

# DISCRETE-TIME AND DISCRETE FOURIER TRANSFORM

## CONTENTS (ADDITIONAL READING )

**SPECTROGRAPHIC ANALYSIS OF SPEECH**

**SHORT TIME FOURIER TRANSFORM ANALYSIS**

**TIME-FREQUENCY RESOLUTION TRADEOFF**

**FAST FOURIER TRANSFORM**

## 1. Spectrographic analysis of speech

- The Fourier transform of the windowed speech waveform, i.e. the **short-time Fourier transform (STFT)**, is given by

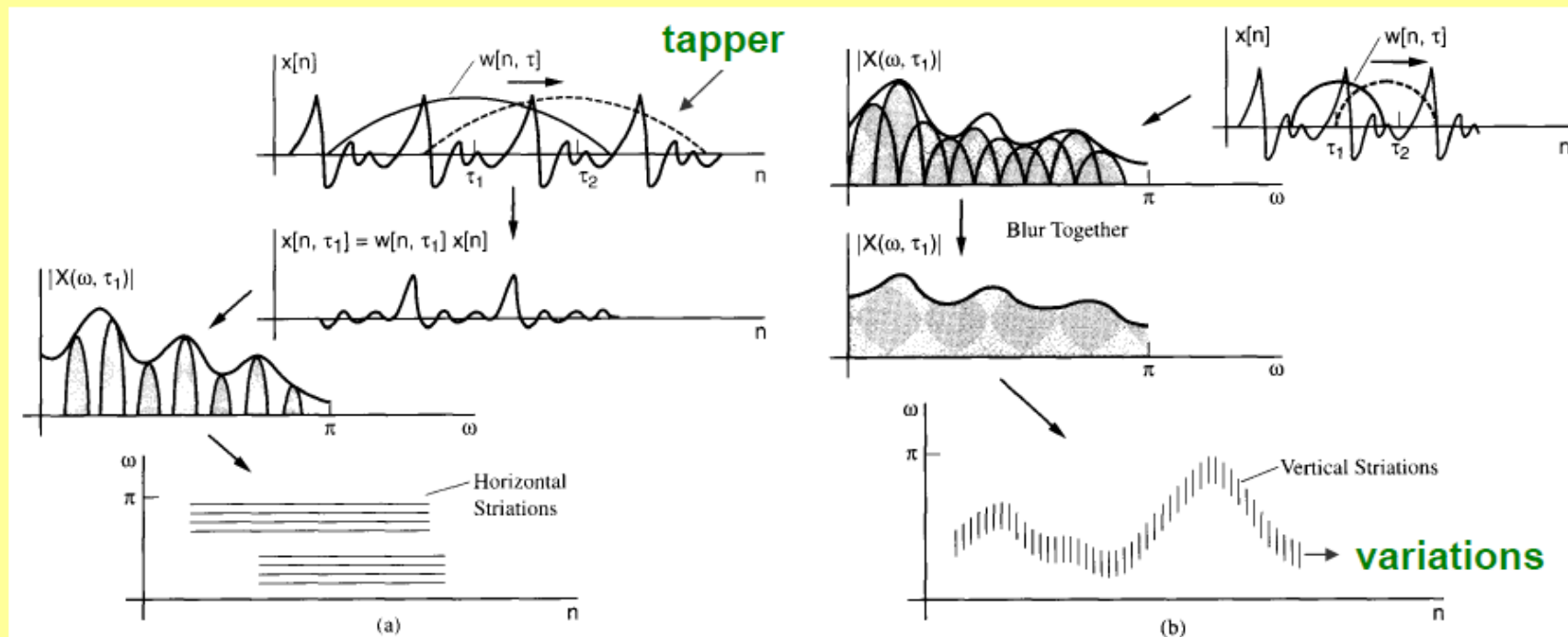
$$X(\omega, \tau) = \sum_{n=-\infty}^{\infty} x[n, \tau] \exp(-jn\omega). \quad (1-1)$$

where  $x[n, \tau] = w[n, \tau] \cdot x[n]$  is the windowed speech segments as a function of the window center at time  $\tau$ .

- The **spectrogram** is a graphical display of the magnitude of the time-varying spectral characteristics and is given by

$$S(\omega, \tau) = |X(\omega, \tau)|^2, \quad (1-2)$$

which is a measure of the energy of the frequency component at frequency  $\omega$  in the neighborhood of  $\tau$ .



**Fig. 3.14 Formation of (a) the narrowband and (b) the wideband spectrograms.**

- The figure shows two types of spectrograms: **narrowband** (good spectral resolution with large window length, e.g. 20ms) and **wideband** (good time resolution with short window length – e.g. 4ms Hamming window).

## 2.1 Short-Time Fourier Transform (STFT) Analysis

- Given time-series  $x[n]$ , the **STFT** at time  $n$  is given as:

$$X(n, \omega) = \sum_{m=-\infty}^{\infty} x[m]w[n-m]e^{-j\omega m}, \quad (2.1)$$

where  $w[n]$  is the **analysis window**, which is assumed to be non-zero only in the interval  $[0, N_w - 1]$ .

- The **discrete STFT** is obtained by sampling  $X(n, \omega)$  over the unit circle:

$$X(n, k) = X(n, \omega) \Big|_{\omega=\frac{2\pi}{N}k} = \sum_{m=-\infty}^{\infty} x[m]w[n-m]e^{-j\frac{2\pi}{N}km}, \quad (2.2)$$

where  $N$  is the frequency sampling factor and  $2\pi/N$  is the frequency sampling interval.

■ An alternate (filtering) view of the discrete STFT is:

$$X(n, \omega_0) = \sum_{m=-\infty}^{\infty} (x[m]e^{-j\omega_0 m})w[n-m] = (x[n]e^{-j\omega_0 n}) * w[n]. \quad (2.3)$$

That is, the signal  $x[n]$  is first modulated with  $e^{-j\omega_0 n}$ , and then passed through a filter with impulsive response  $w[n]$ .

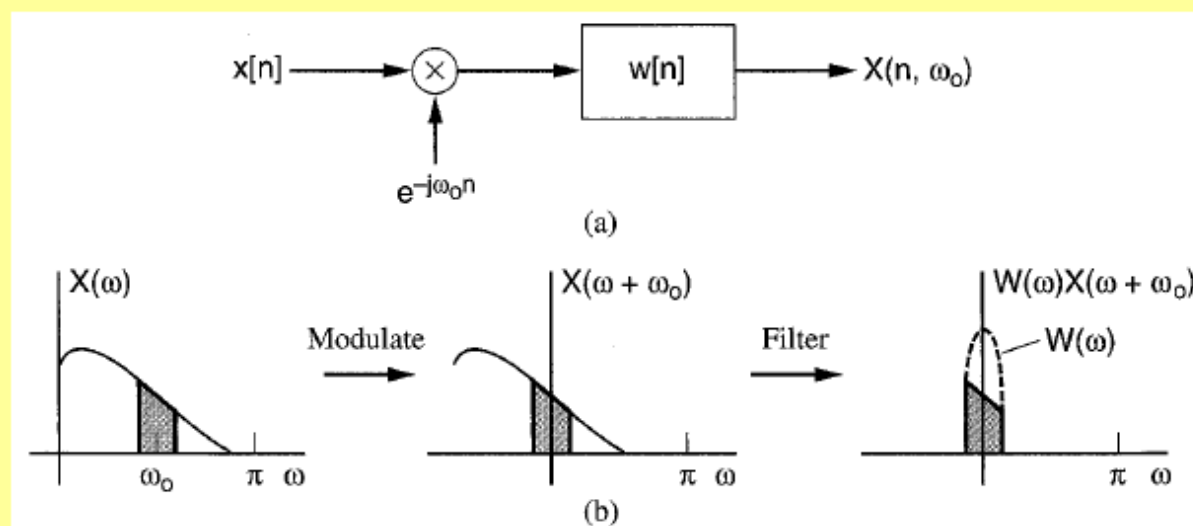


Fig. 7.3 Filtering view of STFT analysis at frequency  $\omega_0$ : (a) block diagram of complex exponential modulation followed by a lowpass filter; (b) operations in the frequency domain.

■ An equivalent representation of (2.3) is:

$$X(n, \omega_0) = e^{-j\omega_0 n} (x[n] * w[n] e^{j\omega_0 n}). \quad (2.4)$$

That is, the sequence  $x[n]$  is first passed through the filter  $w[n]$  with a linear phase factor. The output is then modulated by  $e^{-j\omega_0 n}$ .

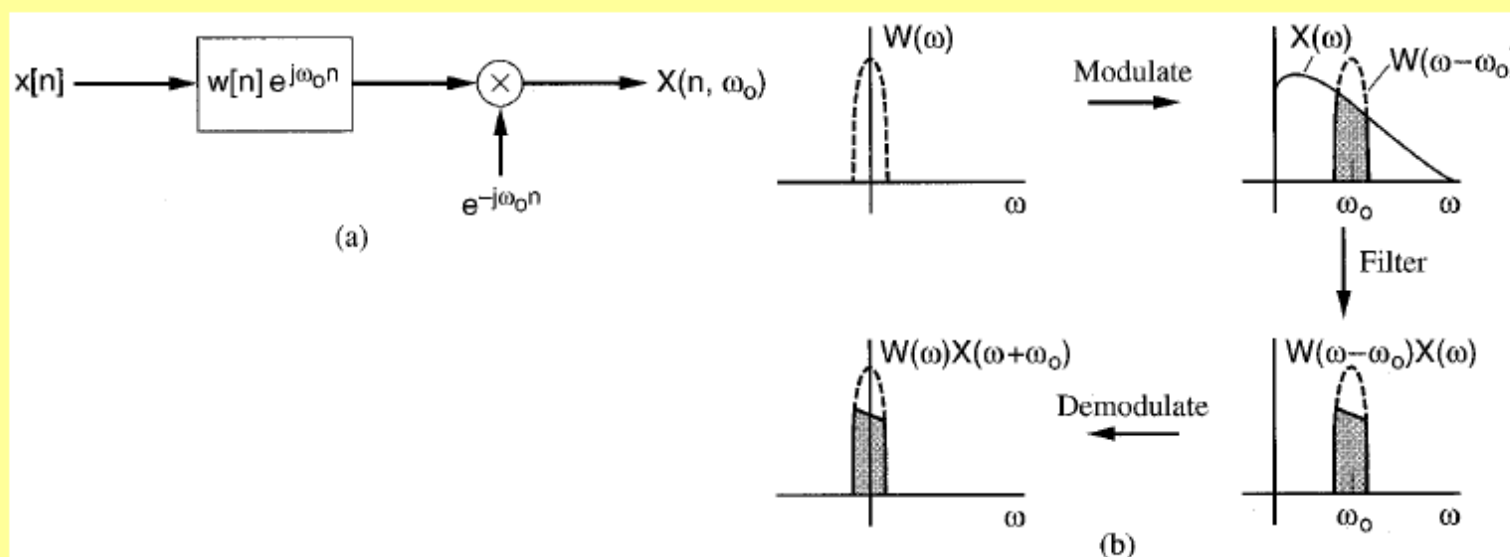


Fig. 7.4 Alternative filtering view of STFT analysis at frequency  $\omega_0$ : (a) block diagram of bandpass filtering followed by complex exponential modulation; (b) operations in the frequency domain.

### 2.1.3 Time-Frequency Resolution Tradeoffs

- The STFT can be also written as

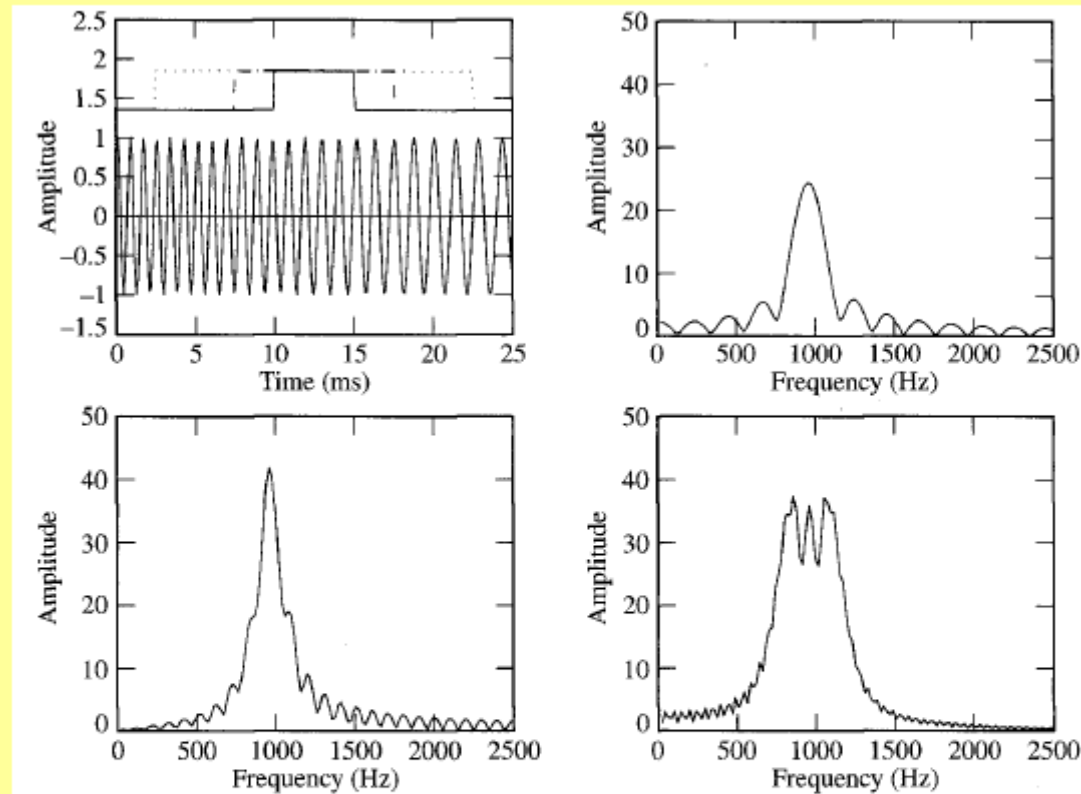
$$X(n, \omega) = \frac{1}{2\pi} \int_{-\pi}^{\pi} W(\theta) e^{j\theta n} X(\omega + \theta) d\theta, \quad (2.5)$$

$X(\omega)$  is the Fourier transform of  $x[m]$  and  $W(-\omega)e^{j\omega n}$  as the Fourier transform of  $w[n - m]$  with respect to  $m$ .

- The size of  $w[n]$  affects the time-frequency resolution of STFT:

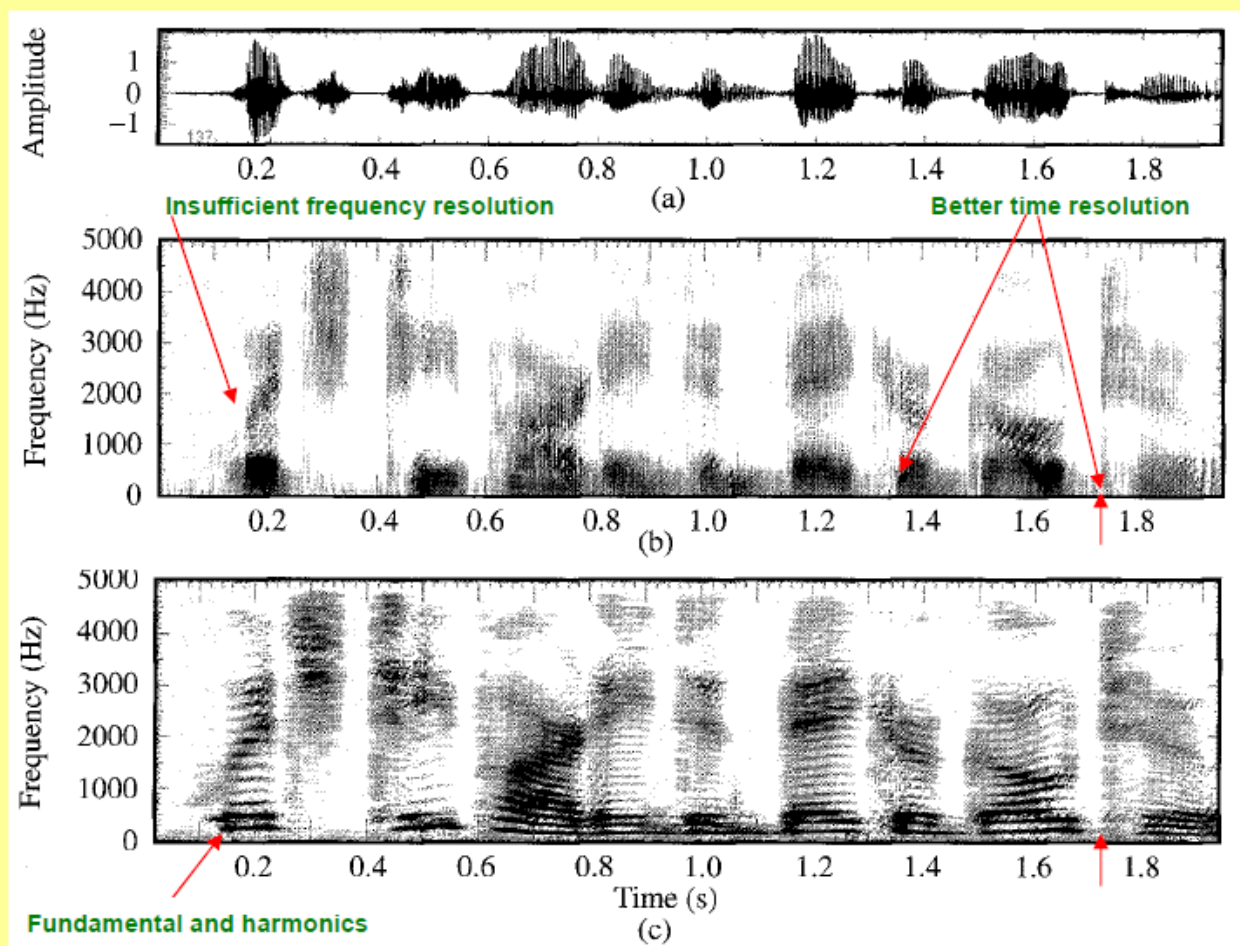
Window size of $w[n]$	Bandwidth of $W(\omega)$	Time resolution	Frequency resolution	Good for:
long	narrow	bad	good	sinusoidal components, (harmonic)
short	wide	good	bad	fast time-varying components, (rapid conversational speech)

A fundamental problem of STFT and other time-frequency analysis techniques is the selection of the windows to achieve a good tradeoff between time and frequency resolution.

**Example:**

**Fig. 7.8 Effect of the length of the analysis window on the discrete Fourier Transform of linearly frequency-modulated sinusoid of 25 ms whose frequency decreases from 1250 Hz to 625 Hz. The Fourier transform uses a rectangular window centered at 12.5 ms, as illustrated in (a). Transform are shown for different window lengths: (b) 5 ms [solid in (a)]; (c) 10 ms [dashed in (a)]; (d) 20 ms [dotted in (a)].**

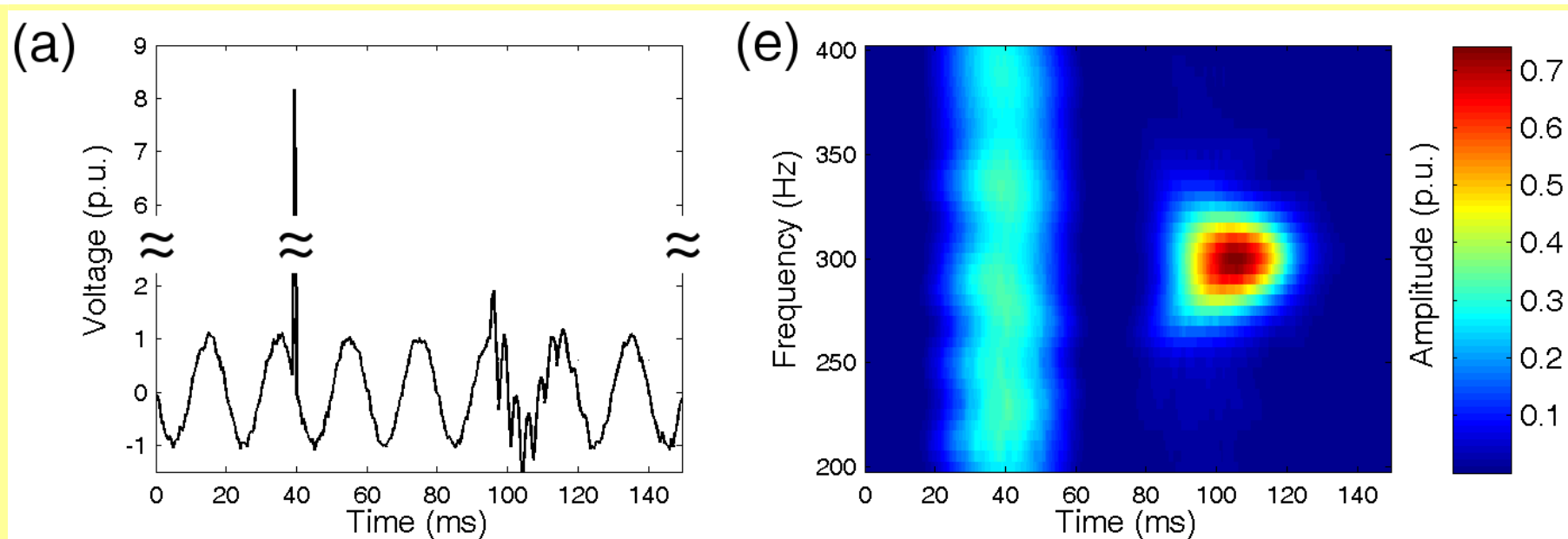




**Fig. 3.15 Comparison of measured spectrograms for the utterance, “which tea party did Baker go to?”: (a) speech waveform; (b) wideband spectrogram; (c) narrowband spectrogram.**

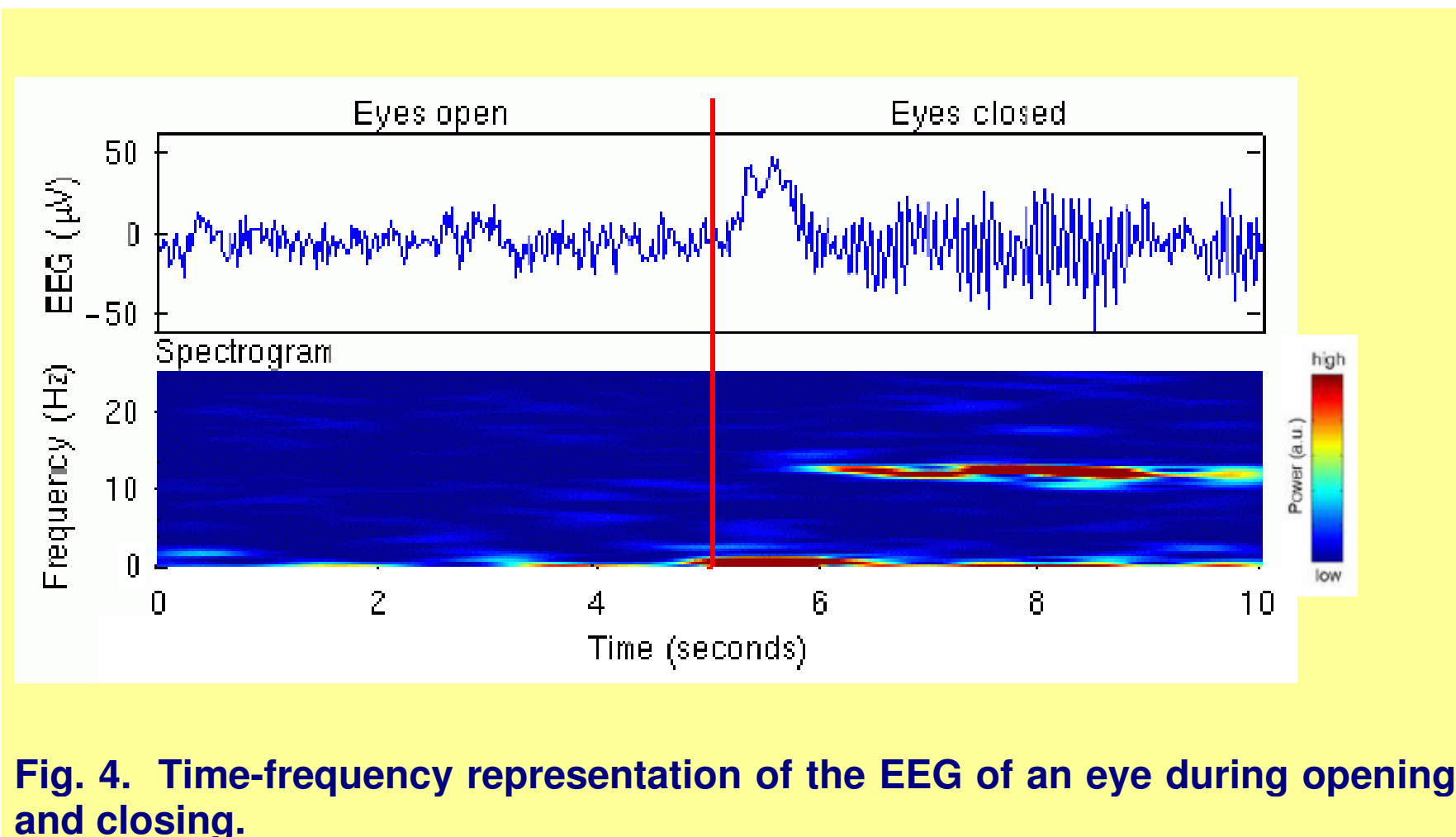
### 3. EXAMPLES

#### Example 1: Power Quality Monitoring



**Fig. 3. Time-frequency representation and separation of impulsive and transient power transients. (a) Simulated 50-Hz power waveforms with an impulsive transient at 40 ms and an oscillatory transient from 95 ms to 125 ms in Time representation; (e) Time-frequency representation of (a) obtained from spectrogram.**

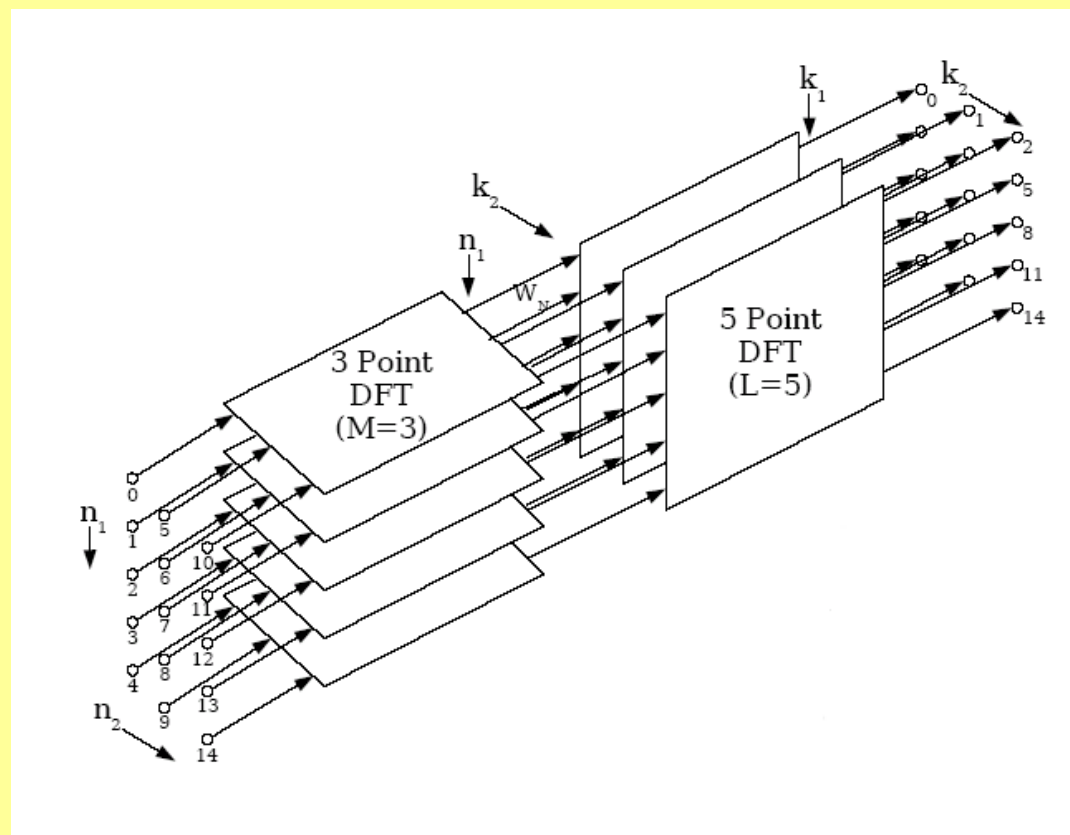
## Example 2: Electroencephalography (EEG) of an eye (event detection in Frequency domain)



**Fig. 4. Time-frequency representation of the EEG of an eye during opening and closing.**

## 4. FAST FOURIER TRANSFORM

- Direct computation of the DFT requires  $N^2$  complex multiplications and  $N^2$  complex additions. Fast algorithms for DFT are called **Fast Fourier Transform** (FFT) with order  $O(N \log_2 N)$  arithmetic complexity.
- In the FFT, a DFT of length  $N = N_1 N_2$  can be decomposed into two or more smaller DFTs with simpler implementation and hence the complexity is reduced. It is based on a technique called **multi-dimensional index mapping**.
- Two classes of **index mapping** are
  - Common factor map (CFM)**, which works for general  $N_1$  and  $N_2$ .
  - Prime Factor Map (PFM)**, which works for relative prime  $N_1$  and  $N_2$ .



**Fig. 5** An example of using **Common Factor Mapping (4.5a and 4.5b)** where the original 15-point DFT is decomposed to a series of row 3-point DFTs followed by twiddle multiplications and a series of column 5-point DFTs.

$N=15$  with  $N_1=3$ ,  $N_2=5$ .

With PFM, the twiddle multiplications can be avoided. The input and output mapping will be given by (4.7a and 4.7b).

## 4.1 Common Factor Map

- The index mapping of **common factor map (CFM)** is given as

$$n = N_2 n_1 + n_2, \quad n_1 = 0, \dots, N_1 - 1; n_2 = 0, \dots, N_2 - 1 \quad (4.1a)$$

$$k = k_1 + N_1 k_2, \quad k_1 = 0, \dots, N_1 - 1; k_2 = 0, \dots, N_2 - 1 \quad (4.1b)$$

This is called decimation in frequency (DIF) form. Substituting into (9.15) gives:

$$\begin{aligned} X[k_1, k_2] &= X[k_1 + N_1 k_2] = \sum_{n=N_2 n_1 + n_2} x[N_2 n_1 + n_2] W_N^{(N_2 n_1 + n_2)(k_1 + N_1 k_2)} \\ &= \sum_{n_2=0}^{N_2-1} \left[ \sum_{n_1=0}^{N_1-1} x[N_2 n_1 + n_2] W_{N_1}^{n_1 k_1} \right] (W_N^{k_1 n_2}) \cdot W_{N_2}^{n_2 k_2}, \text{ where } W_N = e^{-j2\pi/N}. \end{aligned} \quad (4.2)$$

If one treats  $x[N_2 n_1 + n_2]$  as a 2D array  $x[n_1, n_2]$ , then

- the operations in the square bracket is to perform an  $N_1$ -point DFT along  $n_1$  for each  $n_2$  ( $N_2$  in total). After transform, the row index is given by  $k_1$ .
- the term in curve bracket is to multiple each element of the array by  $(W_N^{k_1 n_2})$ .
- the last summation is equivalent to perform an  $N_2$ -point DFT along  $n_2$  for each  $k_1$  (with number  $N_1$  in total). After transform, the row index is given by  $k_2$ .

- In summary, the DFT is done by performing  $N_2$  length- $N_1$  DFTs on the first dimension (row) of the input two dimension array following by the **twiddle multiplications**,  $W_N^{k_1 n_2}$ , and the  $N_1$  length- $N_2$  DFTs along the other dimension (column).
- Notice that the order **cannot be interchange** due to the twiddle factor.
- If  $N_1 = 2$  and  $N_2 = N/2$ ,  $W_{N_1}$  becomes  $W_{N_1} = e^{-j\pi} = -1$ . Then the multiplication with  $W_{N_1}$  can be **simplified to an addition in the 2-point DFT**.
- If  $N = 2^M$ , the process can be repeated M times, leading to the **DIF Radix-2 FFT**.
- The radix  $r$  is related to the small DFT used.
- In the decimation-in-frequency (DIF) FFT, (4.2) reads

$$X[k_1, k_2] = \sum_{n_2=0}^{N/2-1} \left[ \sum_{n_1=0}^1 x[n_1, n_2] (-1)^{n_1 k_1} \right] (W_N^{n_2 k_1}) W_{N/2}^{n_2 k_2} \quad (4.3)$$

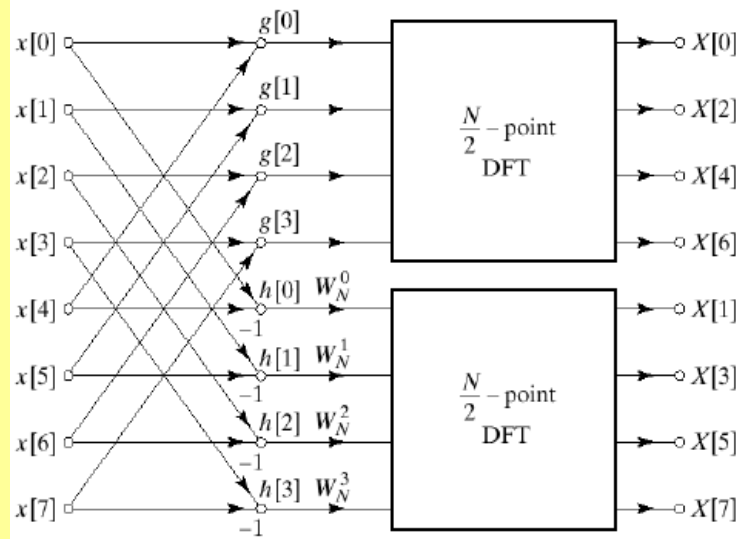
- It is called DIF radix-2 FFT because it can also be obtained by **decimating the frequency indices** separately into the even and odd indexed outputs of the DFT as follows:

$$X[2k] = \sum_{n=0}^{N/2-1} [x[n] + x[n + N/2]] W_{N/2}^{nk} \quad (4.4a)$$

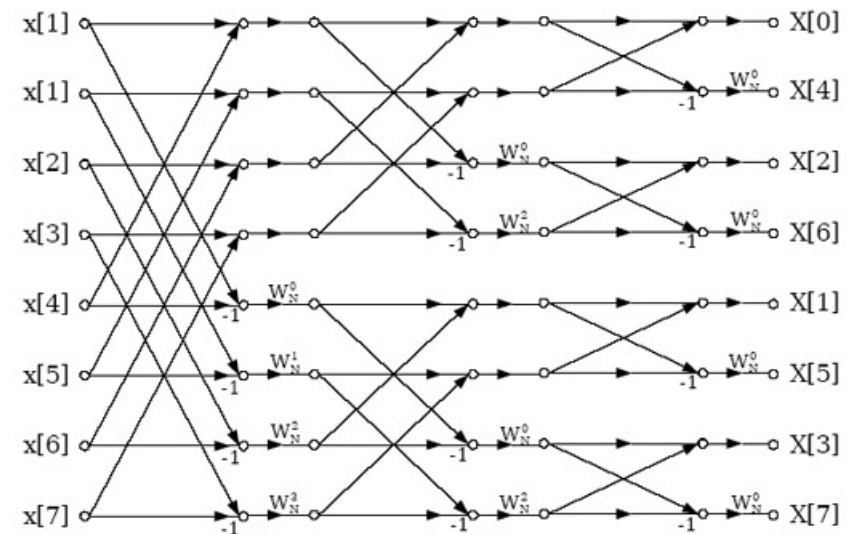
$$X[2k + 1] = \sum_{n=0}^{N/2-1} [x[n] - x[n + N/2]] (W_N^n) W_{N/2}^{nk} \quad (4.4b)$$

- The length- $N$  DFT is computed from two length- $N/2$  DFTs. The decomposition can repeatedly be applied to the smaller DFTs until eventually only trivial two-point DFTs remain.





**Fig. 7a. Decimation in frequency of a length  $N$  DFT into two length  $N/2$  DFTs preceded by a preprocessing stage.**



**Fig. 7b. A length-8 Radix-2 DIF FFT Diagram.**

■ Another equivalent form called **decimation-in-time (DIT)** form can be obtained by interchanging the role of (4.1a) and (4.1b).

$$n = n_1 + N_1 n_2, \quad n_1 = 0, \dots, N_1 - 1; n_2 = 0, \dots, N_2 - 1 \quad (4.5a)$$

$$k = N_2 k_1 + k_2, \quad k_1 = 0, \dots, N_1 - 1; k_2 = 0, \dots, N_2 - 1 \quad (4.5b)$$

$$\begin{aligned}
 X[k_1, k_2] &= X[N_2 k_1 + k_2] = \sum_{n=n_1+N_1 n_2} x[n_1 + N_1 n_2] W_N^{(n_1+N_1 n_2)(N_2 k_1+k_2)} \\
 &= \sum_{n_1=0}^{N_1-1} \left[ \sum_{n_2=0}^{N_2-1} x[n_1 + N_1 n_2] W_{N_2}^{n_2 k_2} \right] (W_N^{n_1 k_2}) \cdot W_{N_1}^{n_1 k_1}, \text{ where } W_N = e^{-j2\pi/N}.
 \end{aligned}
 \tag{4.5c}$$

- The DFT is done by performing  $N_1$  length- $N_2$  DFTs on the second dimension (column) of the input two dimension array following by the **twiddle multiplications**,  $W_N^{n_1 k_2}$ , and the  $N_2$  length- $N_1$  DFTs along the other dimension (row).
- This can be viewed as the DIF algorithm with the row and column of the array interchanged. So they are actually equivalent.
- This can also be derived by decimating the time indices as follows:

$$X[k] = \sum_{n=0}^{N/2-1} x[2n] W_{N/2}^{nk} + W_N^k \sum_{n=0}^{N/2-1} x[2n+1] W_{N/2}^{nk}
 \tag{4.5d}$$

$$X[k + N/2] = \sum_{n=0}^{N/2-1} x[2n]W_{N/2}^{nk} - W_N^k \sum_{n=0}^{N/2-1} x[2n+1]W_{N/2}^{nk} \quad (4.5e)$$

■ For  $N = 2^m$ , the dividing process is repeated  $m = \log_2 N$  times and requires  $N/2$  multiplications each time. This gives an arithmetic complexity of only  $(N/2)\log_2 N$  as compared with  $N^2$  for direct calculation.

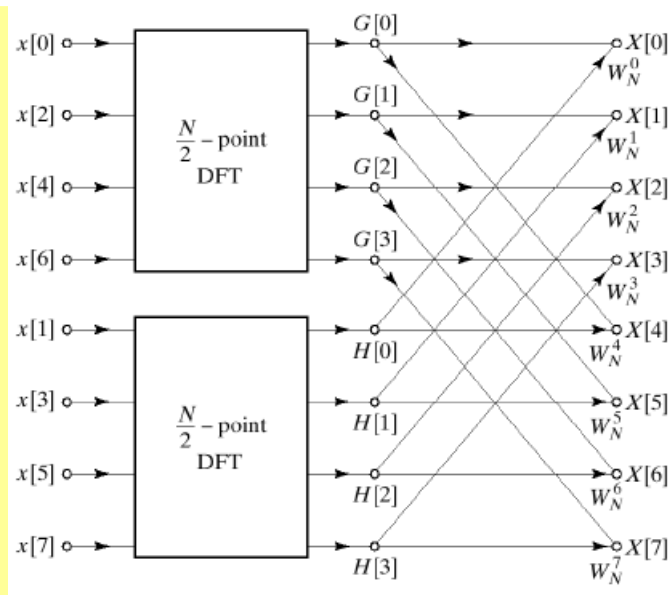


Fig. 8a. Decimation in time of a length  $N$  DFT into two length  $N/2$  DFTs followed by a combining stage.

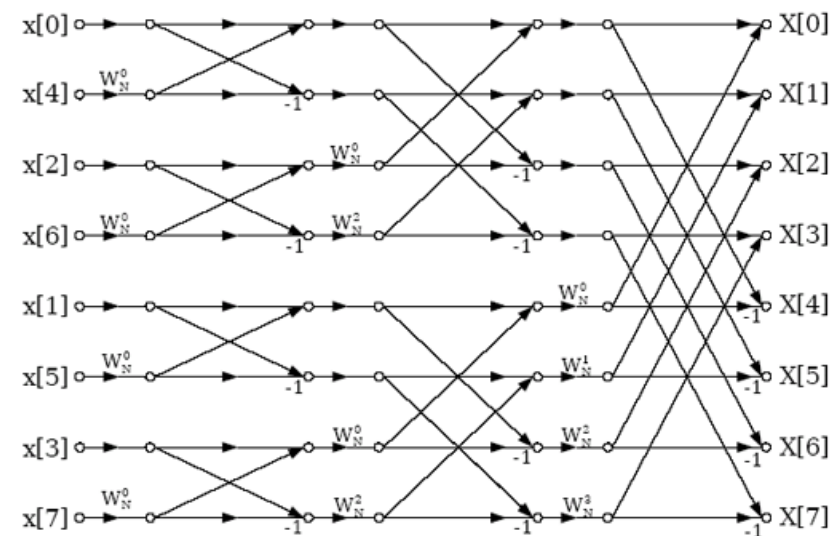


Fig. 8b. A length 8 Radix-2 DIT FFT Diagram.

- It can be seen that Fig. 8b. is a transpose of Fig. 7b.
- Other commonly used Radix-r FFT are Radix-4 ( $N_2 = N / 4$ ) and Radix 8 ( $N_2 = N / 8$ ) FFT. Combination of them is possible.
- Increasing the Radix-r will reduce the number of stages and hence the twiddle factor multiplications, but the complexity for the length-r DFT will also increase. For small r, such as 2, 4, 8 and 16, the short DFTs usually can be implemented efficiently.
- Radix-2 has a simple structure while Radix-4 and Radix-8 are more efficient.

## 4.2 Prime Factor Map

- An advantage of the Prime Factor Algorithm (PFA) is the **elimination of the twiddle factors**.
- If  $N$  is a product of  $m$  **relatively prime factors**,

$$N = N_1 N_2 \dots N_m, \quad (4.6)$$

then the general form of the Prime Factor Map (PFM) is

$$n = \langle r_1 M_1 n_1 + \dots + r_m M_m n_m \rangle_N \quad (4.7a)$$

$$k = \langle \tilde{r}_1 M_1 k_1 + \dots + \tilde{r}_m M_m k_m \rangle_N \quad (4.7b)$$

where  $\langle r \rangle_N = r \bmod N$ ,  $M_i = N / N_i$ ,  $\langle \tilde{r}_i r_i M_i \rangle_N = 1$ ;  $i = 1, \dots, m$ .

- The DFT becomes:

$$X[k_1, \dots, k_m] = \sum_{n_1=0}^{N_1-1} \dots \sum_{n_m=0}^{N_m-1} x[n_1, \dots, n_m] W_{N_1}^{n_1 k_1} \dots W_{N_m}^{n_m k_m} \quad (4.8)$$

$$0 \leq n_i \leq N_i - 1; \quad 0 \leq k_i \leq N_i - 1; \quad i = 1, \dots, m.$$

where  $x[n_1, \dots, n_m] = x[\langle r_1 M_1 n_1 + \dots + r_m M_m n_m \rangle_N]$ , and

$$X[k_1, \dots, k_m] = X[\langle \tilde{r}_1 M_1 k_1 + \dots + \tilde{r}_m M_m k_m \rangle_N].$$

- The 1-D array is now mapped to a  $m$ -dimensional array. (4.8) is a  **$m$ -dimensional DFT** which corresponding to performing  $N_i$ -point DFT along the  $i$ -th dimension ( $N/N_i$  in total). Since the twiddle factor is missing, the order is immaterial and the arithmetic complexity can be greatly reduced.
- An example is given in figure 5 for  $N = 15 = 3 \times 5$ . In a Prime Factor Algorithm (PFA), it is common to use:

$$r_i = 1, i = 1, \dots, m. \quad (\text{Ruritanian map}) \quad (4.9a)$$

$$\tilde{r}_i = M_i^{-1} \bmod N_i, i = 1, \dots, m \quad (\text{Chinese Remainder Map}) \quad (4.9b)$$

## 4.3 Summary

- Two classes of **index mapping** are the **common factor map (CFM)** and the **Prime Factor Map (PFM)**.
- Radix-2, Radix-4, and Radix-8 are some commonly used FFT algorithms **relying on the CFM**. DIT and DIF are two different configurations of the Radix- $r$  FFT.
- **Increasing the Radix- $r$  will reduce** the number of stages and hence the **twiddle factor multiplications**, but the **complexity** for the **length- $r$  DFT** will also **increase**. For small  $r$ , such as 2, 4, 8 and 16, the short DFTs usually can be implemented efficiently.
- An advantage of the Prime Factor Algorithm (PFA) is the **elimination of the twiddle factors**. The structure however is slightly complicated with somewhat restricted lengths, though all both CFM and PFM can be combined to cover composite lengths.