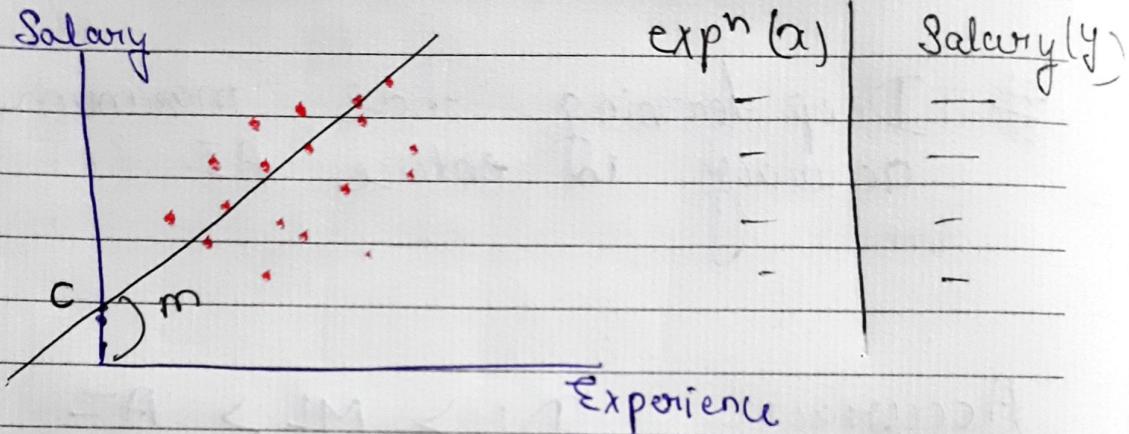


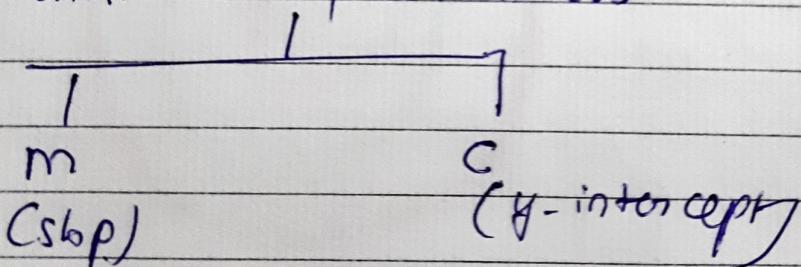
## Linear Regression -

Hypothesis -  $\hat{y} = mx + c$



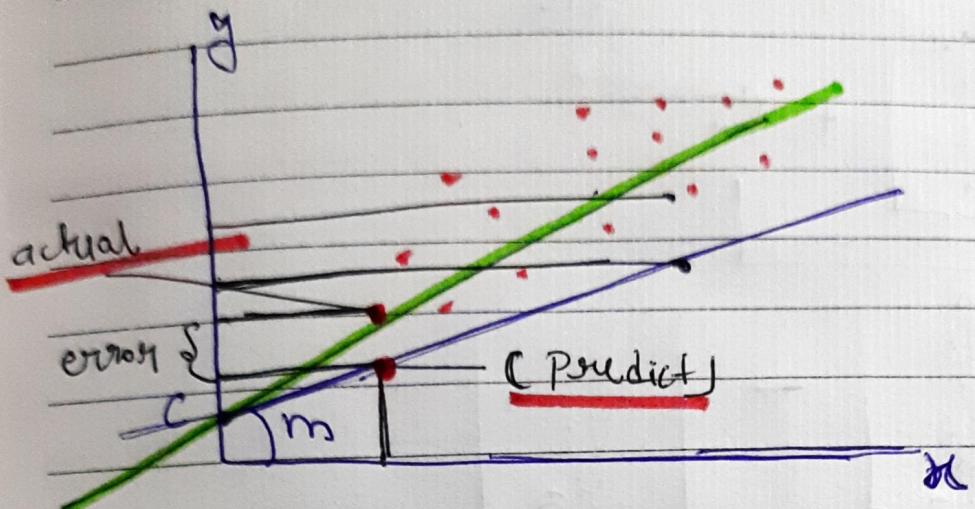
At the time of training : known  
parameters  $y \neq n$

unknown parameters



Target:- To have best fit line will predict output with least error

Putting random value of m & c -



Forward Propagation - and Cost function -

forward propagation -

Step 1 -  $y = mx + c$

Step 2 - calculate the error

$$\text{cost fn} = \sum_{i=1}^n (\hat{y}_i - y_i)^2$$

$\hat{y}$   $n$  no. of instances

$\hat{y}$  — Predicted value

$y$  — Actual value

$$\text{Cost fun} = \frac{\sum_{i=1}^n (mx_i + c - y_i)^2}{2n}$$

$$m \neq \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + c$$

# Cost function — difference between predicted and actual results and helps improve the model

## Step3 - Gradient Descent Algorithm - (Backward Propagation) -

$$m' = m - \alpha \frac{\partial \text{Cost}}{\partial m}$$

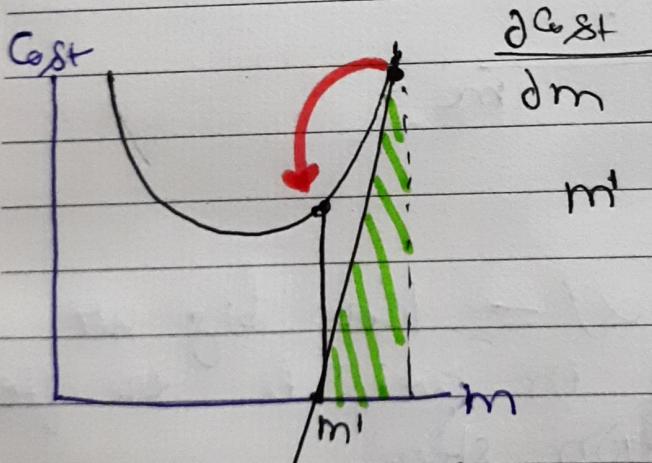
*learning rate*

$$c' = c - \alpha \frac{\partial \text{cost}}{\partial m}$$

## Partial differentiation

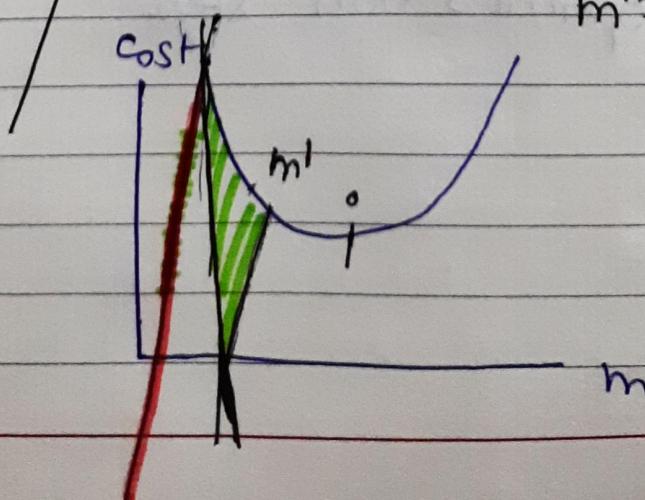
Why we use partial differentiation -

- there are two variable ( $m \neq c$ )
- if there will be is only one variable then it will be fully differentiation

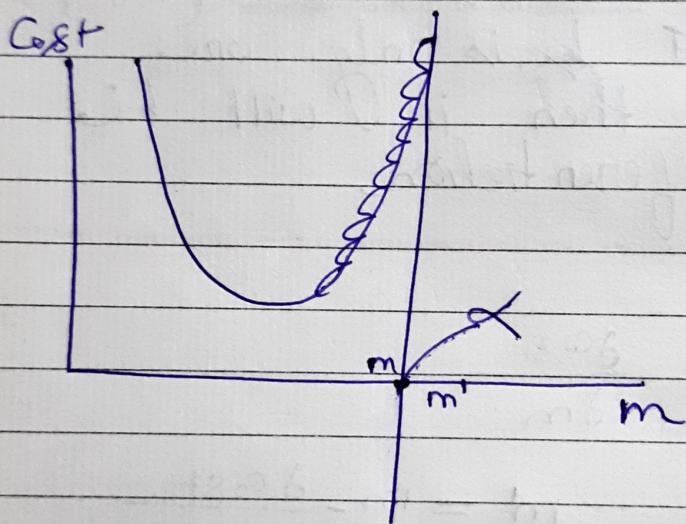
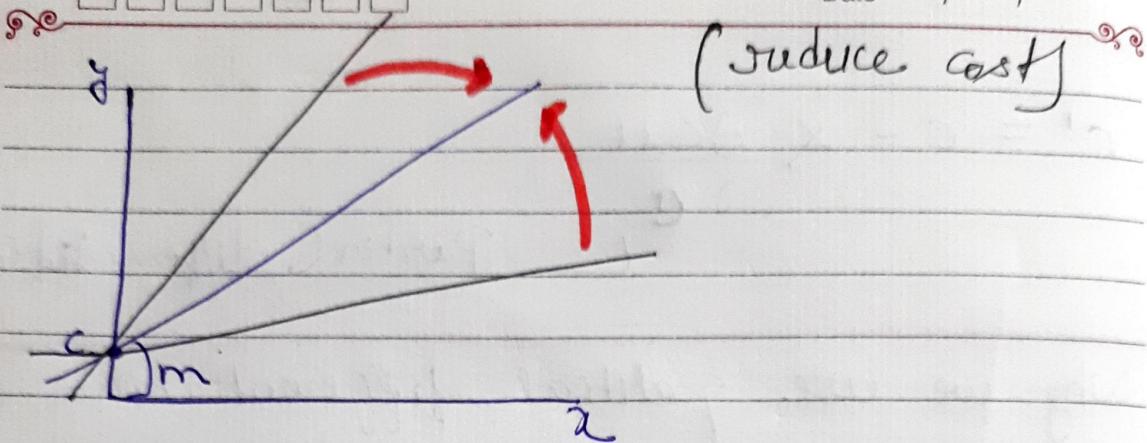


$$\frac{\partial \text{cost}}{\partial m}$$

$$m' = m - \frac{\partial \text{cost}}{\partial m}$$



$$\begin{aligned} m' &= m - \frac{\partial \text{cost}}{\partial m} \\ &= m - (-ve)_{\text{in}} \\ &= m + \text{value} \end{aligned}$$



Learning rate ( $\alpha$ ) - How big are small changes in weights after each optimisation step.

①

②

f

y

③

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Step 1

Forward propagation -  
 $y = mx + c$

Step 2 - Cost function -

$$\text{Cost} = \sum_{i=1}^n \frac{1}{2n} (\hat{y}_i - y_i)^2$$

Step 3 - Gradient Descent

$$m' = m - \alpha \frac{\partial \text{Cost}}{\partial m}$$

$$c' = c - \alpha \frac{\partial \text{Cost}}{\partial c}$$

$$\Rightarrow m' = m - \alpha \frac{\partial \text{Cost}}{\partial m}$$

$$\frac{\partial \text{Cost}}{\partial m} = \frac{\partial \text{Cost}}{\partial f} \cdot \frac{\partial f}{\partial m}$$

$$\text{where } f = \bar{y} = mx + C$$

$$\frac{\partial f}{\partial m} = \frac{\partial \text{Cost}}{\partial f} = \frac{1}{2n} (\bar{y} - y)^2$$

$$= \frac{2}{2n} (\bar{y} - y)^2 \cdot \frac{\partial (\bar{y} - y)}{\partial \bar{y}}$$

$$= \frac{\bar{y} - y}{n} \cdot \left( 1 - \frac{\partial y}{\partial \bar{y}} \right)$$

$$\boxed{\frac{\partial f}{\partial m} = \frac{\bar{y} - y}{n}} \longrightarrow \textcircled{1}$$

$$\textcircled{2} \quad \frac{\partial f}{\partial m} = \frac{\partial (mx + C)}{\partial m}$$

$$= \frac{\partial mx}{\partial m} + \frac{\partial C}{\partial m}$$

$$\textcircled{3} \quad = x + 0$$

$$\textcircled{4} \quad \boxed{\frac{\partial f}{\partial m} = n} \longrightarrow \textcircled{11}$$

$$\frac{\partial f}{\partial c} = \frac{\partial m x + c}{\partial c}$$

$$= 0 + 1$$

$$\boxed{\frac{\partial f}{\partial c} = 1} \rightarrow \text{III}$$

$m, f, c$  - randomly initialised  
 $x, y$ : known  
 training input      training output

$$\text{hypothesis} \Rightarrow \hat{y} = mx + c$$

$$\text{Cost} = \sum_{i=1}^n \frac{1}{2n} (\hat{y}_i - y_i)^2$$

$$dm = \frac{\partial \text{Cost}}{\partial m} = \frac{\partial \text{Cost}}{\partial f} \cdot \frac{\partial f}{\partial m}$$

$$dm = \frac{\hat{y} - y}{n} \cdot x$$

$$dc = \frac{\partial \text{Cost}}{\partial c} = \frac{\hat{y} - y}{n}$$

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$$m' = m - \alpha dm$$

$$c' = c - \alpha dc$$

$$m' = m - \alpha \left( \frac{\vec{y} - \vec{y}_*}{n} \cdot \vec{x} \right)$$

$$c' = c - \alpha \left( \frac{\vec{y}' - \vec{y}_*}{n} \right)$$