

Assignment Report: Breadth-First Search

CSE-0408 Summer 2021

Md.Taskir Rahman Tasin
Department of Computer Science and Engineering
State University of Bangladesh (SUB)
Dhaka, Bangladesh
taskir.rahman72@gmail.com

Abstract—Solving problem and learn about breadth first search algorithm using c++ language. Traversal means visiting all the nodes of a graph. Breadth First Traversal or Breadth First Search is a recursive algorithm for searching all the vertices of a graph or tree data structure.

Index Terms—Nodes, Edges, source, graph, queue, visited, IDE codeblocks.

I. INTRODUCTION

The breadth-first algorithm is a particular graph-search algorithm that can be applied to solve a variety of problems such as finding all the vertices reachable from a given vertex, finding if an undirected graph is connected, finding (in an unweighted graph) the shortest path from a given vertex to all other vertices, determining if a graph is bipartite, bounding the diameter of an undirected graph, partitioning graphs, and as a subroutine for finding the maximum flow in a flow network (using Ford-Fulkerson's algorithm). As with the other graph searches, BFS can be applied to both directed and undirected graphs.

II. LITERATURE REVIEW

Breadth-First Search is an important kernel used by many graph-processing applications. In many of these emerging applications of BFS, such as analyzing social networks, the input graphs are low-diameter and scale-free. We propose a hybrid approach that is advantageous for low-diameter graphs, which combines a conventional top-down algorithm along with a novel bottom-up algorithm. The bottom-up algorithm can dramatically reduce the number of edges examined, which in turn accelerates the search as a whole. On a multi-socket server, our hybrid approach demonstrates speedups of 3.3 – 7.8 on a range of standard synthetic graphs and speedups of 2.4 – 4.6 on graphs from real social networks when compared to a strong baseline. We also typically double the performance of prior leading shared memory (multicore and GPU) implementations.

III. PROPOSED METHODOLOGY

A standard BFS implementation puts each vertex of the graph into one of two categories:

1. Visited
2. Not Visited

The purpose of the algorithm is to mark each vertex as visited while avoiding cycles.

The algorithm works as follows:

1. Start by putting any one of the graph's vertices at the back of a queue.
 2. Take the front item of the queue and add it to the visited list.
 3. Create a list of that vertex's adjacent nodes. Add the ones which aren't in the visited list to the back of the queue.
 4. Keep repeating steps 2 and 3 until the queue is empty.
- The graph might have two different disconnected parts so to make sure that we cover every vertex, we can also run the BFS algorithm on every node.

A. Inputs:

Firstly input the number of edges and number of nodes use in the graph. Then inputs are a graph (directed or undirected) $G = (V, E)$ and a source vertex s , where s is an element of V . The adjacency list representation of a graph is used in this analysis.



```
"C:\Users\Hp\Desktop\summer 2021\cse0408 hasib\tasin\bfsfinal.exe"
Number of node
5
Number of edge
5
undirected graph(u , v)
1 2
undirected graph(u , v)
1 4
undirected graph(u , v)
1 3
undirected graph(u , v)
3 5
undirected graph(u , v)
4 5
From initial starting node
1
```

Fig. 1. input format

B. Outputs:

The outputs are a predecessor graph, which represents the paths travelled in the BFS traversal, and a collection of distances, which represent the distance of each of the vertices from the source vertex.

```

"C:\Users\Hp\Desktop\summer 2021\cse0408 hasib\tasin\bfsfinal.exe"
Number of node
5
Number of edge
5
undirected graph(u , v)
1 2
undirected graph(u , v)
1 4
undirected graph(u , v)
1 3
undirected graph(u , v)
3 5
undirected graph(u , v)
4 5
From initial starting node
1
Distance of 1is : 0
Distance of 2is : 1
Distance of 3is : 1
Distance of 4is : 1
Distance of 5is : 2

Process returned 0 (0x0)   execution time : 99.196 s
Press any key to continue.

```

Fig. 2. output format

```

1  #include<bits/stdc++.h>
2  using namespace std;
3
4  #define MX 110
5
6  vector < int > graph[110];
7  bool vis[MX];
8  int dist[MX];
9
10 void bfs(int source)
11 {
12     queue < int > Q;
13     vis[source]=1;
14     dist[source]=0;
15     Q.push(source);
16
17     while(!Q.empty())
18     {
19         int node =Q.front();
20         Q.pop();
21
22         for (int i=0; i < graph[node].size(); i++)
23         {
24             int next = graph [node][i];
25             if(vis[next]==0)
26             {
27                 vis[next]=1;
28                 dist[next]=dist[node]+1;
29                 Q.push(next);
30             }
31         }
32     }
33 }
34
35
36
37
38 int main()
39 {
40     int nodes,edges;
41     cout << "Number of node " << endl;
42     cin >> nodes;
43     cout << "Number of edge " << endl;
44     cin >> edges ;
45     for (int i=1; i<=edges; i++)
46     {
47         int u,v;
48         cout << "undirected graph(u , v) " << endl;
49         cin>> u >> v;
50         graph[u].push_back(v);
51         graph[v].push_back(u);
52     }
53
54     int source ;
55     cout << "From initial starting node " << endl;
56     cin >> source ;
57     bfs(source);
58     for (int i=1; i<=nodes ; i++)
59     {
60         cout << "Distance of " << i << "is : " <<dist[i] << endl;
61     }
62
63     return 0;
64 }
65

```

Fig. 3. code

ACKNOWLEDGMENT

I would like to thank my honourable **Khan Md. Hasib Sir** for his time, generosity and critical insights into this project.

REFERENCES

- [1] S. Beamer, K. Asanovic and D. Patterson, "Direction-optimizing Breadth-First Search," SC '12: Proceedings of the International Conference on High Performance Computing, Networking, Storage and Analysis, 2012, pp. 1-10, doi: 10.1109/SC.2012.50.
- [2]