Discrete Mathematical Models

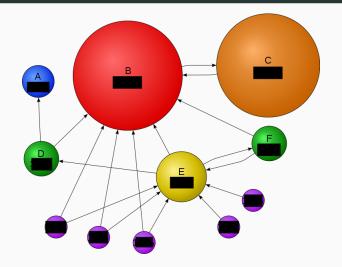
Lecture 30

Kane Townsend

Semester 2, 2024

Wikipedia Example

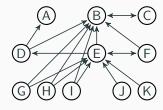
Wiki WebGraph



https://en.wikipedia.org/wiki/PageRank We will fill in \mathcal{R} . It will differ slightly to seen on wiki due to a small difference in our algorithm which is common to do for large n).

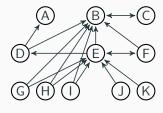
ı

Example 5



At left is the Wikipedia example we mentioned in the previous lecture consisting of miniweb of 11 pages and 17 hyperlinks. Colours, variable sizes and PageRanks have been removed and the bottom five vertices have been labelled G to K, following the given labelling of the top six vertices. The layout is similar to that in the original.

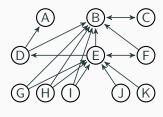
Example 5



Using the steady state method we have been discussing, we will derive the PageRanks given on the Wikipedia diagram.

At left is the Wikipedia example we mentioned in the previous lecture consisting of miniweb of 11 pages and 17 hyperlinks. Colours, variable sizes and PageRanks have been removed and the bottom five vertices have been labelled G to K, following the given labelling of the top six vertices. The layout is similar to that in the original.

Example 5



Using the steady state method we have been discussing, we will derive the PageRanks given on the Wikipedia diagram.

Step 1: Construct G^+ from G

At left is the Wikipedia example we mentioned in the previous lecture consisting of miniweb of 11 pages and 17 hyperlinks. Colours, variable sizes and PageRanks have been removed and the bottom five vertices have been labelled G to K, following the given labelling of the top six vertices. The layout is similar to that in the original.

Step 2: Compile the basic transition matrix T.

Step 2: Compile the basic transition matrix T.

Let n_i be the number vertices to which i is adjacent in G^+ , that is $n_i = |\{j : (i, j) \in E(G^+)\}|$

The p_{ij} of a transition from vertex j to i is given by

$$p_{ij} = \begin{cases} 1/n_i & \text{if } n_i \neq 0 \text{ and } (j,i) \in E(G^+) \\ 0 & \text{otherwise} \end{cases}$$

Step 2: Compile the basic transition matrix T.

Let n_i be the number vertices to which i is adjacent in G^+ , that is $n_i = |\{j : (i, j) \in E(G^+)\}|$

The p_{ij} of a transition from vertex j to i is given by

$$p_{ij} = \begin{cases} 1/n_i & \text{if } n_i \neq 0 \text{ and } (j,i) \in E(G^+) \\ 0 & \text{otherwise} \end{cases}$$

Step 2: Compile the basic transition matrix T.

Let n_i be the number vertices to which i is adjacent in G^+ , that is $n_i = |\{i : (i, i) \in E(G^+)\}|$

The $p_{i,i}$ of a transition from vertex j to i is given by

$$p_{ij} = \begin{cases} 1/n_i & \text{if } n_i \neq 0 \text{ and } (j,i) \in E(G^+) \\ 0 & \text{otherwise} \end{cases}$$

For our Wikipedia example we get

3

Step 3: Compile the matrix $M = (\alpha/n)U + (1-\alpha)T$

Step 3: Compile the matrix $M = (\alpha/n)U + (1-\alpha)T$ That is multiply each entry of T by $(1-\alpha)$ and add α/n to each entry. Recall that Google uses an 85% damping factor, so we set $(1-\alpha) = 0.85$.

Step 3: Compile the matrix $M = (\alpha/n)U + (1-\alpha)T$ That is multiply each entry of T by $(1-\alpha)$ and add α/n to each entry. Recall that Google uses an 85% damping factor, so we set $(1-\alpha) = 0.85$.

$$\begin{aligned} M &= \left(\frac{\alpha}{n} \right) U + \left(1 - \alpha \right) T = \\ &\begin{bmatrix} 3/220 & 3/220 & 193/440 & 3/220 & 3/220 & 3/220 & 3/220 & 3/220 & 3/220 \\ 217/2200 & 3/220 & 199/22 & 193/440 & 49/165 & 193/440 & 193/440 & 193/440 & 193/440 & 193/440 & 3/220 & 3/220 \\ 217/2200 & 19/22 & 3/220 &$$

Step 4: Use a computer to solve MPR = PR using our 'Shortcut method'. For example 'Gauss-Jordan Elimination' in the *Matrix Reshish* online matrix calculator, gives

Step 4: Use a computer to solve MPR = PR using our 'Shortcut method'. For example 'Gauss-Jordan Elimination' in the *Matrix Reshish* online matrix calculator, gives

	5135730/169545563		0.0303	
	3195978661779342/8292828011094295		0.3854	
	165932254119056/482651365725065		0.3438	
	6644106/169545563		0.0392	
	5317726843699199/65574887090606070		0.0811	
PR =	6644106/169545563	\approx	0.0392	(4d.p.)
	2748522/169545563		0.0162	
	2748522/169545563		0.0162	
	2748522/169545563		0.0162	
	2748522/169545563		0.0162	
	2748522/169545563		0.0162	

Iteration method

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)R = 0 becomes computationally infeasible.

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)PR = 0 becomes computationally infeasible.

A computationally simpler method starts from the defining equation attempts to find R by iteratively calculating the chain of probability vectors P_0, P_1, \ldots where P_0 is arbitrary and $P_k = MP_{k-1}$ for $k \geq 1$ (so $P_k = M^k P_0$).

A steady state is reached when $P_k \approx P_{k-1}$. Then declare that $PR \approx P_k$.

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)PR = 0 becomes computationally infeasible.

A computationally simpler method starts from the defining equation attempts to find R by iteratively calculating the chain of probability vectors P_0, P_1, \ldots where P_0 is arbitrary and $P_k = MP_{k-1}$ for $k \ge 1$ (so $P_k = M^k P_0$).

A steady state is reached when $P_k \approx P_{k-1}$. Then declare that $PR \approx P_k$.

Now
$$P_k = MP_{k-1} = [(\alpha/n)U + (1-\alpha)T]P_{k-1}$$

= $(\alpha/n)\mathbf{1} + (1-\alpha)TP_{k-1}$

where 1 is column of 1's.

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)PR = 0 becomes computationally infeasible.

A computationally simpler method starts from the defining equation attempts to find R by iteratively calculating the chain of probability vectors P_0, P_1, \ldots where P_0 is arbitrary and $P_k = MP_{k-1}$ for $k \ge 1$ (so $P_k = M^k P_0$).

A steady state is reached when $P_k \approx P_{k-1}$. Then declare that $PR \approx P_k$.

Now
$$P_k = MP_{k-1} = [(\alpha/n)U + (1-\alpha)T]P_{k-1}$$

= $(\alpha/n)\mathbf{1} + (1-\alpha)TP_{k-1}$

where 1 is column of 1's. It is natural to start with all ranks equal.

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)PR = 0 becomes computationally infeasible.

A computationally simpler method starts from the defining equation attempts to find R by iteratively calculating the chain of probability vectors P_0, P_1, \ldots where P_0 is arbitrary and $P_k = MP_{k-1}$ for $k \ge 1$ (so $P_k = M^k P_0$).

A steady state is reached when $P_k \approx P_{k-1}$. Then declare that $PR \approx P_k$.

Now
$$P_k = MP_{k-1} = [(\alpha/n)U + (1-\alpha)T]P_{k-1}$$

= $(\alpha/n)\mathbf{1} + (1-\alpha)TP_{k-1}$

where 1 is column of 1's. It is natural to start with all ranks equal. So the iterative scheme is

$$P_0 = (1/n)1; \quad P_k = \alpha P_0 + (1-\alpha)TP_{k-1}, \ k \ge 1.$$

When n is huge, as it is with the WWW, solving the the $n \times n$ linear system (M-I)PR = 0 becomes computationally infeasible.

A computationally simpler method starts from the defining equation attempts to find R by iteratively calculating the chain of probability vectors P_0, P_1, \ldots where P_0 is arbitrary and $P_k = MP_{k-1}$ for $k \ge 1$ (so $P_k = M^k P_0$).

A steady state is reached when $P_k \approx P_{k-1}$. Then declare that $PR \approx P_k$.

Now
$$P_k = MP_{k-1} = [(\alpha/n)U + (1-\alpha)T]P_{k-1}$$

= $(\alpha/n)\mathbf{1} + (1-\alpha)TP_{k-1}$

where 1 is column of 1's. It is natural to start with all ranks equal. So the iterative scheme is

$$P_0 = (1/n)1;$$
 $P_k = \alpha P_0 + (1-\alpha)TP_{k-1}, \ k \ge 1.$

Each iteration takes a weighted average of teleporting and hyperlinking.

In Example 4B we used the equation-solving method to find R.

For
$$T = \begin{bmatrix} 0 & 0 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 \end{bmatrix}$$
 and $\alpha = 0.1$ we found $R = \begin{bmatrix} .10 \\ .30 \\ .37 \\ .23 \end{bmatrix}$ to 2d.p.

7

In Example 4B we used the equation-solving method to find R.

For
$$T = \begin{bmatrix} 0 & 0 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 \end{bmatrix}$$
 and $\alpha = 0.1$ we found $R = \begin{bmatrix} .10 \\ .30 \\ .37 \\ .23 \end{bmatrix}$ to 2d.p.

Let's try the same problem using iterative approximation:

$$P_{0} = \begin{bmatrix} .25 \\ .25 \\ .25 \\ .25 \end{bmatrix} \qquad P_{k} = \begin{bmatrix} .025 \\ .025 \\ .025 \\ .025 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & .3 \\ .45 & 0 & .45 & .3 \\ 0 & .9 & 0 & .3 \\ .45 & 0 & .45 & 0 \end{bmatrix} P_{k-1}$$

7

In Example 4B we used the equation-solving method to find R.

For
$$T = \begin{bmatrix} 0 & 0 & 0 & 1/3 \\ 1/2 & 0 & 1/2 & 1/3 \\ 0 & 1 & 0 & 1/3 \\ 1/2 & 0 & 1/2 & 0 \end{bmatrix}$$
 and $\alpha = 0.1$ we found $R = \begin{bmatrix} .10 \\ .30 \\ .37 \\ .23 \end{bmatrix}$ to 2d.p.

Let's try the same problem using iterative approximation:

$$P_{0} = \begin{bmatrix} .25 \\ .25 \\ .25 \\ .25 \end{bmatrix} \qquad P_{k} = \begin{bmatrix} .025 \\ .025 \\ .025 \\ .025 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & .3 \\ .45 & 0 & .45 & .3 \\ 0 & .9 & 0 & .3 \\ .45 & 0 & .45 & 0 \end{bmatrix} P_{k-1}$$

Results of the first ten iterations, rounded to 2d.p. Calcs used 15d.p.

k	1	2	3	4	5	6	7	8	9	10
	[.10]	[.10]	[.09] .31 .35 .25]	[.10] .30 .38 .22]	[.09] .31 .36 .24]	[.10]	[.09] .31 .36 .24]	[.10]	[.09]	.30
D.	.33	.29	.31	.30	.31	[.10] .30]	.31	.30	.30	
l' k	.33	.39	.35	.38	.36	.37	.36	.37	.37	.37 .23
	25_	.22	.25	[.22]	.24	.23	.24	[.23]	.24	[.23]

In Example 4B we used the equation-solving method to find R.

For
$$T = \begin{bmatrix} 0 & 0 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 \end{bmatrix}$$
 and $\alpha = 0.1$ we found $R = \begin{bmatrix} .10 \\ .30 \\ .37 \\ .23 \end{bmatrix}$ to 2d.p.

Let's try the same problem using iterative approximation:

$$P_{0} = \begin{bmatrix} .25 \\ .25 \\ .25 \\ .25 \\ .25 \end{bmatrix} \qquad P_{k} = \begin{bmatrix} .025 \\ .025 \\ .025 \\ .025 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & .3 \\ .45 & 0 & .45 & .3 \\ 0 & .9 & 0 & .3 \\ .45 & 0 & .45 & 0 \end{bmatrix} P_{k-1}$$

Results of the first ten iterations, rounded to 2d.p. Calcs used 15d.p.

k	1	2	3	4	5	6	7	8	9	10
	[.10]	[.10]	[.09]	[.10]	[.09] .31 .36 .24]	[.10]	[.09] .31 .36 .24]	[.10]	[.09]	[.10]
D.	.33	.29	.31	.30 .38 .22	.31	.30 .37	.31	.30	.30	.30
I k	.33	.39	.35	.38	.36	.37	.36	.37	.37	.37
	[.25]	[.22]	.25	.22	.24	[.23]	.24	.23	.24	[.23]

Pretty good after just 2 iterations! Within 1%-point after 4 iterations.

In Example 4B we used the equation-solving method to find R.

For
$$T = \begin{bmatrix} 0 & 0 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 0 & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 \end{bmatrix}$$
 and $\alpha = 0.1$ we found $R = \begin{bmatrix} .10 \\ .30 \\ .37 \\ .23 \end{bmatrix}$ to 2d.p.

Let's try the same problem using iterative approximation:

$$P_{0} = \begin{bmatrix} .25 \\ .25 \\ .25 \\ .25 \end{bmatrix} \qquad P_{k} = \begin{bmatrix} .025 \\ .025 \\ .025 \\ .025 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & .3 \\ .45 & 0 & .45 & .3 \\ 0 & .9 & 0 & .3 \\ .45 & 0 & .45 & 0 \end{bmatrix} P_{k-1}$$

Results of the first ten iterations, rounded to 2d.p. Calcs used 15d.p.

k	1	2	3	4	5	6	7	8	9	10
	[.10]	[.10]	[.09]	[.10]	[.09]	[.10]	[.09]	[.10]	[.09]	[.10]
D.	.33	.29	.31	.30	.31	.30	.31	.30	.30	.30
F k	.33	.39	.35	.38	.36	.37	.36	.37	.37	.37
	[.25]	.22	.25	.22	.24	23_	.24	.23	24_	[.23]

Pretty good after just 2 iterations! Within 1%-point after 4 iterations. **END OF SECTION D3**

End of Course Notes:')

My research in graph theory

Let G be a simple graph with some upper bound on vertex degree. That means no loops, parallel edges and not infinitely many edges at one vertex!

Let G be a simple graph with some upper bound on vertex degree. That means no loops, parallel edges and not infinitely many edges at one vertex!

We assign weights of 1 to each edge in G.

Let G be a simple graph with some upper bound on vertex degree. That means no loops, parallel edges and not infinitely many edges at one vertex!

We assign weights of 1 to each edge in G.

A shortest path from u to v is called a **geodesic** in G.

Let G be a simple graph with some upper bound on vertex degree. That means no loops, parallel edges and not infinitely many edges at one vertex!

We assign weights of 1 to each edge in G.

A shortest path from u to v is called a **geodesic** in G.

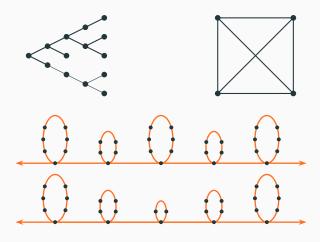
A graph G is called **geodetic** if for all vertices $u, v \in V(G)$, there exists a unique geodesic from u to v

Geodetic graphs

Examples: Trees, complete graphs, odd cycle graphs etc.

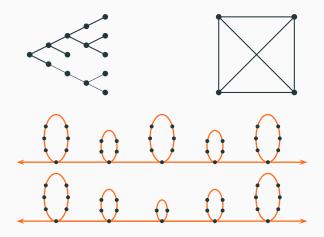
Geodetic graphs

Examples: Trees, complete graphs, odd cycle graphs etc.



Geodetic graphs

Examples: Trees, complete graphs, odd cycle graphs etc.



Question: Characterise all geodetic graphs (Ore in The Theory of Graphs (1962)).

More geodetic talk

The classic example of a non-geodetic graph is an even cycle graph.

More geodetic talk

The classic example of a non-geodetic graph is an even cycle graph.



More geodetic talk

The classic example of a non-geodetic graph is an even cycle graph.



Given a graph there are minimal spanning trees of G consisting of geodesics from v to every other vertex in G. However, in a geodetic graph G, such a minimal spanning tree is unique $v \in V(G)$.

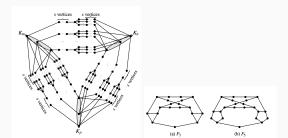
Combining geodetic graphs with bridges and cut vertices

Given two geodetic graphs G_1 and G_2 we can join them at a single vertex or via a single edge and produce a new geodetic graph. Also, if a graph G is geodetic then one can subdivide the edges and obtain a new geodetic graph.

Combining geodetic graphs with bridges and cut vertices

Given two geodetic graphs G_1 and G_2 we can join them at a single vertex or via a single edge and produce a new geodetic graph. Also, if a graph G is geodetic then one can subdivide the edges and obtain a new geodetic graph.

Recently my previous supervisor's colleagues (Weißand his PhD student Stober) used the NAUTY program to generate geodetic graphs (with no cut vertices) of up to 25 vertices (https://arxiv.org/pdf/2308.08970). There are 12969219563 geodetic graphs with 19 vertices, only 19 of them have no cut vertices. Of those 19, only 2 are not subdivisions of a smaller geodetic graph, one is K_{19} and other is F_3 .

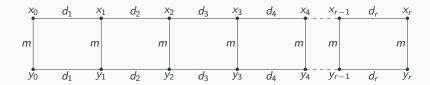


Geodesics in a geodetic graph cannot stay close forever

Suppose we have two long geodesics in a geodetic graph G travelling next to each other (never touching) such that they are at most M>0 away from each other. Then by the generalised pigeonhole principle there are many times they are some they are distance $0< m \leq M$ arbitrarily many times.

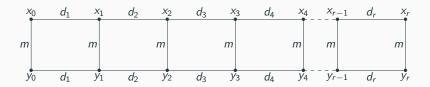
Geodesics in a geodetic graph cannot stay close forever

Suppose we have two long geodesics in a geodetic graph G travelling next to each other (never touching) such that they are at most M>0 away from each other. Then by the generalised pigeonhole principle there are many times they are some they are distance $0< m \leq M$ arbitrarily many times.



Geodesics in a geodetic graph cannot stay close forever

Suppose we have two long geodesics in a geodetic graph G travelling next to each other (never touching) such that they are at most M>0 away from each other. Then by the generalised pigeonhole principle there are many times they are some they are distance $0< m \leq M$ arbitrarily many times.



We get a contradiction!

Let Aut(G) be the collection of all graph isomorphisms $G \to G$.

Let Aut(G) be the collection of all graph isomorphisms $G \to G$.

A graph is called **vertex transitive** if for every $u, v \in V(G)$ there exists $f \in Aut(G)$ such that f(u) = v.

Let Aut(G) be the collection of all graph isomorphisms $G \to G$.

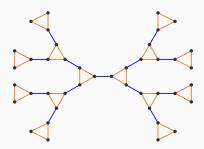
A graph is called **vertex transitive** if for every $u, v \in V(G)$ there exists $f \in Aut(G)$ such that f(u) = v.

Examples: Cycle graphs, complete graphs and more interesting infinite examples like this one below:

Let Aut(G) be the collection of all graph isomorphisms $G \to G$.

A graph is called **vertex transitive** if for every $u, v \in V(G)$ there exists $f \in Aut(G)$ such that f(u) = v.

Examples: Cycle graphs, complete graphs and more interesting infinite examples like this one below:



Recall that a simple circuit is a circuit with no repeated vertices.

Recall that a **simple circuit** is a circuit with no repeated vertices.

We call a simple circuit in a graph G isometric if the geodesic between any two vertices in the simple circuit lie on the circuit.

Recall that a **simple circuit** is a circuit with no repeated vertices.

We call a simple circuit in a graph G isometric if the geodesic between any two vertices in the simple circuit lie on the circuit.

Theorem (Elder-Gardam-Spriano-Piggott-T)Let G be a vertex transitive geodetic graph. Then G has bounded size isometric simple circuits.

Recall that a **simple circuit** is a circuit with no repeated vertices.

We call a simple circuit in a graph G isometric if the geodesic between any two vertices in the simple circuit lie on the circuit.

Theorem (Elder-Gardam-Spriano-Piggott-T)

Let G be a vertex transitive geodetic graph. Then G has bounded size isometric simple circuits.

This means that vertex transitive geodetic graphs are 'quasi-transitive' to a tree (like a tree up to bounded tinkering).

Recall that a **simple circuit** is a circuit with no repeated vertices.

We call a simple circuit in a graph G isometric if the geodesic between any two vertices in the simple circuit lie on the circuit.

Theorem (Elder-Gardam-Spriano-Piggott-T)

Let G be a vertex transitive geodetic graph. Then G has bounded size isometric simple circuits.

This means that vertex transitive geodetic graphs are 'quasi-transitive' to a tree (like a tree up to bounded tinkering).

Conjecture: Let G be a transitive geodetic graph. Then every vertex is a cut vertex? Then there is a bound on simple circuits in G?

Proof of theorem outline

The proof requires understanding of topology outside the scope of this course.

Proof of theorem outline

The proof requires understanding of topology outside the scope of this course.

Step 1: Define something called the geodesic boundary in an infinite graph by setting up an equivalence relation on the collection of geodesic rays in the graph. Motivated by prior work on the Gromov boundary of hyperbolic metric spaces.



Proof of theorem outline

The proof requires understanding of topology outside the scope of this course.

Step 1: Define something called the geodesic boundary in an infinite graph by setting up an equivalence relation on the collection of geodesic rays in the graph. Motivated by prior work on the Gromov boundary of hyperbolic metric spaces.

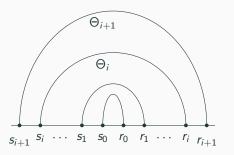


Step 2: Define a topology/metric on the geodesic boundary of a geodetic graph which is dependent on a basepoint vertex.



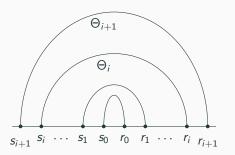
Proof of theorem outline (cont.)

Step 3: Prove that geodetic graphs cannot contain an 'infinite onion' (proof by contradiction using the topological properties of the geodesic boundary of a geodetic graph).



Proof of theorem outline (cont.)

Step 3: Prove that geodetic graphs cannot contain an 'infinite onion' (proof by contradiction using the topological properties of the geodesic boundary of a geodetic graph).



Step 4: Prove that a transitive geodetic graph cannot have unbounded size of isometric simple circuits as this implies that you can construct an infinite onion.

References to prepints

```
\verb|https://arxiv.org/pdf/2311.03730|
```

https://arxiv.org/pdf/2211.13397