



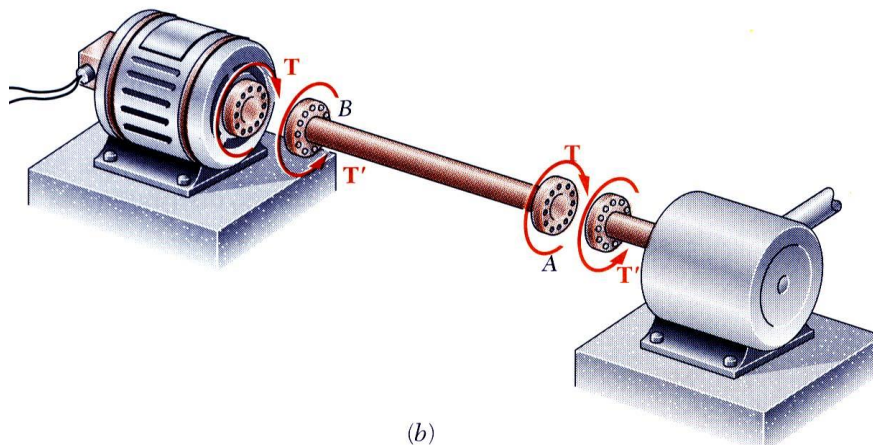
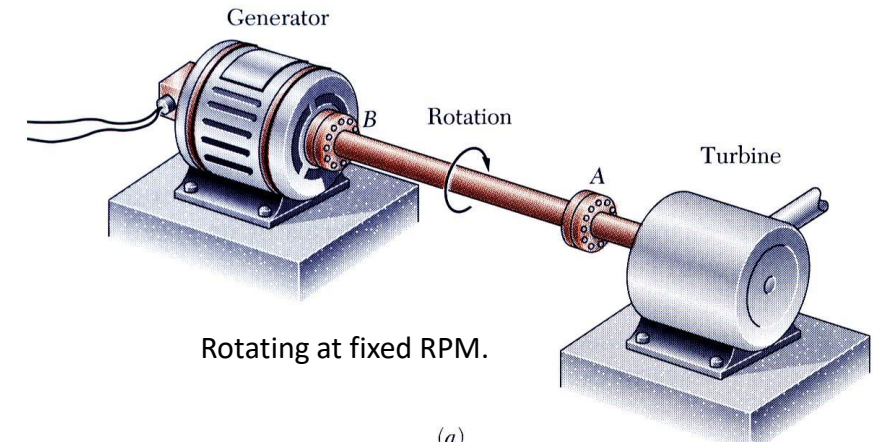
# Torsion

## Lecture 13

Engineering Mechanics - ME102

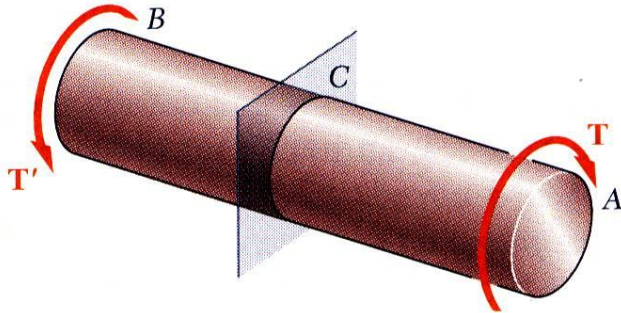
Rishi Raj

# Torsional Loads on Circular Shafts



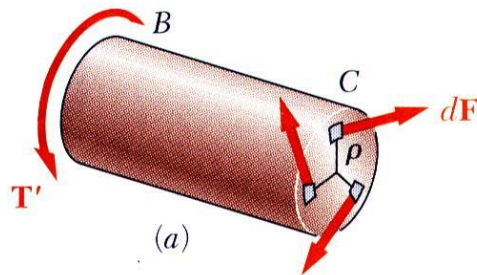
- Interested in stresses and strains of circular shafts subjected to twisting couples or *torques*
- Turbine exerts torque  $T$  on the shaft
- Shaft transmits the torque to the generator
- Generator creates an equal and opposite torque  $T'$

# Net Torque Due to Internal Stresses

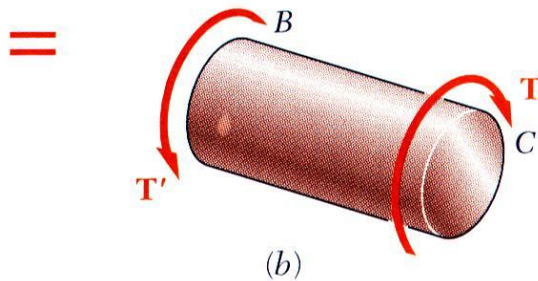


- Net of the internal shearing stresses is an internal torque, equal and opposite to the applied torque,

$$T = \int \rho \, dF = \int \rho (\tau \, dA)$$



- Although the net torque due to the shearing stresses is known, the distribution of the stresses is not



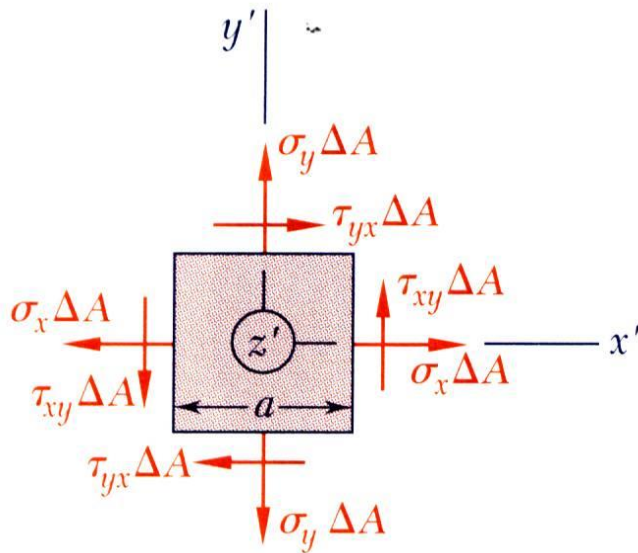
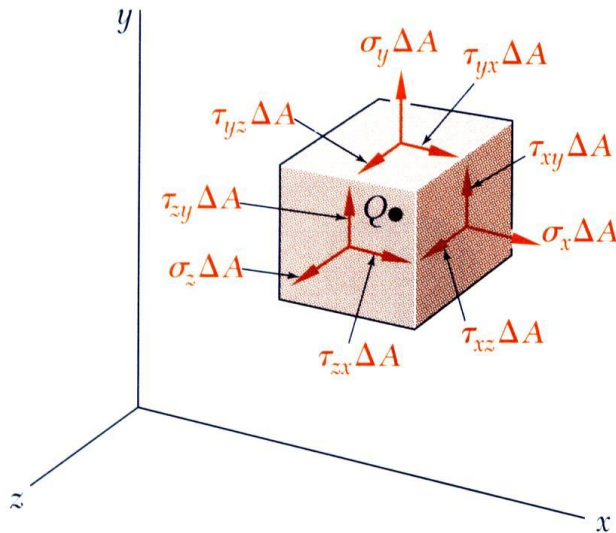
- Distribution of shearing stresses is ***statically indeterminate*** – must consider shaft deformations
- Unlike the normal stress due to axial loads, the ***distribution of shearing stresses due to torsional loads can not be assumed uniform.***

# Do you remember?



- At a point, shear stress cannot take place in one plane only, an equal shear stress must be exerted on another plane perpendicular to the first one.

# State of Stress



- Stress components are defined for the planes cut parallel to the  $x$ ,  $y$  and  $z$  axes. For equilibrium, equal and opposite stresses are exerted on the hidden planes.

- The combination of forces generated by the stresses must satisfy the conditions for equilibrium:

$$\sum F_x = \sum F_y = \sum F_z = 0$$

$$\sum M_x = \sum M_y = \sum M_z = 0$$

- Consider the moments about the  $z$  axis:

$$\sum M_z = 0 = (\tau_{xy}\Delta A)a - (\tau_{yx}\Delta A)a$$

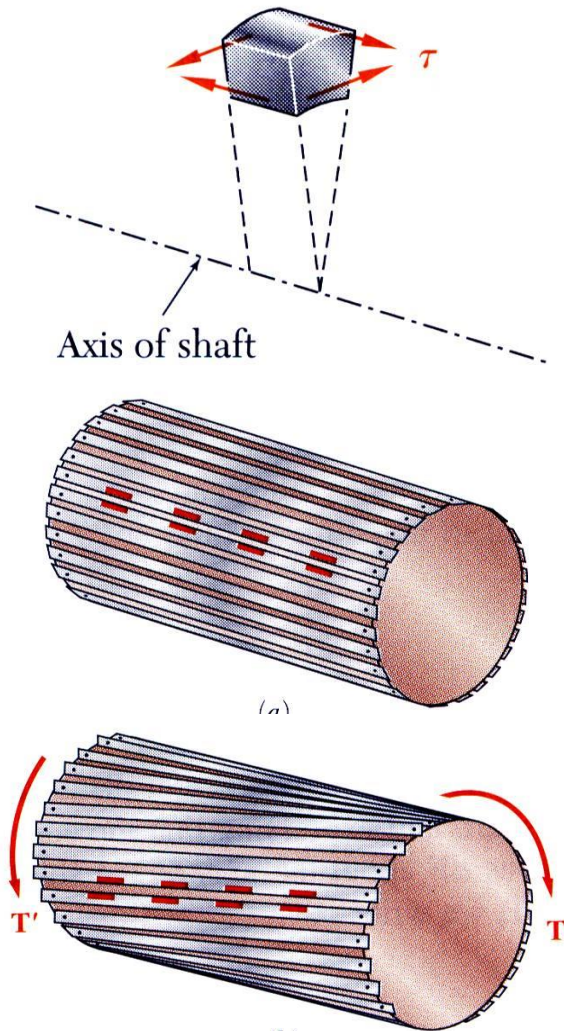
$$\tau_{xy} = \tau_{yx}$$

$$\text{similarly, } \tau_{yz} = \tau_{zy} \quad \text{and} \quad \tau_{yx} = \tau_{xy}$$

- It follows that only 6 components of stress are required to define the complete state of stress



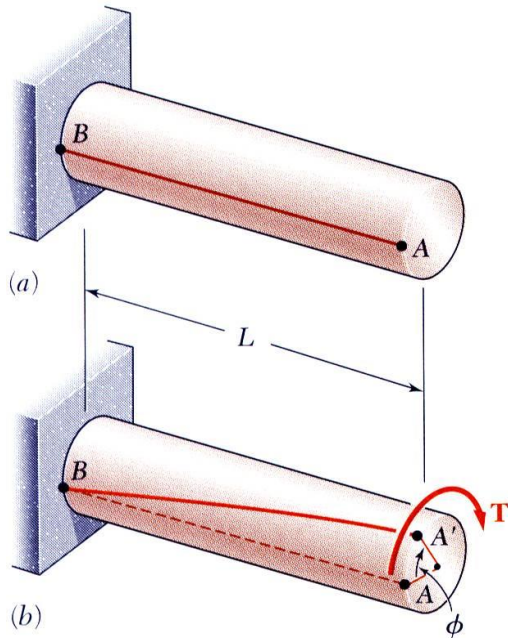
# Axial Shear Components



- Torque applied to shaft produces shearing stresses on the faces perpendicular to the axis.
- *Conditions of equilibrium require the existence of equal stresses on the faces of the two planes containing the axis of the shaft*
- The existence of the axial shear components is demonstrated by considering a shaft made up of axial slats.

The slats slide with respect to each other when equal and opposite torques are applied to the ends of the shaft.

# Shaft Deformations

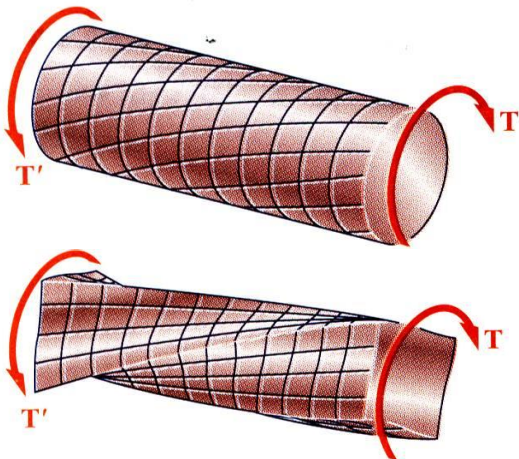


- From observation, the angle of twist of the shaft is proportional to the applied torque and to the shaft length.

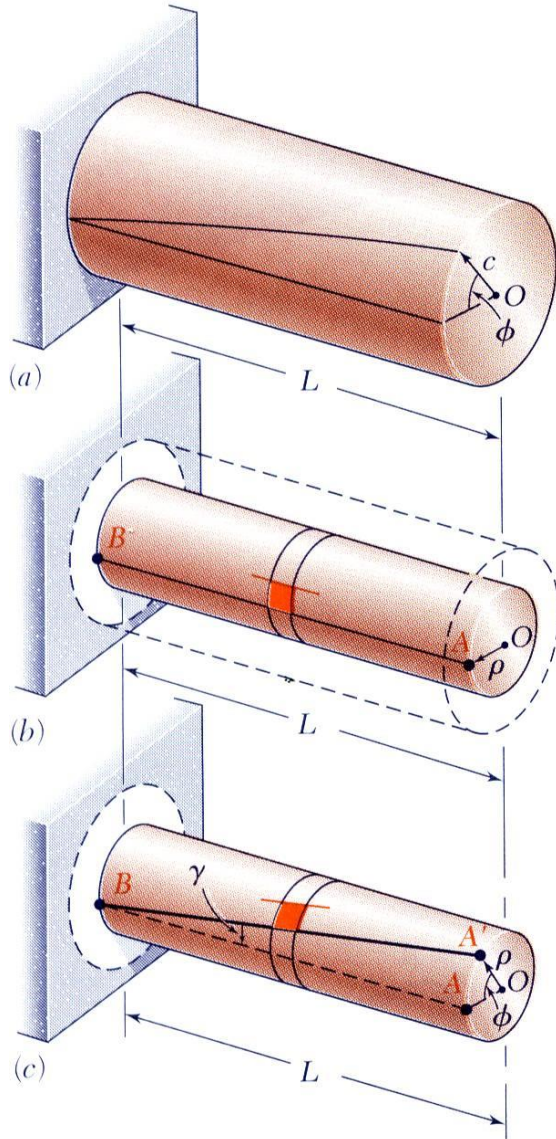
$$\phi \propto T$$

$$\phi \propto L$$

- When subjected to torsion, every cross-section of a circular shaft remains plane and undistorted.
- Cross-sections for hollow and solid circular shafts remain plain and undistorted because a circular shaft is axisymmetric.
- Cross-sections of noncircular (non-axisymmetric) shafts are distorted when subjected to torsion.



# Shearing Strain



- Consider an interior section of the shaft. As a torsional load is applied, an element on the interior cylinder deforms into a rhombus.

- Since the ends of the element remain planar, the shear strain is equal to angle of twist.

- It follows that

$$L\gamma = \rho\phi \quad \text{or} \quad \gamma = \frac{\rho\phi}{L}$$

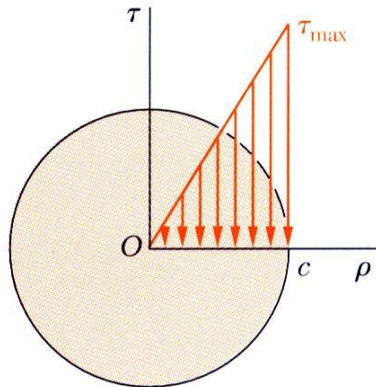
- Shear strain is proportional to twist and radius

$$\gamma_{\max} = \frac{c\phi}{L} \quad \text{and} \quad \gamma = \frac{\rho}{c} \gamma_{\max}$$

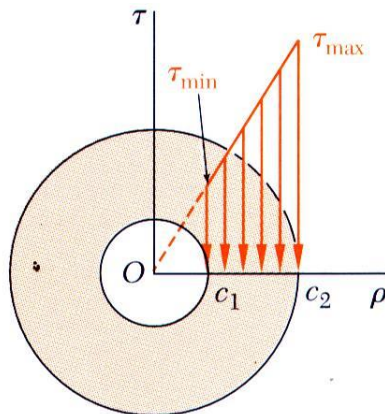
$c$  = surface radius



# Stresses in Elastic Range



$$J = \frac{1}{2} \pi c^4$$



$$J = \frac{1}{2} \pi (c_2^4 - c_1^4)$$

- Multiplying the previous equation by the shear modulus,

$$G\gamma = \frac{\rho}{c} G\gamma_{\max}$$

From Hooke's Law,  $\tau = G\gamma$ , so

$$\tau = \frac{\rho}{c} \tau_{\max}$$

The shearing stress varies linearly with the radial position in the section.

- Recall that the sum of the moments from the internal stress distribution is equal to the torque on the shaft at the section,

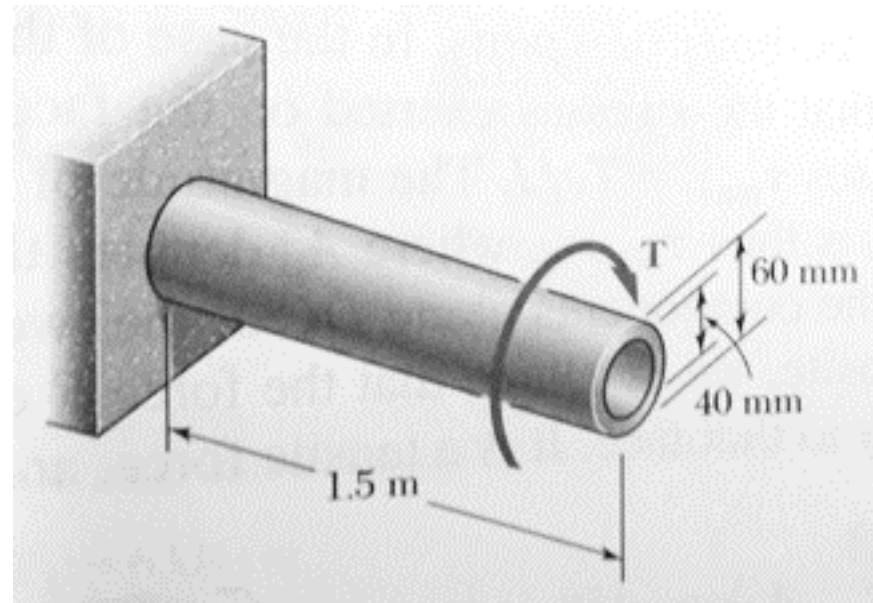
$$T = \int \rho \tau dA = \frac{\tau_{\max}}{c} \int \rho^2 dA = \frac{\tau_{\max}}{c} J$$

- The results are known as the elastic torsion formulas,

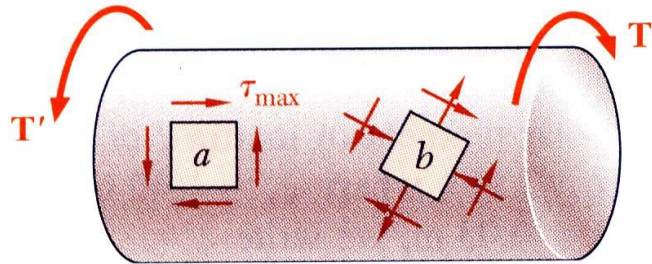
$$\tau_{\max} = \frac{Tc}{J} \quad \text{and} \quad \tau = \frac{T\rho}{J}$$

# Problem 1

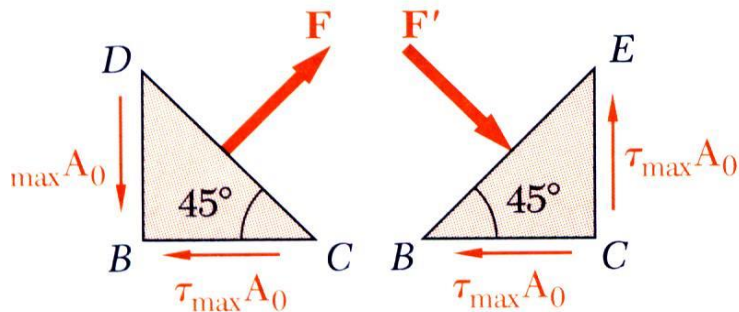
A hollow cylindrical shaft is 1.5 m long and has inner and outer diameters respectively equal to 40 and 60 mm. (a) What is the largest torque that can be applied to the shaft if the shearing stress is not to exceed 120 MPa.? (b) What is the corresponding minimum value of shearing stress in the shaft?



# Normal Stresses



- Elements with faces parallel and perpendicular to the shaft axis are subjected to shear stresses only. Normal stresses, shearing stresses or a combination of both may be found for other orientations.

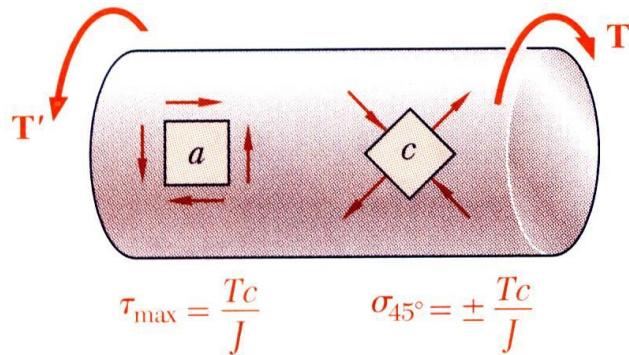


- Consider an element at  $45^\circ$  to the shaft axis,

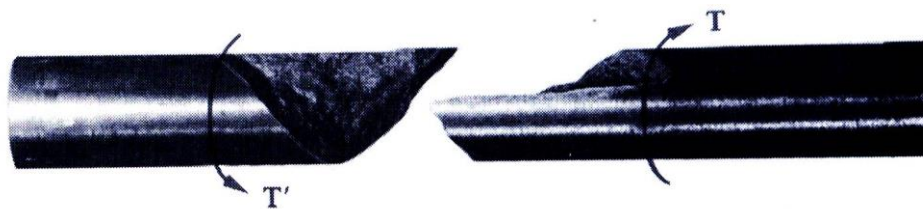
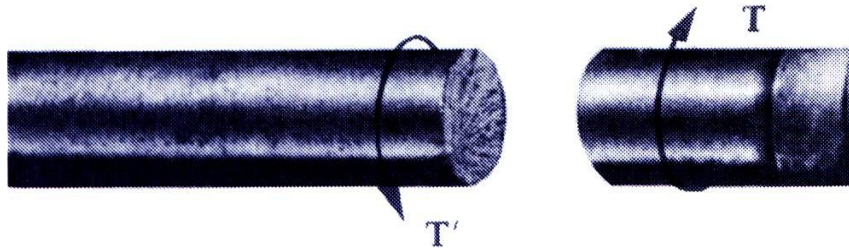
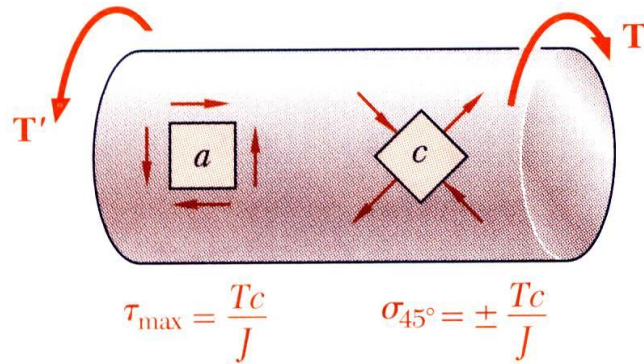
$$F = 2(\tau_{\max} A_0) \cos 45 = \tau_{\max} A_0 \sqrt{2}$$

$$\sigma_{45^\circ} = \frac{F}{A} = \frac{\tau_{\max} A_0 \sqrt{2}}{A_0 \sqrt{2}} = \tau_{\max}$$

- Element  $a$  is in pure shear.
- Element  $c$  is subjected to a tensile stress on two faces and compressive stress on the other two.
- Note that all stresses for elements  $a$  and  $c$  have the same magnitude



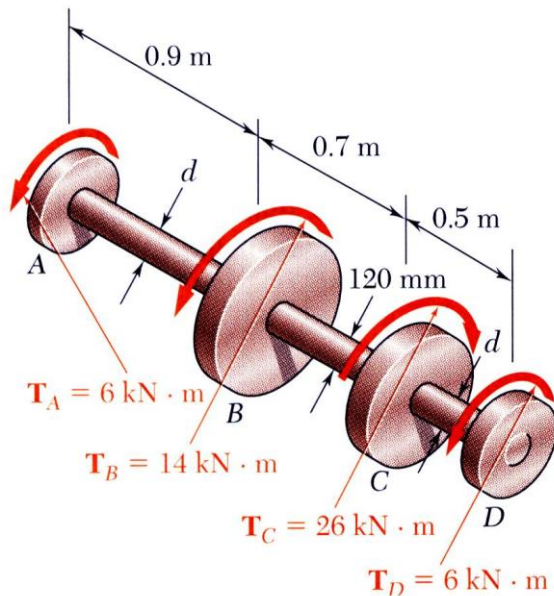
# Torsional Failure Modes



- Ductile materials generally fail in shear. Brittle materials are weaker in tension than shear.
- When subjected to torsion, a ductile specimen breaks along a plane of maximum shear, i.e., a plane perpendicular to the shaft axis.
- When subjected to torsion, a brittle specimen breaks along planes perpendicular to the direction in which tension is a maximum, i.e., along surfaces at  $45^\circ$  to the shaft axis.



# Problem 2

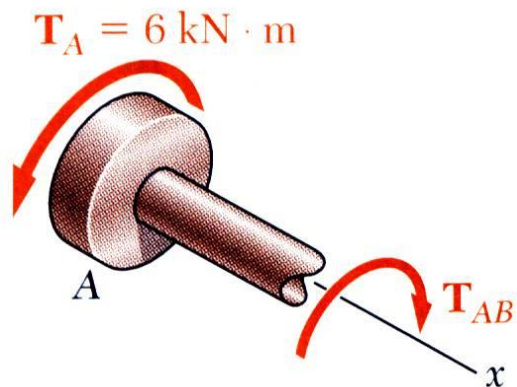


Shaft *BC* is hollow with inner and outer diameters of 90 mm and 120 mm, respectively. Shafts *AB* and *CD* are solid of diameter *d*. For the loading shown, determine (a) the minimum and maximum shearing stress in shaft *BC*, (b) the required diameter *d* of shafts *AB* and *CD* if the allowable shearing stress in these shafts is 65 MPa.



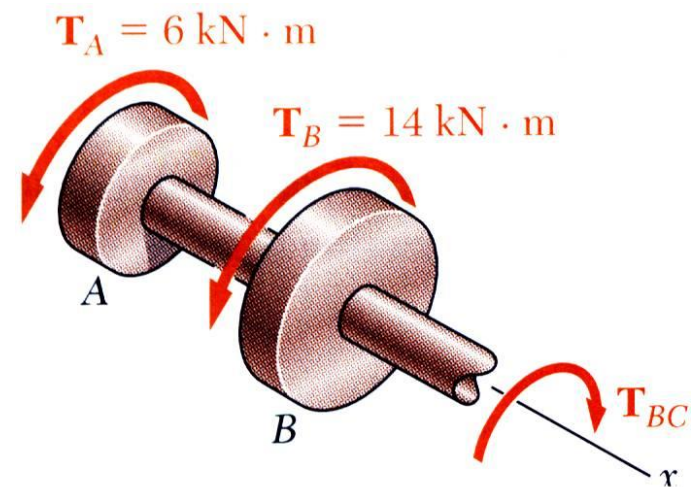
## SOLUTION:

- Cut sections through shafts  $AB$  and  $BC$  and perform static equilibrium analysis to find torque loadings



$$\sum M_x = 0 = (6\text{ kN}\cdot\text{m}) - T_{AB}$$

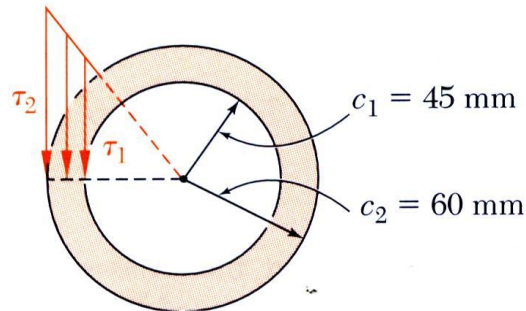
$$T_{AB} = 6\text{ kN}\cdot\text{m} = T_{CD}$$



$$\sum M_x = 0 = (6\text{ kN}\cdot\text{m}) + (14\text{ kN}\cdot\text{m}) - T_{BC}$$

$$T_{BC} = 20\text{ kN}\cdot\text{m}$$

- Apply elastic torsion formulas to find minimum and maximum stress on shaft  $BC$



$$J = \frac{\pi}{2} (c_2^4 - c_1^4) = \frac{\pi}{2} [(0.060)^4 - (0.045)^4]$$

$$= 13.92 \times 10^{-6} \text{ m}^4$$

$$\tau_{\max} = \tau_2 = \frac{T_{BC} c_2}{J} = \frac{(20 \text{ kN} \cdot \text{m})(0.060 \text{ m})}{13.92 \times 10^{-6} \text{ m}^4}$$

$$= 86.2 \text{ MPa}$$

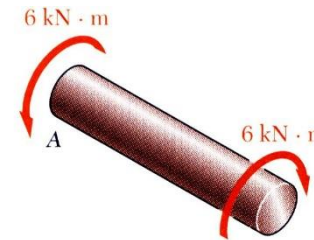
$$\frac{\tau_{\min}}{\tau_{\max}} = \frac{c_1}{c_2} \quad \frac{\tau_{\min}}{86.2 \text{ MPa}} = \frac{45 \text{ mm}}{60 \text{ mm}}$$

$$\tau_{\min} = 64.7 \text{ MPa}$$

$$\tau_{\max} = 86.2 \text{ MPa}$$

$$\tau_{\min} = 64.7 \text{ MPa}$$

- Given allowable shearing stress and applied torque, invert the elastic torsion formula to find the required diameter

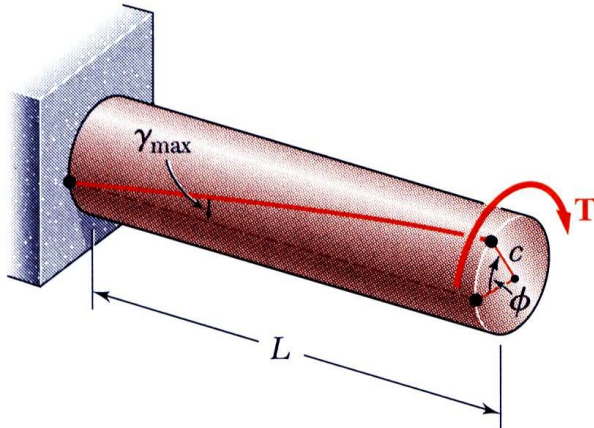


$$\tau_{\max} = \frac{Tc}{J} = \frac{Tc}{\frac{\pi}{2} c^4} \quad 65 \text{ MPa} = \frac{6 \text{ kN} \cdot \text{m}}{\frac{\pi}{2} c^3}$$

$$c = 38.9 \times 10^{-3} \text{ m}$$

$$d = 2c = 77.8 \text{ mm}$$

# Angle of Twist in Elastic Range



- Recall that the angle of twist and maximum shearing strain are related,

$$\gamma_{\max} = \frac{c\phi}{L}$$

- In the elastic range, the shearing strain and shear are related by Hooke's Law,

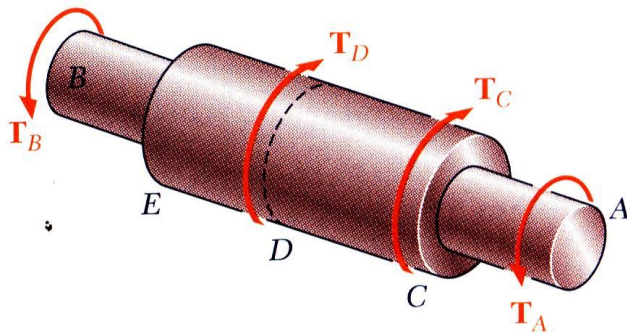
$$\gamma_{\max} = \frac{\tau_{\max}}{G} = \frac{Tc}{JG}$$

- Equating the expressions for shearing strain and solving for the angle of twist,

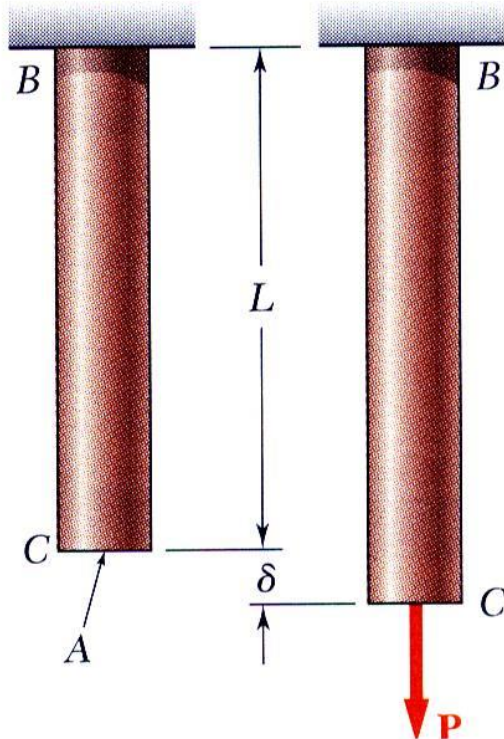
$$\phi = \frac{TL}{JG}$$

- If the torsional loading or shaft cross-section changes along the length, the angle of rotation is found as the sum of segment rotations

$$\phi = \sum_i \frac{T_i L_i}{J_i G_i}$$



# Compare with: Deformations Under Axial Loading



- From Hooke's Law:

$$\sigma = E\varepsilon \quad \varepsilon = \frac{\sigma}{E} = \frac{P}{AE}$$

- From the definition of strain:

$$\varepsilon = \frac{\delta}{L}$$

- Equating and solving for the deformation,

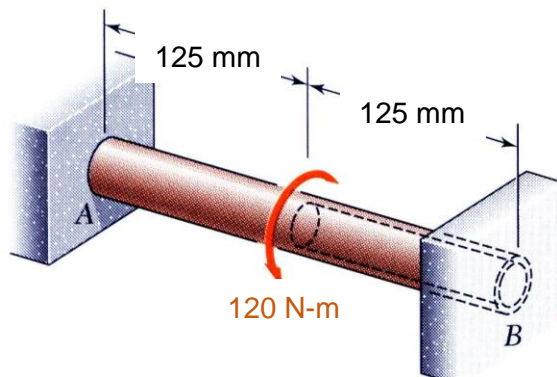
$$\delta = \frac{PL}{AE}$$

$$\phi = \frac{TL}{JG}$$

- With variations in loading, cross-section or material properties,

$$\delta = \sum_i \frac{P_i L_i}{A_i E_i}$$

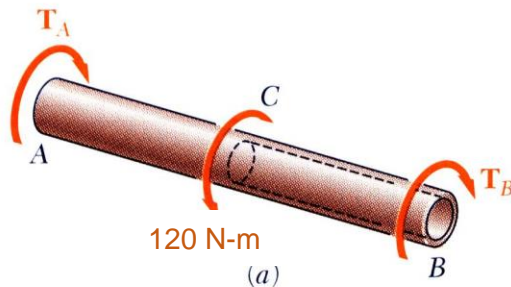
# Statically Indeterminate Shafts



- Given the shaft dimensions and the applied torque, we would like to find the torque reactions at A and B.
- From a free-body analysis of the shaft,

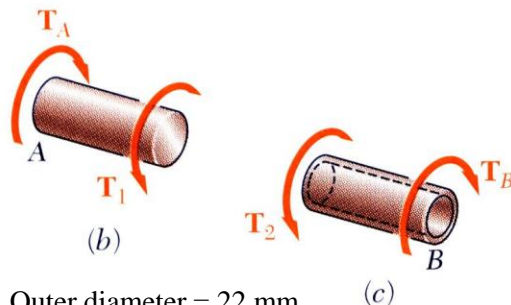
$$T_A + T_B = 120 \text{ N-m}$$

which is not sufficient to find the end torques. The problem is statically indeterminate.



- Divide the shaft into two components which must have compatible deformations,

$$\phi = \phi_1 + \phi_2 = \frac{T_A L_1}{J_1 G} - \frac{T_B L_2}{J_2 G} = 0 \quad T_B = \frac{L_1 J_2}{L_2 J_1} T_A$$



Outer diameter = 22 mm  
Inner diameter = 16 mm

- Substitute into the original equilibrium equation,

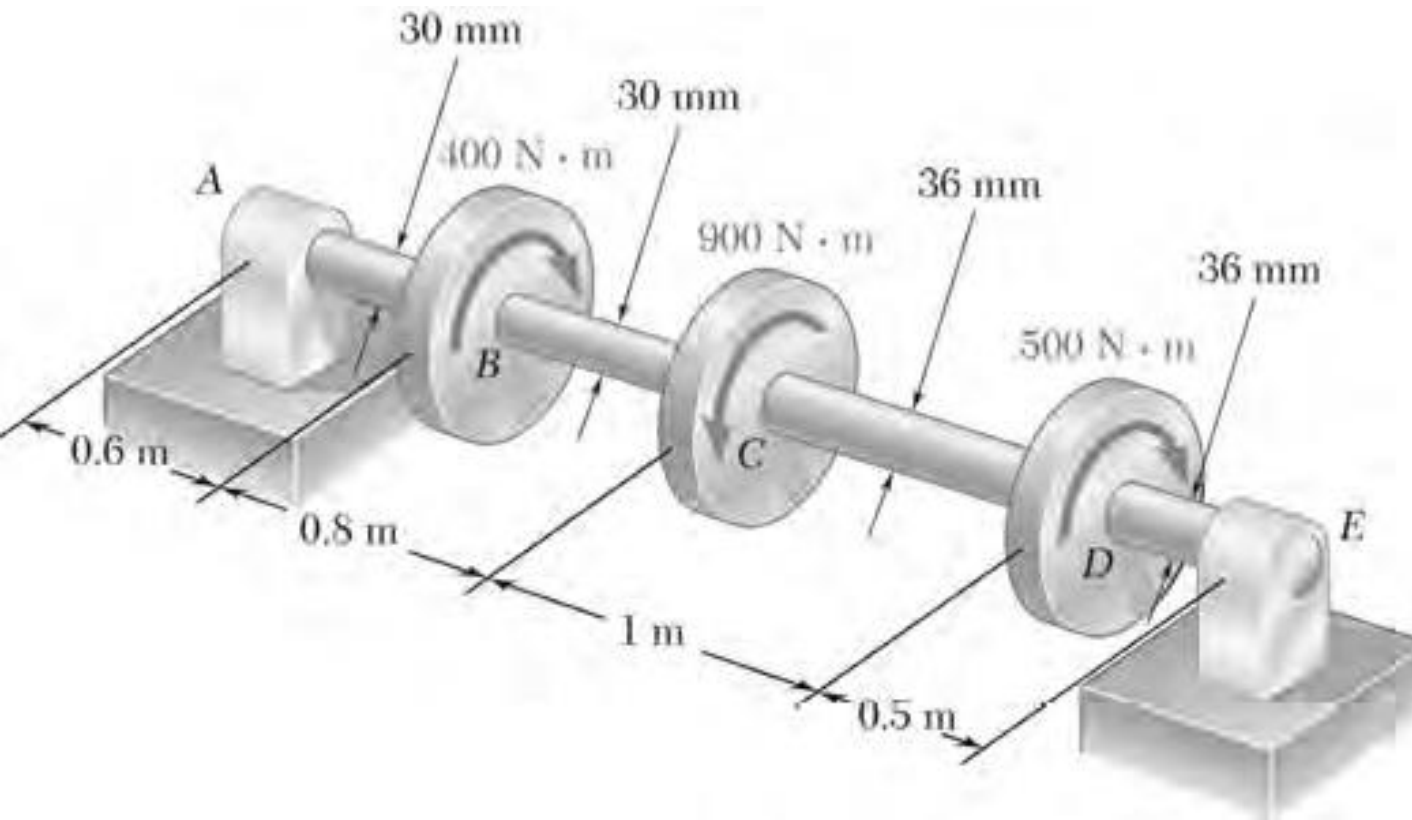
$$T_A + \frac{L_1 J_2}{L_2 J_1} T_A = 120 \text{ N-m}$$

$$T_A = 69.8 \text{ N-m} \quad T_B = 50.2 \text{ N-m}$$



# Problem 3

The torques shown are exerted on pulleys B, C, and D. Knowing that the entire **shaft** is made of steel ( $G = 27$  GPa), determine the angle of twist between (a) C and B, (b) D and B.



# Problem 4

Two solid shafts are connected by gears as shown. Knowing that  $G = 77.2$  GPa for each shaft, determine the angle through which end A rotates when  $T_A = 1200\text{ N} \cdot \text{m}$ .

Given the direction of torque at A, B will rotate clockwise, C will rotate counter-clockwise

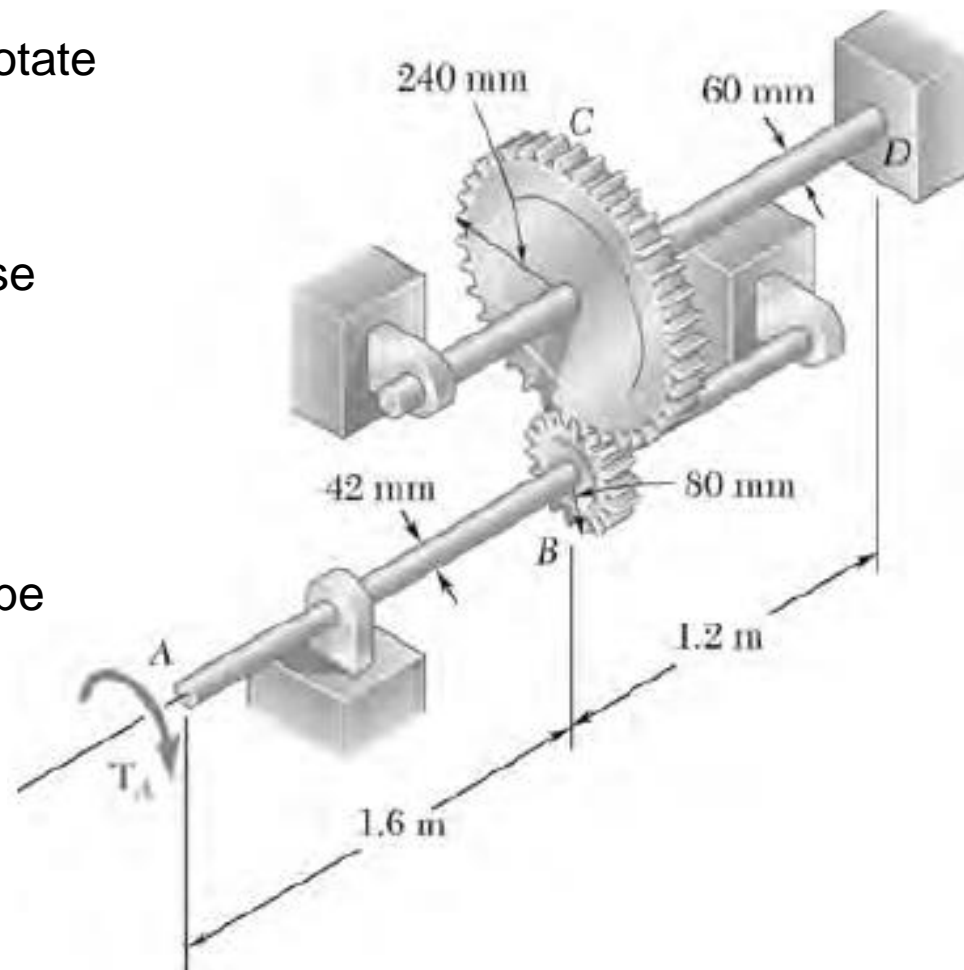
w.r.t. to D, C **twists** counter-clockwise

w.r.t. to C, B **twists** opposite, i.e. clockwise

w.r.t. to D, B **twists** clockwise

w.r.t. to B, A **twists** clockwise

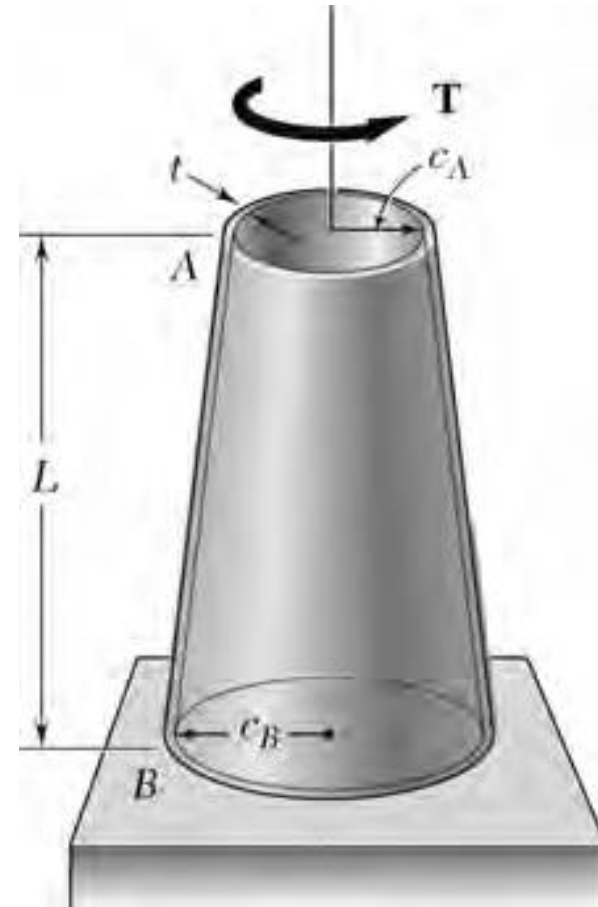
Hence, the twists  $\phi_{B/D}$  and  $\phi_{A/B}$  should be added to get  $\phi_{A/D}$

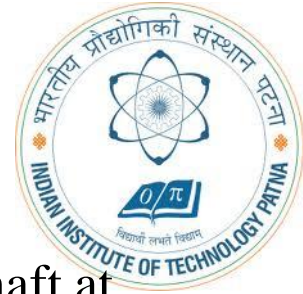


# Problem 5

The long, hollow, tapered shaft AB has a uniform thickness  $t$ . Denoting by  $G$  the modulus of rigidity, shown that the angle of twist at end A is

$$\phi_A = \frac{TL}{4\pi Gt} \frac{c_A + c_B}{c_A^2 c_B^2}$$





# Design of Transmission Shafts

- Principal transmission shaft performance specifications are:

- power
- speed

- Designer must select shaft material and cross-section to meet performance specifications without exceeding allowable shearing stress.

- Determine torque applied to shaft at specified power and speed,

$$P = T\omega = 2\pi fT$$

$$T = \frac{P}{\omega} = \frac{P}{2\pi f}$$

- Find shaft cross-section which will not exceed the maximum allowable shearing stress,

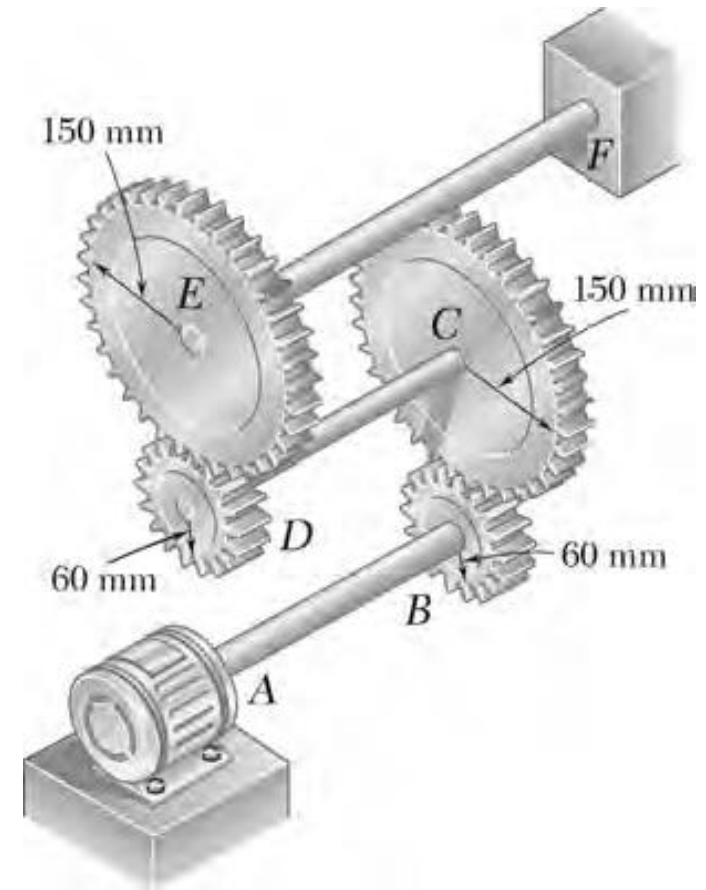
$$\tau_{\max} = \frac{Tc}{J}$$

$$\frac{J}{c} = \frac{\pi}{2} c^3 = \frac{T}{\tau_{\max}} \quad (\text{solid shafts})$$

$$\frac{J}{c_2} = \frac{\pi}{2c_2} (c_2^4 - c_1^4) = \frac{T}{\tau_{\max}} \quad (\text{hollow shafts})$$

# Problem 6

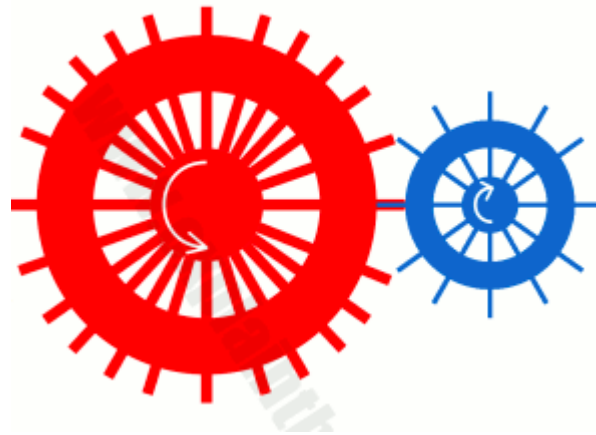
Three shafts and four gears are used to form a gear train that will transmit power from the motor at A to a machine tool at F. (Bearings for the shafts are omitted in the sketch.) The diameter of each shaft is as follows:  $d_{AB} = 16$  mm,  $d_{CD} = 20$  mm,  $d_{EF} = 28$  mm. Knowing that the frequency of the motor is 24 Hz and that the allowable shearing stress for each shaft is 75 MPa, determine the maximum power that can be transmitted.





# Gears: Speed and Power/Force

**Increase speed:** If you connect two gears together and the **first one** has more teeth than the **second one** (generally that means it's a bigger-sized wheel), the **second one** has to turn round much faster to keep up. So this arrangement means the **second wheel** turns faster than the **first one** but with less force. Looking at our diagram on the right (top), turning the **red wheel** (with 24 teeth) would make the **blue wheel** (with 12 teeth) go twice as fast but with half as much force.



**Increase force:** If the **second wheel** in a pair of gears has more teeth than the **first one** (that is, if it's a larger wheel), **it** turns slower than the **first one** but with more force. (Turn the blue wheel and the red wheel goes slower but has more force.)