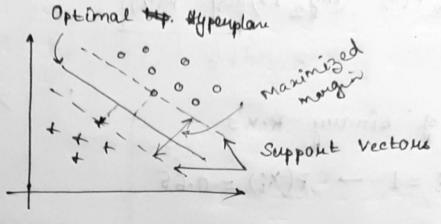
Supposet Vectore Machines

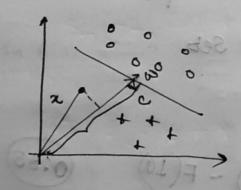
A supervised learning machine to where we by to find a hyper-plane that best seperates the two classes



Margin: Distance between the hyper-plane and observation closest to hyperplane the supposed vectors

→ The best hyper-plane is the plane that has maximum distance from both classes

Mathematical Intuition



- · Assume vector (x) and a vector (w) perpendicular to hyperplane
- · Distance of vector (w) from origin is (c)

X. vo > c (+ ve class)

Decision Rule to dassify

$$y = \begin{cases} +1, \ \vec{X}.\vec{k} + 6 \ge 0 \\ -1, \ \vec{X}.\vec{k} + 6 < 0 \end{cases}$$

= = > > > >

Aim of SVM

Maximize the margin / maximize diotana (d)

Constraint for Marinizing Margin

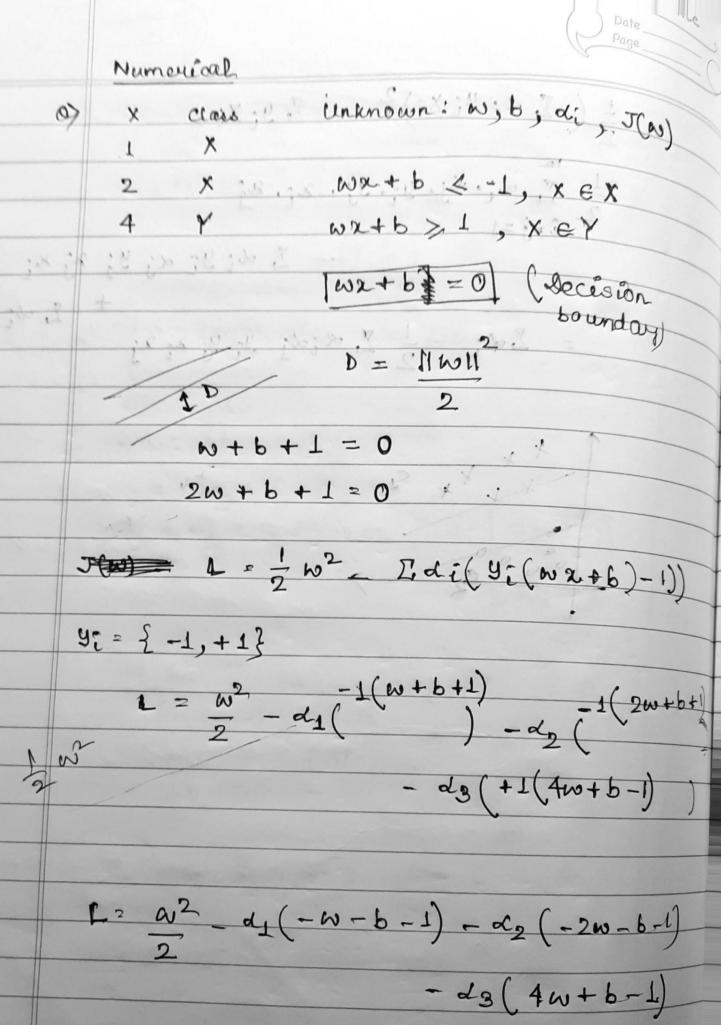
$$\omega_1 z_1 + \omega_2 z_2 + b = 0$$

$$z_2 = -\frac{b}{\omega_2} - \frac{\omega_1}{\omega_2} z_1$$

L1:
$$\vec{w} \cdot \vec{z} + b = 1$$
 } Considering - ve slope,
L26 $\vec{w} \cdot \vec{z} + b = -1$ $w_1, w_2 \rightarrow +ve$

$$\overrightarrow{W}.\overrightarrow{X}+b \leq -1$$
, when $y_{\tilde{i}}=-1$ $\overrightarrow{W}.\overrightarrow{X}+b \geq 1$, when $y_{\tilde{i}}=+1$

augmax (
$$w^*$$
, b^*), $\frac{2}{\|w\|}$ such that $y_i(\vec{w} \cdot \vec{x} + b) \ge 1$



$$\frac{SL}{S\omega} = 0$$
, $\frac{SL}{S\omega} = 0$

$$\frac{3L}{5d_1} = +\omega + b + 1, \quad \frac{3L}{5d_2} = 2\omega + b + 1$$

$$\frac{\delta L}{\delta d3} = -4w - b + 1, \quad \frac{\delta L}{\delta b} = d_1 + d_2 - d_3$$

$$\frac{31}{50} = 0$$

$$w+b+1=0$$
 3 $w=0$, $b=1$

d+ ow+ we 11+

$$w=1, b=-3$$

$$d_1 = 0$$
, $d_2 = d_3$, $w = 2d_3$

$$w=1$$
, $b=-3$, $d_3=\frac{1}{2}=d_2$, $d_1=0$

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Two-Feature Problem of SVM

$$w_1x_1 + w_2x_2 + b = 0$$
 $w_1x_1 + w_2x_2 + b < -1$

$$-1(N_1 + 3N_2 + b + 1) d_1$$

$$-1(2N_1 + 4N_2 + b + 1) d_2$$

$$+1(3N_1 + N_2 + b - 1) d_3$$

$$\frac{3L}{5W} = W - d_1(1,3)^{T} \qquad 5L \qquad -(W_1 + 3W_2 + b + 1) \\
\frac{5L}{5W} = d_2(2,4)^{T} \qquad 5d_1 \\
+ d_3(3,1) \qquad 5L \qquad = \frac{5L}{5b} = (-d_1 - d_2 + d_3) \qquad 5L \qquad = \frac{5L}{5b}$$

$$SL = W - \alpha_1(1,3)^T - \alpha_2(2,4)^T$$

 $SW + \alpha_3(3,1)^T$

$$\frac{34}{3w_1 + w_2 + b - 1} = 0$$

$$\frac{SL}{Sb} = -d_1 - d_2 + d_3 = 0$$

$$\frac{SL}{Sd_1} = w_1 + 3w_2 + b + 1 = 0$$

$$\frac{3L}{3d_2} = 2w_1 + 4w_2 + b + 1 = 0$$

$$\frac{3L}{3d_2} = 2w_1 + 4w_2 + b + 1 = 0$$

$$2w_1 + 4w_2 + b + 1 = 0$$

$$3w_1 + w_2 + b - 1 = 0$$

$$\frac{d_2-d_3}{d_2-d_2+3d_3-\omega_1}$$

$$W = \frac{1}{2}$$
, $W_2 = -1$, $b = 0$