

$$\{X_1, X_2, X_3\}$$

$$E[X_1] = E[X_2] = E[X_3] = 0$$

$$\text{Cov}(X_1, X_2) = 0 \Rightarrow E[X_1 X_2] = 0$$

$$\text{Hence, } E[X_1 X_3] = 0 = E[X_2 X_3]$$

$$\begin{aligned} \sigma_{X_1}^2 &= 1 = \sigma_{X_2}^2 = \sigma_{X_3}^2 = E[X_1^2] \\ &= E[X_2^2] = E[X_3^2] = \sigma^2 \end{aligned}$$

$$Y_1 = A_{11} X_1 + A_{12} X_2 + A_{13} X_3$$

$$Y_2 = A_{21} X_1 + A_{22} X_2 + A_{23} X_3$$

$$Y_3 = A_{31} X_1 + A_{32} X_2 + A_{33} X_3$$

$$\text{or, } \begin{pmatrix} Y_1 \\ Y_2 \\ Y_3 \end{pmatrix} = \begin{pmatrix} & & \\ & \ddots & A_{ij} \\ & & \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix}$$

$$E[Y_i] = \sum_{j=1}^3 A_{ij} E[X_j] = 0$$

$$C_{Y_1 Y_2} = E[Y_1 Y_2] = A_{11} A_{21} + A_{12} A_{22} \\ + A_{13} A_{23}$$

$$\sigma_{Y_1} = \sqrt{E[Y_1^2]} = \sqrt{A_{11}^2 + A_{12}^2 + A_{13}^2}$$

$$\therefore \varphi_{12} = \frac{C_{Y_1 Y_2}}{\sigma_{Y_1} \sigma_{Y_2}} = \frac{A_{11} A_{21} + A_{12} A_{22} + A_{13} A_{23}}{\sqrt{A_{11}^2 + A_{12}^2 + A_{13}^2} \sqrt{A_{21}^2 + A_{22}^2 + A_{23}^2}}$$

$$\vec{V}_1 = (A_{11}, A_{12}, A_{13}) = \frac{\vec{V}_1 \cdot \vec{V}_2}{|\vec{V}_1| |\vec{V}_2|}$$

$$\vec{V}_2 = (A_{21}, A_{22}, A_{23})$$

$$\text{Choose } \vec{V}_1 = (\sin \theta_1, \cos \theta_1, 0)$$

$$\text{ & } \vec{V}_2 = (0, \sin \theta_2, \cos \theta_2)$$

$$\text{Then, } \varphi_{12} = \sin \theta_2 \cos \theta_1 \equiv \varphi_1$$

$$\& \begin{aligned} y_1 &= x_1 \sin \theta_1 + x_2 \cos \theta_2 \\ y_2 &= x_2 \sin \theta_2 + x_3 \cos \theta_2 \end{aligned}$$

But  $y_3 = ?$

$$f_{23} = \frac{C_{y_2 y_3}}{\sigma_{y_2} \sigma_{y_3}} = \frac{\vec{V}_2 \cdot \vec{V}_3}{|\vec{V}_2| |\vec{V}_3|}$$

$$\text{where } \vec{V}_2 = (A_{21}, A_{22}, A_{23})$$

$$\& \vec{V}_3 = (A_{31}, A_{32}, A_{33})$$

But we already have,

$$\vec{V}_2 = (0, \sin \theta_2, \cos \theta_2)$$

$$\therefore \text{let } \vec{V}_3 = (\sin \theta_3, 0, \cos \theta_3)$$

$$\text{then, } f_{23} = \cos \theta_2 \cos \theta_3 \equiv f_2$$

$$f_{13} = \frac{\vec{v}_1 \cdot \vec{v}_3}{|\vec{v}_1| |\vec{v}_3|} = \sin\theta_1 \sin\theta_3 \equiv f_3$$

$$\underline{A} = \begin{pmatrix} \sin\theta_1 & \cos\theta_1 & 0 \\ 0 & \sin\theta_2 & \cos\theta_2 \\ \sin\theta_3 & 0 & \cos\theta_3 \end{pmatrix}$$