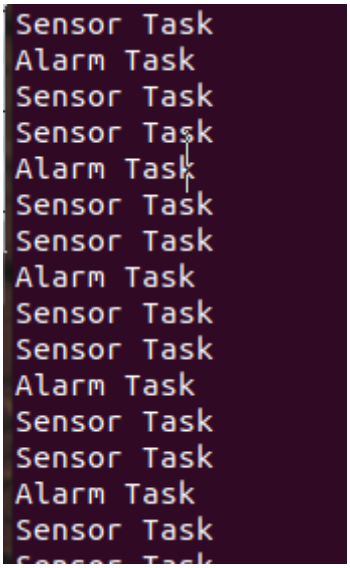
GPIO using RTOS:

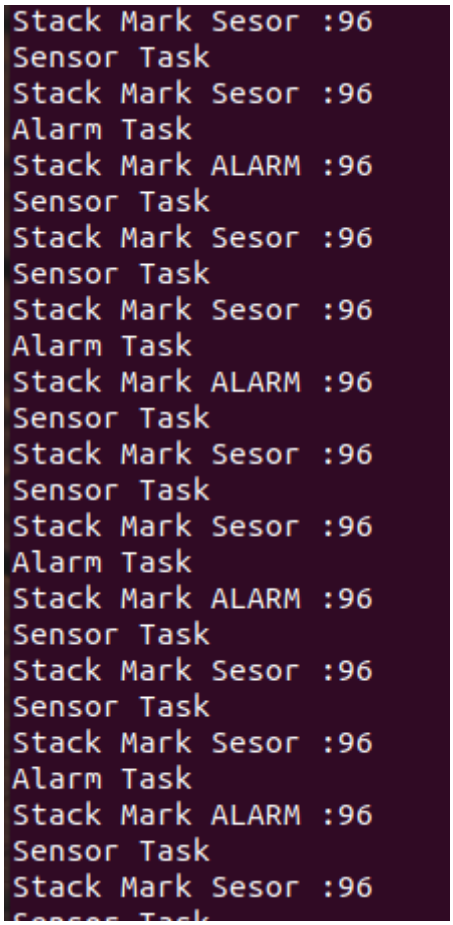
1: The below output is of two task running with same priority :



2: The 2nd image which show the Stack Mark:

API used:

```
uxTaskGetStackHighWaterMark(TaskHandle_t xTask);
```



3: The 3rd image show priority of both task:

```
uxTaskPriorityGet( TaskHandle_t xTask );
```