

Math 435 10/27/2025 Notes

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Review

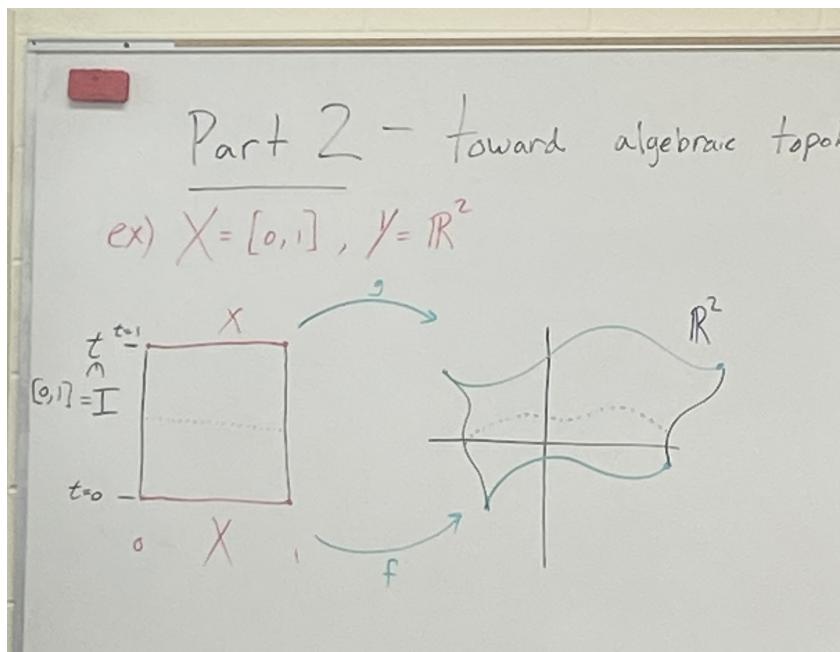
Today

- Starting Algebraic Topology!
 - Homotopy
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Homotopy

Definition 1. Let $f, g : X \rightarrow Y$ be continuous. Assume $[0, 1]$ has the subspace topology (from \mathbb{R}), and assume $X \times [0, 1]$ has the product topology. We say f and g are **homotopic**, and write $f \simeq g$ iff there exists a continuous function $H : X \times [0, 1] \rightarrow Y$ such that $H(x, 0) = f(x)$ and $H(x, 1) = g(x)$ for all $x \in X$. H is called a **homotopy**.

Example 1. Let $X = [0, 1]$, $Y = \mathbb{R}^2$.

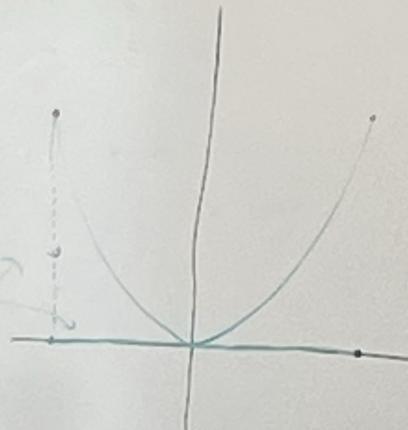
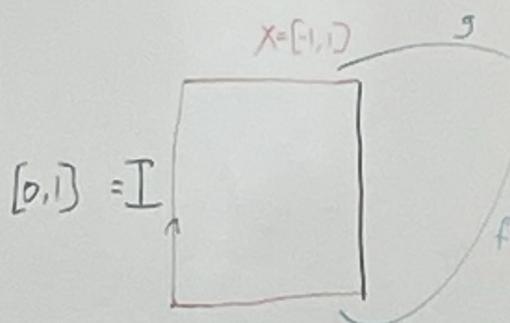


Example 2. Let $X = [-1, 1]$, $Y = \mathbb{R}^2$. Let $f(x) = x^2$ and $g(x) = 0$. This is called the straight line homotopy, and it implies that all polynomials are homotopic.

arc topology

$$\text{ex)} \quad X = [-1, 1], \quad Y = \mathbb{R}^2$$

$$f(x) = x^2, \quad g(x) = 0$$



Definition 2. An equivalence relation on a set A is a subset $R \subseteq A \times A$ such that:

1. (Reflexive) $(a, a) \in R, \forall a \in A$
2. (Symmetric) $(a, b) \in R$ implies that $(b, a) \in R, \forall a, b \in A$
3. (Transitive) $(a, b), (b, c) \in R$ implies $(a, c) \in R, \forall a, b, c \in A$.

We usually write $a \sim b$ to mean $(a, b) \in R$.

Definition 3. Let $C(X, Y) = \{\text{continuous maps from } X \text{ to } Y\}$.

Theorem 1. \simeq (homotopy) is an equivalence relation on the set of continuous maps $X \rightarrow Y$.

Proof:

1. Let $f \in C(X, Y)$. Is $f \simeq f$? Yes, via the homotopy, $H : X \times I \rightarrow Y$, where $H(x, t) = f(x)$.
2. Let $f, g \in C(X, Y)$ such that $f \simeq g$ via $H : X \times I \rightarrow Y$. We now want to show that there exists an $G : X \times I \rightarrow Y$. This works for $G(x, t) = H(x, 1 - t)$. Notice that $G(x, 0) = H(x, 1 - 0) = H(x, 1) = g(x)$ and $G(x, 1) = H(x, 1 - 1) = H(x, 0) = f(x)$, as desired, for any $x \in X$.
3. Transitivity: Exercise.