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♠ TaoChenOSU

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## **EDUCATION**

#### University of Southern California

Master of Computer Science in Intelligence Robotics

# **Oregon State University**

Bachelor of Computer Science in Computer System

Los Angeles, CA

August 2017 - May 2019

Corvallis, OR

September 2014 - June 2017

# **KEY SKILLS**

- o Programming Languages: Python, C++, C, Bash Script, Java
- Frameworks & Libraries: TensorFlow, boost, OpenAI, Garage
- o Web Development: AWS, HTML, CSS, PHP, JavaScript, Node.js, jQuery, AngularJS, XML
- o Robotics: ROS, Gazebo, Sensor fusion, State estimation, CAD design, 3D Printing
- o Artificial Intelligence: Machine Learning, Reinforcement Learning, Natural Language Processing
- Systems/Tools: LATEX, Git
- o Communication: English, Mandarin, Cantonese

# **WORK & RESEARCH EXPERIENCE**

#### Robotic Embedded Systems Laboratory (RESL)

Los Angeles, CA May 2018 - Present

Research Assistant

- Conducted research on applying reinforcement learning techniques to quadrotor controls.
- o Implemented imitation learning pipeline with TensorFlow.
- o Implemented neural network controllers in ROS and Gazebo simulator to analyze performance.
- o Implemented software framework to covert TensorFlow graph to run on STM32 micro-controllers.
- o Improved realism of our customized flight simulator written in Python.
- Co-authored a paper accepted to IROS 2019 (see "Publications").

# **Dynamic Robotics Laboratory**

Corvallis, OR

Intern

*May 2016 - September 2016* 

- Participated in the development of the bipedal robot Cassie.
- Customized a communication protocol on top of MAVLINK to transfer telemetry data between the robot and the remote control.
- Customized a user interface written in Lua on the remote controller to display the robot's status, e.g. robot pose, temperature, battery, etc.

#### Media Service, Oregon State University

Corvallis, OR

Student Worker

October 2015 - June 2017

- Resolved urgent technical issues affecting presentation devices (e.g. computers, projectors, lecture capturing, and stage control) that occurred during lectures and special events.
- o Maintained and built classroom presentation technologies for the entire campus.

#### **PROJECTS**

Stock Quote Website and Android App

September 2017 - December 2017

- o Goal: create a dynamic website that displays real-time stock quotes in user-defined watch list, and an Android App that has similar behavior.
- o Developed the website with responsive design using AngularJS, Bootstrap, and React.
- Used Node.js on AWS Beanstalk backend as a portal for REST APIs.
- Used Ajax techniques to create asynchronous web applications.

**Autonomous RC** September 2016 - May 2017

- o Goal: build an RC car platform capable of autonomous driving using cheap hardware.
- Worked in a team of 3 and led the software development in simulation using ROS and Gazebo/Stage.
- o Used ROS packages AMCL for localization and Teb\_local\_planner for planning within the ROS navigation stack.
- Selected to present in front of the engineering college and industry partners of the school.
- Won the best project of the year award.

**Kaggle Competition** March 2017

- o Goal: train a machine learning model to tell if two Quora questions are semantically identical.
- o Built the pipeline for data preparation and feature extraction in Python with NumPy.
- Trained a classification model using logistic regression in TensorFlow.
- o Experimented with text processing techniques such as word filtering, part-of-speech tagging, language modeling using recurrent neural network, and word embedding, etc.
- Beat 70% of the competitors.

## **PUBLICATIONS**

Artem Molchanov\*, Tao Chen\*, Wolfgang Hönig, James A. Preiss, Nora Ayanian and Gaurav S. Sukhatme, "Sim-to-(Multi)-Real: Transfer of Low-Level Robust Control Policies to Multiple Quadrotors", International Conference on Intelligent Robots and Systems, 2019. (\* equal contribution)

# AWARDS AND ACHIEVEMENTS

Winner, Capstone project, Oregon State University	2017
College of Engineering Scholarship, Oregon State University	2016 & 2017
Spotlight presenter at the Southern California Robotics Symposium	2019
Master's Best Research Award, USC	2019

## **Hobbies**

# Things I like @ Anywhere Programming, Building robots, Playing with LEGOs

Forever

- Listening to music, Playing guitar, Watching movies
- o Swimming, Running, Skiing