

	balltr.m			Test3.m ×	addtitl.m	× Test	6.m ×	eci2ecf2.m		n × []	linkbudget42.m	X	Main2.m	× +	
75)=246.5598;												<u> </u>
76			0=14.7869;												-
77		58	at='CARTOSAT 2A';												
78															
79			CARTOSAT 2B												
80			n=97.4082;												
81			hm0=259.6822;												
82			0=0.014936;												
83			nega0=183.8495;												
84			0=176.2627;												
85			0=14.7869;												
86			at='CARTOSAT 2B';												
87			CARTOCAT OC												
88			CARTOSAT 2C												
89			n=97.4082; nm0=259.6822;												
90															
91			0=0.0014936;												
92			nega0=129.0233;												
93			D=288.5499;												
94			D=15.1924; at='CARTOSAT 2C';												
95			at-'CARIOSAI ZC';												
96 97			CARTOSAT 2D												
98			n=97.4428;												
99			hm0=260.1310;												
100			D=0.005160;												
101			nega0=281.3608;												
102			D=78.7046;												
103			0=15.1925;												
104			at='CARTOSAT 2D';												
105			,												
106		응(CARTOSAT 2E												
107			n=97.3975;												
108			nm0=256.9172;												
109			0=0.0080;												
110			mega0=332.8002;												
111			0=27.2809;												
112			n=15 1025·												v

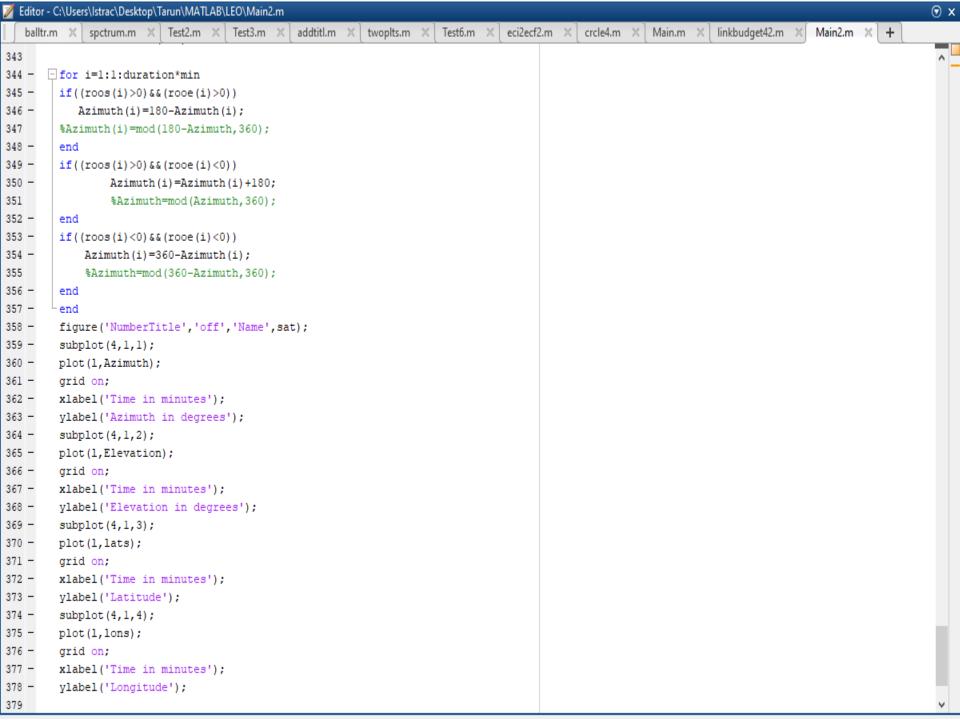
```
Editor - C:\Users\lstrac\Desktop\Tarun\MATLAB\LEO\Main2.m
                                                                                                                                                        balltr.m × spctrum.m × Test2.m × Test3.m ×
                                               addtitl.m X
                                                           twoplts.m X
                                                                       Test6.m X
                                                                                  eci2ecf2.m ×
                                                                                              crcle4.m × Main.m × linkbudget42.m ×
                                                                                                                                     Main2.m ×
159
160
161
162 -
         nrad=2*pi*n0/86400;%Mean motion in rad/s
        ndd=nrad*86400*rad2deg;%Mean motion in deg/day
163 -
        v=v0+(ndd.*duration);%Total motion in terms of days
164 -
165
166 -
        vrot=linspace(v0,v,duration*min); %True anamoly for total duration updated minute by minute
167 -
        vrot=mod(vrot,360);%scaled to 360 deg format
168
169 -
        a=(u./(nrad.^2))^0.333;%Semimajor axis a
170 -
         a=a/1000; %km
171 -
         rapogee=a.*(1+e0);%apogee
172 -
         rperigee=a.*(1-e0);%perigee
173 -
        ha=rapogee-re;%Apogee height
        hp=rperigee-re;%Perigee height
174 -
175 -
         k1=66063.17:%km^2
176
        %for l=linspace((Startfrac*min), (duration*min), (duration*min))
177
        1=linspace((Startfrac*min), (duration*min), (duration*min)); %Calculating for number of days in minutes
178 -
         k=(ndd.*k1)./((a.^2).*(1-e0.^2)); %deg/day
179 -
        dohmdt=cos(in.*deg2rad).*k.*(-1); %Rate of regression of nodes (Related to RAAN)
180 -
         ohm=ohm0+(dohmdt.*1);
181 -
        ohm=mod(ohm, 360);
182 -
183
184 -
         domegadt=k.*(2-2.5.*(sin(in.*deg2rad).^2));%deg/day
         omega=omega0+(domegadt.*1);
185 -
         omega=mod(omega,360);
186 -
        omegar=omega.*deg2rad;
187 -
         % scatter(1,ohm);
188
189
         % grid on;
         % hold on;
190
191
        % xlim([0 5000]);
192
        % ylim([0 370]);
193
        % pause (0.01)
194
        % end
195 -
         gmstr=gmst.*deg2rad;
106
```

```
Editor - C:\Users\lstrac\Desktop\Tarun\MATLAB\LEO\Main2.m
             spctrum.m X Test2.m X
                                                                                                                                      Main2.m × +
   balltr.m X
                                      Test3.m ×
                                                addtitl.m X
                                                                                                                      linkbudget42.m
                                                            twoplts.m X
                                                                        Test6.m X
                                                                                   eci2ecf2.m X
                                                                                                crcle4.m X
                                                                                                            Main.m X
         gmstr=gmst. ^aeg2raa;
195 -
196
197 -
         r=(a.*(1-(e0.^2)))/(1+e0.*cos(v0));
198 -
         vrotr=vrot.*deg2rad;
199 -
         rp=r.*(cos(vrotr));
200 -
         rq=r.*(sin(vrotr));
201 -
         rl=(cos(ohm).*cos(omega));
202 -
         r2=(sin(ohm).*sin(omega).*cos(in));
         r3=((-1).*cos(ohm).*sin(omega));
203 -
204 -
         r4=(sin(ohm).*cos(omega).*cos(in));
205 -
         r5=(sin(ohm).*cos(omega));
206 -
         r6=cos(ohm).*sin(omega).*cos(in);
207 -
         r7=((-1).*sin(ohm).*sin(omega));
208 -
         r8=cos(ohm).*cos(omega).*sin(in);
209 -
         r9=(sin(omega).*sin(in));
210 -
         rl0=(cos(omega).*sin(in));
211 -
         R12=r1-r2;
212 -
         R34=r3-r4:
213 -
         R56=r5+r6;
214 -
         R78=r7+r8;
215 -
         R9=r9;
216 -
         R10=r10;
217
         % alpha=(atan(cos(in).*tan(omegar+vrotr)).*rad2deg)+ohm;
218
         % alpha=mod(alpha, 360);
219
         % delta=(asin(sin(in).*sin(omegar+vrotr)).*rad2deg);
220
         % delta=mod(delta,360);
221
         % lons=alpha-gmst;
222
         % lons=mod(lons, 360);
223
224
225 -
         R=[R12;R56;R9;R34;R78;R10];
226 -
         Rm=[R12 R34;R56 R78;R9 R10];%R'
         Rd=[rp;rq];%|rp|
227 -
228
                     %|rq|
229
         % rI=(R12.*rp)+(R34.*rq);
         % rJ=(R56.*rp)+(R78.*rq);
230
231
         % rK=(R9.*rp)+(R10.*rq);
         $ S=/rT ^2\4/r.T ^2\4/rW ^2\.
```

```
Editor - C:\Users\lstrac\Desktop\Tarun\MATLAB\LEO\Main2.m
                                                                                                                                      Main2.m × +
   balltr.m × spctrum.m × Test2.m × Test3.m ×
                                                addtitl.m X
                                                            twoplts.m X Test6.m X
                                                                                   eci2ecf2.m 💥
                                                                                                crcle4.m X
                                                                                                           Main.m X
                                                                                                                      linkbudget42.m
         % rk=(k9.*rp)+(klu.*rq);
231
232
         S = (rI.^2) + (rJ.^2) + (rK.^2);
233
         % rv=sqrt(S);
234 -
       - for i=1:1:duration*min
235 -
         R2=R(1:3,i)*rp;%rl r3 r5
236 -
         R3=R(4:6,i)*rq;%r2 r4 r6
237 -
         rI=R2(1,1:i)+R3(1,1:i);%rI
238 -
         rJ=R2(2,1:i)+R3(2,1:i);%rJ
239 -
         rK=R2(3,1:i)+R3(3,1:i);%rK
240 -
         rIJK=[rI;rJ;rK];
241
         % S=(((rI(1,1:i)).^2)+((rJ(1,1:i)).^2)+((rK(1,1:i)).^2));
242
         % rv=sqrt(S);
243 -
         end
244 -
         xd=((rI.*cos(gmstr))+(rJ.*sin(gmstr)));
245 -
         yd=(((-1).*rI.*sin(gmstr))+rJ.*cos(gmstr));
246 -
         zd=rK;
247 -
         lons=atan(yd./xd);
248 -
         lats=atan(zd./sqrt((xd.^2)+(yd.^2)));
249 -
         lons=(lons.*rad2deg);
250 -
         lats=(lats.*rad2deg);
251 -
         S=(rI.^2)+(rJ.^2)+(rK.^2);
252 -
         rv=sqrt(S);
253 -
         Ee=0.08182; % Eccentricity of the earth
254 -
         nl=1-((Ee.^2).*(sin(lonr).^2));
255 -
         N=ae./sqrt(nl);
256 -
         L=(N+H) .*cos(lonr);
257 -
         lmstr=lmst.*deg2rad;
258 -
         RI=L.*cosd(lmstr);
259 -
         RJ=L.*sind(lmstr);
260 -
         RK = (N.*(1-(Ee.^2)) + H).*sind(lonr);%Z
261 -
         rooI=rI-RI;
262 -
         rooJ=rJ-RJ;
263 -
         rooK=rK-RK;
264 -
         siE=atan(RK./L);
265 -
         siED=siE.*rad2deg;
266 -
         w=siE;
267 -
         sll=sin(w).*cos(lmstr);
268 -
         ol?=oin/w/ *oin/lmotr/.
```

```
Editor - C:\Users\lstrac\Desktop\Tarun\MATLAB\LEO\Main2.m
                                                                                                                                                         Test3.m X
                                                                        Test6.m X
                                                                                   eci2ecf2.m X
                                                                                                           Main.m X
                                                                                                                     linkbudget42.m
                                                                                                                                      Main2.m ×
                                                                                                                                                 +
              spctrum.m × Test2.m
                                                addtitl.m X
                                                            twoplts.m X
                                                                                                crcle4.m X
267 -
         sil=sin(w).*cos(lmstr);
268 -
         s12=sin(w).*sin(lmstr);
269 -
         s13=(-1).*cos(w);
270 -
         s21=(-1).*sin(lmstr);
271 -
         s22=cos(lmstr);
272 -
         s23=0;
273 -
         s31=cos(w).*cos(lmstr);
274 -
         s32=cos(w).*sin(lmstr);
275 -
         s33=sin(w);
276 -
         S13=(1:(duration*min));
277 -
         S23=(1:(duration*min));
278 -
         S33=(1:(duration*min));
279 -
       for i=1:1:(duration*min)
280 -
             S13(i)=s13;
281 -
             S23(i)=s23;
282 -
             S33(i)=s33;
283 -
         end
284
         %rooSEZ=[sl1 sl2 Sl3;s21 s22 S23;s31 s32 S33];
285 -
         roosez=[s11;s21;s31;s12;s22;s32;S13;S23;S33];
286 -
        for i=1:1:duration*min
287 -
         rooA=roosez(1:3,i)*rooI;
288 -
         rooB=roosez(4:6,i)*rooJ;
289 -
         rooC=roosez(7:9,i)*rooK;
         % rooS=rooA(1,1:i)+rooB(1,1:i)+rooC(1,1:i);
290
291
         % rooE=rooA(2,1:i)+rooB(2,1:i)+rooC(2,1:i);
292
         % rooZ=rooA(3,1:i)+rooB(3,1:i)+rooC(3,1:i);
293
294
         % roo=sqrt(de);
295
         % des=(rooZ./roo);
296 -
         rooS=(sl1.*rooI)+(sl2.*rooJ)+(Sl3.*rooK);
297 -
         rooE=(s21.*rooI)+(s22.*rooJ)+(S23.*rooK);
298 -
         rooZ=(s31.*rooI)+(s32.*rooJ)+(S33.*rooK);
299 -
         de=(rooS(1,1:i).^2)+(rooE(1,1:i).^2)+(rooZ(1,1:i).^2);
300
         % de=(rooA(1,1:i).^2)+(rooB(1,1:i).^2)+(rooC(1,1:i).^2);
         rooSEZ=[rooS;rooE;rooZ];
301 -
302
         % de=(rooS.^2)+(rooE.^2)+(rooZ.^2);
303
         % roo=sqrt(de);
304
           dee=(roo7 /roo):
```

```
Editor - C:\Users\Istrac\Desktop\Tarun\MATLAB\LEO\Main2.m
                                                                                                                                                            balltr.m X
                                      Test3.m ×
                                                             twoplts.m X
                                                                                    eci2ecf2.m X
                                                                                                                        linkbudget42.m
                                                                                                                                        Main2.m ×
                                                                                                                                                   +
                           Test2.m X
                                                 addtitl.m
                                                                          Test6.m
                                                                                                 crcle4.m X
                                                                                                             Main.m X
3Ú6
          % roob=(sii.^rooi)+(siz.^roou)+(sis.^rook);
307
         % rooE=(s21.*rooI)+(s22.*rooJ)+(s23.*rooK);
308
         % rooZ=(s31.*rooI)+(s32.*rooJ)+(s33.*rooK);
         % rooSEZ=[rooS;rooE;rooZ];
309
310
         % % de=(rooS.^2)+(rooE.^2)+(rooZ.^2);
311
         % % roo=sqrt(de);
         % % des=(rooZ./roo);
312
313
         % de=(rooS.^2)+(rooE.^2)+(rooZ.^2);
314
         % roo=sqrt(de);
         % des=(rooZ./roo);
315
         % Elevation=asind(des);
316
317
         %Elevation=Elevation.*rad2deg;
318
         %Elevation=(Elevation);
319
         %Elevation=mod(Elevation, 180);
320 -
         roos=(1:duration*min);
321 -
         rooe=(1:duration*min);
322 -
        - for i=1:1:duration*min
323 -
              roos(i)=rooS(i);
324 -
             rooe(i)=rooE(i);
325
         % if(rooE(i)<0)
                rooE(i)=rooE(i).*(-1);
326
327
328
         % end
329
         % end
330
          % for i=1:1:duration*min
331
          % if(rooS(i)<0)
332
                rooS(i) = rooS(i) .*(-1);
333
         % end
334 -
          end
         Azimuth=atand(abs(rooE)./abs(rooS));
335 -
         %Azimuth=mod(Azimuth, 360);
336
         % %Azimuth=Azimuth.*rad2deg;
337
338 -
         azi=Azimuth:
339
          %Azimuth=mod(Azimuth, 360);
340 -
         roo=sqrt (de);
341 -
         des=((rooZ)./(roo));
342 -
         Elevation=asind(des);
3/13
```



Indian - Notepad	ΔX
File Edit Format View Help	
IRS P6 1 28051U 03046A 18199.1701254200000023 00000-0 76858-5 0 9994 2 28051 98.5525 276.0870 0056831 303.7850 55.7928 14.34156773766018	^
CARTOSAT-1 (IRS P5) 1 28649U 05017A 18199.16117770 .00000084 00000-0 16599-4 0 9996 2 28649 97.8218 271.3703 0001871 148.3680 211.7671 14.83476051714686	
CARTOSAT 2AT 1 29710U 07001B 18199.1836022900000129 00000-0 -10719-4 0 9992 2 29710 97.8733 257.9920 0001044 51.2651 308.8671 14.78714543621715	
CARTOSAT 2A 1 32783U 08021A 18199.16133920 .00000125 00000-0 23941-4 0 9998 2 32783 97.8747 258.1189 0014365 113.7127 246.5598 14.78698447551651	
CARTOSAT 28 1 36795U 10035A 18199.19809141 .00000053 00000-0 14227-4 0 9998 2 36795 97.8725 257.8589 0014378 183.8495 176.2627 14.78698878432708	
CARTOSAT 2C 1 41599U 16040A 18199.17104508 .00000403 00000-0 22284-4 0 9992 2 41599 97.4082 259.6822 0014936 129.0233 288.5449 15.19248425114778	
CARTOSAT 2D 1 41948U 17008A 18198.86589900 +.00000363 +00000-0 +20454-4 0 9995 2 41948 097.4428 260.1310 0005160 281.3608 078.7046 15.19252302078596	
CARTOSAT 2E 1 42767U 17036C 18198.87379413 +.00000363 +00000-0 +20401-4 0 9995 2 42767 097.3975 256.9172 0008080 332.8002 027.2809 15.19241156059168	
OCEANSAT 2 1 35931U 09051A 18199.23755978 .00000076 00000-0 30419-4 0 9994 2 35931 98.3062 293.7925 0003537 67.0117 293.1451 14.50848789466889	
RESOURCESAT 2A 1 41877U 16074A 18199.16276453 .00000002 00000-0 20571-4 0 9998 2 41877 98.6703 273.5977 0000619 109.6629 250.4627 14.21654907 83546	
RISAT 1 1 38248U 12017A 18199.06791515 .00000196 00000-0 16147-4 0 9997 2 38248 97.5702 206.8083 0005542 115.9290 293.4380 15.09559923342957	
SARAL 1 39086U 13009A 18198.9266308000000012 +00000-0 +11750-4 0 9992 2 39086 098.5409 025.3311 0001845 124.3523 235.7835 14.32018797281743	
GEOSYNCHRONOUS SATELLITES:	
IRNSS R1A 1 39199U 13034A 18197.33087615 .00000068 00000-0 00000+0 0 9994 2 39199 29.4959 108.3047 0017870 178.4468 181.5322 1.00269647 18630	

3 day plot for IRS P6

■ IRS P6

