view_frames Result Recorded at time: 26.088 jetbot/odom Broadcaster: /gazebo Average rate: 11.000 Hz Most recent transform: 25.996 (0.092 sec old) Buffer length: 1.000 sec jetbot/chassis Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Broadcaster: /robot/robot_state_publisher Average rate: 25.926 Hz Average rate: 10000.000 Hz Average rate: 25.926 Hz Most recent transform: 0.000 (26.088 sec old) Most recent transform: 26.083 (0.005 sec old) Most recent transform: 26.083 (0.005 sec old) Buffer length: 0.000 sec Buffer length: 1.080 sec Buffer length: 1.080 sec jetbot/camera_link jetbot/left_wheel jetbot/right_wheel Broadcaster: /robot/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (26.088 sec old) Buffer length: 0.000 sec

jetbot/camera_link_optical