EX.NO.: 03

DATE: 23.06.2025

POINT DETECTION AND PERFORMANCE COMPARISON

AIM

To implement and compare the performance of three point detection algorithms—Harris Corner Detector, Shi-Tomasi Corner Detector, and SIFT Detector—based on the number of keypoints detected and their execution time.

ALGORITHM

- 1. Load the input image and convert it to grayscale.
- 2. Apply Harris Corner Detection and record the number of corners detected and execution time.
- 3. Apply Shi-Tomasi Corner Detection and record the number of corners detected and execution time.
- 4. Apply SIFT Keypoint Detection and record the number of keypoints detected and execution time.
- 5. Plot bar charts to compare the number of detected points and execution time for each method.
- 6. Display the performance comparison and print the numerical values for clarity.

CODE AND OUTPUT

```
import time
img = cv2.imread('image3.jpg')
gray = cv2.cvtColor(img, cv2.COLOR BGR2GRAY)
start = time.time()
harris = cv2.cornerHarris(np.float32(gray), blockSize=2, ksize=3, k=0.04)
harris = cv2.dilate(harris, None)
harris img = img.copy()
harris img[harris > 0.01 * harris.max()] = [0, 0, 255] # Mark corners in red
harris time = time.time() - start
start = time.time()
shi corners = cv2.goodFeaturesToTrack(gray, maxCorners=100, qualityLevel=0.01,
minDistance=10)
shi img = img.copy()
if shi corners is not None:
   for c in shi corners:
       x, y = c.ravel()
       cv2.circle(shi img, (int(x), int(y)), 3, (0, 255, 0), -1) # Green
shi_time = time.time() - start
start = time.time()
sift = cv2.SIFT create()
```

```
keypoints = sift.detect(gray, None)
sift img = cv2.drawKeypoints(img, keypoints, None,
flags=cv2.DRAW MATCHES FLAGS DRAW RICH KEYPOINTS)
sift time = time.time() - start
titles = ['Harris Corner', 'Shi-Tomasi Corner', 'SIFT Keypoints']
images = [harris img, shi img, sift img]
plt.figure(figsize=(18, 6))
for i in range(3):
   plt.subplot(1, 3, i + 1)
   plt.imshow(cv2.cvtColor(images[i], cv2.COLOR BGR2RGB))
   plt.title(f"{titles[i]}")
   plt.axis('off')
plt.show()
print(f"Harris Detector: {np.sum(harris > 0.01 * harris.max())} points, Time:
print(f"Shi-Tomasi Detector: {len(shi corners)} points, Time: {shi time:.4f}s")
print(f"SIFT Detector: {len(keypoints)} keypoints, Time: {sift time:.4f}s")
```







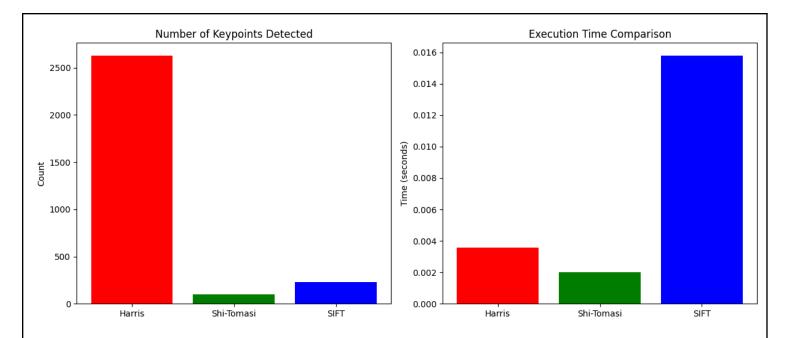
Harris Detector: 2090 points, Time: 0.0020s Shi-Tomasi Detector: 65 points, Time: 0.0000s SIFT Detector: 196 keypoints, Time: 0.0141s

```
import cv2
import numpy as np
import matplotlib.pyplot as plt
import time

# Load Image
img = cv2.imread('image1.jpg')
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# === 1. Harris Corner Detector ===
start = time.time()
harris = cv2.cornerHarris(np.float32(gray), blockSize=2, ksize=3, k=0.04)
harris = cv2.dilate(harris, None)
harris_points = np.sum(harris > 0.01 * harris.max()) # Approximate point count
harris_time = time.time() - start
```

```
start = time.time()
shi corners = cv2.qoodFeaturesToTrack(qray, maxCorners=100, qualityLevel=0.01,
minDistance=10)
shi points = len(shi corners) if shi corners is not None else 0
shi time = time.time() - start
# === 3. SIFT Detector ===
start = time.time()
sift = cv2.SIFT create()
keypoints = sift.detect(gray, None)
sift points = len(keypoints)
sift time = time.time() - start
# === Data for Chart ===
detectors = ['Harris', 'Shi-Tomasi', 'SIFT']
keypoints count = [harris points, shi points, sift points]
execution_time = [harris_time, shi_time, sift_time]
plt.figure(figsize=(12, 5))
plt.subplot(1, 2, 1)
plt.bar(detectors, keypoints count, color=['red', 'green', 'blue'])
plt.title('Number of Keypoints Detected')
plt.ylabel('Count')
plt.subplot(1, 2, 2)
plt.bar(detectors, execution time, color=['red', 'green', 'blue'])
plt.title('Execution Time Comparison')
plt.ylabel('Time (seconds)')
plt.tight layout()
plt.show()
# === Print for clarity ===
print(f"Harris: {harris points} points, Time: {harris time:.4f} sec")
print(f"Shi-Tomasi: {shi points} points, Time: {shi time:.4f} sec")
print(f"SIFT: {sift_points} points, Time: {sift_time:.4f} sec")
```



INFERENCE

Harris and Shi-Tomasi detectors are fast and suitable for simple corner detection tasks, while SIFT provides more robust and distinctive features but requires higher computation time. The comparison helps in choosing an appropriate detector based on accuracy and speed requirements.