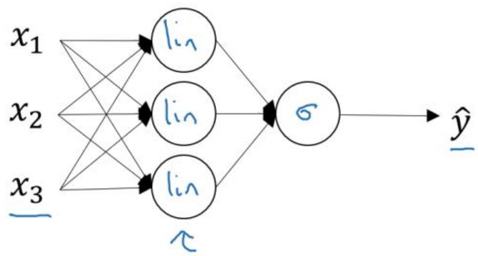
Activation function



Given x:

$$\begin{cases} z^{[1]} = W^{[1]}x + b^{[1]} \\ a^{[1]} = \cancel{g^{[1]}(z^{[1]})}\ z^{[1]} \end{cases}$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$a^{[2]} = \cancel{g^{[2]}(z^{[2]})}\ z^{[2]}$$

$g(z) = z$
"linear activation function"

$$\underbrace{a^{[1]} = z^{[1]}}= W^{[1]}x + b^{[1]}$$

$$a^{[2]} = z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$a^{[2]} = W^{[2]}\big(\underbrace{W^{[1]}x + b^{[1]}}_{a^{[1]}}\big) + b^{[2]}$$

$$= \underbrace{(W^{[2]}W^{[1]})}_{W'}x + \underbrace{(W^{[2]}b^{[1]} + b^{[2]})}_{b'}$$

$$= \underline{W'x + b'}$$

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Formulas for computing derivatives

Forward propagation:

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = g^{[1]}(Z^{[1]})$$

$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g^{[2]}(Z^{[2]}) = \sigma(Z^{[2]})$$

Back propagation:

$$dZ^{[2]} = A^{[2]} - Y \qquad Y = [y^{(1)}\ y^{(2)} \dots, y^{(m)}]$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$$

$(n^{[2]},)$

$(n^{[2]}, 1)$

$$db^{[2]} = \frac{1}{m} \text{np.sum}(dZ^{[2]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$$dZ^{[1]} = \underbrace{W^{[2]T} dZ^{[2]}}_{(n^{[1]}, m)} * \underbrace{g^{[1]'}(Z^{[1]})}_{(n^{[1]}, m)}$$

element-wise product

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} \text{np.sum}(dZ^{[1]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$(n^{[1]}, 1)$ $\quad$ $(n^{[1]},)$

The `sigmoid` function is implemented in python as shown in the cell below.

```
4]: def sigmoid(z):
        """
        Compute the sigmoid of z

        Args:
            z (ndarray): A scalar, numpy array of any size.

        Returns:
            g (ndarray): sigmoid(z), with the same shape as z

        """

        g = 1/(1+np.exp(-z))

        return g
```

Summary of gradient descent

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]}a^{[1]^T}$$

$$db^{[2]} = dz^{[2]}$$

$$\underbrace{dz^{[1]}}_{(n^{[1]},1)} = W^{[2]T}dz^{[2]} * g^{[1]\prime}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]}x^T$$

$$db^{[1]} = dz^{[1]}$$

$$dZ^{[2]} = A^{[2]} - Y$$

$$J(\ldots) = \frac{1}{m}\sum_{i=1}^{n} \mathcal{L}(\hat{y}, y)$$

$$dW^{[2]} = \frac{1}{m}dZ^{[2]}A^{[1]^T}$$

$$db^{[2]} = \frac{1}{m}np.sum(dZ^{[2]}, axis = 1, keepdims = True)$$

elementwise product

$$\underbrace{dZ^{[1]}}_{(n^{[1]},m)} = \underbrace{W^{[2]T}dZ^{[2]}}_{(n^{[1]},m)} * \underbrace{g^{[1]\prime}(Z^{[1]})}_{(n^{[1]},m)}$$

$$dW^{[1]} = \frac{1}{m}dZ^{[1]}X^T$$

$$db^{[1]} = \frac{1}{m}np.sum(dZ^{[1]}, axis = 1, keepdims = True)$$

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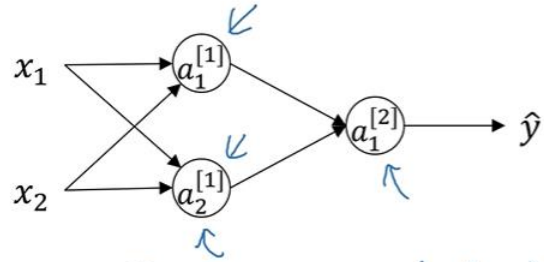
Random initialization



$W^{[1]}$ = np.random.randn((2,2)) * 0.01

100?

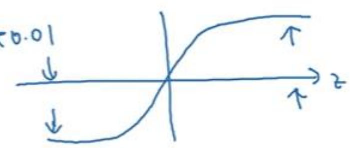
$b^{[1]}$ = np.zeros((2,1))

$W^{[2]}$ = np.random.randn((1,2)) * 0.01

$b^{[2]} = 0$

$z^{[1]} = W^{[1]} x + b^{[1]}$

$a^{[1]} = g^{[1]}(z^{[1]})$



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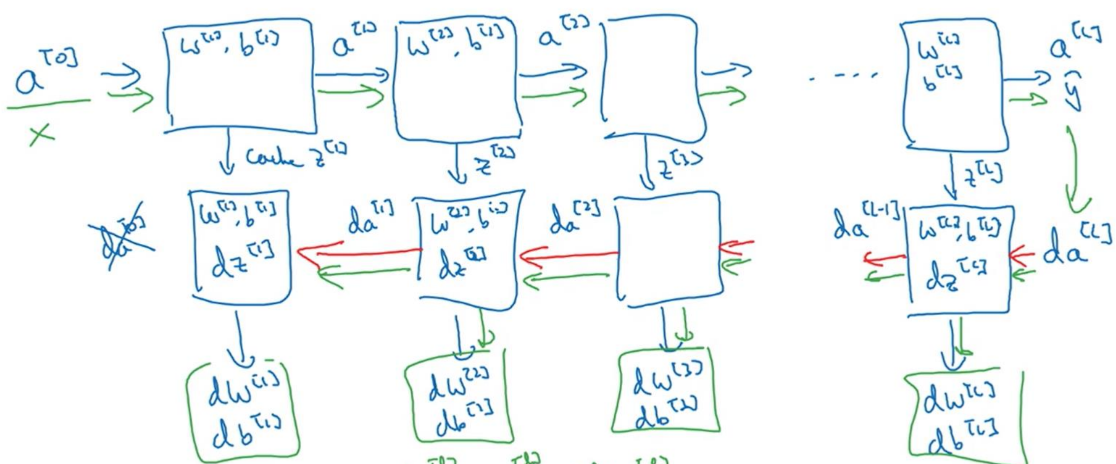
Forward and backward functions



$W^{[l]} := W^{[l]} - \alpha \, dW^{[l]}$

$b^{[l]} := b^{[l]} - \alpha \, db^{[l]}$

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Backward propagation for layer l

- Input $da^{[l]}$
- Output $\boxed{da^{[l-1]}}, dW^{[l]}, db^{[l]}$

$$dz^{[l]} = da^{[l]} * g^{[l]\prime}(z^{[l]})$$

$$dW^{[l]} = dz^{[l]} \cdot a^{[l-1]}$$

$$db^{[l]} = dz^{[l]}$$

$$\boxed{da^{[l-1]}} = W^{[l]T} \cdot dz^{[l]}$$

$$dz^{[l]} = W^{[l+1]T} dz^{[l+1]} * g^{[l]\prime}(z^{[l]})$$

$$dZ^{[l]} = dA^{[l]} * g^{[l]\prime}(Z^{[l]})$$

$$dW^{[l]} = \frac{1}{m} dZ^{[l]} \cdot A^{[l-1]T}$$

$$db^{[l]} = \frac{1}{m} \text{np.sum}(dZ^{[l]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$$\boxed{dA^{[l-1]}} = W^{[l]T} \cdot dZ^{[l]}$$

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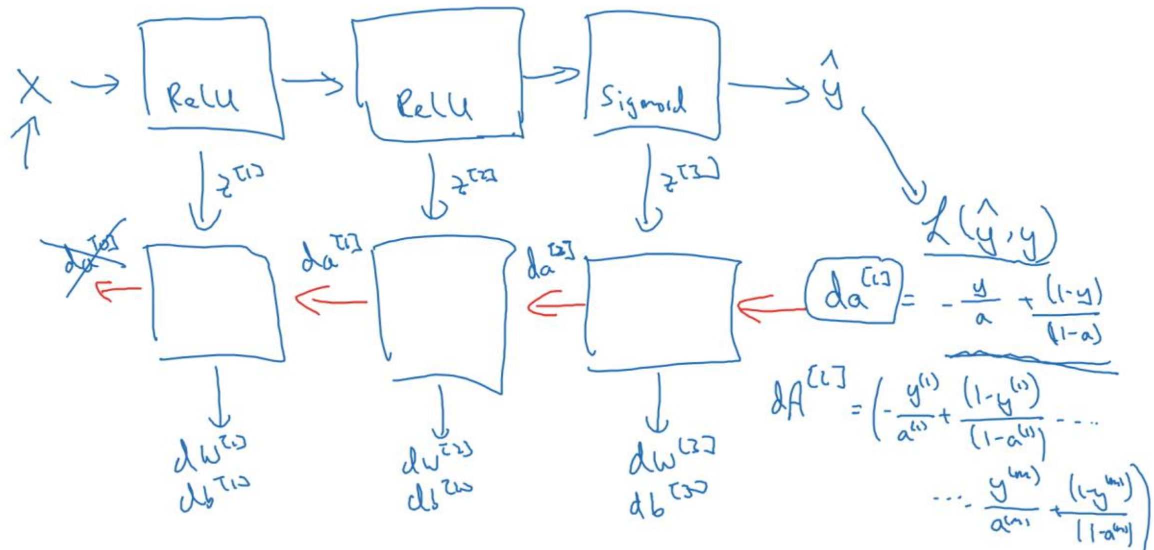
Summary



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Forward and backward propagation

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$
$$A^{[1]} = g^{[1]}(Z^{[1]})$$
$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$
$$A^{[2]} = g^{[2]}(Z^{[2]})$$
$$\vdots$$
$$A^{[L]} = g^{[L]}\left(Z^{[L]}\right) = \hat{Y}$$

$$dZ^{[L]} = A^{[L]} - Y$$
$$dW^{[L]} = \frac{1}{m} dZ^{[L]} A^{[L]^T}$$
$$db^{[L]} = \frac{1}{m} np.\mathrm{sum}(\mathrm{d}Z^{[L]}, axis = 1, keepdims = True)$$
$$dZ^{[L-1]} = dW^{[L]^T} dZ^{[L]} g'^{[L]}(Z^{[L-1]})$$
$$\vdots$$
$$dZ^{[1]} = dW^{[L]^T} dZ^{[2]} g'^{[1]}(Z^{[1]})$$
$$dW^{[1]} = \frac{1}{m} dZ^{[1]} A^{[1]^T}$$
$$db^{[1]} = \frac{1}{m} np.\mathrm{sum}(\mathrm{d}Z^{[1]}, axis = 1, keepdims = True)$$