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## B. TECH. (SEM V) THEORY EXAMINATION 2022-23 COMPUTER INTEGRATED MANUFACTURING

Time: 3 Hours Total Marks: 100

**Note:** Attempt all Sections. If you require any missing data, then choose suitably.

#### **SECTION A**

#### 1. Attempt *all* questions in brief.

2x10 = 20

- (a) What are the essential needs of CIM?
- (b) Differentiate between analytic surfaces and synthetic surfaces
- (c) What do you mean by BLOBBY OBJECTS?
- (d) Explain the term HALF SPACES
- (e) Differentiate G and M codes.
- (f) Discuss is the purpose of canned cycles?
- (g) State the main objectives of FMS.
- (h) What are the objectives of MRP system
- (i) Define the term stereo lithography.
- (j) Define the meaning Tessellation?

#### SECTION B

#### 2. Attempt any *three* of the following:

10x3 = 30

- (a) Explain the five levels of automation
- (b) Illustrate the concept of B-rep approach of solid modelling with example
- (c) List any five important factors to be considered while designing guide ways
- (d) Explain with neat sketch AS/RS system used in FMS
- (e) Examine with a neat sketch the working principle of fused deposition modelling process

#### **SECTION C**

### 3. Attempt any *one* part of the following:

10x1 = 10

- (a) List any ten strategies for automation and production systems
- (b) Compare between fixed, programmable and flexible automation system

#### 4. Attempt any *one* part of the following:

10 x1 = 10

- (a) Using Bresenham's line algorithm, calculate the pixel positions along the line between end points (15, 8) and (28,16).
- (b) Classify and compare continuities in curve modeling

# 5. Attempt any *one* part of the following:

10x1 = 10

- (a) Sketch and explain the general configuration of Direct Numerical Control (DNC) system
- (b) List any five advantages of automatic tool changer (ATC).

### 6. Attempt any *one* part of the following:

10x1 = 10

- (a) Explain the classification and coding system in Group Technology
- (b) With block diagram, explain developing a retrival type of computer aided process planning and generative type of computer aided process planning

## 7. Attempt any *one* part of the following:

10x1 = 10

- (a) Compare SCARA Robot configuration with other configurations
- (b) Examine the Classification of the different types of rapid prototyping techniques. Explain the Stereo lithography techniques with neat sketch

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