

2) From section 6.1.1 under Bordered algorithm variant, we know that loop invariant is

$$\left(\begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) = \left(\begin{array}{c|c} L/V_{TL} & \hat{A}_{TR} \\ \hline \hat{A}_{BL} & \hat{A}_{BR} \end{array} \right) \wedge L_{TL} V_{TL} = \hat{A}_{TL}$$

Only matrix A_{TL} is being overwritten under this algorithm, the rest remain unchanged. The loop invariant for simple backward analysis is rewritten as

$$\left(\begin{array}{c|c} [\check{L}/\check{V}]_{TL} = [L\check{V}(A_{TL})] & \check{V}_{TR} = 0 \\ \hline \check{L}_{BL} = 0 & [\check{L}/\check{V}]_{BR} = 0 \end{array} \right) \quad \text{where } \check{L} \text{ and } \check{V} \text{ satisfy } \check{L}\check{V} = A + \Delta A$$

The error invariant is $\left(\begin{array}{c|c} \check{L}\check{V}_{TL} = (A_{TL} + \Delta A_{TL}) & \check{V}_{TR} = 0 \\ \hline \check{L}_{BL} = 0 & [\check{L}/\check{V}]_{BR} = 0 \end{array} \right)$

a) Base case

For $n=1$, matrix $A \in \mathbb{R}$ such that $A = LV$, where $A, L, V \in \mathbb{R}$ (L and V are also $\in \mathbb{R}$). Since the matrix is a 1×1 matrix, there will be no L and V factorization that will be suitable in this case. Since these values will be null.

From section 6.2.2, we know that error is ~~floating point~~ ^(floating point) being stored as a floating point number as follows:

$$|A| \leq \epsilon_{mach} |A|$$

In addition, from section 6.3.2.3, we know ~~the~~ ^{from the} definition of δ_n , which is:

$$\delta_n = \frac{n \epsilon_{mach}}{1 - n \epsilon_{mach}} \quad \text{for all } n \geq 1 \text{ and } n \epsilon_{mach} < 1$$

~~where~~ for $n=1$, $\delta_n = \frac{\epsilon_{mach}}{1 - \epsilon_{mach}} \approx \epsilon_{mach} \approx 10^{-16}$ for a double precision floating point number

Therefore, $|A| \leq \delta_n |\tilde{L}| |\tilde{V}|$ which means $|A| \leq \delta_n |A|$ is true for $n=1$,
 $(LV) = |L| |V|$ are all in \mathbb{R}

b) Inductive step:

Assume that for $A_{00} \in \mathbb{R}^{n \times n}$, the bordered LV factorization computes \tilde{L} and \tilde{U} where

$$A_{00} + \Delta A_{00} = \tilde{L} \tilde{U} \quad \text{with} \quad |\Delta A_{00}| \leq \gamma_n |\tilde{L}_{00}| |\tilde{U}_{00}|, \text{ which holds for any } n.$$

Now, we apply bordered algorithm to $\left(\begin{array}{c|c} A_{00} & a_{01} \\ \hline a_{10}^T & a_{11} \end{array} \right)$

From section 5.5.1.1, we know that the above matrix can be rewritten as:

$$A \rightarrow \left(\begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right), U \rightarrow \left(\begin{array}{c|c} U_{TL} & U_{TR} \\ \hline 0 & V_{BR} \end{array} \right), L \rightarrow \left(\begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right)$$

~~At the top of the loop~~ At the top of the loop, after reordering, A then contains

$$\left(\begin{array}{c|c|c} A_{00} & a_{01} & a_{02} \\ \hline a_{10}^T & a_{11} & a_{12} \\ \hline a_{20}^T & a_{21} & a_{22} \end{array} \right)$$

while after updating A it must contain

$$\left(\begin{array}{c|c|c} A_{00} & a_{01} & a_{02} \\ \hline a_{10}^T & a_{11} & a_{12} \\ \hline a_{20}^T & a_{21} & a_{22} \end{array} \right) = \left(\begin{array}{c|c|c} \tilde{L}_{00} \tilde{U}_{00} & \tilde{U}_{01} & \hat{a}_{02} \\ \hline \tilde{L}_{10}^T & v_{11} & \hat{a}_{12} \\ \hline \hat{A}_{20} & \hat{a}_{21} & \hat{a}_{22} \end{array} \right)$$

$$\hat{A}_{00} = \tilde{L}_{00} \tilde{U}_{00} = \hat{A}_{00} \quad \hat{L}_{00} \tilde{U}_{01} = \hat{a}_{01}$$

$$\hat{L}_{10}^T \tilde{U}_{00} = \hat{a}_{10}^T \quad \hat{L}_{10}^T \tilde{U}_{01} + v_{11} = \hat{a}_{11}$$

$$\hat{A}_{20} = \tilde{L}_{20} \tilde{U}_{00} = \hat{A}_{20} \quad \hat{L}_{20} \tilde{U}_{01} = \hat{a}_{20}$$

$$\hat{A}_{21} = \tilde{L}_{20} \tilde{U}_{01} + \hat{a}_{21} = \hat{a}_{21}$$

$$\hat{A}_{22} = \tilde{L}_{20} \tilde{U}_{02} + \hat{a}_{22} = \hat{a}_{22}$$

$$\hat{A} = \begin{pmatrix} \hat{A}_{00} & \hat{a}_{01} \\ \hat{a}_{10}^T & \hat{a}_{11} \end{pmatrix}$$

$$\hat{A}_{01} = \hat{a}_{01} + a_{01}$$

$$\hat{A}_{10}^T = \hat{a}_{10}^T + a_{10}^T$$

$$\hat{A}_{11} = \hat{a}_{11} + a_{11}$$

$$\hat{A}_{00} = A_{00} + \Delta A_{00}$$

~~We know~~ This gives us the equation

$$\left(\begin{array}{c|c} A_{00} & a_{01} \\ \hline a_{10}^T & a_{11} \end{array} \right) + \left(\begin{array}{c|c} \Delta A_{00} & \Delta a_{01} \\ \hline \Delta a_{10}^T & \Delta a_{11} \end{array} \right) = \left(\begin{array}{c|c} \hat{L}_{00} & 0 \\ \hline \hat{L}_{10}^T & 1 \end{array} \right) \left(\begin{array}{c|c} \hat{U}_{00} & \hat{U}_{01} \\ \hline 0 & \hat{U}_{11} \end{array} \right)$$

This is bounded by the error $|\Delta A_{00}| \leq \gamma_n |\tilde{L}_{00}| |\tilde{U}_{00}|$ and the base case which $|\Delta A| \leq \frac{\gamma_n}{10}$

Combining these two boundaries

$$\text{we get } \left| \left(\begin{array}{c|c} \Delta A_{00} & \Delta a_{01} \\ \hline \Delta a_{10}^T & \Delta a_{11} \end{array} \right) \right| \leq \gamma_{n+1} \left| \left(\begin{array}{c|c} \tilde{L}_{00} & 0 \\ \hline \tilde{L}_{10}^T & 1 \end{array} \right) \left(\begin{array}{c|c} \tilde{U}_{00} & \tilde{U}_{01} \\ \hline 0 & \tilde{U}_{11} \end{array} \right) \right|$$