

# SOFTWARE ARCHITECTURE

## 1.1 Software Architecture Overview

The software follows a **layered IoT architecture**:

Application Layer  
(Dashboard, Alerts, Routing)

Cloud / Gateway Layer  
(ESP32 + Processing)

Communication Layer  
(LoRa SX1278)

Edge Layer  
(Arduino + Sensors)

## 1.2 Software Responsibilities

### Edge Layer (Arduino UNO)

- Sensor reading
- Distance → Fill % conversion
- Packet formation
- Low-frequency transmission

### Gateway Layer (ESP32)

- Packet reception
- Threshold evaluation
- Alert generation
- Cloud forwarding (conceptual)

## 1.3 Data Flow (Software Perspective)

```
Sensor Read → Local Processing → LoRa Tx  
→ LoRa Rx → Alert Logic → Dashboard Update
```

# ALGORITHMS USED

## 2.1 Fill Level Detection Algorithm

### Logic

- Empty bin → larger distance
- Filled bin → smaller distance

```
fill_percentage =  
(1 - (measured_distance / bin_height)) × 100
```

Mapping used for simplicity.

## 2.2 Alert Algorithm

```
IF fill_level ≥ 80%  
    Trigger ALERT  
ELSE  
    Store data normally
```

## 2.3 Transmission Control Algorithm

```
Read Sensor  
Process Data  
Send Packet  
Sleep for fixed interval
```

# FLOW CHART

```
Start
|
Initialize Hardware
|
Read Ultrasonic Sensor
|
Calculate Fill Level
|
Is Fill ≥ 80%?
|      |
Yes    No
|      |
Send Alert Normal Data
|
Transmit via LoRa
|
Gateway Receives
|
Display / Upload
|
End
```