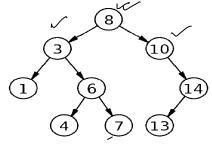


Binary Search Trees

- A binary search tree (BST) is a node-based binary tree data structure which has the following properties:
 - The left subtree of a node contains only nodes with keys less than the node's key.
 - The right subtree of a node contains only nodes with keys greater than of equal to the node's key.
 - Both the left and right subtrees must also be binary search trees.



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Binary Search Trees

- Firstly, it is a binary tree
- It is represented by a linked data structure
- It combines
 - the advantage of an array -- the ability to do a binary search with
 - the advantage of a linked list -- its dynamic size
- The efficiency of all of the operations is $O(h) = O(\log n)$, only if the tree is reasonably height-balanced
- Each node contains at least the following fields
 - key: an identifying field
 - *left*: pointer to a left child (may be NIL)
 - *right*: pointer to a right child (may be NIL)
 - p: pointer to the parent node (NIL for root)

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Binary Search Trees

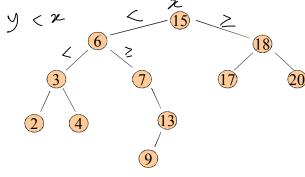
- Secondly, the binary-search-tree property
 - For any nodex

key [y] < key [x]

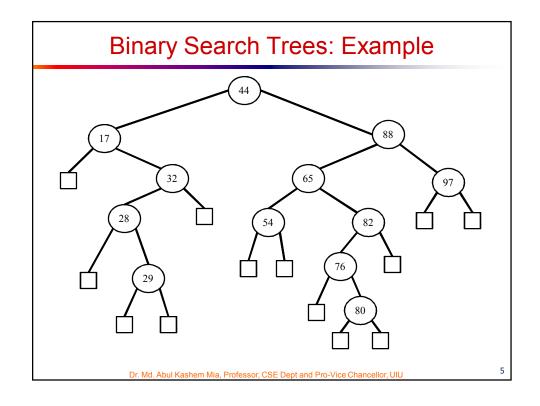
if y in left subtree of x

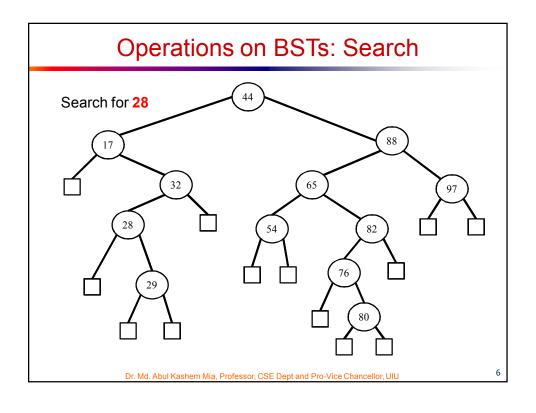
 $\text{key}[y] \ge \text{key}[x]$

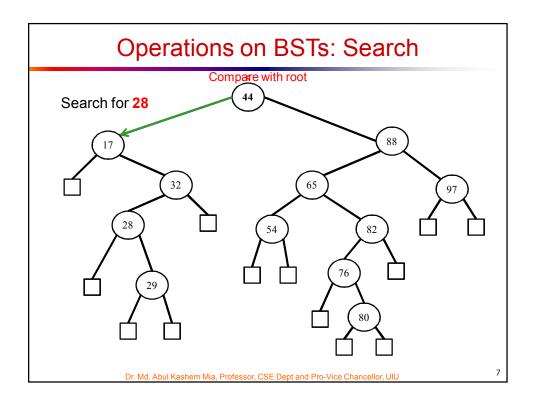
if y in right subtree of x

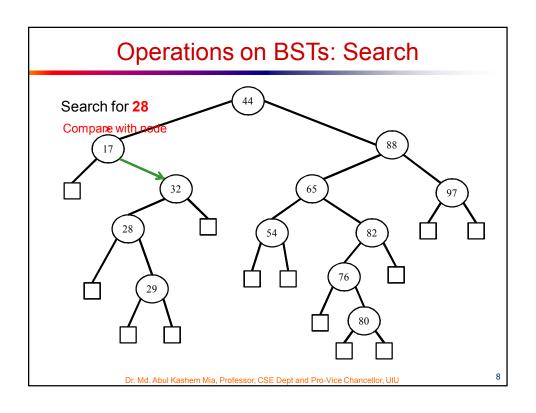


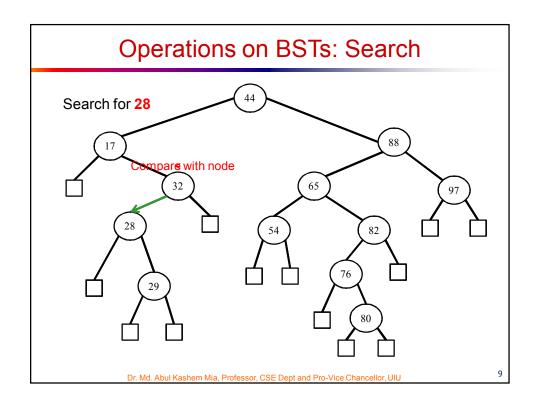
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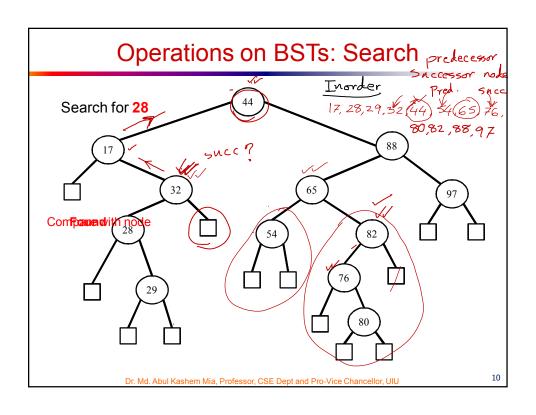












Operations on BSTs: Search

• Given a key *k* and a pointer to the root, Tree-Search returns a pointer to a node with key *k* or NIL:

```
Tree-Search(x, k)
  if (x == NIL or k == key[x])
    return x;
  if (k < key[x])
    return Tree-Search(left[x], k);
  else
    return Tree-Search(right[x], k);</pre>
```

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Operations on BSTs: Search

• Here is another function that does the same:

```
Tree-Search(x, k)

while (x != NIL and k != key[x])

if (k < key[x])

x = left[x];

else

x = right[x];

return x;
```

• Which of these two functions is more efficient?

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Operations on BSTs: Min & Max

TREE-MINIMUM(x)

- 1 **while** $left[x] \neq NIL$
- 2 **do** $x \leftarrow left[x]$
- 3 return x

TREE-MAXIMUM(x)

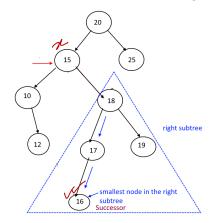
- 1 **while** $right[x] \neq NIL$
- 2 **do** $x \leftarrow right[x]$
- 3 return x

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Operations on BSTs: Successor

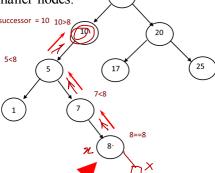
- Two cases:
 - Case 1: x has a right subtree:
 - successor is minimum node in right subtree



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Operations on BSTs: Successor

- Two cases:
 - Case 2: x has no right subtree:
 - successor is first ancestor of x whose left child is also ancestor of x
 - Intuition: As long as you move to the left up the tree, you're visiting smaller nodes.

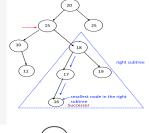


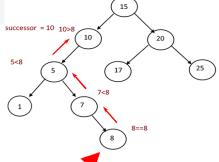
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Operations on BSTs: Successor

TREE-SUCCESSOR (x)

- **if** $right[x] \neq NIL$
- then return TREE-MINIMUM(right[x])
- 3 $y \leftarrow p[x]$
- **while** $y \neq \text{NIL}$ and x = right[y]
- 5 $\mathbf{do} \ x \leftarrow y$
- 6 $y \leftarrow p[y]$
 - return y





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Operations on BSTs: Predecessor

- Two cases:
 - similar to Successor algorithm

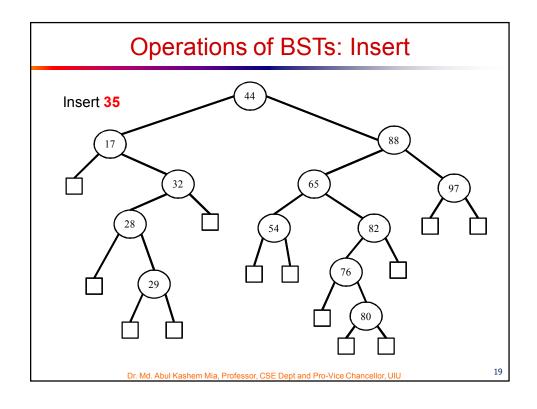
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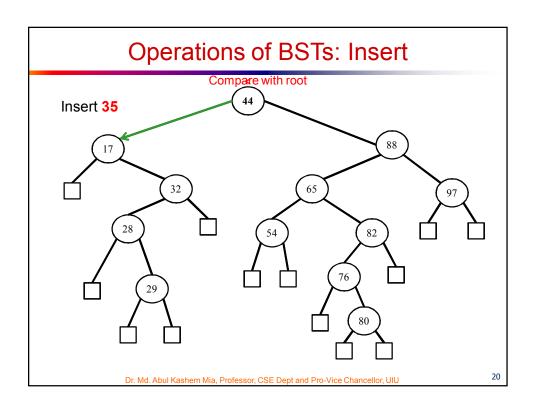
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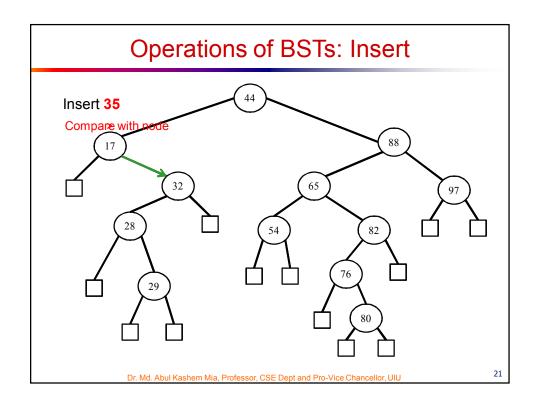
Operations of BSTs: Insert

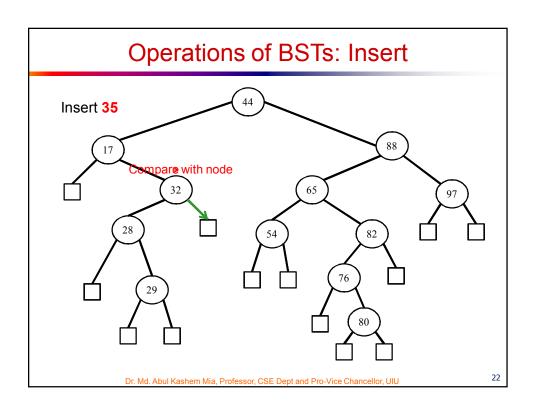
- Inserts an element z to the tree so that the binary search tree property continues to hold
- The basic algorithm
 - Like the search procedure as discussed before
 - Insert z in place of NIL
 - Use a "trailing pointer" to keep track of where you came from (like inserting into singly linked list)

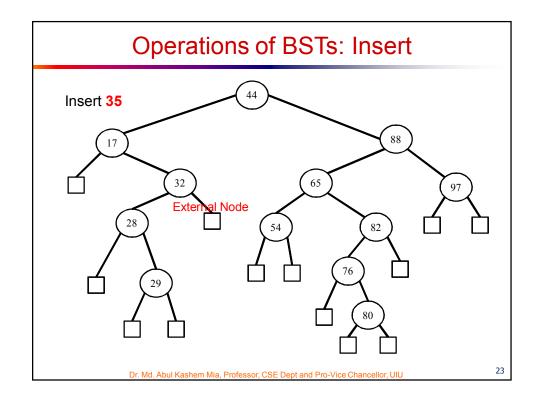
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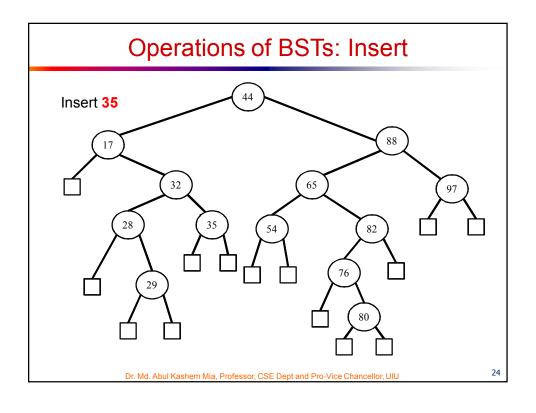


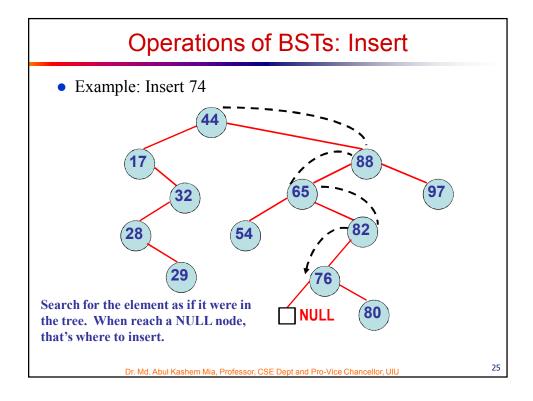


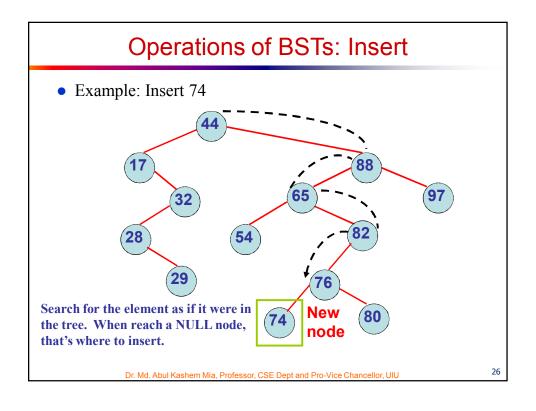


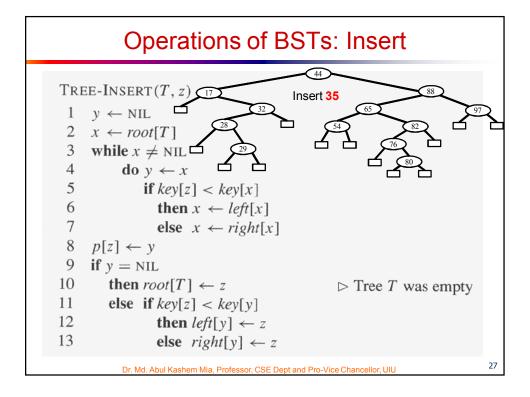






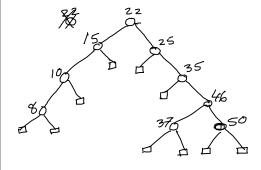




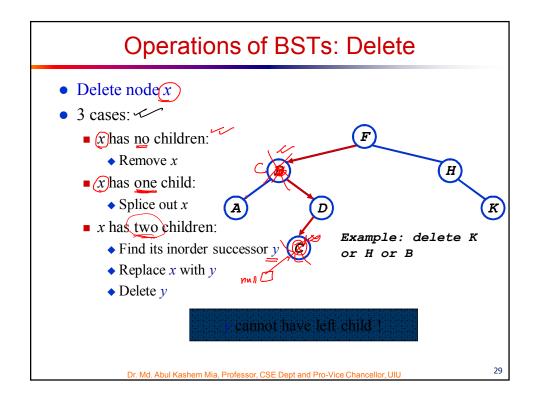


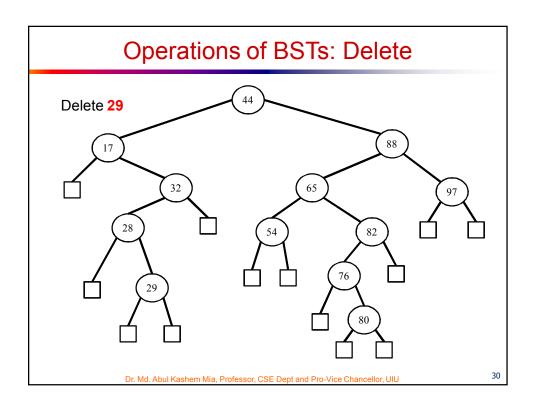
Operations of BSTs: Insert

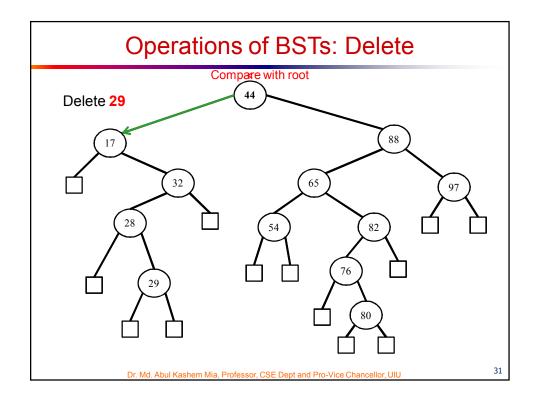
Draw a binary search tree (show each step) after inserting the following keys.

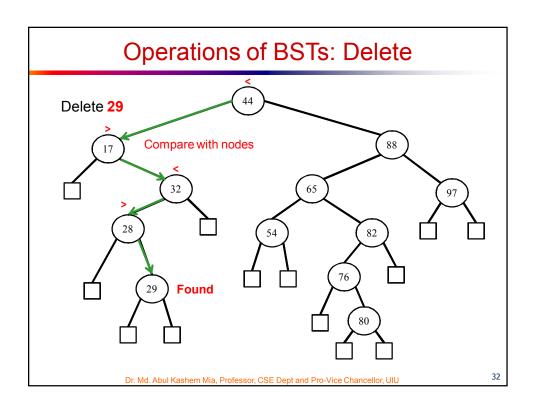


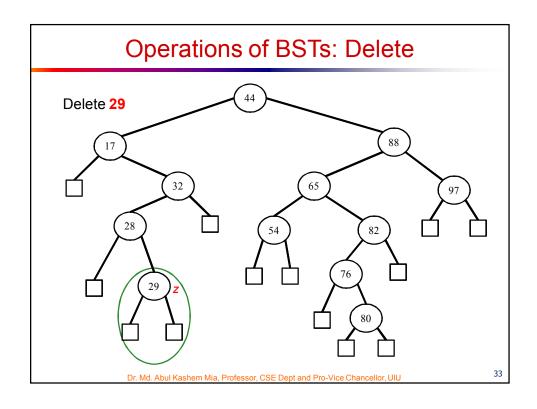
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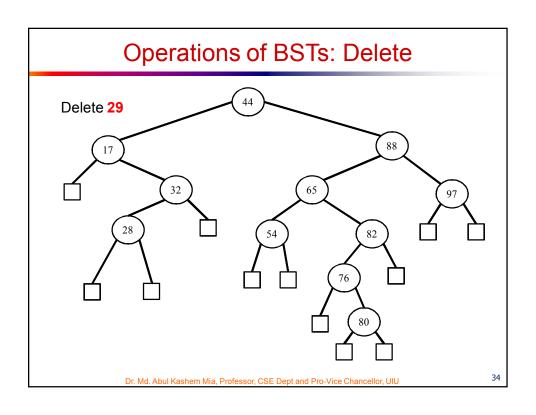


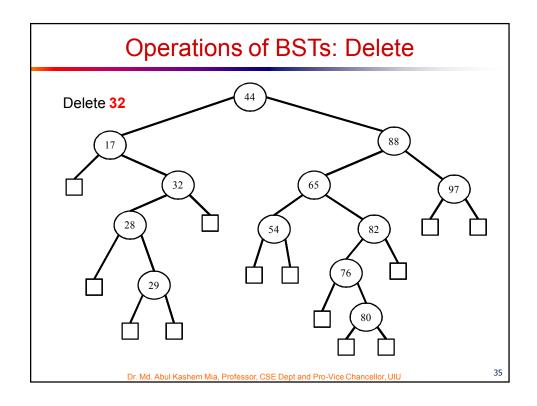


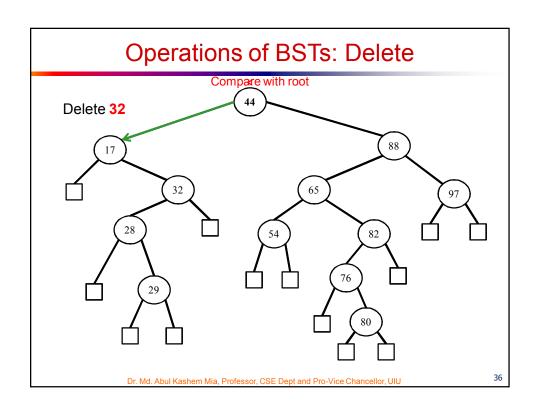


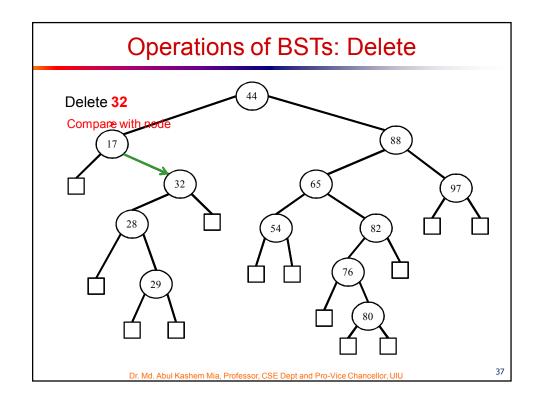


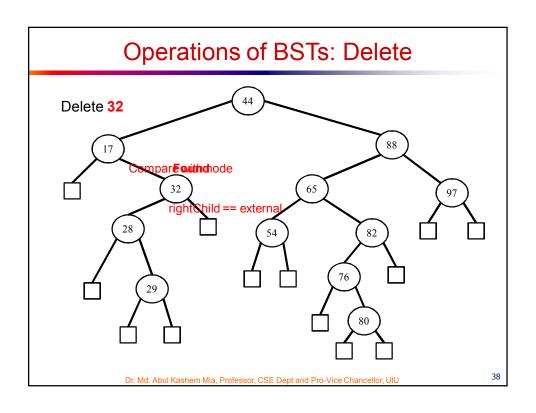


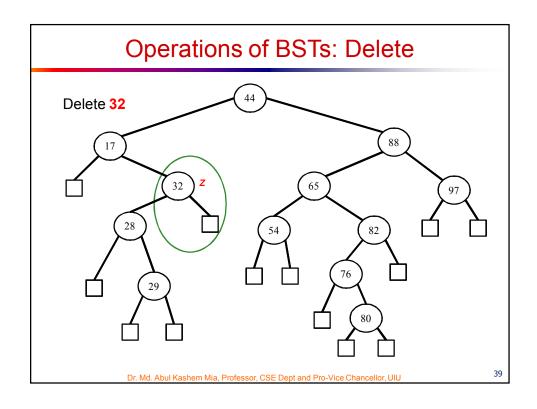


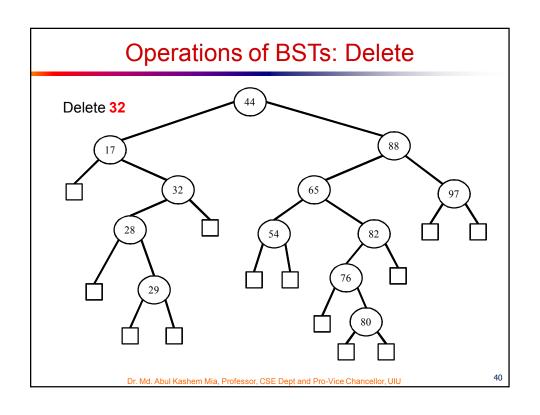


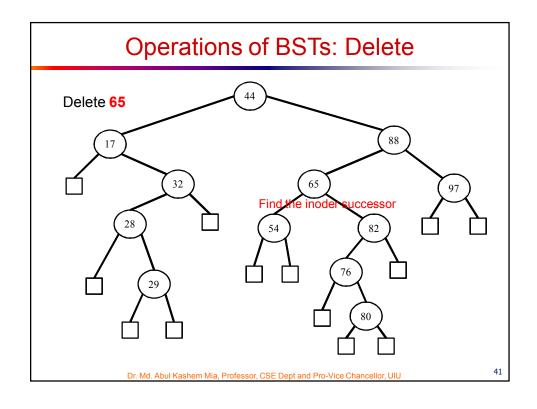


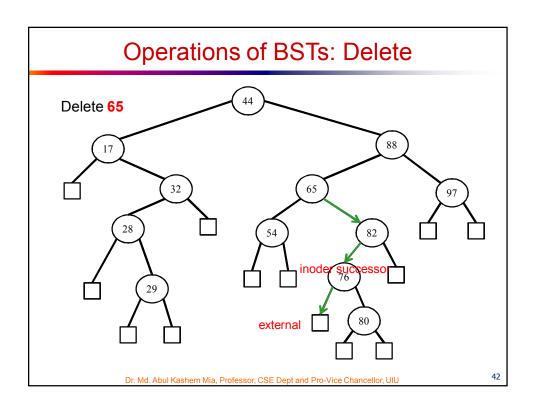


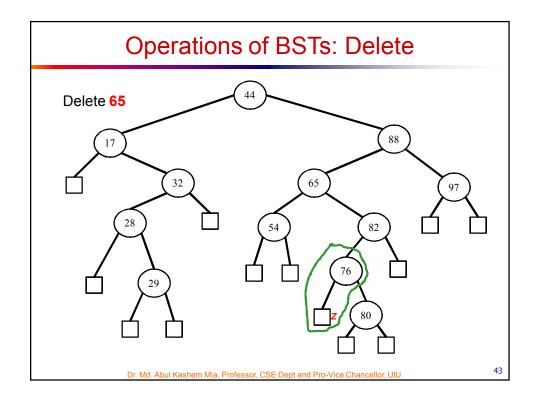


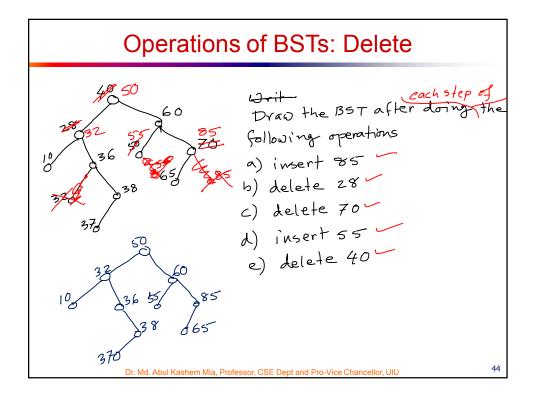












Operations of BSTs: Delete

• Given two nodes *u* and *v*, Transplant replaces the subtree rooted at *u* with the subtree rooted at *v*: node *u*'s parent becomes node *v*'s parent.

```
\begin{aligned} & \text{Transplant}(\mathsf{T},\mathsf{u},\mathsf{v}) \\ & \text{if } (\mathsf{p}[\mathsf{u}] = \mathsf{NIL}) \\ & \text{root}[\mathsf{T}] = \mathsf{v} \\ & \text{elseif } (\mathsf{u} = \mathsf{eleft}[\,\mathsf{p}[\mathsf{u}]\,] \\ & \text{left}[\,\mathsf{p}[\mathsf{u}]\,] = \mathsf{v}; \\ & \text{else right}[\,\mathsf{p}[\mathsf{u}]\,] = \mathsf{v}; \\ & \text{if } \mathsf{v} \mathrel{!=} \mathsf{NIL} \\ & \mathsf{p}[\mathsf{v}] = \mathsf{p}[\mathsf{u}]; \end{aligned}
```

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Operations of BSTs:

• Deletes node z from binary search tree T

```
\begin{split} \text{Tree-Delete}(\mathsf{T}, \mathsf{z}) \\ & \text{if } (\mathsf{left}[\mathsf{z}] = = \mathsf{NIL}) \\ & \text{Transplant}(\mathsf{T}, \mathsf{z}, \mathsf{right}[\mathsf{z}]) \\ & \text{elseif } (\mathsf{right}[\mathsf{z}] = = \mathsf{NIL}) \\ & \text{Transplant}(\mathsf{T}, \mathsf{z}, \mathsf{left}[\mathsf{z}]) \\ & \text{else } \mathsf{y} = \mathsf{Tree-Minimum}(\mathsf{right}[\mathsf{z}]) \\ & \text{if } \mathsf{p}[\mathsf{y}] != \mathsf{z} \\ & \text{Transplant}(\mathsf{T}, \mathsf{y}, \mathsf{right}[\mathsf{y}]) \\ & \text{right}[\mathsf{y}] = \mathsf{right}[\mathsf{z}] \\ & \mathsf{p}[\, \mathsf{right}[\mathsf{y}] \,] = \mathsf{y} \\ & \text{Transplant}(\mathsf{T}, \mathsf{z}, \mathsf{y}) \quad //\, \mathsf{p}[\mathsf{y}] = = \mathsf{z} \\ & \text{left}[\mathsf{y}] = \mathsf{left}[\mathsf{z}] \\ & \mathsf{p}[\, \mathsf{left}[\mathsf{y}] \,] = \mathsf{y} \end{split}
```

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Sorting with BSTs

• Informal code for sorting array A of length *n*:

```
BSTSort(A)
  for i=1 to n
     TreeInsert(A[i]);
  InorderTreeWalk(root);
```

- Running time is $\Omega(n \lg n)$
- What will be the running time in the
 - Worst case?
 - Average case?

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BST: Remarks

- All complexity depends on height h
- $h = \Omega(\lg n)$
- To guarantee performance:
 - Balanced tree!
- Randomly build tree
 - **Theorem**: The expected height of a randomly built binary search tree on n distinct keys is $O(\lg n)$

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Balanced Binary Search Trees

- Keep $O(\lg n)$ height under dynamic operations
- General framework:
 - First a binary search tree
 - Maintain properties that ensure height guarantee
- AVL tree, red-black tree, ...

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Codes for Binary Search Trees

```
#include<stdio.h>
#include<stdib.h>

typedef struct BSTnode{
   int key;
   struct BSTnode *left;
   struct BSTnode *right;
} BSTnode;

BSTnode *create(){
   BSTnode *temp;
   printf("\nEnter key: ");
   temp = (BSTnode*)malloc(sizeof(BSTnode));
   scanf("%d", &temp->key);
   temp->left = temp->right = NULL;
   return temp;
}
```

Codes for Binary Search Trees

```
void insert(BSTnode *root, BSTnode *temp){
  if(temp->key < root->key){
     if(root->left!= NULL)
        insert(root->left, temp);
     else
        root->left = temp;
  if(temp->key > root->key){
     if(root->right!= NULL)
        insert(root->right, temp);
        root->right = temp;
} }
BSTnode *minValueNode(BSTnode *node){
  BSTnode *current = node;
  while (current->left != NULL)
     current = current->left;
   return current;
}
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```

Codes for Binary Search Trees

```
BSTnode* deleteNode(BSTnode *root, int key){
  if (root == NULL) return root;
   // If the key to be deleted is smaller than the root's key, then it lies in left subtree
  if (key < root->key)
      root->left = deleteNode(root->left, key);
   // If the key to be deleted is greater than the root's key, then it lies in right subtree
  else if (key > root->key)
      root->right = deleteNode(root->right, key);
  // if key is same as root's key, then This is the node to be deleted
  else {
                 // node with only one child or no child
      if (root->left == NULL) {
         BSTnode *temp = root->right;
         free(root);
         return temp; }
      else if (root->right == NULL) {
         BSTnode *temp = root->left;
         free(root);
         return temp; }
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```

Codes for Binary Search Trees

```
// node with two children: Get the inorder successor (smallest in the right subtree)
BSTnode *temp = minValueNode(root->right);

// Copy the inorder successor's content to this node
root->key = temp->key;

// Delete the inorder successor
root->right = deleteNode(root->right, temp->key);
}
return root;
}

void inorder(BSTnode *root){
if(root!= NULL) {
   inorder(root->left);
   printf("%d", root->key);
   inorder(root->right);
}

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```

Codes for Binary Search Trees

```
int main() {
                             BSTnode *root = NULL, *temp;
  char ch;
               int item;
     temp = create();
     if(root == NULL)
        root = temp;
        insert(root, temp);
                                                                        scanf("%c", &ch);
     printf("\n Do you want to enter more(y/n)? ");
                                                          getchar();
  } while(ch=='y'|ch=='Y');
  printf("\n Inorder traversal of the tree:\t");
                                                    inorder(root);
     if(root == NULL){}
          printf("\n No key to delete!"); return 0; }
     else {
          printf("\nDelete what? ");
                                         scanf("%d", &item);
          root = deleteNode(root, item);
          printf("\nInorder traversal of the modified tree \t"); inorder(root);
     printf("\nDo you want to delete more(y/n)? ");
                                                           getchar();
                                                                          scanf("%c", &ch);
  } while(ch=='y'|ch=='Y');
return 0; }
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```