

# Linear Algebra HW3

---

1

(a)

$$A = LDU$$

$$A^T = U^T D^T L^T$$

$D$  and  $D^T$  have same pivots. – < ans >

(b)

$$A \text{ is symmetric} \rightarrow A^T = A$$

$$(AA^{-1})^T = (A^{-1})^T A^T = I$$

$$\Rightarrow (A^{-1})^T = (A^T)^{-1} = A^{-1} \text{ – < ans >}$$

(c)

$$\because A \text{ is symmetric} \rightarrow A = A^T$$

$$(R^T A R)^T = R^T A^T R = R^T A R$$

$$\Rightarrow R^T A R \text{ is symmetric. – < ans >}$$

$$\dim((R^T)_{nm} A_{mn} R_{mn}) = n * n \text{ – < ans >}$$

2

(a) True

for any triangular matrix  $A$ ,  $A$  can be factorized by  $LD$  or  $DU$ .

where  $L = L_1 L_2 \dots L_n$ ,  $U = U_1 U_2 \dots U_n$  can be solved by Gauss Elimination.

inverse of  $L_1, \dots, L_n, U_1, \dots, U_n$  are also triangular matrices

Hence,  $A^{-1} = D^{-1} L^{-1}$  or  $D^{-1} L^{-1}$  is also a

triangular matrix. – < ans >

(b) True

From the result in 1(b), we can get

$$(A^{-1})^T = A^{-1} \text{ – < ans >}$$

**(c) False**

*proof by contradiction :*

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 3 & 4 & 5 \\ 0 & 6 & 7 \end{bmatrix}, \quad A^{-1} = \begin{bmatrix} \frac{1}{22} & \frac{7}{22} & \frac{-5}{22} \\ \frac{21}{44} & \frac{-7}{44} & \frac{5}{44} \\ \frac{-9}{22} & \frac{3}{22} & \frac{1}{22} \end{bmatrix}$$

**(d) False**

*When calculating  $A^{-1}$  by Gauss – Jordan method, all entries might not be whole numbers after calculation.*

**(e) True**

*$\therefore$  fractions  $\in \mathbb{Q}$ , and  $\mathbb{Q}$  is a field.*

*$\therefore$  fractions have closure with operations  $(+, -, *, /)$ .*

**3**

$$D_{j+1} - 2D_j + D_{j-1} = h^2 f(jh) \quad j = 1, \dots, 5$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -2 & 1 \end{bmatrix} \begin{bmatrix} D_0 \\ D_1 \\ D_2 \\ D_3 \\ D_4 \\ D_5 \\ D_6 \end{bmatrix} = \begin{bmatrix} h^2 f(h) \\ h^2 f(2h) \\ h^2 f(3h) \\ h^2 f(4h) \\ h^2 f(5h) \end{bmatrix}$$

*because of initail conditions,  $D_0 = D_1 = 0$ , the equations can be reduced to*

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ -2 & 1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 \end{bmatrix} \begin{bmatrix} D_2 \\ D_3 \\ D_4 \\ D_5 \\ D_6 \end{bmatrix} = \begin{bmatrix} h^2 f(h) \\ h^2 f(2h) \\ h^2 f(3h) \\ h^2 f(4h) \\ h^2 f(5h) \end{bmatrix}$$

*Since final speed equals to 0,  $D_5 = D_6$ .*

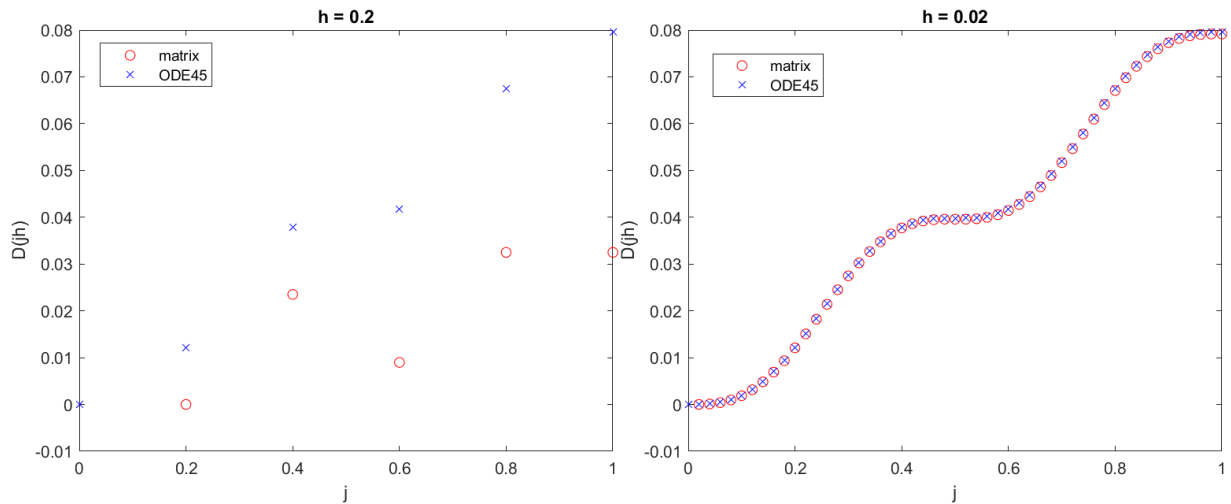
*the equation can be represented as below :*

$$\begin{bmatrix} -2 & 1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} D_1 \\ D_2 \\ D_3 \\ D_4 \\ D_5 \end{bmatrix} = \begin{bmatrix} h^2 f(h) \\ h^2 f(2h) \\ h^2 f(3h) \\ h^2 f(4h) \\ h^2 f(5h) \end{bmatrix}$$

*Let  $h = 0.2$*

$$\begin{bmatrix} D_1 \\ D_2 \\ D_3 \\ D_4 \\ D_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0.0235 \\ 0.090 \\ 0.0325 \\ 0.0325 \end{bmatrix} - \langle ans \rangle$$

the plot  $D(jh)$  vs.  $j$ :



**4**

without patial pivoting :

$$A = \begin{bmatrix} .0001 & 0 \\ 1 & 10000 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 10000 & 1 \end{bmatrix} \begin{bmatrix} .0001 & 0 \\ 0 & 10000 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

with partial pivoting :

$$A' = \begin{bmatrix} 1 & 10000 \\ .0001 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ .0001 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 10000 \\ 0 & 1 \end{bmatrix}$$

after scaling by multiply 10000

without patial pivoting :

$$A = \begin{bmatrix} 1 & 0 \\ 10000 & 10^8 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 10000 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 10^8 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

with partial pivoting :

$$A = \begin{bmatrix} 10000 & 10^8 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ .0001 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -10000 \end{bmatrix} \begin{bmatrix} 1 & 10^8 \\ 0 & 1 \end{bmatrix}$$

after pivoting, we can get more stable pivots.

after scaling, we can avoid gettig small pivots.

**5**

**(a) True**

$b_1 = 0$ ,  $\vec{B} = (0, b_2, b_3)$ , where  $b_2, b_3 \in \mathbb{R}$

For any two vectors  $\vec{B}_1, \vec{B}_2$  in  $\vec{B}$ ,  $\vec{B}_1 + \vec{B}_2$  is still in  $\vec{B}$ .

$$\forall c \in \mathbb{R}, \quad \text{and} \quad \forall \vec{B}_1 \in \vec{B}, \quad c\vec{B}_1 \in \vec{B}$$

**(b) False**

$\therefore$  for scaling,  $b_1$  might not be 1, as well as scaling.

**(c) False**

*Proof by contradiction,*

$$\text{let } \vec{b}_1 = (0, 0, 1), \vec{b}_2 = (0, 1, 0), \vec{b}_1 + \vec{b}_2 = (0, 1, 1)$$

**(d) True**

*All combinations means that for addition and scaling still in the span of given vectors.*

**(e) True**

*For addition of any two vectors which are lying in plane is still lying in plane, as well as scaling.*

**6**

**(f) False**

*Proof by contradictions :*

$$\text{Let } A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, b_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, b_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$b_1 + b_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \text{ in the column space of } A.$$

**(g) True**

$\therefore$  the column space of  $A$  contains only zero vector,

$\therefore$  All entries of  $A$  is 0.

**(h) True**

*Scaling would not change column space.*

**(i) False**

*Proof by contradiction :*

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad A - I = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

**(j) True**

$\therefore$  Dimension of  $\mathbb{R}^2$  and  $\mathbb{R}^3$  is different.

Although  $\mathbb{R}^2$  is isomorphic to the subset  $(a, b, 0)$  of  $\mathbb{R}^3$ ,  
but it's also isomorphic to infinitely many other subspaces  
of  $\mathbb{R}^3$ .

**7**

**(a)**

$$\begin{aligned}[A \quad B] &= \begin{bmatrix} 1 & 2 & 0 & 3 & b_1 \\ 4 & 5 & 1 & 8 & b_2 \\ 2 & 1 & 1 & 2 & b_3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 & 0 & 3 & b_1 \\ 0 & -3 & 1 & -4 & b_2 - 4b_1 \\ 0 & -3 & 1 & -4 & b_3 - 2b_1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 & 0 & 3 & b_1 \\ 0 & -3 & 1 & -4 & b_2 - 4b_1 \\ 0 & 0 & 0 & 0 & 2b_1 - b_2 + b_3 \end{bmatrix}\end{aligned}$$

**(b)**

$b$  have to lie in the column space of  $A$ .

That is,  $2b_1 - b_2 + b_3 = 0$  — *< ans >*

**(c)**

$$U = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & -3 & 1 & -4 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 1 & \frac{-1}{3} & \frac{4}{3} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Null space can be obtained from solving  $Ux = 0$

$$\text{Null space of } U \text{ is: } \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ -1 \\ -2 \end{bmatrix} \text{ — } < \text{ans} >$$