```
traccc::fitting_config
    < scalar_type >

+ n_iterations
+ pathlimit
+ overstep_tolerance
+ step_constraint
+ mask_tolerance
```

-m_cfg

```
traccc::kalman_fitter
< stepper_t, navigator_t >

- m_detector
- m_field

+ kalman_fitter()
+ fit()
+ filter()
+ smooth()
+ update_statistics()
```