

Linear 1st order ODEs

General form

$$a(x)y' + b(x)y = c(x)$$

Standard form

$$y' + p(x)y = q(x)$$

Solution → follow two steps

$$\text{I.f. } u(x) = e^{\int p(x)dx} \quad \text{①}$$

$$\text{Then } y(x) = \int q(x)u(x)dx + C \quad \text{②}$$

Keywords to learn in this lecture

• formula to solve

$$y'(x) = p y + q(x)$$

$y(t_0) = y_0$; where P is constant
and its extension for system
of equations

• steady-state solution
and transient solution

• Input - response
and superposition rule of
linearity.

• Geometrical meaning of
 $y' = f(x, y)$

and IVPs.

Heat conduction model

$$\frac{dT}{dt} = k(T_e - T)$$

$$\Rightarrow \frac{dT}{dt} = -kT + kT_e$$

concentration diffusion model

$$\frac{dc}{dt} = k(C_e - C)$$

Fluid mixing model

$$\frac{dx}{dt} + \frac{V}{V} \partial x = r C_e$$

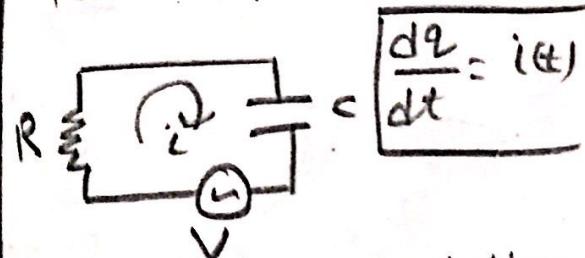
population growth

$$\frac{dx}{dt} = a x$$

Bank A/c interest

$$\frac{dx}{dt} - I(t)x(t) = q(t)$$

RC - Circuits



$q(t)$: charge on C at time t .

By Kirchhoff's Law

$$Ri + \frac{q}{C} = V(t)$$

$$\Rightarrow \frac{dq}{dt} + \frac{1}{RC} q = \frac{1}{R} V(t)$$

Solve:

NOTE that
ODE is not written in
standard form

$$\text{ODE} \rightarrow \dot{x} = px + q(t)$$

where p is a constant and

$$I/C \rightarrow x(t_0) = x_0$$

$$\dot{x} \equiv \frac{dx}{dt}$$

first solve ODE

$$\frac{dx}{dt} = px + q(t)$$

$$\Rightarrow \dot{x} - px = q(t) \quad [\text{standard form}]$$

$$\text{Find IF } u(t) = e^{-\int p dt} = e^{-pt}$$

$\because p$ is a constant

Then solution

$$x(t)u(t) = \int u(t) q(t) dt + C$$

$$\Rightarrow x(t) \bar{e}^{-pt} = \int \bar{e}^{-ps} q(t) dt + C$$

$$= \int \bar{e}^{-ps} q(s) ds + C$$

$$\Rightarrow x(t) = e^{pt} \int \bar{e}^{-ps} q(s) ds + e^{pt} C$$

Since, initial time is t_0 , we can write solution $x(t)$ in the form of definite integral

$$x(t) = e^{pt} \int_{t_0}^t \bar{e}^{-ps} q(s) ds + e^{pt} C_0$$

put $x(t_0) = x_0$ and obtain $C_0 = x_0$

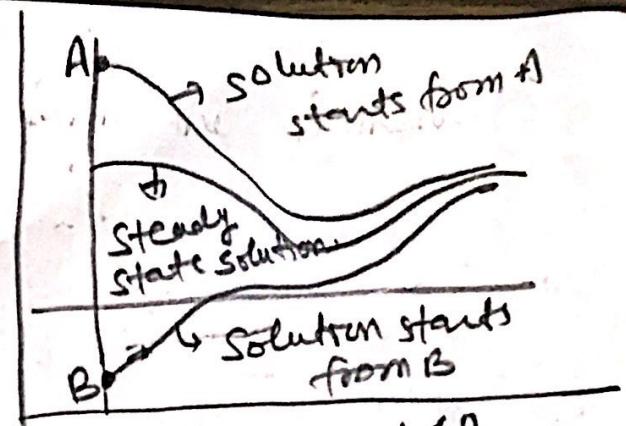
$$x(t) = e^{pt} x_0 + \int_{t_0}^t e^{p(t-s)} q(s) ds$$

Some Important conclusions

Thus, for IVP

$$\frac{dx}{dt} = x' = p x + q(t)$$

$$x(t_0) = x_0$$



Solution is

$$x(t) = \underbrace{-e^{pt} x_0}_{\text{(If } p < 0 \text{ and } t \rightarrow \infty)} + \boxed{\int_{t_0}^t e^{p(t-s)} q(s) ds}$$

in case $p < 0$
called steady-state solution

\rightarrow [called transient solution]

In engineering models : these keywords are very famous as 'in many ODEs term $p < 0$

steady state solution
transient solution

[see Heat conduction
concentration diffusion
mixing problems
RC-circuits.]

Remember! ↑
Keywords for linear ODE

$$y' = py + q(t)$$

are valid when $p < 0$. [p is a negative constant]
But this ($p < 0$) is not the case in all situations: Normally $p > 0$ in models in economics and biology

↑
See bank Account model

↑
population / decay model / model-

One more reason to define formula

$$x(t) = e^{pt} x_0 + \int_{t_0}^t e^{p(t-s)} q(s) ds$$

for IVP $\begin{cases} \dot{x} = px + q(t) \\ x(t_0) = x_0 \end{cases}$

is that it works in system of equation.

$$\dot{x} = Ax + f(t)$$

$$x(0) = x_0$$

Its solution is

$$x(t) = e^{At} x_0 + \int_{t_0}^t e^{A(t-s)} f(s) ds$$

details will come
after 2 weeks.

$$\dot{x} = 2x + 3y + f_1(t)$$

$$\dot{y} = 5x + 2y + f_2(t)$$

|||

$$\dot{x} = Ax + f(t)$$

where

$$x = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 3 \\ 5 & 2 \end{bmatrix}$$

$$f = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

Always use algorithm to solve scalar linear ODE after writing it in standard form.

Another Imp keywords for

$$y' + p(x)y = q(x)$$

are

Input \rightarrow RHS term $q(x)$

Response \rightarrow solution $y(x)$.

one Imp property of linear equations.

If response for

$$q_1 \xrightarrow{\text{is}} y_1$$

$$\text{and } q_2 \xrightarrow{\text{is}} y_2$$

Then response for $q_1 + q_2 \xrightarrow{\text{is}} y_1 + y_2$

$$\text{and } \alpha q_1 \xrightarrow{\text{is}} \alpha y_1$$

[THIS is called

superposition rule

of linearity

Imp
Keywrd

Easy to prove

\hookrightarrow check yourself!)

find response of $y' + ky = kq(t)$ when $q(t) = \cos \omega t$

$k > 0$ is constant

"
Solve

$$\frac{dy}{dt} + ky = k \cos \omega t$$

$k > 0$ is constant

Apply Algorithm

$$\frac{dy}{dt} + ky = k \cos \omega t \quad (\text{standard form})$$

$$IF = e^{\int k dt}$$

$$\text{so } y e^{\int k dt} = \int e^{\int k dt} \cos \omega t dt + C$$

()
|
|
|

OR use a trick due to superposition rule

$$\cos \omega t \rightarrow y_1(t)$$

$$\sin \omega t \rightarrow y_2(t)$$

$$\text{then } \cos \omega t + i \sin \omega t \rightarrow y_1 + iy_2$$

$$\text{OR } e^{i\omega t} \rightarrow \bar{y} (\in y_1 + iy_2)$$

$$\text{so first find } \bar{y} \text{ for } e^{i\omega t}$$

and then find real part of \bar{y} .

$$y' + ky = k \cos \omega t \quad \text{--- (1)}$$

Complexify the ODE

$$\tilde{y}' + k\tilde{y} = k e^{i\omega t} \quad \text{--- (2)}$$

Now solve (2)

$$\begin{aligned}\tilde{y} e^{kt} &= k \int e^{kt} e^{i\omega t} dt + C \\ &= k \int e^{(k+i\omega)t} dt + C \\ &= \frac{k}{k+i\omega} e^{(k+i\omega)t} + C\end{aligned}$$

$$\Rightarrow \tilde{y} = \frac{k}{k+i\omega} e^{i\omega t} + C e^{-kt}$$

$$= \frac{k(k-i\omega)}{k^2+\omega^2} (\cos \omega t + i \sin \omega t) + C e^{-kt}$$

If $\tilde{y} = y + iu$ then the required response
is y , and that is

$$\begin{aligned}y(t) &= \frac{k}{k^2+\omega^2} \operatorname{Re} \left\{ (k-i\omega) (\cos \omega t + i \sin \omega t) \right\} \\ &\quad + C e^{-kt} \\ &= \frac{k}{k^2+\omega^2} [k \cos \omega t + \omega \sin \omega t] + C e^{-kt}.\end{aligned}$$

A meaningful assumption

GEOMETRICAL METHOD

OR
Graphical method

ODE has one and only solution passing through any point (x_0, y_0)

↳ All other ODEs are not of practical importance

- We will read in details under what conditions this assumption holds.

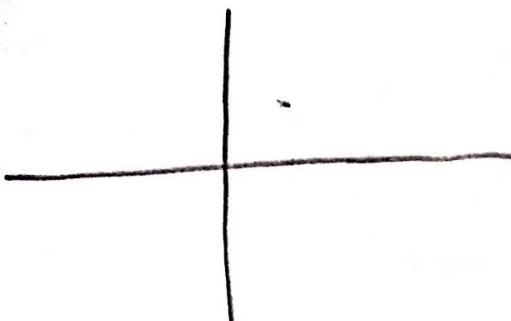
	Analytical meaning	geometrical names
ODE $\rightarrow y' = f(x, y)$		Direction field
Solution	A function $y(x)$ that satisfies ODE	integral/solution curve

Geometrically problem is - we know $\frac{dy}{dx}$ in the $x-y$ plane, i.e. given by $f(x, y)$, and we have to find y .

Slope is given; function is to be calculated

→ How to draw direction field for $y' = f(x, y)$ with the help of computer (computer method)

1. Pick (x_i, y) - (equally spaced)
2. Compute $f(x_i, y)$
3. draw a small line segment at (x_i, y) having slope $f(x_i, y)$



By using pen and paper (manual method)

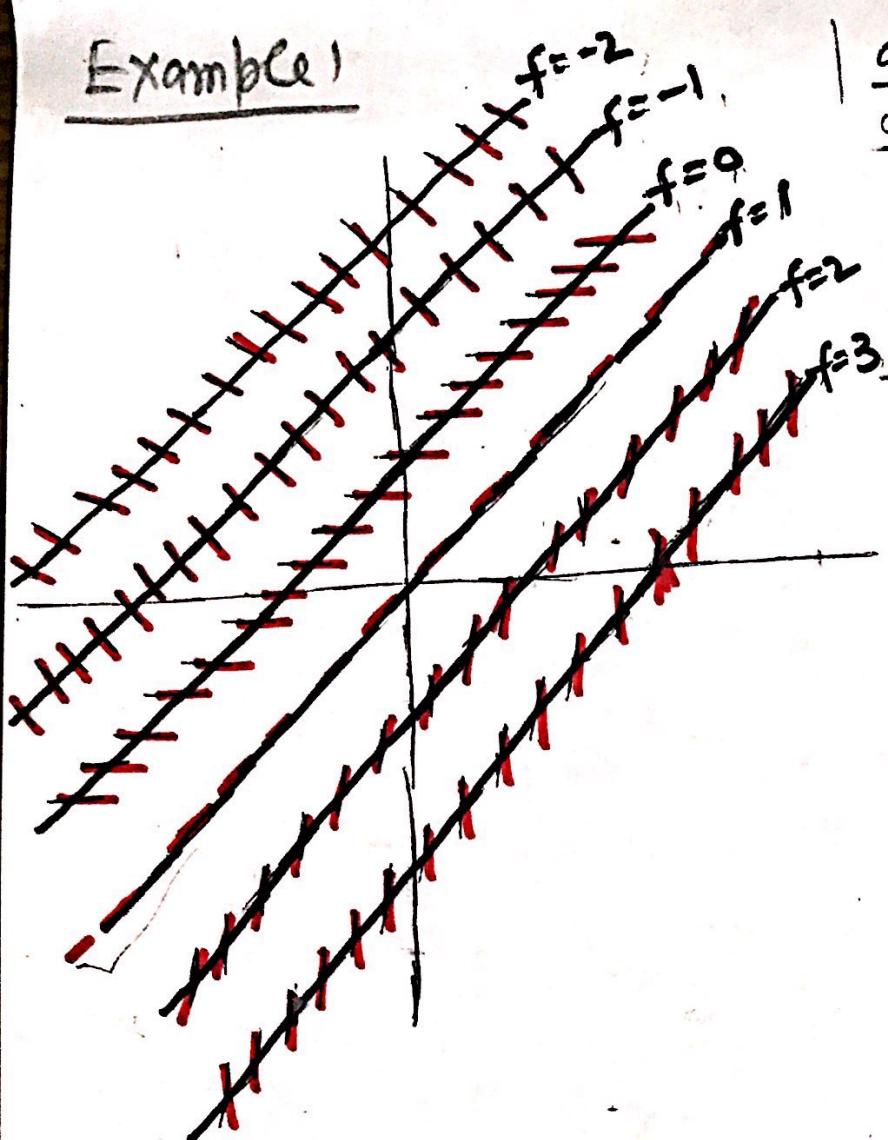
step 1 pick slope c

step 2 plot $f(x,y) = c \rightarrow$
called isocline

MA101
level curve of
 f at level
value c .

step 3 draw small line segment
on above isoclines having
slope c .

Example 1



$$\frac{dy}{dx} = 1 + x - y$$

Step 1

Plot some isolines

$$(i) \quad f = -2$$

$$1 + x - y = -2$$

$$\Rightarrow y = x + 3$$

$$(ii) \quad f = -1$$

$$1 + x - y = -1$$

$$\Rightarrow y = x + 2$$

$$(iii) \quad f = 0$$

$$1 + x - y = 0$$

$$\Rightarrow y = x + 1$$

$$(iv) \quad f = 1 \Leftrightarrow y = x$$

$$(v) \quad f = 2 \Leftrightarrow y = x - 1$$

$$(vi) \quad f = 3 \Leftrightarrow y = x - 2$$

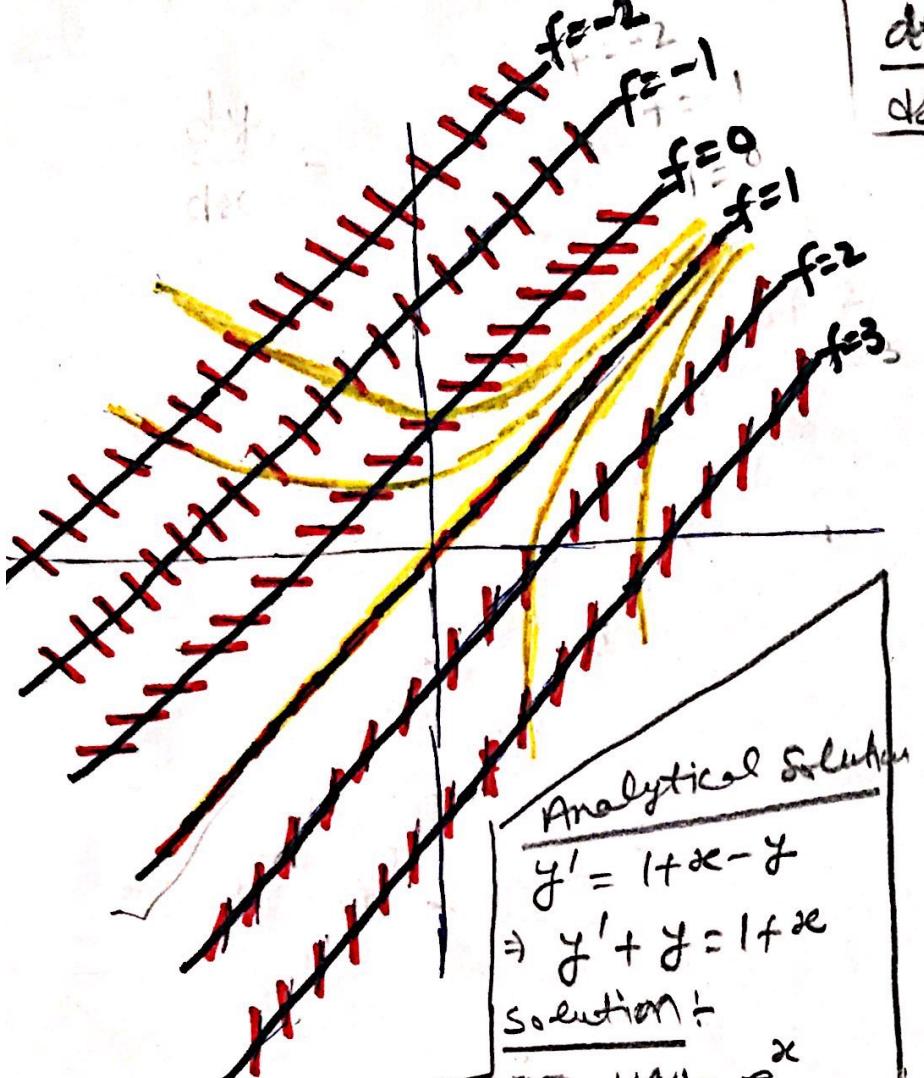
Step 2

draw direction

field on isolines

Step 3

draw a few
integral curves.



$$\frac{dy}{dx} = 1 + xe - y$$

Step 1

Plot some isoclines

$$(i) \quad f = -2$$

$$1 + xe - y = -2$$

$$\Rightarrow y = xe + 3$$

$$(ii) \quad f = -1$$

$$1 + xe - y = -1$$

$$\Rightarrow y = xe + 2$$

$$(iii) \quad f = 0$$

$$1 + xe - y = 0$$

$$\Rightarrow y = xe + 1$$

$$(iv) \quad f = 1 \Leftrightarrow y = xe$$

$$(v) \quad f = 2 \Leftrightarrow y = xe - 1$$

$$(vi) \quad f = 3 \Leftrightarrow y = xe - 2$$

$$y(0) e^{2x} = \int (1 + xe) e^{2x} dx + C$$

$$\Rightarrow y(0) = \underbrace{xe + C e^{-2x}}_{\text{as } x \rightarrow \infty}$$

Yellow curves

↳ Integral / solution curves.

Remember

• Two integral curves cannot cross

• Two integral curves cannot touch

Geometrical method gives some feeling how analytical solution behaves / qualitative properties

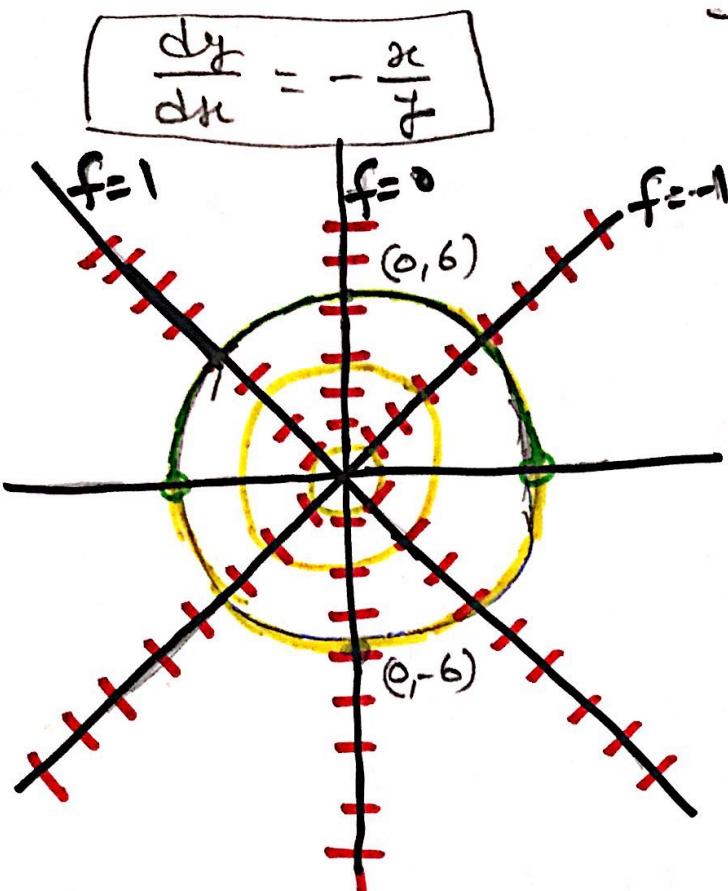
Step 2
draw direction

field on isoclines

Step 3

draw a few
integral curves.

Example 2



Analytic solution

Separable case

$$\begin{aligned} dx dx + y dy &= 0 \\ \Rightarrow x^2 + y^2 &= C \end{aligned}$$

geometric view

Step 1 draw isoclines

$$\begin{aligned} (i) \quad f &= -1 \\ \Rightarrow -\frac{x}{y} &= -1 \\ \Rightarrow y &= x \end{aligned}$$

$$(ii) \quad f = 0 \Rightarrow x = 0$$

$$(iii) \quad f = 1 \Rightarrow y = -x$$

See again

$$\frac{dy}{dx} = -\frac{x}{y}; \quad y(0) = 6 \rightarrow \text{IVP1}$$

$$\frac{dy}{dx} = -\frac{x}{y}; \quad y(0) = -6 \rightarrow \text{IVP2}$$

The particular solution of both IVPs is

$$x^2 + y^2 = 36,$$

This gives that upper part of circle $x^2 + y^2 = 36$ is an explicit solution of IVP①; and lower part of the circle is an explicit solution of IVP②. Moreover interval of validity for both is $(-6, 6)$.

Step 2 draw direction field

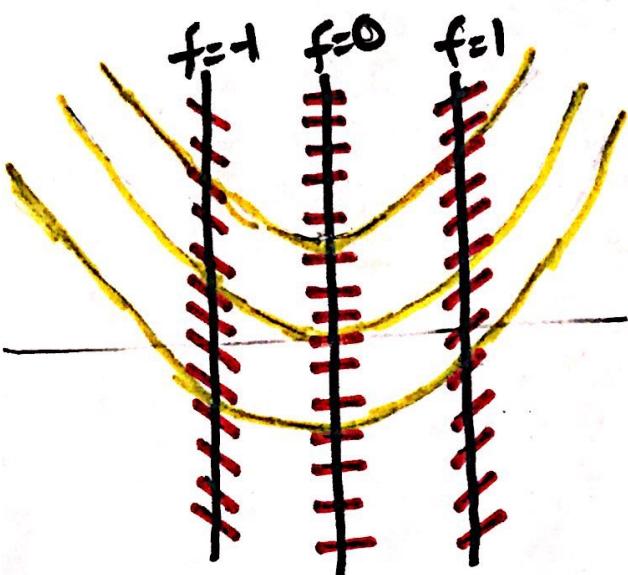
Step 3 draw some integral curves

Example ③

$$\frac{dy}{dx} = f(x)$$

particular example

$$\frac{dy}{dx} = 2x$$



Analytic solution

(Separation of variables)

$$y = \int f(x) dx + C$$

Using fundamental thm, we write

$$y = \int_a^x f(t) dt + C$$

↳ provided initial data is given at $x = a$
i.e. $y(a) = c$

Step 1 draw isoclines

$$(i) f = -1 \Rightarrow x = -\frac{1}{2}$$

$$(ii) f = 0 \Rightarrow x = 0$$

$$(iii) f = 1 \Rightarrow x = \frac{1}{2}$$

Step 2 draw direction field

Step 3 draw a few integral curves.

In case $y = f(x)$

- ① Isoclines are \parallel to y -axis.
- ② If we know one integral curve then ~~it has~~ its vertical translation is also an integral curve.

Example ④

$$\frac{dy}{dx} = f(y)$$

Such equations are known as
Autonomous ODEs.

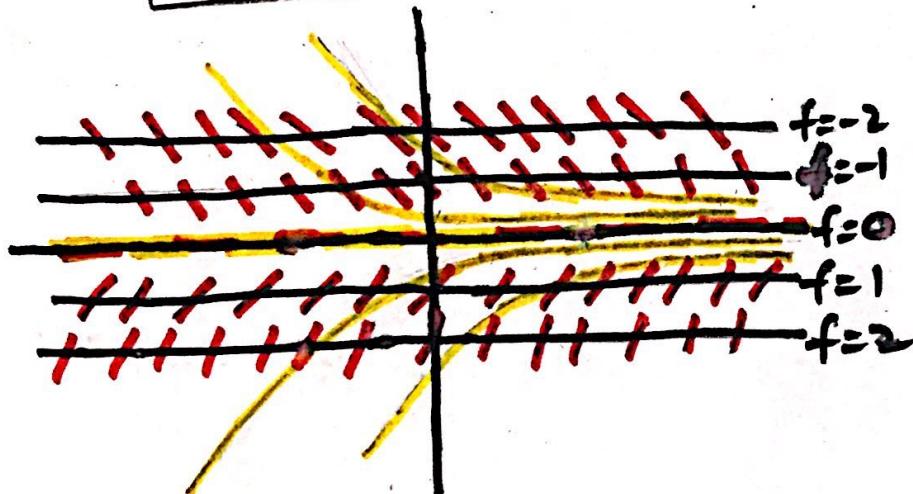
when $x \rightarrow \text{time } (t)$ then other famous name is
time-invariant ODEs.

Particular example

$$\frac{dy}{dx} = -3y$$

Solution Analytic $\rightarrow y(x) = C e^{-3x}$

geometrical



Analytic solution
Use method for separable
equations.
Use Solver for linear
equation if $f(y) = ay$

Step 1 draw isoclines

$$(i) f = -2 \Rightarrow y = \frac{2}{3}$$

$$(ii) f = -1 \Rightarrow y = \frac{1}{3}$$

$$(iii) f = 0 \Rightarrow y = 0$$

$$(iv) f = 1 \Rightarrow y = \frac{1}{3}$$

$$(v) f = 2 \Rightarrow y = \frac{2}{3}$$

Step 2 direction field

Step 3 integral curves

Some Important facts about $y' = f(y)$

① (Definition) If $f(y_0) = 0$ at some value y_0 of y ,
Then y_0 is called a critical point and curve
 $y = y_0$ is called a steady state solution of ODE.

② Isoclines are \parallel to x -axis

③ If we knew one integral curve then its
horizontal translation is also an integral
curve.

④ Result) The critical point $y = y_0$ is called stable for ODE $y' = f(y)$

If $\frac{df}{dy} \Big|_{y=y_0} < 0$ and unstable

If $\frac{df}{dy} \Big|_{y=y_0} > 0$.

Stable means

$y(t) \rightarrow y_0$ as $t \rightarrow \infty$
when $|y(t_0) - y_0| < \epsilon$ for some t_0

Justification of Result

$$\begin{aligned}\frac{d}{dt}(y(t) - y_0) &= \frac{dy}{dt} - \frac{dy}{dt}|_{y=y_0} \\ &= f(y) - 0 \xrightarrow{\text{from ODE}} \frac{dy}{dt} = f(y) \\ &= f(y) - f(y_0) \quad \left. \begin{array}{l} \text{& } y_0 \text{ is constant} \\ \text{by definition} \\ \text{of critical pt} \end{array} \right\} \\ &\leq \frac{df}{dy} (y - y_0) \\ &< 0 \quad \underline{\text{when } \frac{df}{dy} < 0 \text{ and } |y - y_0| > 0}\end{aligned}$$

$\Rightarrow y(t) - y_0$ is decreasing as t increases.

Hence for this example $y=0$ is a stable critical point.

OR

$y=0$ is a stable steady state solution. ??

Ex(5)

$$\frac{dy}{dt} = ay - by^2 \quad (a, b > 0)$$

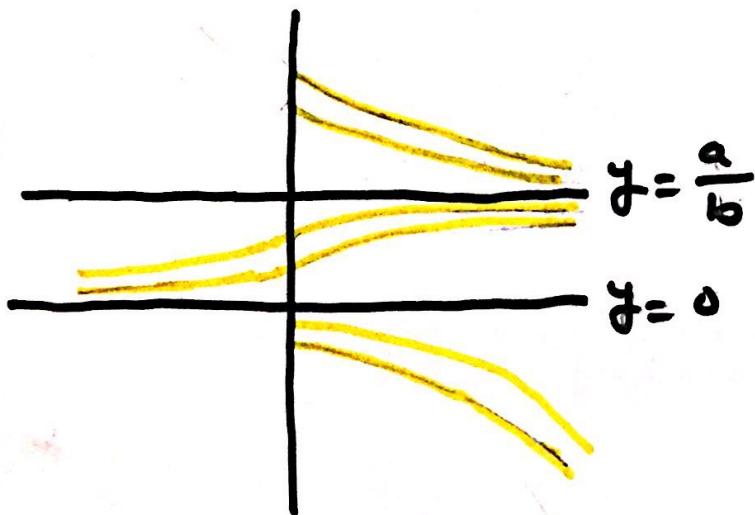
$$f(y) = ay - by^2 \\ = y(a - by)$$

$$\therefore f(y) = 0$$

$$\Rightarrow y = 0, \frac{a}{b}$$

$$\left. \frac{df}{dy} \right|_{y=0} = a - 2by \Big|_0 = a \Rightarrow y=0 \text{ is unstable}$$

$$\left. \frac{df}{dy} \right|_{y=\frac{a}{b}} = a - 2by \Big|_{y=\frac{a}{b}} = -2a \Rightarrow y=\frac{a}{b} \text{ is stable}$$



Thus, we can find the nature of solution curves without drawing direction field.

$$\frac{dy}{dx} = f(y)$$

Note that logistic model is non-linear and its analytic sol. is not easy by separation.

About ODE

Remember basic population model

$$\frac{dy}{dt} = ky \quad k > 0 \text{ is growth rate/tim}$$

Actually a declines as y increases because resources are limited. Take $f = a - by$ ($a, b > 0$)

Thus this model is well known as Logistic model for population dynamics.

Figure 0.4

Read Section 8.1 from SL Ross.

Exercises

Employ the method of isoclines to sketch the approximate integral curves of each of the differential equations in Exercises 1–12.

$$1. \frac{dy}{dx} = 3x - y.$$

$$2. \frac{dy}{dx} = \frac{y}{x}.$$

$$3. \frac{dy}{dx} = \frac{y}{x^2}.$$

$$4. \frac{dy}{dx} = x^2 + 2y^2.$$

$$5. \frac{dy}{dx} = \frac{3x - y}{x + y}.$$

$$6. \frac{dy}{dx} = \sin x - y.$$

$$7. \frac{dy}{dx} = y^3 - x^2.$$

$$8. \frac{dy}{dx} = \frac{3x + 2y + x^2}{x + 2y}.$$

$$9. \frac{dy}{dx} = \frac{3x + y + x^3}{5x - y}.$$

$$10. \frac{dy}{dx} = \frac{\sin x + y}{x - y}.$$

$$11. \frac{dy}{dx} = \frac{(1 - x^2)y - x}{y}.$$

$$12. \frac{dy}{dx} = \frac{10(1 - x^2)y - x}{y}.$$