

I Introduction

- Nuclear Energy is a carbon free energy source and an attractive alternative to fossil fuel
- Computational fluid dynamics can characterize the turbulent flow in nuclear reactors with greater accuracy than other methods
- Uncertainty quantification of computer simulations will drive the practicality of sourcing clean energy from boiling water reactors
- The Standard k-ε model was used for the computer simulations

Standard k-ε	
2-layer [all y+]	
meshing	state
coarse	steady(1)
medium (2x)	steady(2)/unsteady(4)
fine (4x)	steady(3)
resolved	steady(5)
low re [all y+]	
resolved	steady(6)

Assessment of a Physics Based UQ Method for the Application of CFD

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4 Summary & Future Work

- The UQ method has successfully bounded experimental data
- The UQ method is a new implantation of modeling uncertainty was characterized in CFD. This quantification will allow for CFD use in nuclear reactor safety analysis
- The UQ method has been designed for single phase flow. Boiling and pressurized water reactors frequently experience two phase flows
- Future work includes developing a UQ method for two phase flow
- Employ this UQ method in code, scaling, applicability, & uncertainty (CSAU) during reactor licensing²

2 Discretization Study

- Discretization is a numerical method used to employ simpler equations to approximate solutions of separate elements in a system
- A discretization study was utilized to determine the best suitable model to use for UQ
- To compare to experimental data, three profiles were graphed of the 6 computed simulations

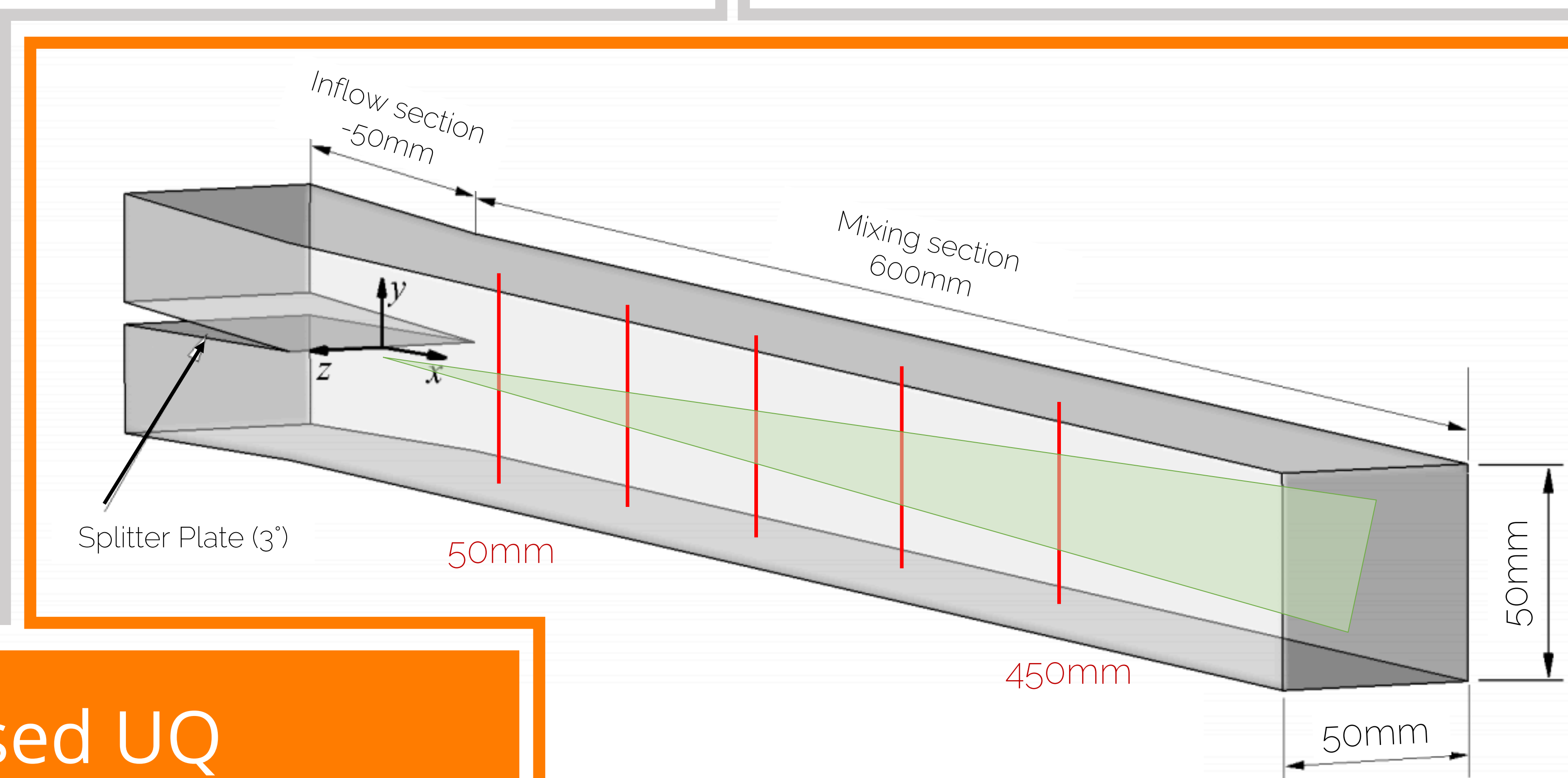


Fig 1. GEMIX Geometry¹

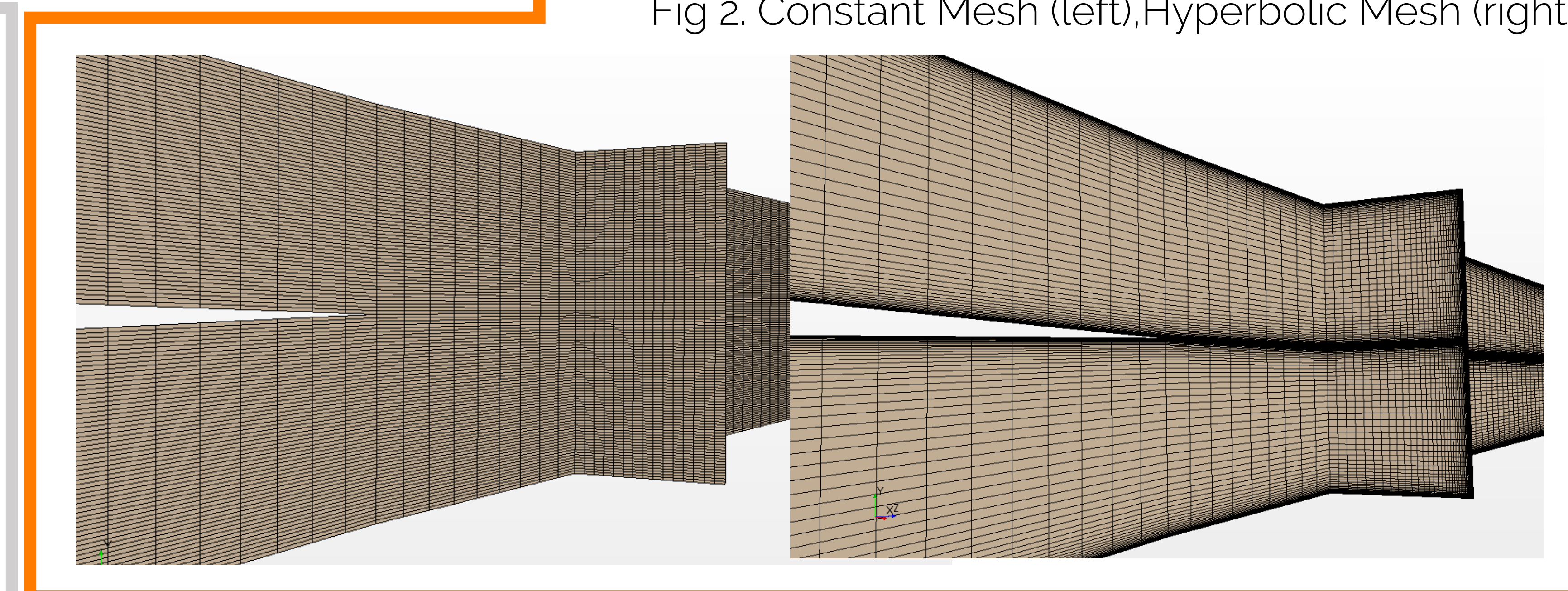


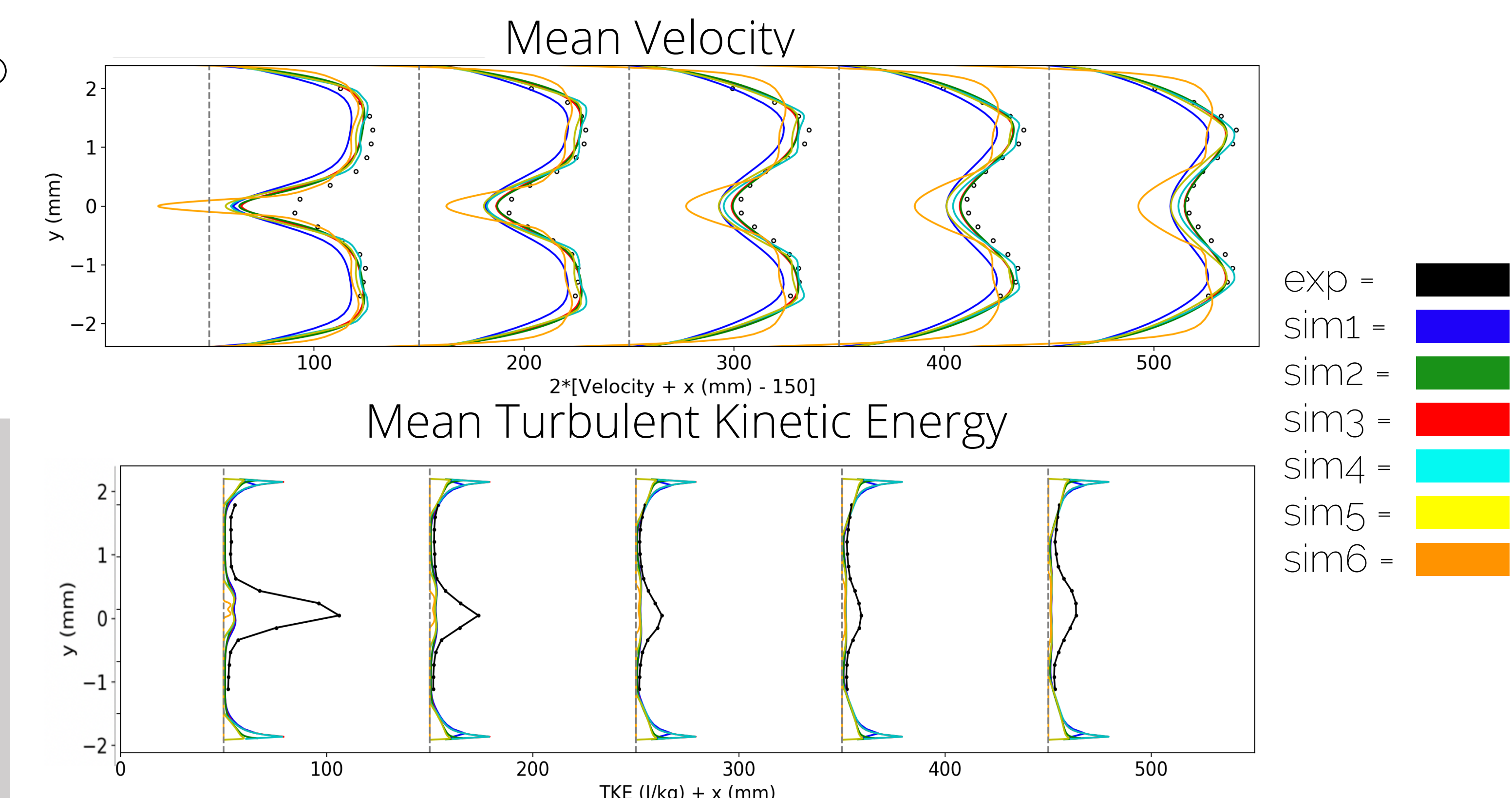
Fig 2. Constant Mesh (left), Hyperbolic Mesh (right)

- Source of uncertainty : model
- RANS Momentum Equation

$$\frac{\partial(\rho \bar{u}_i)}{\partial t} + \rho \bar{u}_i \frac{\partial(\bar{u}_i)}{\partial x_j} = -\frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_j} - \frac{\partial}{\partial x_i} \rho \overline{u'_i u'_j}$$

- Boussinesq assumption

$$\overline{u'_i u'_j} = \mu_t \left(\frac{\partial \bar{u}_j}{\partial x_i} + \frac{\partial \bar{u}_i}{\partial x_j} \right) - \frac{2}{3} k \delta_{ij}$$



3 Uncertainty Quantification

