Pépelining is a process/technique that helps en emplementing a form of instruction level parallelism. In this technique, multiple instructions are overlapped during execution.

The above schematic is an implementation of 6 stage pipelined ovichitecture where data memory is divided into 2 stages DMI and DM2. Pipelining increases the overall throughput

(b) Yes, the performance may increase on dividing the data memory into DM, and DMz, given the uncumstance that memory stage is major lime defining step.

As we know that once the pipeline is full one instruction is completed energy cycle let us assume instruction is completed energy cycle let us assume for our circuit <u>CPI=1</u>. (for large no of instruction)

Total time for executing a set of instruction

= Number of cycles x time period

e (m+k-1) x T

2 nxT

It the data memory stage is the most time consuming step, then it will determine time period "T" of the circuit. The Therefore, by dividing data memory into "2 parts, we can speed up our performance.

(P.T.O)

On dividing,

DM, Only decodes and provide address to

memory array where the data is stored while DM2

"reads and outputs the data . Let time required

by original data memory be "t_1", DM, be "t_2"

and DM2 be "(t, -t_2)"="t_3"

and DM2 be "t_1" . This can

therefore the time required the This can "t" to "man (tz, t,-tz)". This can considerably improve the throughput and

For en: - let us suppose that $t_1 = 50 \text{ ns}$

Time for (DM_1) . $t_2 = 15 \text{ ms}$

Time for (DM2) (t1-t2) = t3 = 35 ns

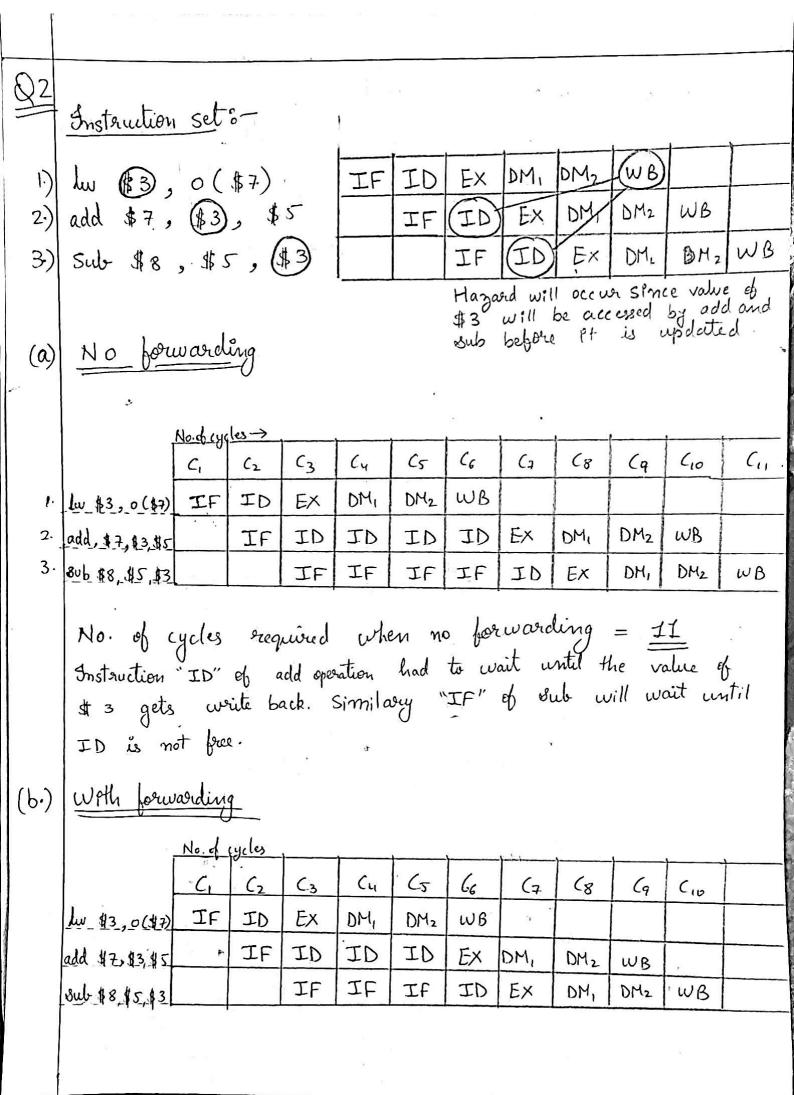
Suppose Time for all other stage is 35ns, then the new time period will be man (35, 15) = 35 ns.

.. Initial execution time = mx50 after dividing into estageir = mx35

35n < 50 m

Thus performance invæsed considerably.

(P.T.O.)



No. of clock cycle required = 10 TD' stage of add instruction will wait until the value of o(\$17) is fetched from DM2. and forwarded to it. Thus add can access value of \$13 one stage before UB, thus it require the 1 cycle less.

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