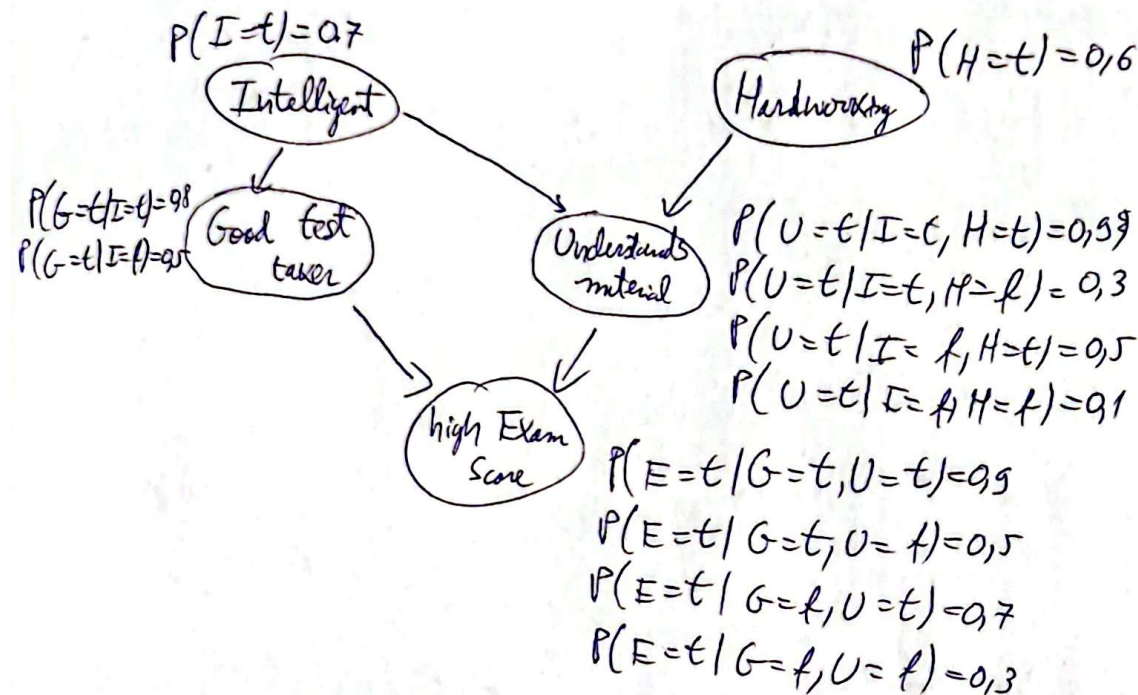


Problem 1



a) $\# P(I=t|E=t)$

Using Bayes' theorem $\Rightarrow P(I=t|E=t) = \frac{P(E=t|I=t) \cdot P(I=t)}{P(E=t)}$

$$P(E=t) = \sum_{I, G, U, H} P(E=t|G, U) \cdot P(G|I) \cdot P(U|I, H) \cdot P(H)$$

Total probability

$$= P(E=t|I=t) \cdot P(I=t) + P(E=t|I=f) \cdot P(I=f)$$

For $P(E=t|I=t)$:

$$P(E=t|I=t) = \sum_{G, U} P(E=t|G, U) \cdot P(G|I) \cdot P(U|I)$$

$\Rightarrow P(G|I=t): P(G=t|I=t) = 0,8 \Rightarrow P(G=f|I=t) = 0,2$

$\Rightarrow P(U|I=t):$

$$\begin{cases} P(U=t|I=t, H=t) = 0,99 \\ P(U=t|I=t, H=f) = 0,3 \end{cases}$$

$H \perp I \Rightarrow P(U=t|I=t) =$

$$P(U=t|I=t) = P(U=t|I=t, H=t)P(H=t) + P(U=t|I=t, H=f)P(H=f)$$

$$= 0,99 \cdot 0,6 + 0,3 \cdot 0,4 = 0,594 + 0,12 = 0,714$$

$\Rightarrow P(U=f|I=t) = 1 - P(U=t|I=t) = 1 - 0,714 = 0,286$

$$\rightarrow P(E=t | I=t) = \sum_{G,U} P(E=t | G,U) \cdot P(G | I=t) \cdot P(U | I=t)$$

$$\Rightarrow \begin{cases} P(E=t | G=t, U=t) \cdot P(G=t | I=t) \cdot P(U=t | I=t) = 0.9 \cdot 0.8 \cdot 0.74 = 0.5328 \\ P(E=t | G=t, U=f) \cdot P(G=t | I=t) \cdot P(U=f | I=t) = 0.5 \cdot 0.8 \cdot 0.26 = 0.104 \\ P(E=t | G=f, U=t) \cdot P(G=f | I=t) \cdot P(U=t | I=t) = 0.7 \cdot 0.2 \cdot 0.74 = 0.1036 \\ P(E=t | G=f, U=f) \cdot P(G=f | I=t) \cdot P(U=f | I=t) = 0.3 \cdot 0.2 \cdot 0.26 = 0.0156 \end{cases}$$

$$\Rightarrow \underline{P(E=t | I=t)} = 0.5328 + 0.104 + 0.1036 + 0.0156 = \underline{0.756}$$

For $P(E=t | I=f)$:

$$\begin{aligned} \rightarrow P(G | I=f): & P(G=t | I=f) = 0.5 \Rightarrow P(G=f | I=f) = 0.5 \\ \rightarrow P(U | I=f): & \begin{cases} P(U=t | I=f, H=t) = 0.5 \\ P(U=t | I=f, H=f) = 0.1 \end{cases} \Rightarrow P(U=t | I=f) = 0.5 \cdot 0.6 + 0.1 \cdot 0.5 = 0.34 \end{aligned}$$

$$\Rightarrow \underline{P(U=f | I=f)} = 1 - P(U=t | I=f) = 1 - 0.34 = \underline{0.66}$$

$$\rightarrow P(E=t | I=f) = \sum_{G,U} P(E=t | G,U) \cdot P(G | I=f) \cdot P(U | I=f)$$

$$\Rightarrow \begin{cases} P(E=t | G=t, U=t) \cdot P(G=t | I=f) \cdot P(U=t | I=f) = 0.9 \cdot 0.5 \cdot 0.34 = 0.153 \\ P(E=t | G=t, U=f) \cdot P(G=t | I=f) \cdot P(U=f | I=f) = 0.5 \cdot 0.5 \cdot 0.66 = 0.165 \\ P(E=t | G=f, U=t) \cdot P(G=f | I=f) \cdot P(U=t | I=f) = 0.7 \cdot 0.5 \cdot 0.34 = 0.119 \\ P(E=t | G=f, U=f) \cdot P(G=f | I=f) \cdot P(U=f | I=f) = 0.3 \cdot 0.5 \cdot 0.66 = 0.099 \end{cases}$$

$$\Rightarrow \underline{P(E=t | I=f)} = 0.153 + 0.165 + 0.119 + 0.099 = \underline{0.536}$$

$$\begin{aligned} P(E=t) &= P(E=t | I=t) \cdot P(I=t) + P(E=t | I=f) \cdot P(I=f) \\ &= 0.756 \cdot 0.7 + 0.536 \cdot 0.3 \\ &= 0.5292 + 0.1608 = 0.69 \end{aligned}$$

$$P(I=t | E=t) = \frac{P(E=t | I=t) \cdot P(I=t)}{P(E=t)} = \frac{0.756 \cdot 0.7}{0.69} \approx 0.767$$

b) Using the code from lab 5 it gives me 0.756052

c) • G and U are independent \rightarrow False

$$G \leftarrow I \rightarrow U$$

Common cause:
Case Since I is not conditioned, the path is active meaning G ~~is~~ and U are not independent

• G and U are conditionally independent given I, E and H \rightarrow True

$$G \leftarrow I \rightarrow U$$

Common cause:
Case Now I is conditioned \Rightarrow blocks the dependency between G and U

$$\Rightarrow G \perp U \mid I, E, H$$

• G and U are conditionally independent given I and H \rightarrow True

$$G \leftarrow I \rightarrow U$$

Common cause:
Case The additional conditioning on H doesn't create any active paths between G and U $\Rightarrow G \perp U \mid I, H$

• E and H are conditionally independent given U \rightarrow ~~True~~ False

$$H \rightarrow U \rightarrow E$$

Causal chain:
Case Conditioning on U blocks the path between H and E, as H is part of the causal chain $\Rightarrow E \not\perp H \mid U$

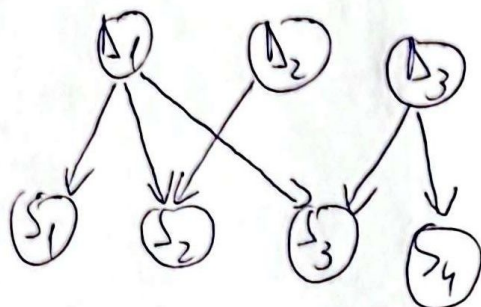
• E and H are conditionally independent given U, I and G \rightarrow True

$$H \rightarrow U \rightarrow E$$

Causal chain:
Case Given U, I and G all paths between H and E are blocked $\Rightarrow E \perp H \mid U, I, G$

• Problem 2

a)



b)

Δ_1 , Δ_2 and Δ_3 don't require cpds, but for:

$S_1 \rightarrow$ it has 1 parent (Δ_1) \Rightarrow a cpd table of 2 entries ($\Delta_1 = \text{true/false}$) and 1 output

$S_2 \rightarrow$ it has 2 parents (Δ_1 and Δ_2) \Rightarrow a table of 4 entries ($\Delta_1 = \text{true/false}$, $\Delta_2 = \text{true/false}$) and 1 output

$S_3 \rightarrow$ it has 2 parents (Δ_1 and Δ_3) \Rightarrow a table of 4 entries ($\Delta_1 = \text{true/false}$, $\Delta_3 = \text{true/false}$) and 1 output

$S_4 \rightarrow$ it has 1 parent (Δ_3) \Rightarrow a table of 2 entries ($\Delta_3 = \text{true/false}$) and 1 output

$$\Rightarrow \text{Total \# of parameters} = 3 (\text{marginal probs. for } \Delta_1, \Delta_2, \Delta_3) + 2 (\text{for } S_1) + 4 (\text{for } S_2) + 4 (\text{for } S_3) + 2 (\text{for } S_4) = 15$$

c) If there would be no conditional independence we would have to compute probabilities for all possible combinations of variables

$$\Rightarrow 2^7 - 1 = 127 \text{ parameters}$$

d) The markov blanket for S_2 :

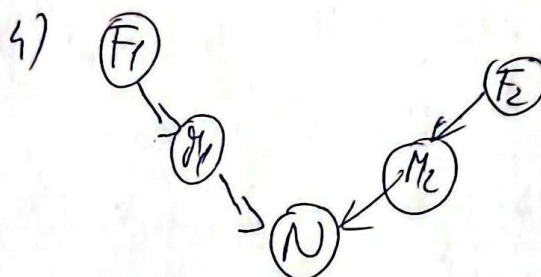
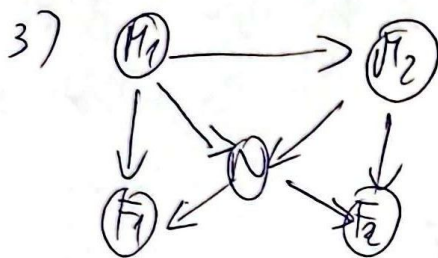
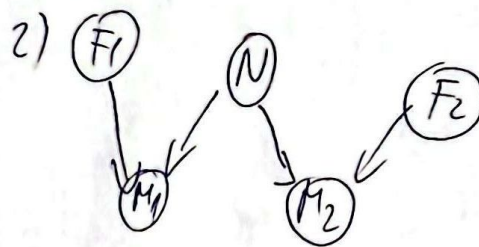
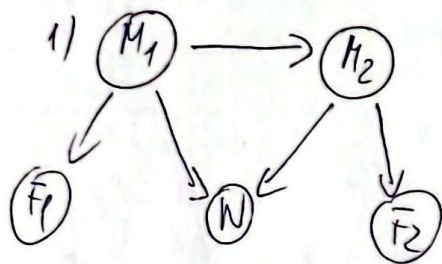
\rightarrow The parents of S_2 : $\{\Delta_1, \Delta_2\}$

\rightarrow The children of S_2 : $\{\emptyset\}$

\rightarrow Other parents of its children: $\{\emptyset\}$

$$\Rightarrow \text{The markov blanket of } S_2 = \{\Delta_1, \Delta_2\}$$

Problem 3:



- Variable N is measured using M_1 and M_2
- M_1 and M_2 measurements depend on whether the telescope is out of focus (F_1 and F_2)
- $M_1 \perp M_2 \mid N$ and F_1 is independent of F_2

a) The first one represents the information wrong, as there's a direct edge between M_1 and M_2 . This suggests that the 2 measurements influence each other, which is false, as the error in one measurement impacts directly only the corresponding measurement.

The second one is correct as N influences both M_1 and M_2 , and these measurements are directly affected only by their corresponding error (F_1 for M_1) (F_2 for M_2)

The third one is similar to the first one, but it also adds edges between N and F_1 and F_2 . Even though M_1 and M_2 are connected correctly to their errors F_1 and F_2 , there appears to be the same problem, as there's a direct edge between M_1 and M_2 . Also, it doesn't respect the relation $M_1 \perp M_2 \mid N$, as the N generates the number of stars captured by each measurement M_1 and M_2 .

The fourth diagram represents the information correctly, as F_1 affects M_1 , F_2 affects M_2 and N influences both M_1 and M_2 .

b) The best network out of the 4 examples is the 4th one as it has a hierarchical structure that's clear: the main value N influences directly the 2 measurements M_1 and M_2 and the errors of the telescopes F_1 and F_2 are directly linked to their measurements M_1 and M_2 . Even though, both the 2nd and 4th networks are representing correctly the conditional independence $M_1 \perp M_2 \mid N$, it's clearer in the 4th one as there are not any useless edges used, making it more easier to read. Also the 4th network uses the minimum number of edges: $(F_1 \rightarrow M_1, F_2 \rightarrow M_2, M_1 \rightarrow N, M_2 \rightarrow N)$ also the 2nd one does but it isn't as clear to see from the network that the main component N creates a V-shape ($M_1 \leftarrow N \rightarrow M_2$) displaying that M_1 and M_2 are ~~can~~ not connected directly, but by N .