# CS101 Algorithms and Data Structures

Graphs
Textbook Ch B.4, B.5.1, 22.1



## Outline

- Definitions
  - Undirected graphs
  - Directed graph
- Representation
  - Adjacency matrix
  - Adjacency list

# **Undirected Graphs**

We will define an Undirected Graph ADT as a collection of *vertices* 

$$V = \{v_1, v_2, ..., v_n\}$$

The number of vertices is denoted by

$$|V| = n$$

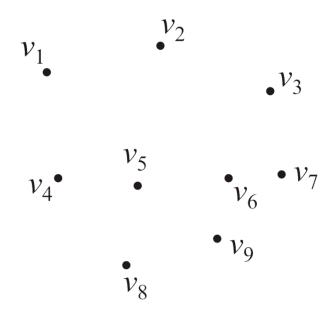
- Associated with this is a collection E of <u>unordered</u> pairs  $\{v_i, v_j\}$  termed edges which connect the vertices

# **Undirected Graphs**

Consider this collection of vertices

$$V = \{v_1, v_2, ..., v_9\}$$

where |V| = n = 9

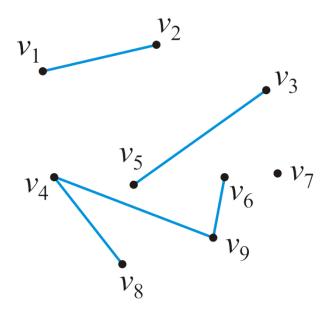


# Undirected graphs

Associated with these vertices are |E| = 5 edges

$$E = \{\{v_1, v_2\}, \{v_3, v_5\}, \{v_4, v_8\}, \{v_4, v_9\}, \{v_6, v_9\}\}$$

- The pair  $\{v_j, v_k\}$  indicates that both vertex  $v_j$  is adjacent to vertex  $v_k$  and vertex  $v_k$  is adjacent to vertex  $v_j$ 



# Undirected graphs

We will assume that a vertex is never adjacent to itself

- For example,  $\{v_1, v_1\}$  will not define an edge

The maximum number of edges in an undirected graph is

$$|E| \le {|V| \choose 2} = \frac{|V|(|V|-1)}{2} = O(|V|^2)$$

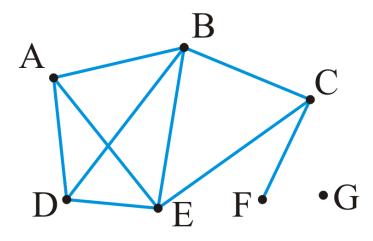
# An undirected graph

Example: given the |V| = 7 vertices

$$V = \{A, B, C, D, E, F, G\}$$

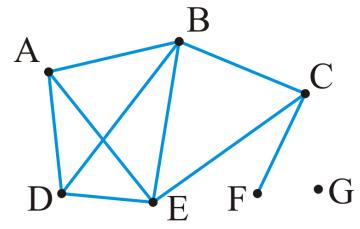
and the |E| = 9 edges

$$E = \{\{A, B\}, \{A, D\}, \{A, E\}, \{B, C\}, \{B, D\}, \{B, E\}, \{C, E\}, \{C, F\}, \{D, E\}\}\}$$



# Degree

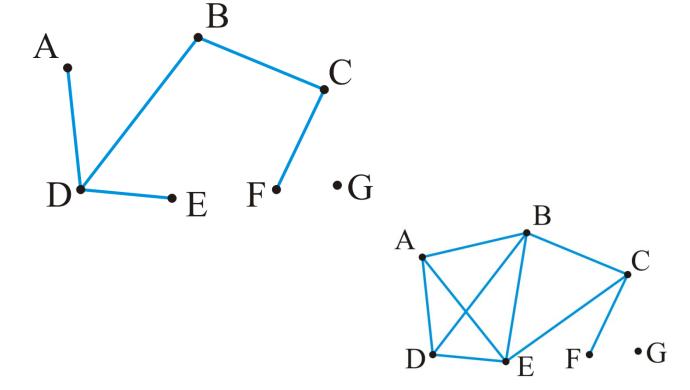
The degree of a vertex is defined as the number of adjacent vertices



Those vertices adjacent to a given vertex are its *neighbors* 

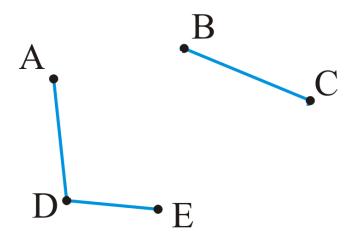
# Sub-graphs

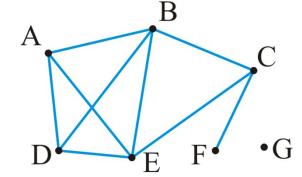
A *sub-graph* of a graph contains a *subset* of the vertices and a subset of the edges that connect the *subset* of the vertices in the original graph



# Sub-graphs

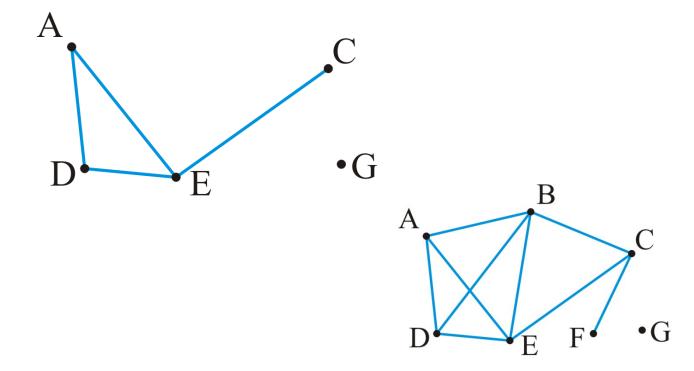
A *sub-graph* of a graph contains a subset of the vertices and a subset of the edges that connect the subset of the vertices in the original graph





# Vertex-induced sub-graphs

A *vertex-induced sub-graph* contains a subset of the vertices and all the edges in the original graph between those vertices



A path in an undirected graph is an ordered sequence of vertices

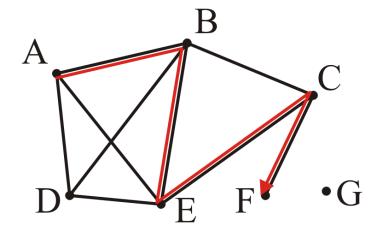
$$(v_0, v_1, v_2, ..., v_k)$$

where  $\{v_{j-1}, v_j\}$  is an edge for j = 1, ..., k

- Termed a path from  $v_0$  to  $v_k$
- The length of this path is k

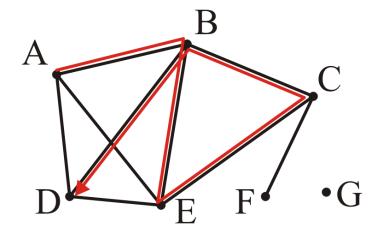
A path of length 4:

(A, B, E, C, F)



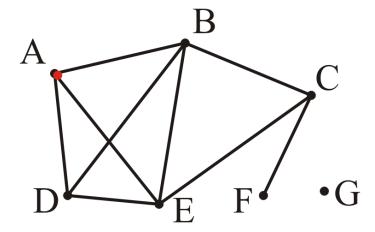
A path of length 5:

(A, B, E, C, B, D)



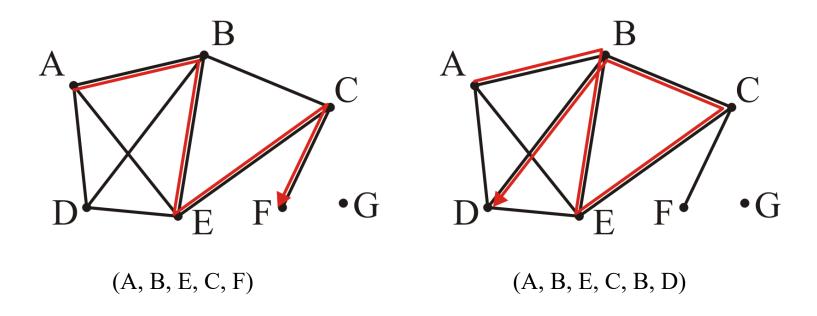
### A trivial path of length 0:

(A)



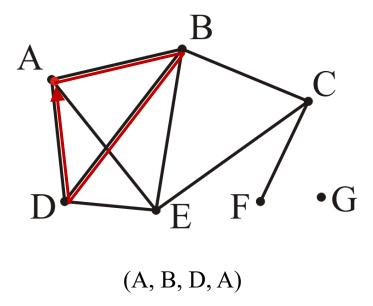
# Simple path

A simple path has no repetitions (other than perhaps the first and last vertices)



# Simple cycle

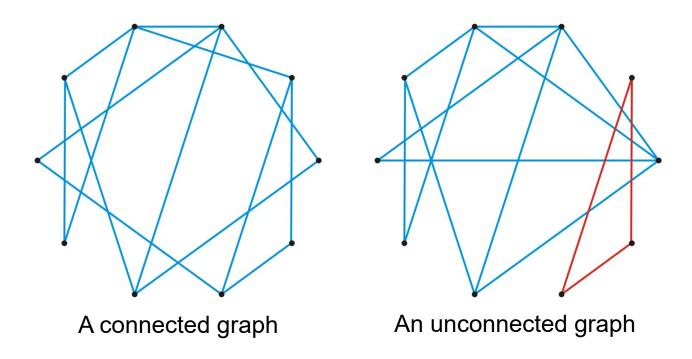
A simple cycle is a simple path of at least two vertices with the first and last vertices equal



#### Connectedness

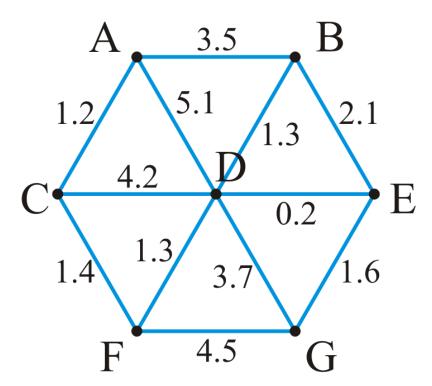
Two vertices  $v_i$ ,  $v_j$  are said to be *connected* if there exists a path from  $v_i$  to  $v_j$ 

A graph is connected if there exists a path between any two vertices



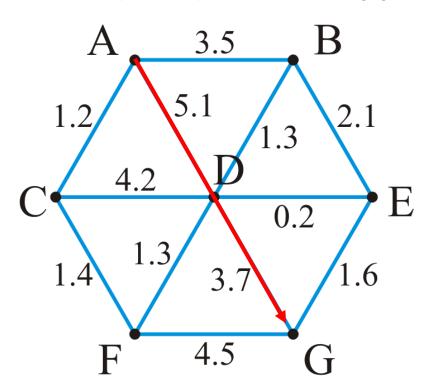
A weight may be associated with each edge in a graph

- This could represent distance, energy consumption, cost, etc.
- Such a graph is called a weighted graph



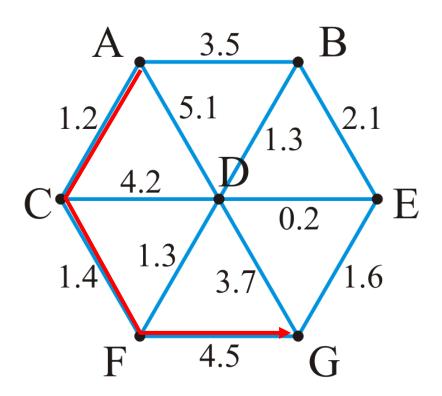
The *length* of a path within a weighted graph is the sum of all of the edges which make up the path

- The length of the path (A, D, G) in the following graph is 5.1 + 3.7 = 8.8



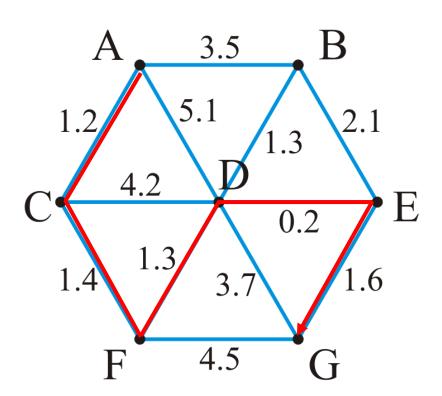
Different paths may have different weights

- Another path is (A, C, F, G) with length 1.2 + 1.4 + 4.5 = 7.1



#### Problem: find the shortest path between two vertices

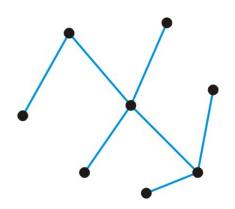
- Here, the shortest path from A to G is (A, C, F, D, E, G) with length 5.7

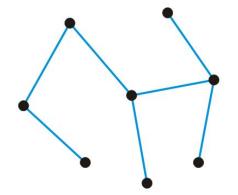


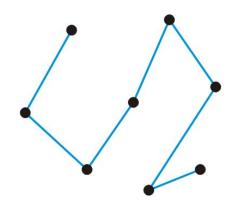
#### **Trees**

#### A graph is a tree if it is connected and there is a unique path between any two vertices

Example: three trees on the same eight vertices







#### Properties:

- The number of edges is |E| = |V| 1
- The graph is acyclic, that is, it does not contain any cycles
- Adding one more edge must create a cycle
- Removing any one edge creates two unconnected sub-graphs

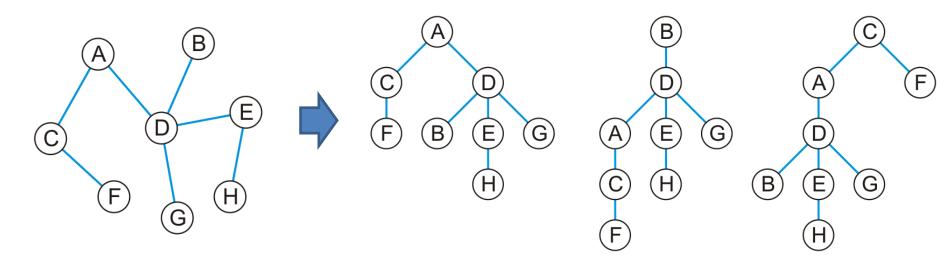
#### **Trees**

#### Any tree can be converted into a rooted tree by:

- Choosing any vertex to be the root
- Defining its neighboring vertices as its children

#### and then recursively defining:

 All neighboring vertices other than that one designated its parent to be its children



#### **Forests**

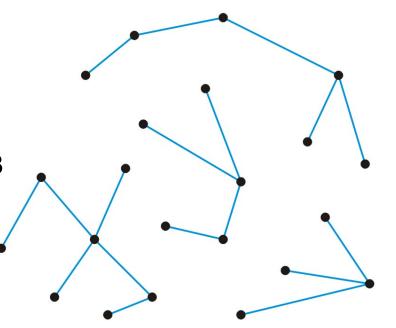
#### A forest is any graph that has no cycles

#### Consequences:

- The number of edges is |E| < |V|
- The number of trees is |V| |E|
- Removing any one edge adds one more tree to the forest

Here is a forest with 22 vertices and 18 edges

There are four trees



## Outline

- Definitions
  - Undirected graphs
  - Directed graph
- Representation
  - Adjacency matrix
  - Adjacency list

# Directed graphs

In a directed graph, the edges on a graph are be associated with a direction

- Edges are ordered pairs  $(v_j, v_k)$  denoting a connection from  $v_j$  to  $v_k$
- The edge  $(v_i, v_k)$  is different from the edge  $(v_k, v_i)$

#### Streets are directed graphs:

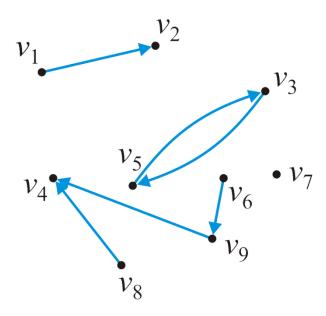
In most cases, you can go two ways unless it is a one-way street

# Directed graphs

Given a graph of nine vertices  $V = \{v_1, v_2, ... v_9\}$ 

- These six pairs  $(v_j, v_k)$  are directed edges

$$E = \{(v_1, v_2), (v_3, v_5), (v_5, v_3), (v_6, v_9), (v_8, v_4), (v_9, v_4)\}$$



# Directed graphs

The maximum number of directed edges in a directed graph is

$$|E| \le 2 \binom{|V|}{2} = 2 \frac{|V|(|V|-1)}{2} = |V|(|V|-1) = O(|V|^2)$$

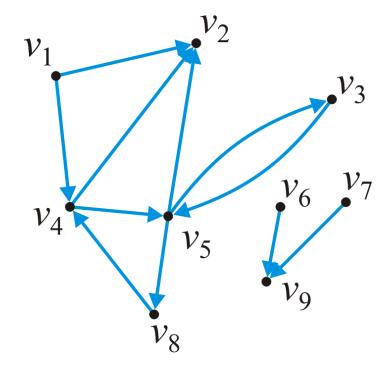
# In and out degrees

#### The degree of a vertex in a directed graph:

- The out-degree of a vertex is the number of outward edges from the vertex
- The *in-degree* of a vertex is the number of inward edges to the vertex

#### In this graph:

in\_degree
$$(v_1) = 0$$
 out\_degree $(v_1) = 2$   
in\_degree $(v_5) = 2$  out\_degree $(v_5) = 3$ 



#### Sources and sinks

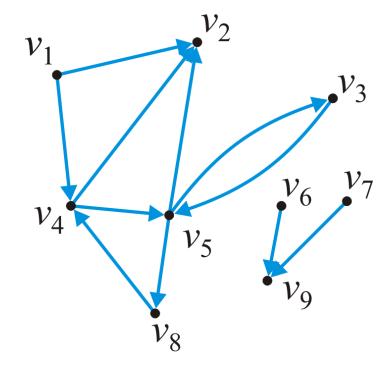
#### **Definitions:**

- Vertices with an in-degree of zero are described as sources
- Vertices with an out-degree of zero are described as sinks

#### In this graph:

- Sources:  $v_1$ ,  $v_6$ ,  $v_7$ 

- Sinks:  $v_2, v_9$ 



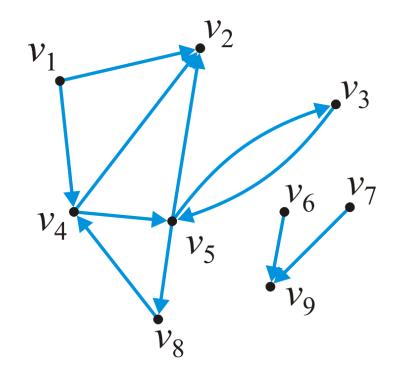
A path in a directed graph is an ordered sequence of vertices

$$(v_0, v_1, v_2, ..., v_k)$$

where  $(v_{j-1}, v_j)$  is an edge for j = 1, ..., k

A path of length 5 in this graph is  $(v_1, v_4, v_5, v_3, v_5, v_2)$ 

A simple cycle of length 3 is  $(v_8, v_4, v_5, v_8)$ 



#### Connectedness

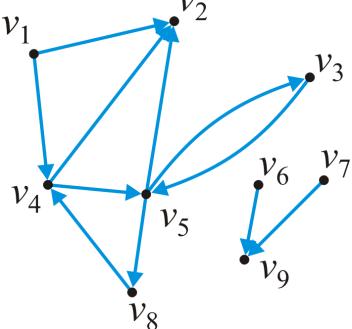
Two vertices  $v_j$ ,  $v_k$  are said to be *connected* if there exists a path from  $v_j$  to  $v_k$ 

 A graph is strongly connected if there exists a directed path between any two vertices

- A graph is *weakly connected* there exists a path between any two vertices that ignores the direction  $v_2$ 

#### In this graph:

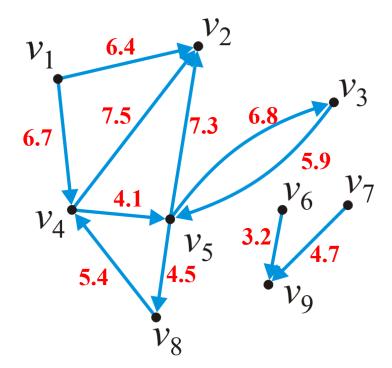
- The sub-graph  $\{v_3, v_4, v_5, v_8\}$  is strongly connected
- The sub-graph {v<sub>1</sub>, v<sub>2</sub>, v<sub>3</sub>, v<sub>4</sub>, v<sub>5</sub>, v<sub>8</sub>} is weakly connected



# Weighted directed graphs

In a weighted directed graphs, each edge is associated with a value

If both  $(v_j, v_k)$  and  $(v_k, v_j)$  are edges, it is not required that they have the same weight



## Outline

- Definitions
  - Undirected graphs
  - Directed graph
- Representation
  - Adjacency matrix
  - Adjacency list

# The Graph ADT

The Graph ADT describes a container storing an adjacency relation

- Queries include:
  - The number of vertices
  - The number of edges
  - List the vertices adjacent to a given vertex
  - Are two vertices adjacent?
  - Are two vertices connected?
- Modifications include:
  - Inserting or removing an edge
  - Inserting or removing a vertex (and all edges containing that vertex)

The run-time of these operations will depend on the representation

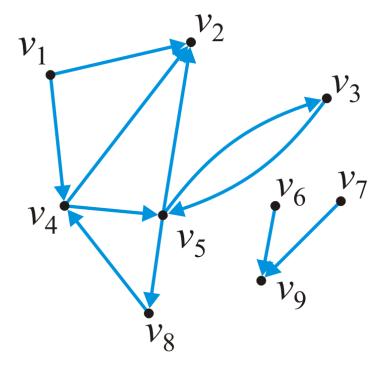
### Binary-relation list

#### The most inefficient is a relation list:

A container storing the edges

$$\{(1, 2), (1, 4), (3, 5), (4, 2), (4, 5), (5, 2), (5, 3), (5, 8), (6, 9), (7, 9), (8, 4)\}$$

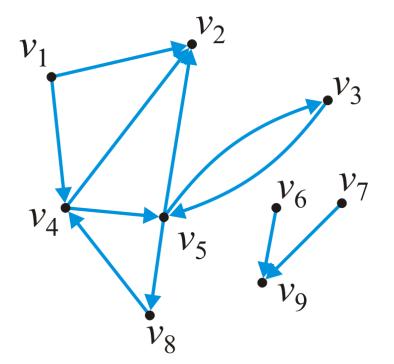
- Requires  $\Theta(|E|)$  memory
- Determining if  $v_j$  is adjacent to  $v_k$  is O(|E|)
- Finding all neighbors of  $v_j$  is  $\Theta(|E|)$



Requiring more memory but also faster, an adjacency matrix

- The matrix entry (j, k) is set to true if there is an edge  $(v_j, v_k)$ 

	1	2	3	4	5	6	7	8	9
1		T		T					
2									
3					T				
4		T			T				
5		T	T					T	
6									T
7									T
8 9	Requires $\Theta( V ^2)$ memory								
_	Determining if $v_j$ is adjacent to $v_k$ is $O(1)$								
_	– Finding all neighbors of $v_i$ is $\Theta( V )$								



Most efficient for algorithms is an adjacency list

Each vertex is associated with a list of its neighbors

$$1 \quad \bullet \to 2 \to 4$$

$$\begin{array}{ccc} 2 & \bullet \\ 3 & \bullet \rightarrow 5 \end{array}$$

$$4 \cdot \rightarrow 2 \rightarrow 5$$

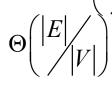
$$5 \rightarrow 2 \rightarrow 3 \rightarrow 8$$

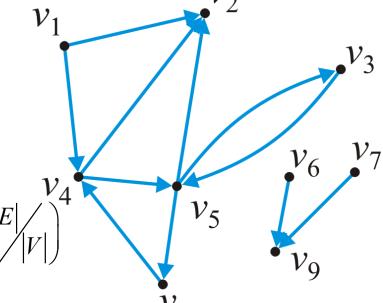
$$6 \rightarrow 9$$

$$7 \cdot \rightarrow 9$$

$$8 \cdot \rightarrow 4$$

- Requires  $\Theta(|V| + |E|)$  memory
- On average:
  - Determining if  $v_i$  is adjacent to  $v_k$  is
  - Finding all neighbors of  $v_j$  is





A graph of *n* vertices may have up to

$$\binom{n}{2} = \frac{n(n-1)}{2} = \mathbf{O}(n^2)$$

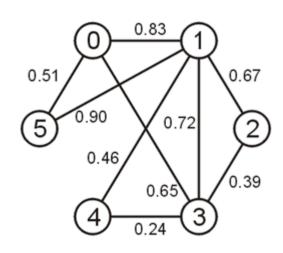
edges

The first straight-forward implementation is an adjacency matrix

Define an  $n \times n$  matrix  $\mathbf{A} = (a_{ij})$  and if the vertices  $v_i$  and  $v_j$  are connected with weight w, then set  $a_{ij} = w$  and  $a_{ji} = w$ 

That is, the matrix is symmetric, e.g.,

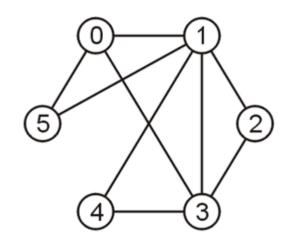
	0	1	2	3	4	5
0		0.83		0.65		0.51
1	0.83		0.67	0.72	0.46	0.90
2		0.67		0.39		
3	0.65	0.72	0.39		0.24	
4		0.46		0.24		
5	0.51	0.90				



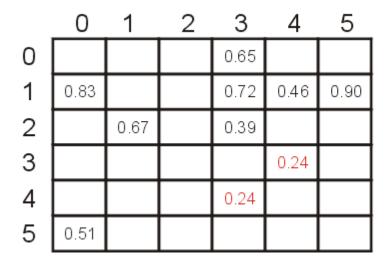
An unweighted graph may be saved as an array of Boolean values

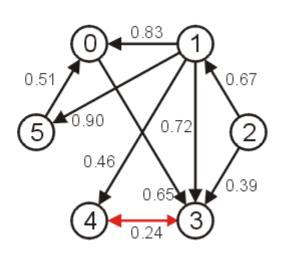
- vertices  $v_i$  and  $v_j$  are connected then set  $a_{ij} = a_{ji} = true$ 

	0	1	2	3	4	5
0		Т	F	Т	F	Т
1	Т		Т	Т	Т	Т
2	F	Т		Т	F	F
2	Т	Т	Т		Т	F
4	F	Т	F	Т		F
5	Т	Т	F	F	F	



If the graph was directed, then the matrix would not necessarily be symmetric





### **Default Values**

Question: what do we do about vertices which are not connected?

- the value 0
- a negative number, e.g., -1
- positive infinity: ∞

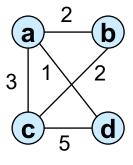
The last is the most logical, in that it makes sense that two vertices which are not connected have an infinite distance between them

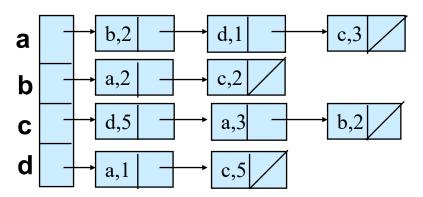
The distance from a node to itself is 0

### **Sparse Matrices**

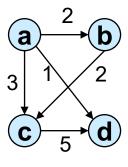
- The memory required for creating an  $n \times n$  matrix using a 2D array is  $\Theta(n^2)$  bytes
- This could potentially waste a significant amount of memory:
  - Consider a friendship graph: nodes represent persons and edges represent friendship
  - − The world population is 7.4 billion => the size of the matrix is  $(7.4 \times 10^9)^2$  ≈  $55 \times 10^{18}$
  - However, each person on average has, say, 100 friends. Hence only  $\frac{100}{7.4\times10^9}$  of the matrix elements are true. The other elements are the default value: false.

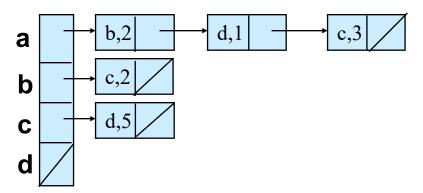
- For an undirected graph, use an array of linked lists to store edges
  - Each vertex has a linked list that stores all the edges connected to the vertex
  - Each node in a linked list must store two items of information: the connecting vertex and the weight





- To store a directed graph
  - Each vertex has a linked list that stores all the edges originated from the vertex
  - Each node in a linked list stores two items of information: the vertex that the edge connects to, the weight





### Summary

- Definitions
  - Undirected graphs
  - Directed graph
- Representation
  - Adjacency matrix
  - Adjacency list