Quaternion

+ s
+ v

+ Quaternion()
+ Quaternion()
+ Conjugate()
+ netswap()
+ Magnitude()
+ operator*()
+ operator*=()
+ Normalize()
+ to_matrix()
+ from_vectors()
+ from_axis_angle()

#OA
#OB

Prediction

A0
B
A1
A2
A3
VA
VB
AA
AB
deltatime

+ Prediction()
+ ~Prediction()
+ InitInterpolation()
+ InterpolatePosition()
+ InterpolateOrientation()
+ Interpolate()