

Discrete Mathematical Models

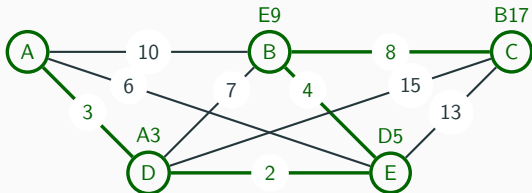
Lecture 26

Kane Townsend

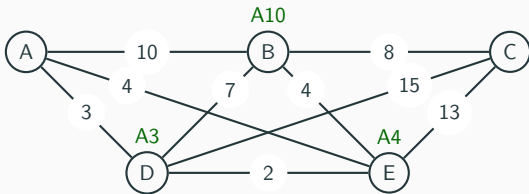
Semester 2, 2024

Dijkstra's Algorithm again

Last lecture we found a minimal path from A to C in the following weighted graph:



We now consider the same problem but with an adjustment to the graph:



Weighted digraphs

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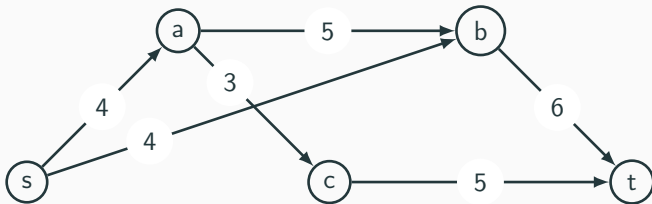
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A **weighted digraph** is a digraph G together with a **weight function** $\text{weight} : E(G) \rightarrow \mathbb{Q}_+$.

Transport Networks

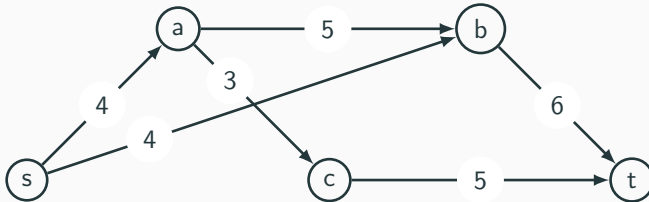
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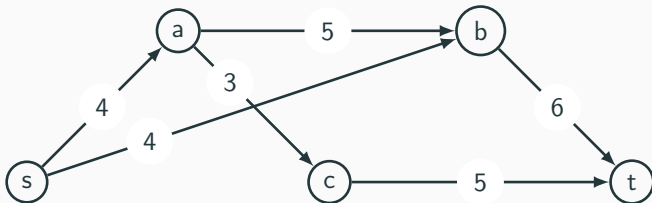


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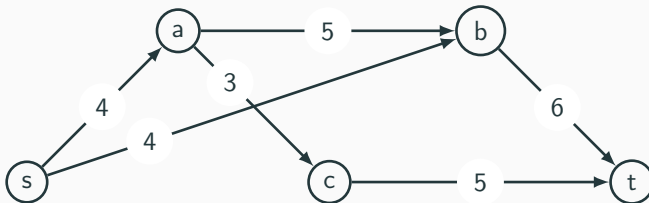


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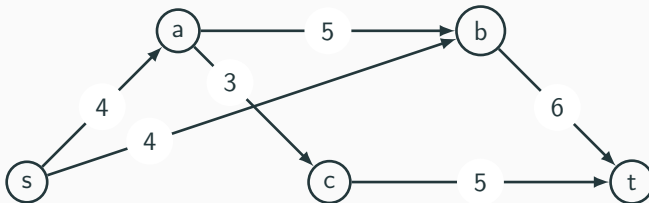


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- Every edge lies on some simple (directed) path from s to t.

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- (1) Flow cannot exceed capacity. [$\forall e \in E(D) \quad F(e) \leq C(e)$.]
- (2) In each edge, flow direction = edge direction.
- (3) Total flow into a node equals total flow out, except for nodes s, t .
[$\forall v \in V(D) \setminus \{s, t\} \quad \sum_{e \in v_{\text{in}}} F(e) = \sum_{e \in v_{\text{out}}} F(e)$, where $v_{\text{in}}, v_{\text{out}}$ are the sets of edges coming **in** to, and **out** of, v , respectively.]

Finding a maximum flow

For any flow F the constraints on the network imply that the total flow out of the source must equal the total flow into the target:

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At stage i , flow F_i is constructed as $F_i = F_{i-1} + f_i$, where the incremental flow f_i is based on a constant $k_i \in \mathbb{Q}^+$ and a simple path p_i from s to t :

$$f_i(e) = \begin{cases} k_i & \text{for every edge } e \text{ on the path } p_i \\ 0 & \text{for every other edge } e. \end{cases}$$

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Given a transport network D with capacity and flow functions C, F , we know that $F(e) \leq C(e)$ for every edge $e \in E(D)$. I will call the non-negative difference $S(e) = C(e) - F(e)$ the **spare capacity** of the edge e . (Some authors use the term “excess capacity”.)

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To depict a flow I will follow the capacity value $C(e)$ on each (directed) edge e with the flow value $F(e)$ for that edge. For example



represents a flow of 3 in the edge from x to y , with spare capacity 2.

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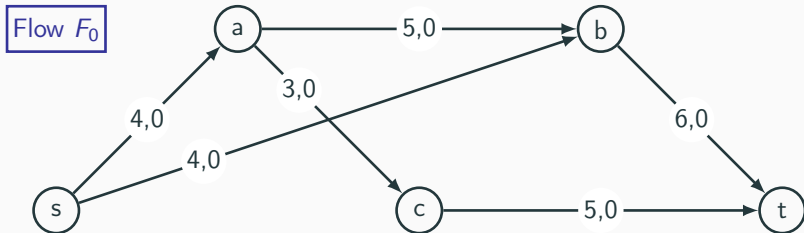
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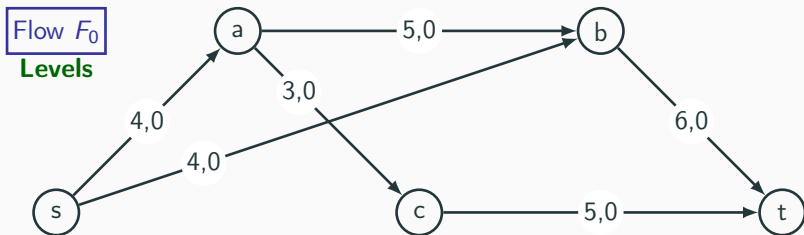
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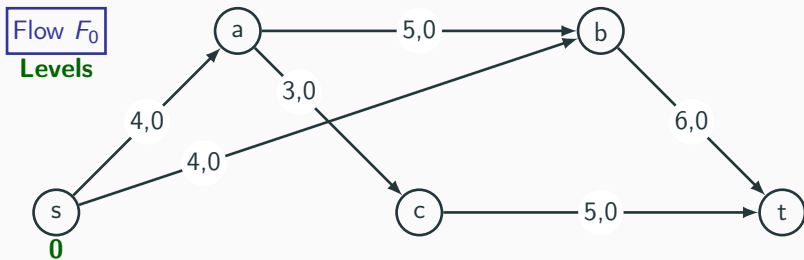
Vertex labelling algorithm, Example 1: Stage 1: F_0 to F_1



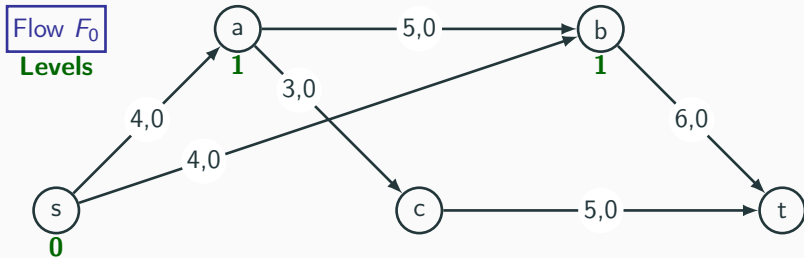
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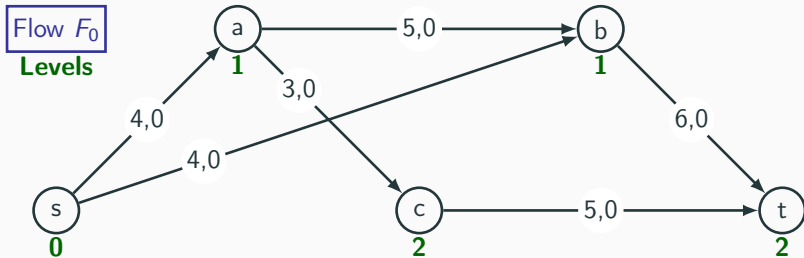
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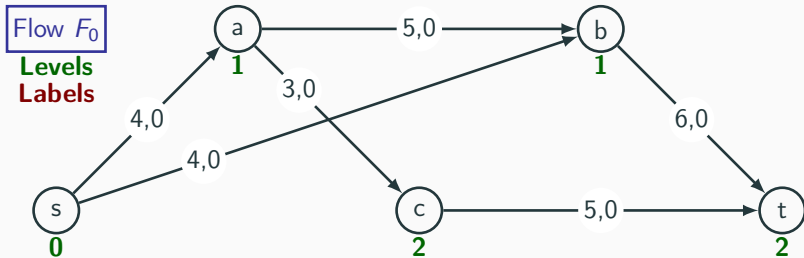
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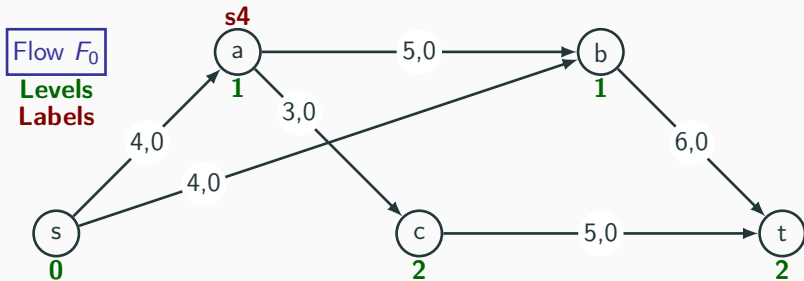
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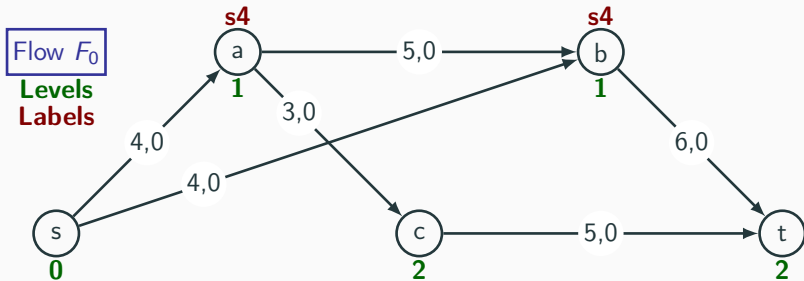
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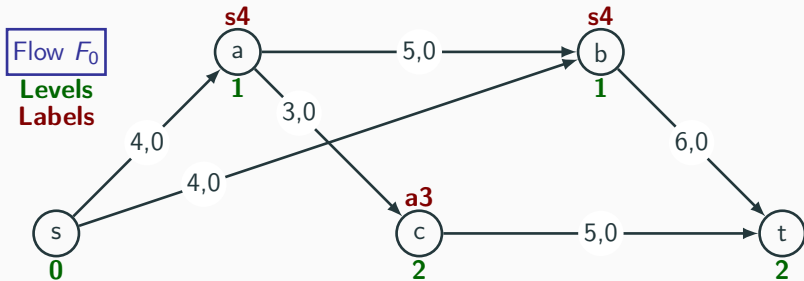
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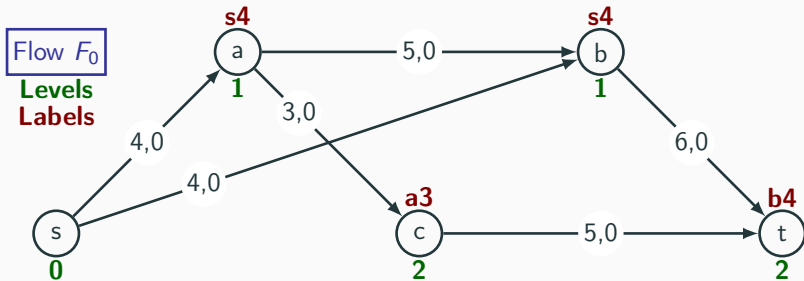
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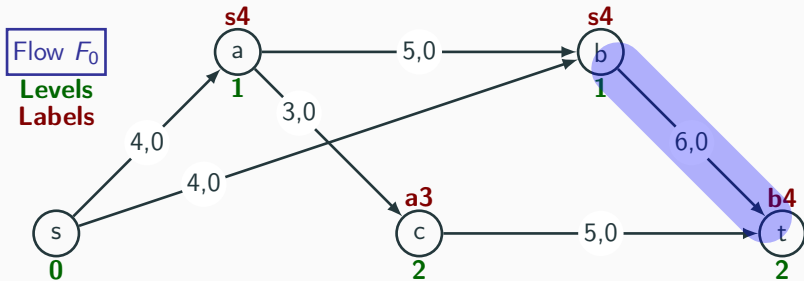
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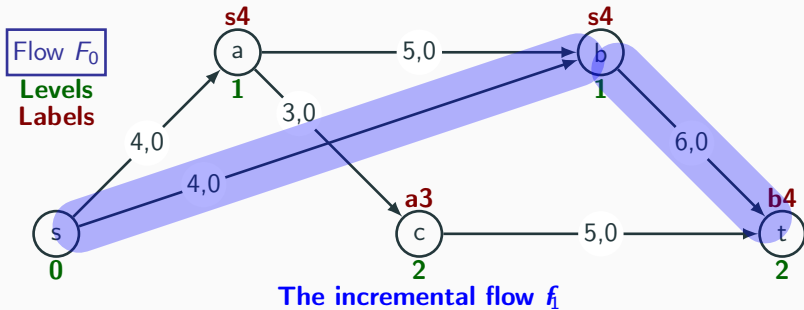
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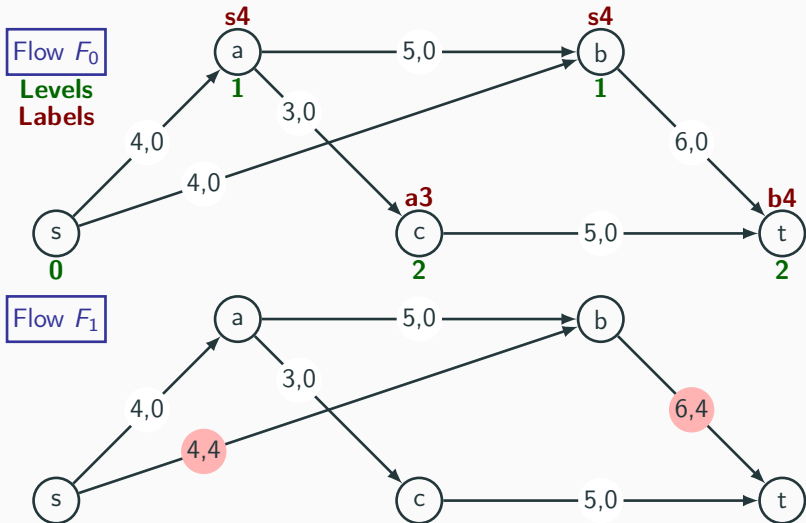
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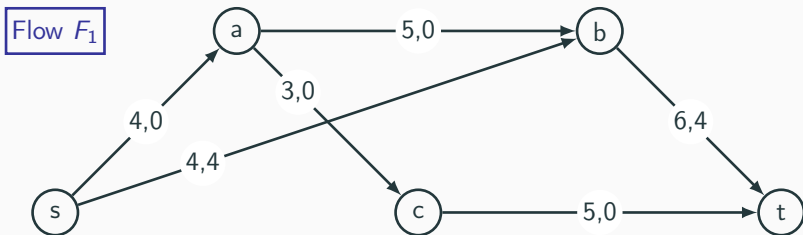
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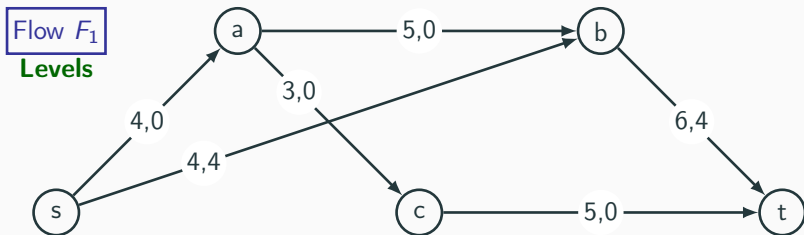
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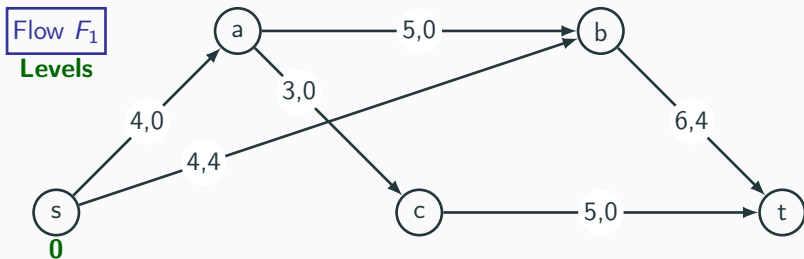
Vertex labelling algorithm, Example 1: Stage 2: F_1 to F_2



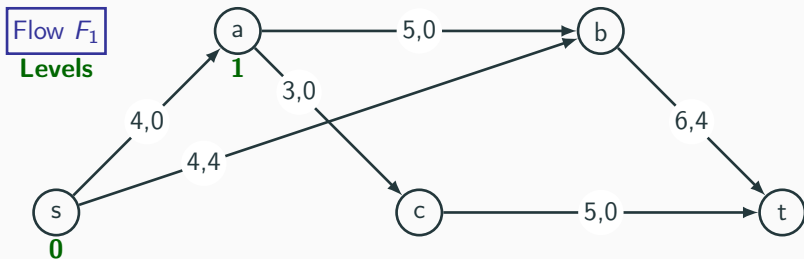
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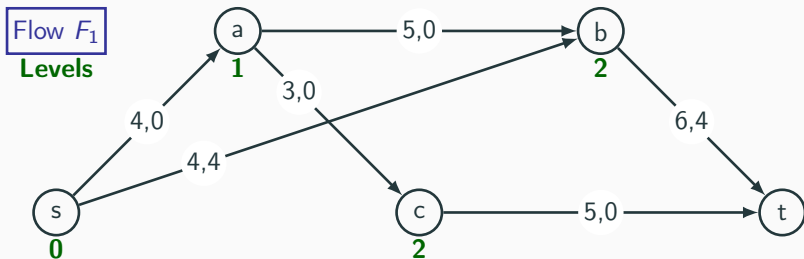
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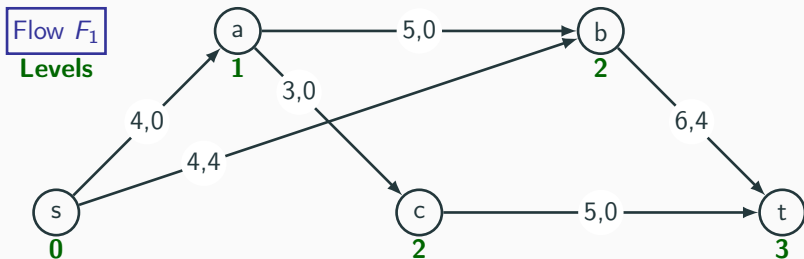
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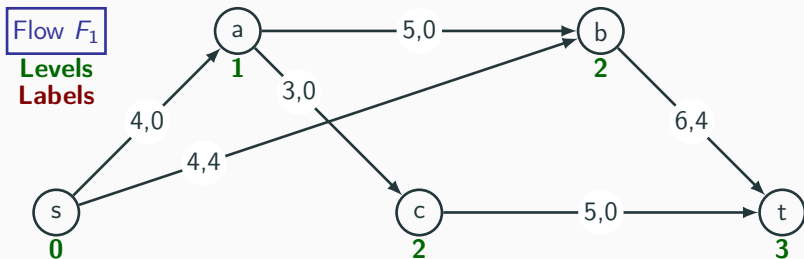
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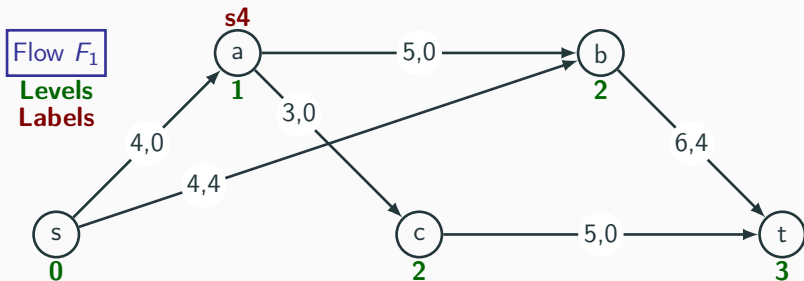
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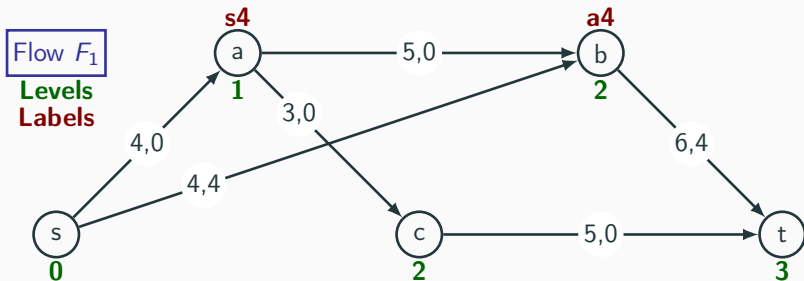
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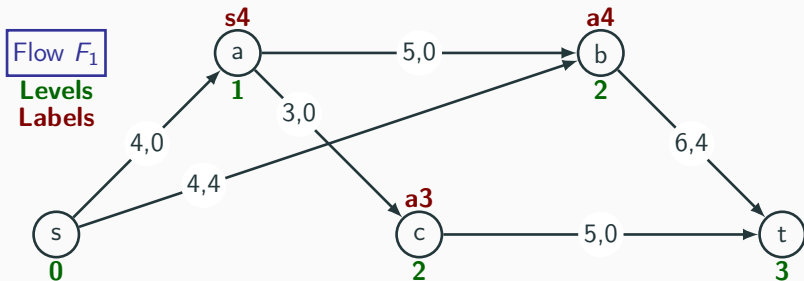
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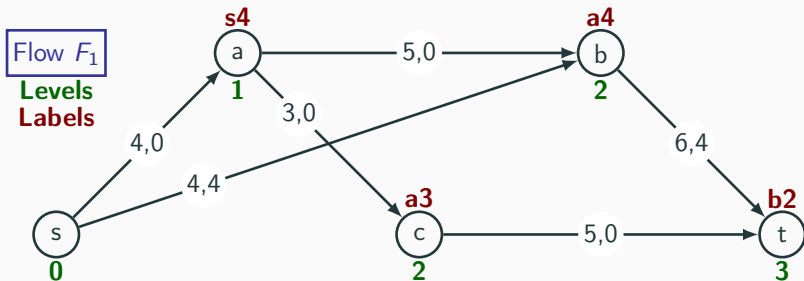
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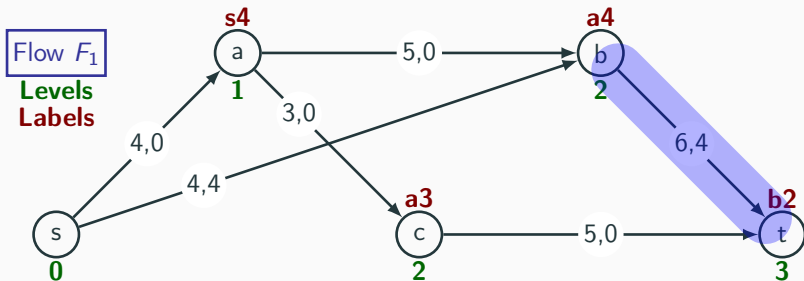
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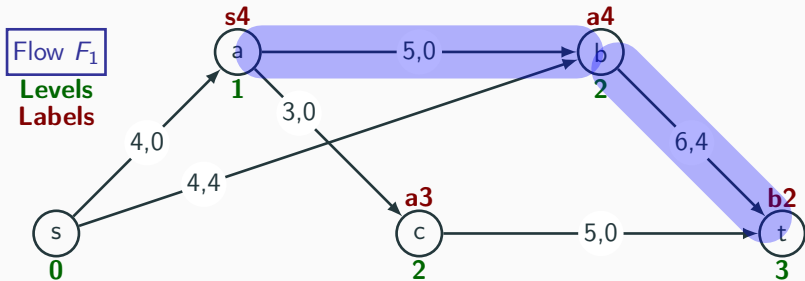
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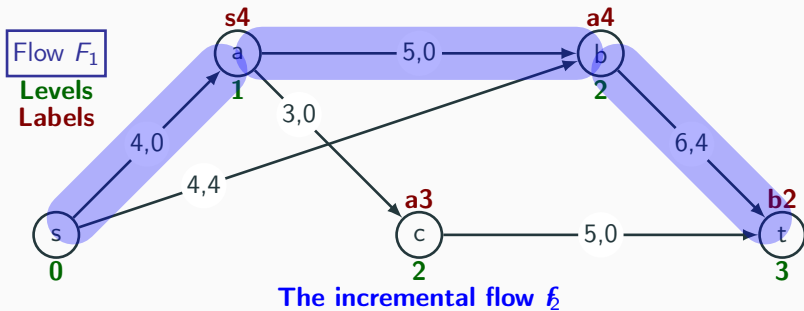
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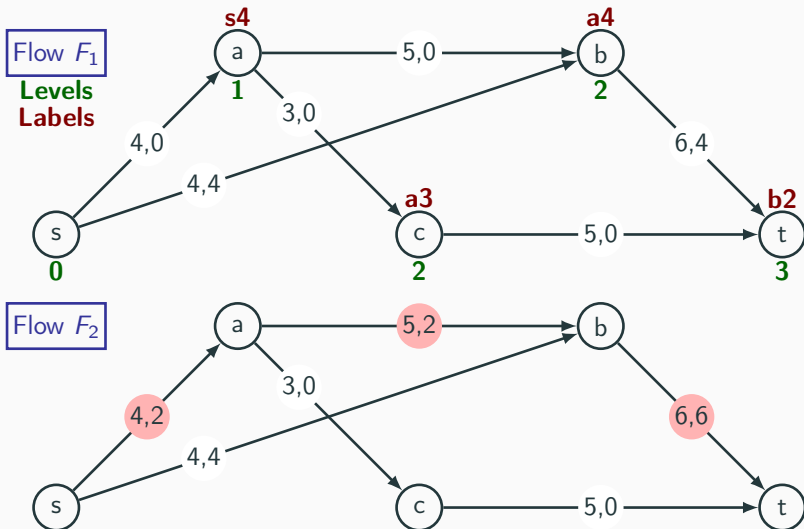
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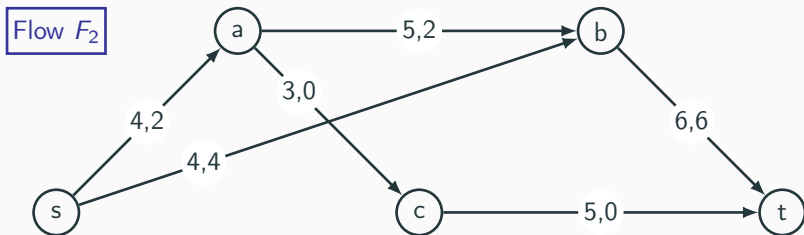
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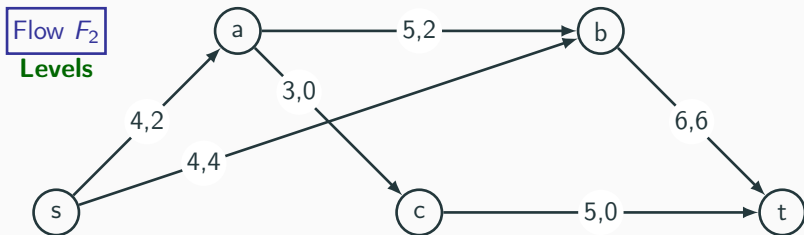
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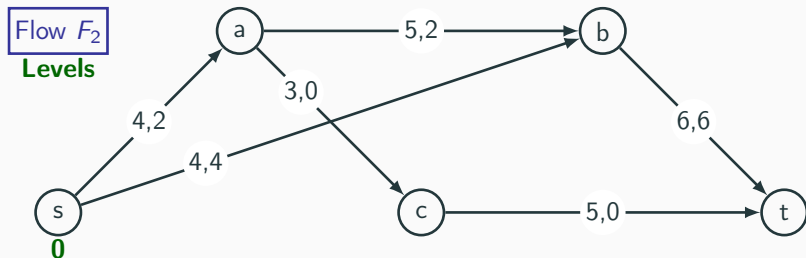
Vertex labelling algorithm, Example 1: Stage 3: F_2 to F_3



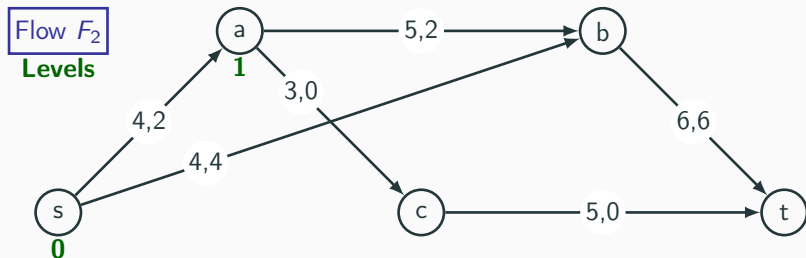
Vertex labelling algorithm, Example 1: Stage 3: F_2 to F_3



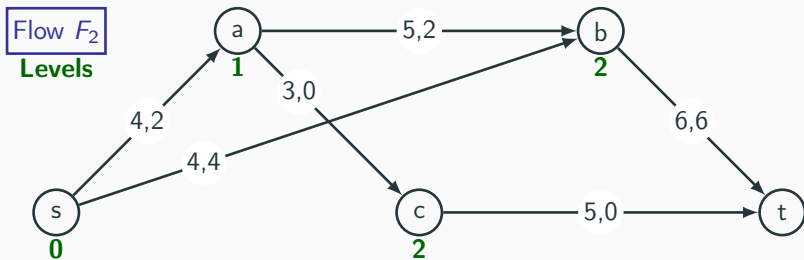
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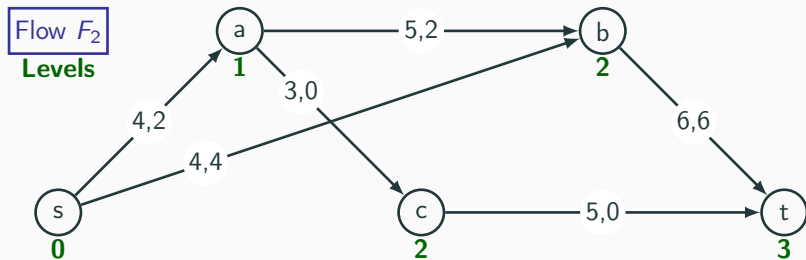
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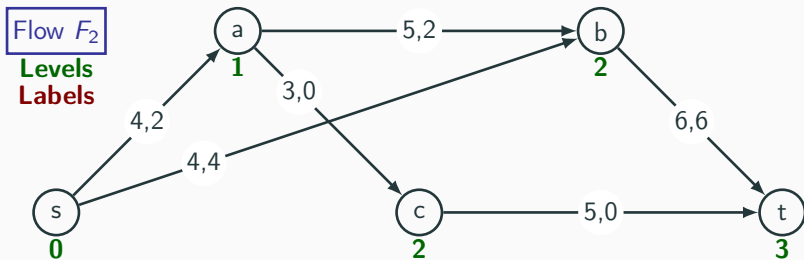
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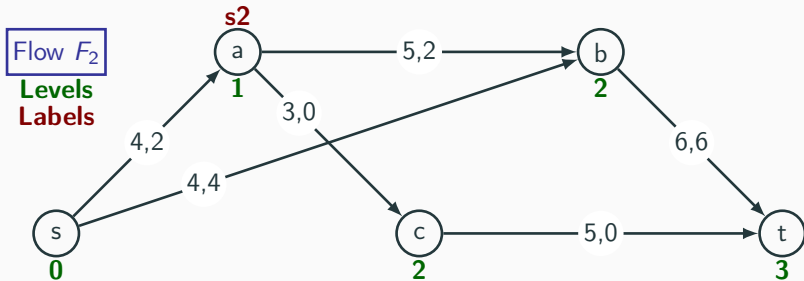
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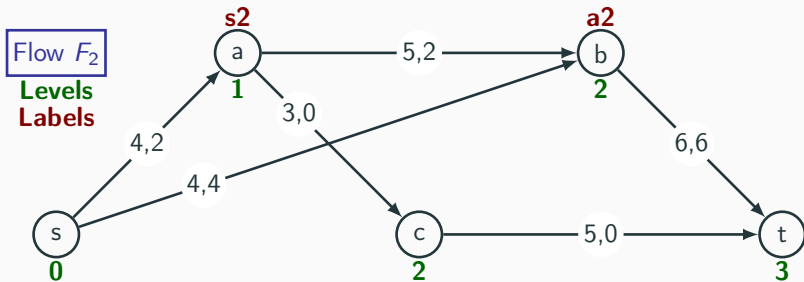
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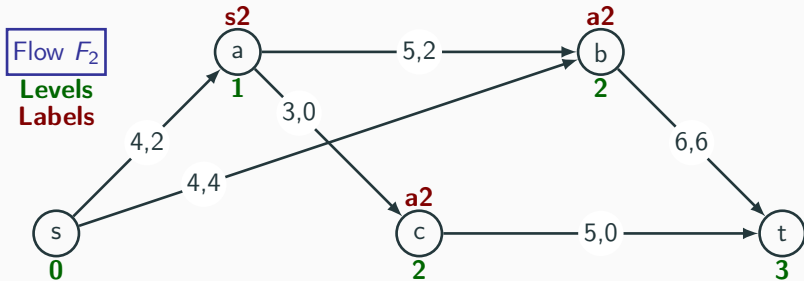
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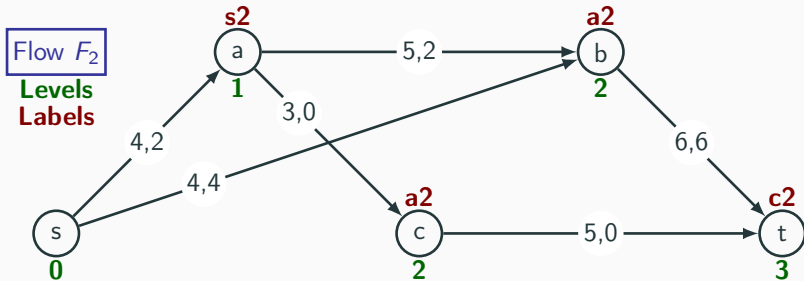
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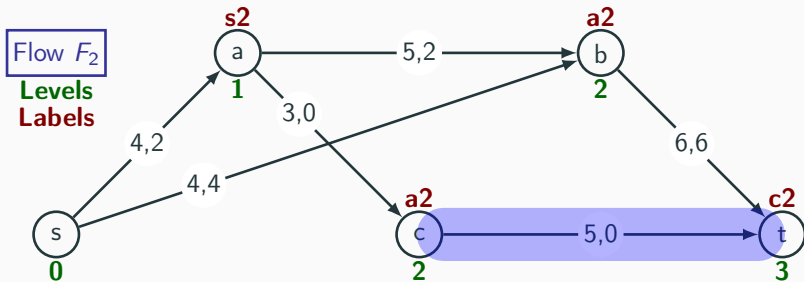
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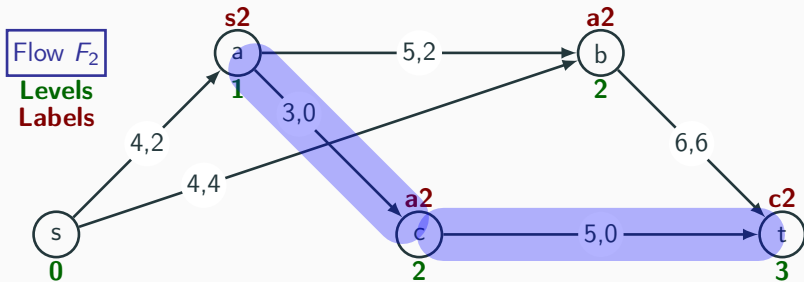
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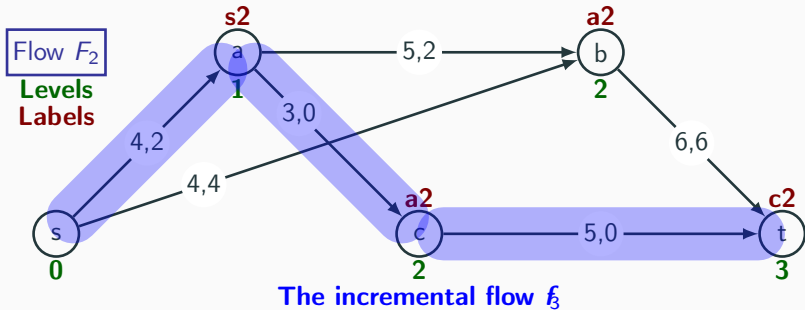
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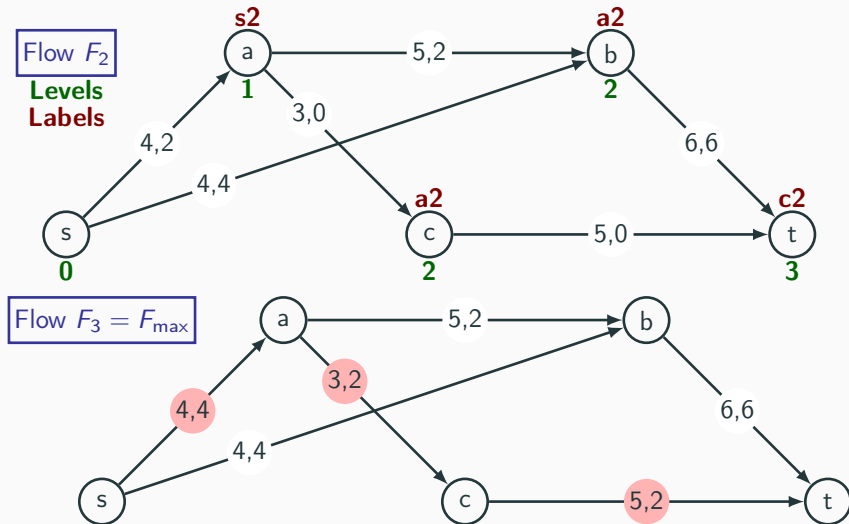
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3. Next slide....

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5. Let p_i be the path $u_0u_1 \dots u_n$ where $u_n = t$ and for $0 < j \leq n$ u_j has label $u_{j-1}k_j$.
Define f_i to be the incremental flow on p_i with flow value k_n .

End of Method