

Staochenosu.github.io

☑ taotaochen95@hotmail.com

TaoChenOSU

541-829-8140

EDUCATION

University of Southern California

Los Angeles, CA

Master of Computer Science in Intelligence Robotics, GPA: 3.6

August 2017 - May 2019

Oregon State University

Corvallis, OR

Bachelor of Computer Science in Computer Systems, GPA: 3.8

September 2014 - June 2017

WORK & RESEARCH EXPERIENCE

Xpeng Motors/Xsense.ai

San Diego, CA

Software Engineer

Dec 2019 - Present

- o Develop and evaluate multi-object tracking sensor fusion algorithms for ADAS on production vehicles equipped with radars and cameras.
- o Developed a 3D real-time visualization tool. Gained adaption and completely replaced Rviz across the company.
- o Skills: C++, Qt, OpenGL, Python, Bash Script, Docker

Robotic Embedded Systems Laboratory (RESL)

Los Angeles, CA

Research Assistant

May 2018 - Dec 2019

- Researched on applying machine learning techniques to quadrotor control problems and published papers at academic conferences.
- o Developed simulation environment and training pipelines that automatically convert neural network graphs to efficient embedded software that could run on STM32 micro-controllers.
- o Skills: Python, C++, C, TensorFlow, OpenAI, ROS, Gazebo, Docker, Boost, LATEX

Dynamic Robotics Laboratory

Corvallis, OR

Intern

May 2016 - September 2016

- o Participated in the development of the bipedal robot Cassie that became widely used in the research community.
- o Implemented a communication protocol to reliably transfer telemetry data between the robot and the remote control. Customized a user interface on the remote controller to display the robot's status, e.g. robot pose, temperature, battery etc.
- o Skills: C, C++, Python, MAVLINK, Lua, Bash Script

PROJECTS

Autonomous RC

September 2016 - June 2017

- o Led the software development in a team of 3 to build a RC car platform capable of autonomous driving using open source software and cheap hardware (< \$2000). Aimed to reduce the cost of building small self-driving car platforms for hobbyists.
- o Selected to present in front of the engineering school board of trustees and won the best computer science project of the year.
- o Skills: C++, Python, ROS, Stage, AMCL, Teb_local_planner, LIDAR, IMU

PUBLICATIONS

Artem Molchanov*, Tao Chen*, Wolfgang Hönig, James A. Preiss, Nora Ayanian and Gaurav S. Sukhatme, "Sim-to-(Multi)-Real: Transfer of Low-Level Robust Control Policies to Multiple Quadrotors", International Conference on Intelligent Robots and Systems, 2019.

(* equal contribution)

AWARDS AND ACHIEVEMENTS

Honor Roll, Oregon State University	2015 & 2016 & 2017
Winner, Capstone project, Oregon State University	2017
College of Engineering Scholarship, Oregon State University	2016 & 2017
Spotlight presenter, Southern California Robotics Symposium	2019
Master's Best Research Award, USC	2019

Hobbies

Things I like @ Anywhere