

$$a) \min_{\omega, b, s} \frac{1}{2} \|\omega\|_2^2$$

$$y_i(\omega^T x_i + b) \geq 1 - s_i \quad s_i \geq 0 \quad \forall i = 1, \dots, n$$

$$\Rightarrow y_i(\omega^T x_i + b) - 1 + s_i \geq 0$$

$$s_i \geq 0$$

$$L(\omega, b, s, \alpha, \beta) = \frac{1}{2} \|\omega\|_2^2 - \sum_i \alpha_i [y_i(\omega^T x_i + b) - 1 + s_i] - \sum_i \beta_i s_i$$

$$b) \frac{\partial L}{\partial \omega} = \omega - \sum_i \alpha_i y_i x_i = 0$$

$$\Rightarrow \omega = \sum_i \alpha_i y_i x_i$$

$$\frac{\partial L}{\partial b} = + \sum_i \alpha_i [y_i] = 0$$

$$\frac{\partial L}{\partial s} = + \sum_i \alpha_i + \sum_i \beta_i = 0$$

~~0~~

$$c) \omega = \sum_i \alpha_i y_i x_i$$

$$\sum_i \alpha_i y_i = 0$$

$$\sum_i \beta_i + \sum_i \alpha_i = 0 \Rightarrow \sum_i (\alpha_i + \beta_i) = 0$$

$$\alpha_i \geq 0 \quad \beta_i \geq 0$$

$$L(\omega, b, S, \alpha, \beta) = \frac{1}{2} \left(\left(\sum_i (\alpha_i y_i x_i)^2 \right)^{\frac{1}{2}} \right)^2$$

$$- \sum_i \alpha_i y_i \sum_{j=0}^n \alpha_j y_j x_j$$

$$- \sum_i \alpha_i y_i b + \sum_i \alpha_i - \sum_i \alpha_i s_i$$

$$- \sum_i \beta_i s_i$$

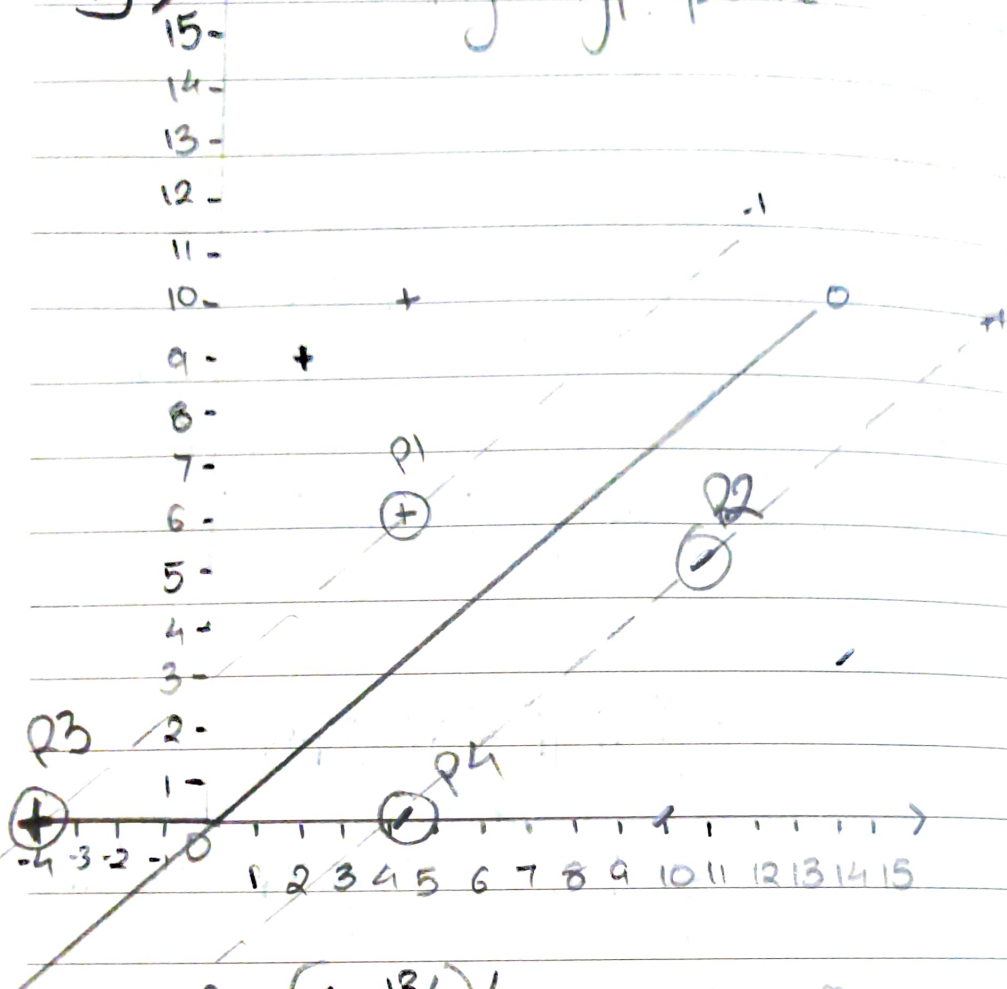
$$= \frac{1}{2} \sum_i (\alpha_i y_i x_i)^2 - \sum_{i,j} \alpha_i y_i \alpha_j y_j x_j x_i$$

$$+ \sum_i \alpha_i - \sum_i (\alpha_i + \beta_i) s_i$$

$$= \frac{1}{2} \sum_i (\alpha_i y_i x_i)^2 - \sum_{i,j} \alpha_i y_i \alpha_j y_j x_j x_i + \sum_i \alpha_i$$

2] a) ↑

My hyperplane



$$d = \frac{(-4 + 13/3)}{2} \quad \text{for my diagram above}$$

$$= 0.1\bar{6}$$

Created by measuring slope & eq. of $P3-P1$ & $P2-P4$
took the centre of two

b) Points $\Rightarrow (4, 6, +1)$, ~~(10, 5, -1)~~ $(11, 5, -1)$ $(-4, 0, 1)$

$(4, 6, +1)$

$$(+1)(4w_1 + 6w_2 + b) = 1$$

$$\Rightarrow 4w_1 + 6w_2 + b = 1 \quad (1)$$

$(11, 5, -1)$

$$-1(11w_1 + 5w_2 + b) = 1$$

$$\Rightarrow 11w_1 + 5w_2 + b = -1 \quad (2)$$

$$(-40, 1)$$

$$-4\omega_1 + b_1 = 1 \quad \text{--- (3)}$$

(let $\omega_1 = a$, $\omega_2 = b$ & $b_1 = c$)

$$\textcircled{3} \text{ gives } a = \frac{(1-b)}{4} = \frac{b-1}{4}$$

Plugging in $\textcircled{1}$ gives

$$2c + 6b - 1 = 1 \Rightarrow c = -3b + 1 \quad \text{--- (4)}$$

Plugging in $\textcircled{2}$

$$5b - \left(\frac{-11 + 15(-3b + 1)}{4} \right) = -1$$

$$\Rightarrow \frac{-25b + 4}{4} = 1$$

$$\Rightarrow b = \frac{8}{25}$$

$$\Rightarrow c = \frac{1}{25}$$

$$\Rightarrow a = \frac{-6}{25}$$

$$\text{Thus, } \omega_1 = \frac{-6}{25}, \omega_2 = \frac{8}{25}, b = \frac{1}{25}$$

c.) removing $(30, -1)$ might not change ω^* as there is still $(15, 1)$ to

a.) keep the solution same but removing $(15, -1)$ will change ω^* (might shift right)

3] gradient of hinge loss

$$\frac{1}{2} \alpha^T K \alpha + \frac{\lambda}{n} \sum_{i=1}^n \max(0, 1 - y_i (K \alpha)_i)$$

$$\frac{\partial}{\partial \alpha} K \alpha + \frac{\lambda}{n} \sum_{i=1}^n \nabla \max(0, 1 - y_i (K \alpha)_i)$$

$$\begin{array}{l} 1 \quad \text{if } 1 - y_i (K \alpha)_i > 0 \\ 0 \quad \text{if } 1 - y_i (K \alpha)_i \leq 0 \end{array}$$