Derivative Rules

$f(x)$	$f'(x)$
$u(x)v(x)$	$u'v+uv'$
$\frac{u(x)}{v(x)}$	$\frac{u'v-uv'}{v^2}$
$u(v(x))$	$u'(v(x))v'(x)$
x^n	nx^{n-1}
$\ln(u(x))$	$\frac{u'(x)}{u(x)}$
$\sin(ax)$	$a\cos(ax)$
$\cos(ax)$	$-a\sin(ax)$
$\tan(ax)$	$a\sec^2(ax)$
$\cot(ax)$	$-a\csc^2(ax)$
$\sec(ax)$	$a\sec(ax)\tan(ax)$
$\csc(ax)$	$-a\csc(ax)\cot(ax)$

Trigonometric Identities

$$1=\sin^2(x)+\cos^2(x)$$
$$\sin(2x)=2\sin(x)\cos(x)$$
$$\cos(2x)=\cos^2(x)-\sin^2(x)$$
$$\sin^2(x)=\frac{1-\cos(2x)}{2}$$
$$\cos^2(x)=\frac{1+\cos(2x)}{2}$$

Partial Fraction Decomposition

Given the LHS in the denominator, substitute the RHS.

$$(ax+b)^k\to\frac{A_1}{ax+b}+\cdots+\frac{A_k}{(ax+b)^k}$$
$$(ax^2+bx+c)^k\to\frac{A_1x+B_1}{ax^2+bx+c}+\cdots+\frac{A_kx+B_k}{(ax^2+bx+c)^k}$$

Integration Techniques

$$\int u\,\mathrm{d}v=uv-\int v\,\mathrm{d}u$$
$$\int f(g(x))\frac{\mathrm{d}g(x)}{\mathrm{d}x}\,\mathrm{d}x=\int f(u)\,\mathrm{d}u$$

where $u=g(x)$.

Trigonometric Substitutions

Form	Substitution
$a^2-b^2x^2$	$x=\frac{a}{b}\sin(\theta)$
$a^2+b^2x^2$	$x=\frac{a}{b}\tan(\theta)$
$b^2x^2-a^2$	$x=\frac{a}{b}\sec(\theta)$

L'Hôpital's Rule

If $\lim_{x\to x_0}f(x)=\lim_{x\to x_0}g(x)=0$ or $\pm\infty$, then $\lim_{x\to x_0}\frac{f(x)}{g(x)}=\lim_{x\to x_0}\frac{f'(x)}{g'(x)}$.

Continuity

$f(x)$ continuous at c iff $\lim_{x\to c}f(x)=f(c)$.
$f(x)$ is continuous on $I:(a,\,b)$ if it is continuous for all $x\in I$.
$f(x)$ is continuous on $I:[a,\,b]$ if it is continuous for all $x\in I$, but only right continuous at a and left continuous at b.

Intermediate Value Theorem

If $f(x)$ is continuous on $I:[a,\,b]$ and $f(a)\le c\le f(b)$, then $\exists x\in I:f(x)=c$.

Differentiability

$f(x)$ is differentiable at $x=x_0$ iff
$$f'(x_0)=\lim_{x\to x_0}\frac{f(x)-f(x_0)}{x-x_0}$$
exists. This defines the derivative
$$f'(x_0)=\lim_{h\to 0}\frac{f(x_0+h)-f(x_0)}{h}.$$
Differentiability implies continuity.

Mean Value Theorem

If $f(x)$ is continuous and differentiable on $I:[a,\,b]$, then
$$\exists c\in I:f'(c)=\frac{f(b)-f(a)}{b-a}.$$

Definite Integrals

$$A=\int_a^b f(x)\,\mathrm{d}x$$

Fundamental Theorem of Calculus

$$\int_a^b\frac{\mathrm{d}F(x)}{\mathrm{d}x}\,\mathrm{d}x=F(b)-F(a)$$
$$\frac{\mathrm{d}}{\mathrm{d}x}\left(\int_a^x f(t)\,\mathrm{d}t\right)=f(x)$$

Taylor Polynomials

$$f(x)\approx p_n(x)=\sum_{k=0}^{n}\frac{f^{(k)}(x_0)}{k!}(x-x_0)^k$$

Taylor Series

$$f(x)=\sum_{n=0}^{\infty}\frac{f^{(n)}(x_0)}{n!}(x-x_0)^n$$

Maclaurin Series: $x_0=0$.

Common Maclaurin Series

Function	Series Term	Conv.
e^x	$\frac{x^n}{n!}$	all x
$\sin(x)$	$(-1)^n\frac{x^{2n+1}}{(2n+1)!}$	all x
$\cos(x)$	$(-1)^n\frac{x^{2n}}{(2n)!}$	all x
$\frac{1}{1-x}$	x^n	$(-1,\,1)$
$\frac{1}{1+x^2}$	$(-1)^n x^{2n}$	$(-1,\,1)$
$\ln(1+x)$	$(-1)^{n+1}\frac{x^n}{n}$	$(-1,\,1]$

Power Series: $\sum_{n=0}^{\infty}c_n(x-x_0)^n$

Series Tests

For a series of the form $\sum_{i=i_0}^{\infty}a_i$:

Alternating Series Test

Given $a_i=(-1)^i b_i$ and $b_i>0$.
If $b_{i+1}\leqslant b_i$ & $\lim_{i\to\infty}b_i=0$, then convergent, else inconclusive.

Ratio Test

Given $\rho=\lim_{i\to\infty}\left|\frac{a_{i+1}}{a_i}\right|$:

$\rho<1$: convergent
$\rho>1$: divergent
$\rho=1$: inconclusive

Multivariable Functions

$$f:\mathbb{R}^n\to\mathbb{R}$$

Level Curves

$$L_c(f)=\{(x,\,y):f(x,\,y)=c\}$$

If $f(x,\,y)\to L$ as $(x,\,y)\to(x_0,\,y_0)$, then $\lim_{(x,\,y)\to(x_0,\,y_0)}=L$ along any smooth curve.
The limit does not exist if L changes along different smooth curves.
Partial Derivatives: w.r.t one variable, others held constant.
Gradient: $\boldsymbol{\nabla}=\langle\partial x_1,\,\partial x_2,\,\dots,\,\partial x_n\rangle$

Multivariable Chain Rule

For $f=f(\mathbf{x}(t_1,\,\dots,\,t_n))$ with $\mathbf{x}=[x_1\;\cdots\;x_m]$
$$\frac{\partial f}{\partial t_i}=\boldsymbol{\nabla}f\cdot\frac{\partial\mathbf{x}}{\partial t_i}.$$

Directional Derivatives

$$\boldsymbol{\nabla}_{\mathbf{u}}f=\boldsymbol{\nabla}f\cdot\mathbf{u}$$
where $\mathbf{u}$ is a unit vector and the slope is given by $\|\boldsymbol{\nabla}_{\mathbf{u}}f\|$. If $\boldsymbol{\nabla}_{\mathbf{u}}f=0$, $\mathbf{u}$ is tangent to the level curve at $\mathbf{x}_0$.
$$\max_{\|\mathbf{u}\|=1}\boldsymbol{\nabla}_{\mathbf{u}}f=\boldsymbol{\nabla}f$$
If $\boldsymbol{\nabla}f\ne 0$, $\boldsymbol{\nabla}f$ is a normal vector to the level curve at $\mathbf{x}_0$.

Critical Points

$(x_0,\,y_0)$ is a critical point if $\boldsymbol{\nabla}f(x_0,\,y_0)=\mathbf{0}$ or if $\boldsymbol{\nabla}f(x_0,\,y_0)$ is undefined.

Classification of Critical Points

$$D=f_{xx}f_{yy}-\left(f_{xy}\right)^2$$

$D>0$ **and** $f_{xx}<0$**:** local maxima

$D>0$ **and** $f_{xx}>0$**:** local minima

$D<0$**:** saddle point

$D=0$**:** inconclusive

Double Integrals

The volume of the solid enclosed between the surface $z=f(x,\,y)$ and the region Ω is defined by
$$V=\iint_\Omega f(x,\,y)\,\mathrm{d}A.$$
If Ω is a region bounded by $a\le x\le b$ and $c\le y\le d$, then
$$\iint_\Omega f(x,\,y)\,\mathrm{d}A=\int_c^d\int_a^b f(x,\,y)\,\mathrm{d}x\,\mathrm{d}y$$
$$=\int_a^b\int_c^d f(x,\,y)\,\mathrm{d}y\,\mathrm{d}x$$

Type I Regions

$$\iint_{\Omega} f(x,\, y)\,\mathrm{d}A = \int_a^b \int_{g_1}^{g_2} f(x,\, y)\,\mathrm{d}y\,\mathrm{d}x$$

Bounded left & right by:

$$x = a \text{ and } x = b$$

Bounded below & above by:

$$y = g_1(x) \text{ and } y = g_2(x)$$

where $g_1(x) \leq g_2(x)$ for $a \leq x \leq b$:

Type II Regions

$$\iint_{\Omega} f(x,\, y)\,\mathrm{d}A = \int_c^d \int_{h_1}^{h_2} f(x,\, y)\,\mathrm{d}x\,\mathrm{d}y$$

Bounded left & right by:

$$x = h_1(y) \text{ and } x = h_2(y)$$

Bounded below & above by:

$$y = c \text{ and } y = d$$

where $h_1(y) \leq h_2(y)$ for $c \leq y \leq d$. To integrate, solve the inner integrals first.

Vector Valued Functions

$$\mathbf{r} : \mathbb{R} \to \mathbb{R}^n$$

The **domain** of $\mathbf{r}(t)$ is the intersection of the domains of its components. The **orientation** of $\mathbf{r}(t)$ is the direction of motion along the curve as the value of the parameter increases. **Limits**, **derivatives** and **integrals** are all *component-wise*. Each component has its <u>own</u> constant of integration.

Parametric Lines

$$\mathbf{l}(t) = \mathbf{P}_0 + t\mathbf{v}$$

where $\mathbf{l}(t)$ passes through $\mathbf{P}_0$, and is parallel to $\mathbf{v}$.

Tangent Lines

If $\mathbf{r}(t)$ is differentiable at t_0 and $\mathbf{r}'(t_0) \neq \mathbf{0}$

$$\mathbf{l}(t) = \mathbf{r}(t_0) + t\mathbf{r}'(t_0).$$

Curves of Intersection

Choose one of the variables as the parameter, and express the remaining variables in terms of that parameter.

Arc Length

$$S = \int_a^b \|\mathbf{r}'(t)\|\,\mathrm{d}t$$

Ordinary Differential Equations

Order: highest derivative in DE.
Autonomous DE: does not depend explicitly on the independent variable.

Qualitative Analysis

$$\frac{\mathrm{d}y}{\mathrm{d}t} = f(y)$$

A fixed point is the value of y for which $f(y) = 0$.

Stability of Fixed Points

Given a positive/negative perturbation from a fixed point, that point is
Stable: if both tend toward FP
Unstable: if both tend away from FP
Semi-Stable: if one tends toward FP, and another tends away from FP

Directly Integrable ODEs

For $\frac{\mathrm{d}y}{\mathrm{d}x} = f(x)$:

$$y(x) = \int f(x)\,\mathrm{d}x.$$

Separable ODEs

For $\frac{\mathrm{d}y}{\mathrm{d}x} = p(x)\,q(y)$:

$$\int \frac{1}{q(y)}\frac{\mathrm{d}y}{\mathrm{d}x}\,\mathrm{d}x = \int p(x)\,\mathrm{d}x.$$

Linear ODEs

For $\frac{\mathrm{d}y}{\mathrm{d}x} + p(x)\,y = q(x)$, use the *integrating factor*: $I(x) = e^{\int p(x)\,\mathrm{d}x}$, so that

$$y(x) = \frac{1}{I(x)}\int I(x)\,q(x)\,\mathrm{d}x.$$

Exact ODEs

$P(x,\, y) + Q(x,\, y)\frac{\mathrm{d}y}{\mathrm{d}x} = 0$ has the solution $\Psi(x,\, y) = c$ iff it is exact, namely, when $P_y = Q_x$, where $P = \Psi_x$ and $Q = \Psi_y$. Then

$$\Psi(x,\, y) = \int P(x,\, y)\,\mathrm{d}x + f(y)$$

$$\Psi(x,\, y) = \int Q(x,\, y)\,\mathrm{d}y + g(x)$$

and $f(y)$ and $g(x)$ can be determined by solving these equations simultaneously.

Second-Order ODEs

$$a_2(x)\,y'' + a_1(x)\,y' + a_0(x)\,y = F(x)$$

Initial Values

$$y(x_0) = y_0 \quad y'(x_0) = y_1$$

Boundary Values

$$y(x_0) = y_0 \quad y(x_1) = y_1$$

Reduction of Order

$$y_2(x) = v(x)\,y_1(x)$$

$v(x)$ can be determined by substituting y_2 into the ODE, using $w(x) = v'(x)$.

General Solution

$$y(x) = y_H(x) + y_P(x)$$

Homogeneous Solution

$$y_H(x) = e^{\lambda x}$$

Real Distinct Roots

$$y_H(x) = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

Real Repeated Roots

$$y_H(x) = c_1 e^{\lambda x} + c_2 t e^{\lambda x}$$

Complex Conjugate Roots

Given $\lambda = \alpha \pm \beta i$:

$$y_H(x) = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Particular Solution

See table below. Substitute y_P into the nonhomogeneous ODE, and solve the undetermined coefficients.

Spring and Mass Systems

$$my'' + \gamma y' + ky = f(t)$$

Newton's Law: $F = my''$
Spring force: $F_s = -ky$
Damping force: $F_d = -\gamma y'$

m : mass	k : spring constant
γ : damping	$f(t)$: external force

Electrical Circuits

The sum of voltages around a loop equals 0.

$$v(t) - iR - L\frac{\mathrm{d}i}{\mathrm{d}t} - \frac{q}{C} = 0$$

$$L\frac{\mathrm{d}^2 q}{\mathrm{d}t^2} + R\frac{\mathrm{d}q}{\mathrm{d}t} + \frac{1}{C}q = v(t)$$

where $i = \frac{\mathrm{d}q}{\mathrm{d}t}$.

Voltage drop across various elements:

$$v_R = iR$$

$$v_C = \frac{q}{C}$$

$$v_L = L\frac{\mathrm{d}i}{\mathrm{d}t}$$

R : resistance	C : capacitance
L : inductance	$v(t)$: voltage supply

$F(x)$	$y_P(x)$
a constant	A
a polynomial of degree n	$\sum_{i=0}^{n} A_i x^i$
e^{kx}	Ae^{kx}
$\cos(\omega x)$ or $\sin(\omega x)$	$A_0 \cos(\omega x) + A_1 \sin(\omega x)$
a combination of the above	a combination of the above
linearly dependent to $y_H(x)$	multiply $y_P(x)$ by x until linearly independent