

Differential Equations and Modelling 2

Semester 2, 2024

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Part I

Symmetry Methods

1 Symmetry Transformations

Consider a partial differential equation for $u(x, t)$ whose domain lies in \mathbb{R}^2 . Such a problem typically does not have any natural length or time scales associated with its fundamental solution. Thus, let us transform the independent and dependent variables through the mapping $(x, t, u) \mapsto (X, T, U)$ where $X = X(x, t, u)$, $T = T(x, t, u)$, and $U = U(x, t, u)$, such that the PDE is invariant under this transformation, that is, the transformed PDE in U has the same form as the original PDE in u .

The choice of mapping may consist of dilations and translations of the independent and dependent variables by some constant factors, where each constant is enforced by the invariance condition. To do this, we must ensure that the function $U(x, t, u(X, T))$ satisfies the transformed PDE. When this is the case, the PDE is said to have a *symmetry transformation*.

The goal of these symmetry methods is to find an appropriate transformation that simplifies the PDE, often reducing it to an ODE.

1.1 Dilation Symmetry

A dilation symmetry is a transformation of the form

$$X = ax, \quad T = a^\beta t, \quad U = a^\gamma u,$$

where a , β , and γ are constants. Note that we do not express the transformation for x as $X = a^\alpha x$ since it does not provide any additional information.

Example 1.1. Consider the transport equation

$$\frac{\partial u(x, t)}{\partial t} + c \frac{\partial u(x, t)}{\partial x} = 0$$

and the mapping

$$X = ax, \quad T = a^\beta t, \quad U = u.$$

After substituting the transformed solution into the PDE, we find

$$\begin{aligned} \frac{\partial u(X, T)}{\partial t} + c \frac{\partial u(X, T)}{\partial x} &= 0 \\ \frac{\partial u(X, T)}{\partial T} \frac{dT}{dt} + c \frac{\partial u(X, T)}{\partial X} \frac{dX}{dx} &= 0 \\ a^\beta \frac{\partial u(X, T)}{\partial T} + ac \frac{\partial u(X, T)}{\partial X} &= 0. \end{aligned}$$

For this PDE to be invariant under a dilation transformation, we must factor out the constant a from the equation. This implies that:

$$a^\beta = a \implies \beta = 1,$$

so that

$$\frac{\partial u(X, T)}{\partial T} + c \frac{\partial u(X, T)}{\partial X} = 0.$$

Here we have shown that the transport equation is invariant under the above dilation transformation when $\beta = 1$.

Example 1.2. Consider the nonlinear PDE

$$\frac{\partial u(x, y)}{\partial x} + y^2 \frac{\partial u(x, y)}{\partial y} = 0$$

and the mapping

$$X = ax, \quad Y = a^\beta y, \quad U = u.$$

By substituting the transformed solution into the PDE, we find

$$\begin{aligned} \frac{\partial u(X, Y)}{\partial x} + y^2 \frac{\partial u(X, Y)}{\partial y} &= 0 \\ \frac{\partial u(X, Y)}{\partial X} \frac{dX}{dx} + y^2 \frac{\partial u(X, Y)}{\partial Y} \frac{dY}{dy} &= 0 \\ a \frac{\partial u(X, Y)}{\partial X} + a^\beta y^2 \frac{\partial u(X, Y)}{\partial Y} &= 0 \\ a \frac{\partial u(X, Y)}{\partial X} + a^\beta (Y/a^\beta)^2 \frac{\partial u(X, Y)}{\partial Y} &= 0 \\ a \frac{\partial u(X, Y)}{\partial X} + a^{-\beta} Y^2 \frac{\partial u(X, Y)}{\partial Y} &= 0. \end{aligned}$$

For this PDE to be invariant under a dilation transformation, we must again factor out a from the equation so that:

$$a = a^{-\beta} \implies 1 = -\beta \implies \beta = -1,$$

and

$$\frac{\partial u(X, Y)}{\partial X} + Y^2 \frac{\partial u(X, Y)}{\partial Y} = 0.$$

Here we have shown that this nonlinear PDE is invariant under the above dilation transformation when $\beta = -1$.

Example 1.3. Consider the nonlinear convection diffusion equation

$$\frac{\partial u(x, t)}{\partial t} = u(x, t) \frac{\partial^2 u(x, t)}{\partial x^2} - \frac{\partial u(x, t)}{\partial x}$$

and the mapping

$$X = ax, \quad T = a^\beta t, \quad U = a^\gamma u.$$

We will once again substitute the transformed solution into the PDE to find

$$\begin{aligned}
a^\gamma \frac{\partial u(X, T)}{\partial t} &= a^{2\gamma} u(X, T) \frac{\partial^2 u(X, T)}{\partial x^2} - a^\gamma \frac{\partial u(X, T)}{\partial x} \\
a^\gamma \frac{\partial u(X, T)}{\partial T} \frac{dT}{dt} &= a^{2\gamma} u(X, T) \frac{\partial}{\partial x} \left[\frac{\partial u(X, T)}{\partial X} \frac{dX}{dx} \right] - a^\gamma \frac{\partial u(X, T)}{\partial X} \frac{dX}{dx} \\
a^{\beta+\gamma} \frac{\partial u(X, T)}{\partial T} &= a^{1+2\gamma} u(X, T) \frac{\partial}{\partial X} \left[\frac{dX}{dx} \frac{\partial u(X, T)}{\partial X} \right] - a^{1+\gamma} \frac{\partial u(X, T)}{\partial X} \\
a^{\beta+\gamma} \frac{\partial u(X, T)}{\partial T} &= a^{2+2\gamma} u(X, T) \frac{\partial^2 u(X, T)}{\partial X^2} - a^{1+\gamma} \frac{\partial u(X, T)}{\partial X}.
\end{aligned}$$

For this PDE to be invariant under a dilation transformation, we must factor out a from the equation so that:

$$a^{\beta+\gamma} = a^{2+2\gamma} = a^{1+\gamma} \implies \beta + \gamma = 2 + 2\gamma = 1 + \gamma \implies \beta = 1, \gamma = -1,$$

and

$$\frac{\partial u(X, T)}{\partial T} = u(X, T) \frac{\partial^2 u(X, T)}{\partial X^2} - \frac{\partial u(X, T)}{\partial X}.$$

Here we have shown that this nonlinear PDE is invariant under the above dilation transformation when $\beta = 1$ and $\gamma = -1$.

1.2 Translation Symmetry

A translation symmetry is a transformation of the form

$$X = x - x_0, \quad T = t - t_0, \quad U = u - u_0,$$

where x_0 , t_0 , and u_0 are constants.

Example 1.4. Consider the heat equation

$$\frac{\partial u(x, t)}{\partial t} = D \frac{\partial^2 u(x, t)}{\partial x^2}$$

and the mapping

$$X = x - x_0, \quad T = t - t_0, \quad U = u - u_0.$$

By substituting the transformed solution into the PDE, we find

$$\begin{aligned}
\frac{\partial}{\partial t} (u(X, T) - u_0) &= D \frac{\partial^2}{\partial x^2} (u(X, T) - u_0) \\
\frac{\partial u(X, T)}{\partial T} \frac{dT}{dt} &= D \frac{\partial}{\partial x} \left(\frac{\partial u(X, T)}{\partial X} \frac{dX}{dx} \right) \\
\frac{\partial u(X, T)}{\partial T} &= D \frac{\partial}{\partial X} \frac{dX}{dx} \left(\frac{\partial u(X, T)}{\partial X} \right) \\
\frac{\partial u(X, T)}{\partial T} &= D \frac{\partial^2 u(X, T)}{\partial X^2}.
\end{aligned}$$

Here we have shown that the heat equation is invariant under the above translation transformation.

2 Similarity Solutions

In the previous section, we considered dilation transformations where both independent variables were scaled by some power of a . Notice that the product $\eta = xt^{-1/\beta}$ is invariant under the same dilation transformation:

$$\eta = xt^{-1/\beta} \implies H = \left(\frac{x}{a}\right) \left(\frac{T}{a^\beta}\right)^{-1/\beta} = XT^{-1/\beta}.$$

Let us therefore consider transformations of the form

$$X = ax, \quad T = a^\beta t, \quad U = t^{-\alpha} f(\eta),$$

where a , α , and β are constant and f is an arbitrary function to be determined. f is called a *similarity solution* (with *similarity variable* η) and our goal is to transform the PDE into an ODE with a single independent variable η . To do this:

1. Substitute $u(X, T)$ into the PDE to solve for α and β while maintaining invariance.
2. Obtain an ODE in terms of $f(\eta)$ by substituting the similarity solution into the PDE.
3. Obtain boundary conditions in terms of η using the same transformation.
4. Solve the ODE to find $f(\eta)$.
5. Transform back to the original variables to find a solution to the PDE.

3 Travelling Wave Solutions

Another type of solution is the *travelling wave solution*, where the solution to a PDE appears to move at a constant velocity when after a long period of time. This is similar to a steady state solution where the solution does not change after a long period of time. In this problem, we assume solutions of the form

$$u(x, t) = f(z), \quad z = x - ct,$$

where c is the speed at which the solution travels. The travelling wave speed is often determined using analysis, boundary conditions, numerical methods, or physical constraints. This method is only applicable to PDEs that are invariant under translations to both independent variables. As such, the PDE must not contain any explicit dependence on x or t .

Part II

Method of Characteristics

The method of characteristics is a technique used to solve nonlinear PDEs by reducing them to a system of ODEs. It considers parametrisations of the solution through a set of curves in the solution space along which the solution is constant.

4 First Order PDEs

4.1 Linearity

Consider the general first order PDE in two variables:

$$a \frac{\partial u}{\partial x} + b \frac{\partial u}{\partial y} = c.$$

This PDE has four classifications based on the value of the variables a , b , and f :

- **Linear:**

$$a(x, y) \frac{\partial u}{\partial x} + b(x, y) \frac{\partial u}{\partial y} = c(x, y).$$

- **Semi-Linear:**

$$a(x, y) \frac{\partial u}{\partial x} + b(x, y) \frac{\partial u}{\partial y} = c(x, y, u).$$

- **Quasi-Linear:**

$$a(x, y, u) \frac{\partial u}{\partial x} + b(x, y, u) \frac{\partial u}{\partial y} = c(x, y, u).$$

- **Nonlinear:** Otherwise.

4.2 Solution Method

Given a quasi-linear PDE of the form:

$$a(x, y, u) \frac{\partial u}{\partial x} + b(x, y, u) \frac{\partial u}{\partial y} = c(x, y, u)$$

with the initial condition $u(x_0, y_0) = u_0(x)$, let us consider the surface $u = u(x, y)$, which has the normal vector:

$$\mathbf{n} = \begin{bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \\ -1 \end{bmatrix}.$$

We can find a tangent vector to \mathbf{n} using the dot product:

$$\begin{bmatrix} a(x, y, u) \\ b(x, y, u) \\ c(x, y, u) \end{bmatrix} \cdot \mathbf{n} = 0.$$

We will call this vector \mathbf{v} :

$$\mathbf{v} = \begin{bmatrix} a(x, y, u) \\ b(x, y, u) \\ c(x, y, u) \end{bmatrix}.$$

Let us now consider a parametric curve defined as:

$$\mathbf{r}(s) = \begin{bmatrix} x(s) \\ y(s) \\ u(s) \end{bmatrix},$$

and let us impose that $\mathbf{r}'(s) = \mathbf{v}$, so that the curve lies on the solution surface. This gives us the following system of equations:

$$\mathbf{r}'(s) = \mathbf{v} \iff \begin{cases} \frac{\partial x}{\partial s} = a(x, y, u), \\ \frac{\partial y}{\partial s} = b(x, y, u), \\ \frac{\partial u}{\partial s} = c(x, y, u). \end{cases}$$

These parametric curves are found through integration and we can solve all integration constants x_0 , y_0 , and u_0 using the parametric initial condition:

$$u(0) = u_0(\xi) \quad \text{on} \quad x(0) = x_0(\xi), \quad y(0) = y_0(\xi).$$

with the parameter ξ^1 . The resulting parametric equations $x(s)$ and $y(s)$ form *characteristic curves* of the PDE, and we can find the solution $u(x, y)$ by eliminating s and ξ from the three parametric equations.

5 System of First Order PDEs

Consider an $n \times n$ coupled system of first order PDEs:

$$\mathbf{A} \frac{\partial \mathbf{u}}{\partial x} + \mathbf{B} \frac{\partial \mathbf{u}}{\partial y} = \mathbf{c},$$

where $\mathbf{A} = \mathbf{A}(x, y, \mathbf{u})$ and $\mathbf{B} = \mathbf{B}(x, y, \mathbf{u})$ are $n \times n$ matrix functions, and $\mathbf{c} = \mathbf{c}(x, y, \mathbf{u})$ is an $n \times 1$ vector function. In this case, we want to find characteristic directions \mathbf{v} that will allow us to decouple the system. We will try to decompose \mathbf{A} and \mathbf{B} into a diagonal form by assuming the following relationship holds for some \mathbf{m} :

$$\mathbf{v}^\top \left(\mathbf{A} \frac{\partial \mathbf{u}}{\partial x} + \mathbf{B} \frac{\partial \mathbf{u}}{\partial y} \right) = \mathbf{m}^\top \left(\alpha \frac{\partial \mathbf{u}}{\partial x} + \beta \frac{\partial \mathbf{u}}{\partial y} \right),$$

where \mathbf{v} and \mathbf{m} are $n \times 1$ vector functions, and $\alpha = \frac{dx}{ds}$ and $\beta = \frac{dy}{ds}$ are parametric functions. For this to hold, we must have:

$$\mathbf{v}^\top \mathbf{A} = \mathbf{m}^\top \alpha \quad \text{and} \quad \mathbf{v}^\top \mathbf{B} = \mathbf{m}^\top \beta.$$

By eliminating \mathbf{m}^\top , we can find a relationship between \mathbf{A} and \mathbf{B} :

$$\begin{aligned} \frac{1}{\alpha} \mathbf{v}^\top \mathbf{A} &= \frac{1}{\beta} \mathbf{v}^\top \mathbf{B} \\ \mathbf{v}^\top \mathbf{A} &= \frac{\alpha}{\beta} \mathbf{v}^\top \mathbf{B} \\ \mathbf{v}^\top \mathbf{A} &= \lambda \mathbf{v}^\top \mathbf{B}. \end{aligned}$$

This is precisely the left-generalised eigenvalue problem for the matrix pair (\mathbf{A}, \mathbf{B}) where the eigenvalues λ_i are found by solving the characteristic equation:

$$\det(\mathbf{A} - \lambda \mathbf{B}) = 0.$$

¹ ξ is introduced to parametrise the variable x in the initial condition.

Assuming a diagonalisable system, we have the following matrix decomposition:

$$\mathbf{A} = \mathbf{B}\mathbf{\Lambda}\mathbf{V}^{-1},$$

where \mathbf{V} is the matrix of eigenvectors and $\mathbf{\Lambda}$ is the diagonal matrix of eigenvalues. Let us now define a new variable $\mathbf{w} = \mathbf{V}^{-1}\mathbf{u}$ to decouple the system:

$$\begin{aligned}\mathbf{A}\frac{\partial \mathbf{u}}{\partial x} + \mathbf{B}\frac{\partial \mathbf{u}}{\partial y} &= \mathbf{c} \\ \mathbf{V}^{-1}\mathbf{B}^{-1}\mathbf{A}\frac{\partial \mathbf{u}}{\partial x} + \mathbf{V}^{-1}\frac{\partial \mathbf{u}}{\partial y} &= \mathbf{V}^{-1}\mathbf{B}^{-1}\mathbf{c} \\ \mathbf{\Lambda}\frac{\partial \mathbf{w}}{\partial x} + \frac{\partial \mathbf{w}}{\partial y} &= \mathbf{V}^{-1}\mathbf{B}^{-1}\mathbf{c}.\end{aligned}$$

As $\mathbf{\Lambda}$ is diagonal, we can form a system of n first order PDEs which can be solved independently to find $w_i(x, y)$. Upon finding these solutions, we can transform back to the original variable \mathbf{u} using $\mathbf{u} = \mathbf{V}\mathbf{w}$.

6 Second Order PDEs

Consider the general linear second order PDE in two variables:

$$a\frac{\partial^2 u}{\partial x^2} + 2b\frac{\partial^2 u}{\partial x \partial y} + c\frac{\partial^2 u}{\partial y^2} + d\frac{\partial u}{\partial x} + e\frac{\partial u}{\partial y} = f.$$

with the initial conditions $u(x_0, y_0) = f(x)$ and $u_y(x_0, y_0) = g(x)$ where variables a through f are functions of x and y only. We will begin by factoring this PDE into it's two first derivatives of u , $u_x = \frac{\partial u}{\partial x}$ and $u_y = \frac{\partial u}{\partial y}$, to convert the second order PDE into a system of first order PDEs:

$$\begin{aligned}a\frac{\partial^2 u}{\partial x^2} + 2b\frac{\partial^2 u}{\partial y \partial x} + c\frac{\partial^2 u}{\partial y^2} + d\frac{\partial u}{\partial x} + e\frac{\partial u}{\partial y} &= f \\ a\frac{\partial u_x}{\partial x} + 2b\frac{\partial u_x}{\partial y} + c\frac{\partial u_y}{\partial y} + du_x + eu_y &= f \\ a\frac{\partial u_x}{\partial x} + 2b\frac{\partial u_x}{\partial y} + c\frac{\partial u_y}{\partial y} &= f - du_x - eu_y,\end{aligned}$$

where we assume Schwarz's theorem holds:

$$\frac{\partial^2 u}{\partial y \partial x} = \frac{\partial^2 u}{\partial x \partial y} \iff \frac{\partial u_x}{\partial y} = \frac{\partial u_y}{\partial x}.$$

We can then form the following system of first order PDEs:

$$\begin{bmatrix} a & 0 \\ 0 & 1 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u_x \\ u_y \end{bmatrix} + \begin{bmatrix} 2b & c \\ -1 & 0 \end{bmatrix} \frac{\partial}{\partial y} \begin{bmatrix} u_x \\ u_y \end{bmatrix} = \begin{bmatrix} f - du_x - eu_y \\ 0 \end{bmatrix}.$$

This system can now be solved using the process described in the previous section, where the initial condition for u_x is simply $u_x(x_0, y_0) = f'(x)$.

6.1 Classification of Second Order PDEs

The eigenvalue problem for this system is given by:

$$\begin{vmatrix} a - 2b\lambda & -c \\ 1 & -\lambda \end{vmatrix} = a\lambda^2 - 2b\lambda + c = 0,$$

and the eigenvalues are given by:

$$\lambda = \frac{2b \pm \sqrt{4b^2 - 4ac}}{2a} = \frac{b \pm \sqrt{b^2 - ac}}{a}.$$

We can classify this second order PDE into 3 types based on the discriminant $b^2 - ac$:

- **Hyperbolic:** (two real distinct eigenvalues)

$$b^2 - ac > 0.$$

- **Parabolic:** (two real equal eigenvalues)

$$b^2 - ac = 0.$$

- **Elliptic:** (two complex eigenvalues)

$$b^2 - ac < 0.$$