

Smart Waste Bin Network

An IoT-Enabled Waste Bin Monitoring and Collection Optimization System

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1. ABSTRACT

Because of rapid urbanization, the generation of waste has increased so much that it puts immense pressure on municipal waste management infrastructures. The traditional approaches to waste collection rely on fixed schedules and manual inspection; this often leads to inefficiencies such as bin overflows, unnecessary pickups of partially filled bins, extremely high fuel consumption, and poor overall sanitation.

The following study presents the development of a Smart Waste Bin Network, an IoT-enabled system for waste monitoring and collection optimization, which in real time provides information about the fill level of the bins and helps perform data-driven decisions on refuse collection. This includes ultrasonic sensing, edge processing through microcontrollers, low-power long-range LoRa communication, and a centralized gateway together with its dashboard. This proposed architecture is scalable, energy-efficient, cost-effective, and compatible with smart city infrastructure requirements.

2. FIELD OF THE WORK

The system falls under the domain of:

- Internet of Things (IoT)
- Smart City Infrastructure
- Urban Waste Management
- Wireless Sensor Networks (WSN)
- Low-Power Embedded Systems

Specifically, this work focuses on **sensor-driven urban infrastructure monitoring combined with data-driven optimization strategies.**

3. BACKGROUND AND EXISTING CHALLENGES

3.1 Traditional Waste Collection Systems

Most cities today follow a **static waste collection model**, where garbage trucks visit bins on a fixed daily or weekly schedule. This approach does not consider real-time usage patterns.

3.2 Limitations of Existing Systems

- Overflowing bins in high-footfall areas
- Premature collection of underutilized bins
- Increased operational costs (fuel, labor, vehicle wear)
- No real-time visibility for municipal authorities
- Poor hygiene and public dissatisfaction

3.3 Need for a Smart Solution

A smart waste management system must:

- Monitor bin status continuously
- Communicate efficiently over long distances
- Operate on low power
- Scale across hundreds of bins
- Support intelligent routing decisions

4. PROBLEM STATEMENT

Design and conceptualize an **IoT-enabled Smart Waste Bin Network** capable of:

1. Detecting and reporting the fill level of waste bins across multiple city zones
2. Notifying municipal authorities when bins approach full capacity
3. Enabling optimized garbage collection routes to reduce operational inefficiencies

5. OBJECTIVES OF THE SYSTEM

The primary objectives of the proposed system are:

- To develop a **real-time bin fill-level monitoring mechanism**
- To minimize waste overflow and improve urban hygiene
- To reduce unnecessary garbage collection trips
- To design a **low-power, scalable, and cost-effective IoT architecture**

- To demonstrate a functional prototype suitable for smart city deployment

6. OVERALL SYSTEM ARCHITECTURE

6.1 Architectural Overview

The system follows a **layered IoT architecture**, which improves modularity, scalability, and maintainability.

Layers:

1. **Edge Layer (Smart Bin Nodes)**
2. **Gateway Layer**
3. **Cloud & Application Layer**

7. SMART BIN NODE (EDGE LAYER)

7.1 Purpose

The Smart Bin Node is responsible for:

- Sensing the waste fill level
- Performing local computation
- Transmitting data wirelessly

7.2 Hardware Components

a) Ultrasonic Sensor (HC-SR04)

- Measures the distance between the bin lid and waste surface
- Uses Time-of-Flight (ToF) principle
- Distance decreases as bin fills, enabling fill-level estimation

Why Ultrasonic?

- Low cost
- Non-contact measurement
- Adequate accuracy for waste level detection

b) Microcontroller – Arduino UNO

- Reads ultrasonic sensor data

- Converts raw distance into fill percentage
- Handles communication with LoRa module

Reason for Selection:

- Simple architecture
- Widely used and reliable
- Sufficient for edge-level processing

c) LoRa Module – SX1278 (433 MHz)

- Enables long-range wireless communication
- Very low power consumption
- Ideal for distributed city-wide sensor networks

7.3 Edge-Level Processing

Instead of transmitting raw sensor values continuously, the node:

- Converts distance into meaningful fill percentage
- Sends data at periodic intervals
- Reduces communication overhead and power usage

8. GATEWAY NODE

8.1 Purpose

The Gateway Node aggregates data from multiple bin nodes and acts as a bridge to the cloud/dashboard.

8.2 Hardware Components

ESP32 Microcontroller

- Receives LoRa packets
- Performs threshold evaluation
- Forwards data to cloud services
- Supports Wi-Fi and future expansions

8.3 Gateway-Level Intelligence

- Immediate alert generation for critical bins
- Temporary buffering of data
- Supports scalability by handling multiple nodes

9. CLOUD & DASHBOARD LAYER

9.1 Cloud Strategy (Conceptual)

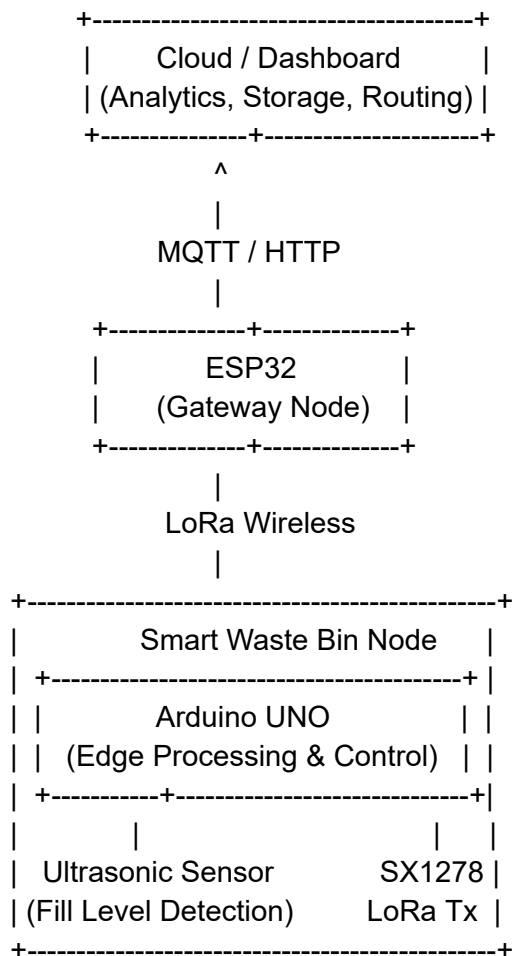
The cloud layer is responsible for:

- Long-term data storage
- Analytics and reporting
- Route optimization algorithms
- Visualization dashboards

9.2 Dashboard Features

- Real-time bin status (percentage-based)
- Color-coded alerts
- Zone-wise bin distribution
- Optimized garbage truck routes
- Historical data trends

10. BLOCK DIAGRAM



11. DATA FLOW DESIGN

Step-by-Step Data Flow

1. Ultrasonic sensor emits pulse
2. Echo return time is measured
3. Distance is calculated
4. Fill percentage is derived
5. Data packet transmitted via LoRa
6. ESP32 receives and processes data
7. Dashboard updated
8. Alerts generated if required

12. COMMUNICATION PROTOCOLS

12.1 LoRa

- Long range (2–10 km urban)
- Low power consumption
- Supports star topology
- Ideal for smart city sensors

12.2 MQTT (Cloud Layer)

- Lightweight publish/subscribe protocol
- Efficient for IoT telemetry
- Scales easily with large node count

13. ROUTE OPTIMIZATION STRATEGY

13.1 Rule-Based Prioritization

Fill Level	Priority
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$\geq 80\%$	High
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60–80%	Medium
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$< 60\%$	Low
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13.2 Algorithmic Logic

- Bins grouped by zone
- High-priority bins clustered
- Shortest-path / greedy routing applied

13.3 Pseudocode

For each bin:

 Read fill_level

 If fill_level \geq 80%:

 Mark as HIGH priority

Group bins by zone

Sort by priority and distance

Generate optimized route

14. FLOW CHART

Start

|

Initialize System

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Read Ultrasonic Sensor

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Compute Fill Percentage

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Is Fill \geq 80% ?

/

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Yes

No

|

Send Alert

|

Store Data

|

Transmit via LoRa

|

ESP32 Receives

|

Update Dashboard

|

End

15. POWER MANAGEMENT STRATEGY

- Periodic sensing instead of continuous
- Low-power LoRa transmission
- Sleep modes between readings
- Event-triggered communication
- Optional solar charging

16. RELIABILITY & FAULT HANDLING

- Averaging multiple readings
- Software filtering for noise
- Detection of blocked sensors
- Maintenance alerts
- Future redundancy via weight sensors

17. SCALABILITY & NETWORK CONSIDERATIONS

Topology: Star

Why Star?

- Lower node complexity
- Better energy efficiency
- Simplified maintenance
- Easier scaling to 100+ bins

18. COST & FEASIBILITY ANALYSIS

Component	Cost (INR)
Arduino UNO	₹450
Ultrasonic Sensor	₹150
SX1278 LoRa	₹500
Battery & Enclosure	₹300
Total	₹1400–1500

19. APPLICATIONS

- Municipal waste management
- Smart campuses
- Industrial waste tracking
- Residential complexes

20. CONCLUSION

This work presents a Smart Waste Bin Network that demonstrates how IoT technologies can support the revolution of urban waste management by incorporating low-power wireless communication and intelligent data processing. The proposed system is scalable, cost-effective, and viable for real-world deployment. It aligns well with the aims of smart city objectives and the research objectives of the Smart City Living Lab.