

Lab Instructions - session 2

Linear Combination, Span, Basis

Drawing 3D vectors

To draw 3D objects first add these three lines after importing matplotlib:

```
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
```

A vector can be plotted either as a *point* or an *arrow*. To plot a set of 3D points you can use the `scatter` function.

`plot1.py`

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

# plot multiple points
u = np.array([1,2,3])
v = np.array([2, 0, -2])
w = np.array([-1, -1, -1])

xs = [u[0], v[0], w[0]]
ys = [u[1], v[1], w[1]]
zs = [u[2], v[2], w[2]]

ax.scatter(xs, ys, zs)
plt.show()
```

To plot an arrow you may use the `quiver` function:

`plot2.py`

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

# plot multiple points
u = np.array([1,2,3])
v = np.array([2, 0, -2])
w = np.array([-1, -1, -1])

xs = [u[0], v[0], w[0]]
ys = [u[1], v[1], w[1]]
zs = [u[2], v[2], w[2]]

# base of the vectors set to the origin
tail_x = [0,0,0]
tail_y = [0,0,0]
tail_z = [0,0,0]

ax.set_xlim(-3,3)
ax.set_ylim(-3,3)
ax.set_zlim(-3,3)

ax.quiver(tail_x, tail_y, tail_z, xs, ys, zs, color='r')
plt.show()
```

- Rotate the plot to view it from different angles. Do you think \mathbf{u} , \mathbf{v} and \mathbf{w} are linearly dependent? If yes, how can you write one of them as a linear combination of the others?

Linear combination/span

The following code generates 2 random scalars \mathbf{a} and \mathbf{b} using the `numpy.random.rand` function and plots the linear combination $\mathbf{w} = \mathbf{a} \mathbf{u} + \mathbf{b} \mathbf{v}$ of the vectors \mathbf{u} and \mathbf{v} .

`plot3.py`

```
import numpy as np
```

```
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

# plot multiple points
u = np.array([1,2,3])
v = np.array([2, 0, -2])

xs = [u[0], v[0]]
ys = [u[1], v[1]]
zs = [u[2], v[2]]

# base of the vectors set to the origin
tail_x = [0,0]
tail_y = [0,0]
tail_z = [0,0]

ax.set_xlim(-3,3)
ax.set_ylim(-3,3)
ax.set_zlim(-3,3)

ax.quiver(tail_x, tail_y, tail_z, xs, ys, zs, color='r')

a,b = np.random.rand(2)
w = a * u + b * v
ax.scatter(w[0], w[1], w[2], color='b')

plt.show()
```

- Change the code to repeat plotting the linear combination w 200 times. This can be done by putting the following three lines in a loop:

```
a,b = np.random.rand(2)
w = a * u + b * v
ax.scatter(w[0], w[1], w[2], color='b')
```

- Notice that the plotted points are in $\text{span}(u,v)$. Rotate the plot to see this. Why is the shape of the scatter like that? Notice that the function `numpy.random.rand` generates random samples in the interval $[0,1]$.
- Replace the function `numpy.random.rand` with `numpy.random.randn`. What happens? and why?

Animating a plot

Run the following piece of code. What does it do?

```
plot4.py
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# %matplotlib

fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

u = np.array([1,2,3])
v = np.array([2.0, 0, -2])

rng = np.linspace(0,1,20)

for alpha in rng:
    w = (1-alpha) * u + alpha * v

    ax.set_xlim(-4,4)
    ax.set_ylim(-4,4)
    ax.set_zlim(-4,4)

    ax.quiver(0,0,0, u[0], u[1], u[2], color='r')
    ax.quiver(0,0,0, v[0], v[1], v[2], color='r')

    ax.quiver(0,0,0, w[0], w[1], w[2], color='b')
    ax.scatter(w[0], w[1], w[2], color='b')

plt.show()
```

- Rotate the plot to observe it from different angles.
- Add the following lines at the end of the body of the `for` loop. What happens?

```
plt.draw()
plt.pause(.1)
* (if using Jupyter notebook, uncomment %matplotlib in the above
to see the output correctly.)
```

- A linear combination $w = a \mathbf{u} + b \mathbf{v}$ of two vectors \mathbf{u} and \mathbf{v} is an **affine** combination if $a + b = 1$. It is also called a **convex** combination if $a, b \geq 0$ in addition to $a + b = 1$. Are the vectors w created here are affine combinations of \mathbf{u} and \mathbf{v} ? Are they also convex combinations?

- Change `np.linspace(0,1,20)` to `np.linspace(-0.5,1.5,20)`.
 - How does the plot change and why?
 - Are all the vectors **w** still affine combinations of **u** and **v**?
 - What about convex combinations?
- Add `ax.cla()` at the beginning of the `for` loop (`cla` stands for **clear axis**).
What happens?

Shape models

A "**shape**" can be represented as an ordered or unordered set of points. Here, we represent a shape consisting of **n** points by an **n by 2** matrix, each row of which represents a point.

The following code creates a pair of 2D shapes and plots them:

`shape1.py`

```
import numpy as np
import matplotlib.pyplot as plt

n = 11

S1 = np.vstack((-np.cos(np.linspace(0,np.pi,n)),
                 -.7+np.sin(np.linspace(0,np.pi,n)))).T

S2 = np.vstack((np.linspace(-1.2,1.2,n),
                 np.zeros(n))).T

print(S1.shape)
print(S2.shape)

plt.plot(S1[:,0], S1[:,1], 'bo-')
plt.plot(S2[:,0], S2[:,1], 'ro-')

plt.axis('equal')
plt.xlim(-2,2)
plt.ylim(-2,2)

plt.show()
```

- What are the shapes (dimensions) of **s1** and **s2**?

Shapes, as defined above, form a vector space (can be scaled and added together).

To look at matrices as vectors, you can **vectorize** them. That is to flatten an **n x 2** shape matrix to form a vector of size **2n**. Then perform addition, scaling, or linear combination:

```
s1 = S1.ravel()
s2 = S2.ravel()
```

```
s3 = a * s1 + b * s2
s3 = s3.reshape((n,2))
```

But, since matrices are added element-wise, you may simply write:

```
s3 = a * s1 + b * s2
```

- Plot the **average** shape $s3 = 0.5 * s1 + 0.5 * s2$.

Task 1 - Shape Morphing

Use what you learned in section "**Animating a plot**" (`plt.draw`, `plt.pause`, `ax.cla`) to animate the shape $s3$ in the form of $s3 = (1-\alpha) * s1 + \alpha * s2$, by letting `alpha` range from 0 to 1 (convex combination). Use `plt.cla()` instead of `ax.cla()`.

- This is called **shape morphing**.
- Vary `alpha` from 0 to 1.5 (affine combinations). What happens?
- Try other ranges (e. g. -2 to 2). What's the output?
- Each shape has **2n** (here 22) entries. But all the shapes you see are in `span(s1,s2)`, that is, they lie in a 2-dimensional subspace of a 22-dimensional vector space.
- (Point correspondence matter) Change `-np.cos(np.linspace(0,np.pi,n))` to `np.cos(np.linspace(0,np.pi,n))` when defining `s1`. What happens? Why?

Task 2 - Face Model

A face can be represented as a shape model consisting of a set of landmark points. The code below imports three faces Face1, Face2, and Face3 and plots Face1. Plotting a face is done using the function `plot_face` defined below. The file `face_data.py` has been provided to you.

`task2a.py`

```
import matplotlib.pyplot as plt
import numpy as np

from face_data import Face1, Face2, Face3, edges

def plot_face(plt,x,edges,color='b'):
    "plots a face"

    plt.plot(x[:,0], x[:,1], 'o', color=color)
```

```
i,j = edges[0] # edge from node i to node j
xi = X[i,0]
yi = X[i,1]

xj = X[j,0]
yj = X[j,1]

# draw a line between X[i] and X[j]
plt.plot((xi,xj), (yi,yj), '- ', color=color)

plt.axis('square')
plt.xlim(-100,100)
plt.ylim(-100,100)

plot_face(plt, Face1, edges, color='b')
plt.show()
```

- The list `edge` contains a list of edges, each in the form of `(i, j)`. Print it to see how it looks.
- The function `plot_face` is supposed to plot the landmark points of the face, plus the edges between them. Currently, it only draws the first edge `edge[0]`. Change it to plot all the edges.
- Using the animation technique you learned above, morph a face shape from `Face1` to `Face2`, from `Face2` to `Face3`, and then from `Face3` back to `Face1`.
- Like before, try varying `alpha` from -.5 to 1.5 instead of 0 to 1.0 and see what happens.

For n vectors v_1, v_2, \dots, v_n , a linear combination $a_1 v_1 + a_2 v_2 + \dots + a_n v_n$ is called an affine combination if $a_1 + a_2 + \dots + a_n = 1$. It is also a convex combination if all the scalars a_i are nonnegative. Here, we want to find linear combinations of `Face1`, `Face2`, and `Face3` to create `TargetFace1` and `TargetFace2`.

`task2b.py`

```
import matplotlib.pyplot as plt
import numpy as np

from face_data import Face1, Face2, Face3, TargetFace1,
TargetFace2, edges
```

```
def plot_face(plt,X,edges,color='b'):  
    "plots a face"  
  
    plt.plot(X[:,0], X[:,1], 'o', color=color)  
  
    i,j = edges[0] # edge from node i to node j  
    xi = X[i,0]  
    yi = X[i,1]  
  
    xj = X[j,0]  
    yj = X[j,1]  
  
    # draw a line between X[i] and X[j]  
    plt.plot((xi,xj), (yi,yj), '-', color=color)  
  
    plt.axis('square')  
    plt.xlim(-100,100)  
    plt.ylim(-100,100)  
  
# make a guess  
a = 1/3.  
b = 1/3.  
c = 1/3.  
  
F = a * Face1 + b * Face2 + c * Face3  
  
plot_face(plt, TargetFace1, edges, color='r')  
plot_face(plt, F, edges, color='g')  
  
# change a,b,c until the two plots align  
  
plt.show()
```

- Find a convex combination of `Face1`, `Face2`, and `Face3` to create `TargetFace1`. Keep tuning the scalars `a`, `b`, and `c` in the code until the blue and green plots align.
- Find a linear (not necessarily convex) combination to create `TargetFace2`. Assume `a`, `b`, and `c` are positive. Try to guess them yourself before reading the hint below:
 - $a = 5.4 / 18 = ?$.
- **(Optional)** Can you think of a way to find the scalars without trial and error?

Task 3 - Practice Vectorization

Consider an arbitrary matrix **A** and a vector **u** like the following

```
m, n = 20, 10
A = np.random.rand(m, n)
u = np.random.rand(n)
```

We perform the following operation on **A** and **u** to create the vector **v**.

```
v = np.zeros(m)
for i in range(n):
    v += A[:,i] * u[i]
```

- Write an equivalent program *without loops* in just a **single line of code**.

```
v = ...
```